

On Tilted Losses in Machine Learning : Theory and Application

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Introduction

Definitions

for each $\theta \in \Theta \subseteq R^d$ and the Dataset $\{x_1, \dots, x_N\}$ we Define ERM as :

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Flaws :

Introduction

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$$\overline{R} := \frac{1}{N} \sum_{i \in [N]} f(x_i; \theta)$$

Flaws :

- average performance is not an appropriate surrogate for the problem of interest

Proposed solution = TERM

for a real-valued hyperparameter, $t \in \mathbb{R} \setminus 0$, TERM is given by :

$$\tilde{R}(t; \theta) := \frac{1}{t} \log \left(\frac{1}{N} \sum_{i \in [N]} e^{t f(x_i; \theta)} \right)$$

- $\tilde{R}(+\infty; \theta) = \text{max-loss}$
- $\tilde{R}(-\infty; \theta) = \text{min-loss}$
- $\tilde{R}(0; \theta) = \text{ERM}$

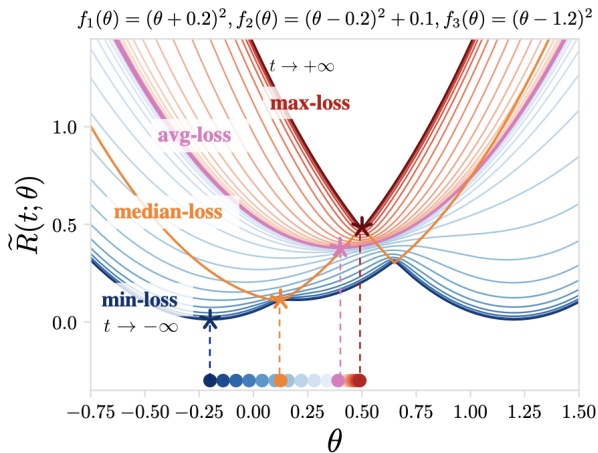


Figure: TERM for different values of t

Let $\mathcal{P} := \{p_\theta\}$.

Define information of x under θ as :

$$f(x : \theta) := -\log p_\theta(x)$$

Also Define : (Cumulant Generating Function)

$$\Lambda_X(t; \theta) := \log \left(\mathbb{E}_{x \sim p} \left[e^{tf(X; \theta)} \right] \right) = \log \sum_x p(x) p_\theta(x)^{-t}$$

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proper scaling of $\tilde{R}(t; \theta)$

Example

- Statistics : Convergence properties of statistical estimation

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- Applied Probability : Concentration bounds in large deviation theory

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- Statistics : Convergence properties of statistical estimation
- Applied Probability : Concentration bounds in large deviation theory
- Information theory : error exponents in channel coding - probability of error in list decoding - computational cost in sequential decoding
- Machine Learning : robust regression - sequential decision making

Motivation Example

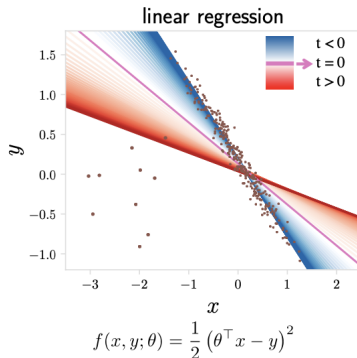
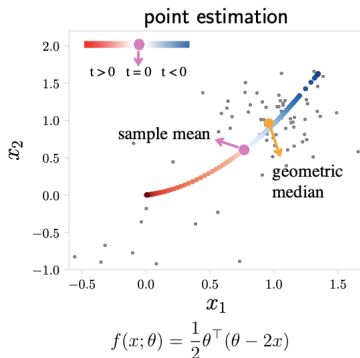


Figure: Motivation examples

Contents

Assumptions

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- 1 (Continuous differentiability) : For $i \in [N]$ the loss function $f(x; \theta)$ belongs to the differentiability class C^1 with respect to $\theta \in \Theta \subseteq \mathbb{R}^d$

Assumptions

Assumptions

- ① (Continuous differentiability) : For $i \in [N]$ the loss function $f(x; \theta)$ belongs to the differentiability class C^1 with respect to $\theta \in \Theta \subseteq \mathbb{R}^d$
- ② (Smoothness and strong convexity) : for any $i \in [N]$, $f(x_i; \theta)$ belongs to differentiability class C^2 with respect to θ , we further assume that

$$\beta_{min} \mathbf{I} \preceq \nabla_{\theta\theta^T}^2 f(x_i; \theta) \preceq \beta_{max} \mathbf{I}$$

Assumptions

Assumptions

- ⑨ (Generalized linear model condition) Assume that

$$f(x; \theta) = A(\theta) - \theta^T T(x),$$

where $A(\cdot)$ is convex such :

$$\beta_{min} \mathbf{I} \preceq \nabla_{\theta\theta^T}^2 A(\theta) \preceq \beta_{max} \mathbf{I}$$

and ,

$$\sum_{i \in [N]} T(x_i) T(x_i)^T \succeq 0$$

Assumptions

Define

$$\check{\theta}(t) \in \operatorname{argmin}_{\theta \in \Theta} \tilde{R}(t; \theta)$$

and,

$$\tilde{F}(t) := \tilde{R}(t; \check{\theta}(t))$$

Then :

Assumptions

- 4 (Strict saddle property) for all $t \in \mathbb{R}$, $\tilde{R}(t; \theta)$ is strict saddle :
 $\nabla_{\theta\theta^T}^2 \tilde{R}(t; \theta) \succ 0$, and for all stationary solutions, $\lambda_{\min}(\nabla_{\theta\theta^T}^2 \tilde{R}(t; \theta)) < 0$

General Properties

Lemma

Lemma 1: (Lipschitzness of $\tilde{R}(t; \theta)$) : for any t and θ , if for $i \in [N]$, $f(x_i; \theta)$ is L -Lip in θ , then $\tilde{R}(t; \theta)$ is L -Lip in θ

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Lemma 1: (Lipschitzness of $\tilde{R}(t; \theta)$) : for any t and θ , if for $i \in [N]$, $f(x_i; \theta)$ is L -Lip in θ , then $\tilde{R}(t; \theta)$ is L -Lip in θ

Lemma

Lemma 2: Under Assumption 2, for any $t \in \mathbb{R}$,

$$\begin{aligned} \nabla_{\theta\theta^T}^2 \tilde{R}(t; \theta) = & \\ \frac{t}{N} \sum_{i \in [N]} & \left(\nabla_{\theta} f(x_i; \theta) - \nabla_{\theta} \tilde{R}(t; \theta) \right) \left(\nabla_{\theta} f(x_i; \theta) - \nabla_{\theta} \tilde{R}(t; \theta) \right)^T e^{t(f(x_i; \theta) - \tilde{R}(t; \theta))} \\ & + \frac{1}{N} \sum_{i \in [N]} \nabla_{\theta\theta^T}^2 f(x_i; \theta) e^{t(f(x_i; \theta) - \tilde{R}(t; \theta))} \end{aligned}$$

so if $t \in \mathbb{R}^{>0}$:

$$\nabla_{\theta\theta^T}^2 \tilde{R}(t; \theta) \succ \beta_{\min} \mathbf{I}$$

General properties

Lemma

Lemma 3 For any $t \in \mathbb{R}$, let $\beta(t)$ be smoothness parameter of \tilde{R} :

$$\beta(t) := \lambda_{max} \left(\nabla_{\theta\theta^T}^2 \tilde{R}(t; \theta) \right)$$

Further, for $t \in \mathbb{R}^{\leq 0}$,

$$\beta(t) < \beta_{max}$$

and for $t \in \mathbb{R}^{> 0}$,

$$0 < \lim_{t \rightarrow +\infty} \frac{\beta(t)}{t} < +\infty$$

General properties

Theorem

- *Theorem 1: Under Assumption 3:*

$$\frac{\partial}{\partial t} \tilde{R}(t; \theta) \geq 0$$

General properties

Theorem

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$$\frac{\partial}{\partial t} \tilde{R}(t; \theta) \geq 0$$

- *Theorem 2: Under Assumption 3:*

$$\frac{\partial}{\partial t} \tilde{F}(t) = \frac{\partial}{\partial t} \tilde{R}(t; \check{\theta}(t)) \geq 0$$

Re-Weighting Samples to Magnify/Suppress Outliers

Lemma

Lemma 5 :

$$\nabla_{\theta} \tilde{R}(t; \theta) = \sum_{i \in [N]} w_i(t; \theta) \nabla_{\theta} f(x_i; \theta)$$

where ,

$$w_i(t; \theta) = \frac{e^{tf(x_i; \theta)}}{\sum_{j \in [N]} e^{tf(x_j; \theta)}} = \frac{1}{N} e^{t(f(x_i; \theta) - \tilde{R}(t; \theta))}$$

Re-Weighting Samples to Magnify/Suppress Outliers

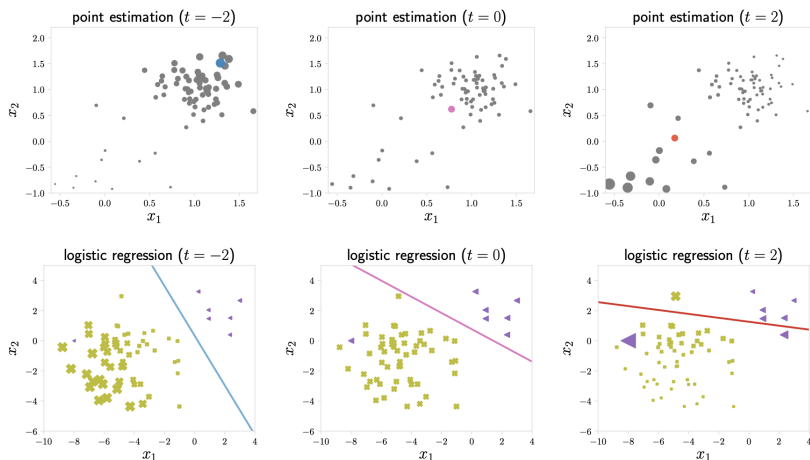


Figure: Interpolation 1

Definition

For $\mathbf{u} \in \mathbb{R}^N$, weighted empirical mean with weights $\mathbf{w} \in \Delta^N$ be :

$$\hat{\mathbb{E}}_{\mathbf{w}}(\mathbf{u}) := \sum_{i \in [N]} w_i u_i$$

Tilted empirical mean: just above, but weights are tilted weights.

$$\hat{\mathbb{E}}_t := \hat{\mathbb{E}}_{\mathbf{w}(t; \tilde{\theta}(t))}(\mathbf{u})$$

and variance as :

$$\hat{var}_t(\mathbf{u}) := \hat{\mathbb{E}}_t \left(u_i - \hat{\mathbb{E}}_t(\mathbf{u}) \right)^2$$

Empirical Bias/Variance Trade-Off

Theorem

Theorem 3 (Variance Reduction), Let

$$\mathbf{f}(\theta) := (f(x_1; \theta), \dots, f(x_N; \theta))$$

, Under assumption 3 and 4 :

$$\frac{\partial}{\partial t} \left\{ \hat{v}ar_{\tau}(\mathbf{f}(\check{\theta}(t))) \right\} \Big|_{t=\tau} < 0$$

Empirical Bias/Variance Trade-Off

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, Under assumption 3 and 4 :

$$\frac{\partial}{\partial t} \left\{ \text{var}_\tau(\mathbf{f}(\tilde{\theta}(t))) \right\} \Big|_{t=\tau} < 0$$

Theorem

Theorem 4: Under assumption 3, 4 for any $t \in \mathbb{R}^{>0}$:

$$\frac{\partial}{\partial t} H(\mathbf{w}(\tau; \tilde{\theta}(t))) \Big|_{\tau=t} > 0$$

Contents

Coming up with a distributional version of TERM :

$$R_X(t; \theta) := \frac{1}{t} \Lambda_X(t; \theta) = \frac{1}{t} \log \left(\mathbb{E} \left[e^{tf(X; \theta)} \right] \right)$$

$$R(t, \theta) = \frac{1}{t} \log \sum_x p(x) p_{\theta}^{-t}(x)$$

TERM and Renyi cross entropy

Remember :

$$H(p||p_\theta) = \sum_x p(x) \log \frac{1}{p_\theta} = \mathbb{E}[f(X; \theta)]$$

For $\rho \in \mathbb{R}^{>0}$, let Renyi cross entropy of order ρ between p and q be defined as :

$$H_\rho(p||q) := \frac{1}{1-\rho} \log \left(\sum_x p(x) q(x)^{\rho-1} \right)$$

So it's straightforward that : $R_X(t; \theta) = H_{1-t}(p||p_\theta)$

And also : $\tilde{R}(t; \theta) = H_{1-t}(\mathbf{u}||\mathbf{w}(1; \theta))$ where \mathbf{u} is uniform N-vector

TERM as a Regularizer to Empirical Risk

The entropic risk of order t can be stated as:

$$R_X(t; \theta) = H(p||p_\theta) + \frac{1}{t} D(p||T(p, p_\theta, -t))$$

Where T is mismatched tilted distribution :

$$T(p, p_\theta, -t)(x) := \frac{p(x)p_\theta(x)^{-t}}{\sum_u p(u)p_\theta(u)^{-t}}$$

also the TERM objective can be written as following :

$$\tilde{R}(t; \theta) = \bar{R}(\theta) + \frac{1}{t} D(\mathbf{u}||\mathbf{w}(t; \theta))$$

Contents

Solving TERM

t -tilted loss remains strongly convex for $t > 0$, so long as the original loss function is strongly convex. On the other hand, for sufficiently large negative t , the t -tilted loss becomes non-convex. Hence, while the t -tilted solutions for positive t are unique, the objective may have multiple (spurious) local minima for negative t even if the original loss function is strongly convex. For negative t , we seek the solution for which the parametric set of t -tilted solutions obtained by sweeping t .()

First order Batch

Theorem 9(Convergence of Algorithm 1 for strongly-convex problems)

under Assumption 2, there exist, $\beta_{max} \leq C_1 < \infty$ and $C_2 < \infty$ that do not depend on t such that for any $t \in \mathbb{R}^{>0}$, setting the step size $\alpha = \frac{1}{C_1 + C_2 t}$ after k iteration:

$$\tilde{R}(t; \theta_k) - \tilde{R}(t; \theta(\check{t})) \leq \left(1 - \frac{\beta}{C_1 + C_2 t}\right)^k (\tilde{R}(t; \theta_0) - \tilde{R}(t; \theta(\check{t})))$$

First order Batch

Algorithm 1: Batch (Non-Hierarchical) TERM

Input: t, α, θ

while *stopping criteria not reached* **do**

 compute the loss $f(x_i; \theta)$ and gradient $\nabla_{\theta} f(x_i; \theta)$ for all $i \in [N]$

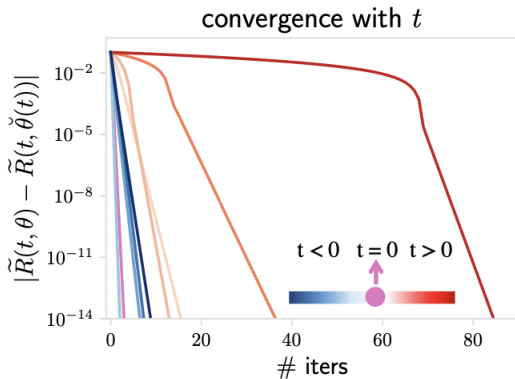
$\tilde{R}(t; \theta) \leftarrow t$ -tilted loss (2) on all $i \in [N]$

$w_i(t; \theta) \leftarrow e^{t(f(x_i; \theta) - \tilde{R}(t; \theta))}$

$\theta \leftarrow \theta - \frac{\alpha}{N} \sum_{i \in [N]} w_i(t; \theta) \nabla_{\theta} f(x_i; \theta)$

end

First order Batch



First order Batch

Theorem 10(Convergence of Algorithm 1 for smooth problems satisfying PL conditions)

Assume $f(x, \theta)$ is β_{max} smooth and Possibly non-convex. Further assume $\sum_{i \in [N]} p_i f(x, \theta)$ is $\mu/2$ -PL for any $P \in \Delta_N$ where P is $P := (p_1, \dots, p_n)$. There exists $\beta_{max} \leq C_1 < \infty$ and $C_2 < \infty$ that do not depend on t such that for any $t \in \mathbb{R}_{\geq 0}$ with setting step $\alpha = \frac{1}{C_1 + C_2 t}$ after k iteration:

$$\tilde{R}(t; \theta_k) - \tilde{R}(t; \theta(\check{t})) \leq \left(1 - \frac{\mu}{C_1 + C_2 t}\right)^k (\tilde{R}(t; \theta_0) - \tilde{R}(t; \theta(\check{t})))$$

Theorem 10 applies to both convex and non-convex smooth functions satisfying PL conditions.

First order Stochastic Methods

To obtain unbiased stochastic gradients, we need to have access to the normalization weights for each sample, which is often intractable to compute for large-scale problems. Hence, we use \tilde{R}_t , a term that incorporates stochastic dynamics, to estimate the tilted objective. For the purpose of analysis, we sample two independent mini-batches to obtain the gradient of the original loss functions.

First order Stochastic Methods

Algorithm 2: Stochastic (Non-Hierarchical) TERM

Initialize: $\theta, \tilde{R}_t = \frac{1}{t} \log \left(\frac{1}{N} \sum_{i \in [N]} e^{tf(x_i; \theta)} \right)$

Input: t, α, λ

while *stopping criteria not reached* **do**

 sample a minibatch B uniformly at random from $[N]$

 compute the loss $f(x; \theta)$ and gradient $\nabla_{\theta} f(x; \theta)$ for all $x \in B$

$\tilde{R}_{B,t} \leftarrow t$ -tilted loss (2) on minibatch B

$\tilde{R}_t \leftarrow \frac{1}{t} \log \left((1 - \lambda) e^{t\tilde{R}_t} + \lambda e^{t\tilde{R}_{B,t}} \right)$

$w_{t,x} \leftarrow e^{tf(x; \theta) - t\tilde{R}_t}$

$\theta \leftarrow \theta - \frac{\alpha}{|B|} \sum_{x \in B} w_{t,x} \nabla_{\theta} f(x; \theta)$

end

Contents

Solving Hierarchical TERM

Definition

$$\tilde{J}(t, \tau, \theta) := \frac{1}{t} \log \frac{1}{N} \sum_{g \in [G]} |g| e^{t \tilde{R}_g(\tau, \theta)}$$

lemma

$$\nabla_{\theta} \tilde{J}(t, \tau, \theta) = \sum_{g \in [G]} \sum_{x \in g} = w_{g,x}(t, \tau, \theta) \nabla_{\theta} f(x; \theta)$$

where:

$$w_{g,x}(t, \tau, \theta) := e^{\tau f(x, \theta)} \frac{\left(\frac{1}{|g|} \sum_{y \in g} e^{\tau f(y, \theta)} \right)^{\frac{t}{\tau} - 1}}{\sum_{g' \in [G]} |g'| \left(\frac{1}{|g'|} \sum_{y \in g'} e^{\tau f(y, \theta)} \right)^{\frac{t}{\tau}}}$$

Solving Hierarchical TERM

To solve hierarchical TERM in the batch setting, we can directly use gradient-based methods with tilted gradients defined for the hierarchical objective in Lemma.

We next discuss stochastic solvers for hierarchical multi-objective tilting. We extend Algorithm 2 to the multi-objective setting, presented in Algorithm 4. At a high level, at each iteration, group-level tilting is addressed by choosing a group based on the tilted weight vector.

Solving Hierarchical TERM

Algorithm 3: Batch Hierarchical TERM

Input: t, τ, α

while *stopping criteria not reached* **do**

for $g \in [G]$ **do**

 compute the loss $f(x; \theta)$ and gradient $\nabla_{\theta} f(x; \theta)$ for all $x \in g$

$\tilde{R}_{g,\tau} \leftarrow \tau$ -tilted loss (83) on group g

$\nabla_{\theta} \tilde{R}_{g,\tau} \leftarrow \frac{1}{|g|} \sum_{x \in g} e^{\tau f(x; \theta) - \tau \tilde{R}_{g,\tau}} \nabla_{\theta} f(x; \theta)$

end

$\tilde{J}_{t,\tau} \leftarrow \frac{1}{t} \log \left(\frac{1}{N} \sum_{g \in [G]} |g| e^{t \tilde{R}_g(\tau; \theta)} \right)$

$w_{t,\tau,g} \leftarrow |g| e^{t \tilde{R}_{\tau,g} - t \tilde{J}_{t,\tau}}$

$\theta \leftarrow \theta - \frac{\alpha}{N} \sum_{g \in [G]} w_{t,\tau,g} \nabla_{\theta} \tilde{R}_{g,\tau}$

end

Solving Hierarchical TERM

Algorithm 4: Stochastic Hierarchical TERM

Initialize: $\tilde{R}_{g,\tau} = 0 \ \forall g \in [G]$

Input: t, τ, α, λ

while *stopping criteria not reached* **do**

sample g on $[G]$ from a Gumbel-Softmax distribution with logits $\tilde{R}_{g,\tau} + \frac{1}{t} \log |g|$
and temperature $\frac{1}{t}$

sample minibatch B uniformly at random within group g

compute the loss $f(x; \theta)$ and gradient $\nabla_{\theta} f(x; \theta)$ for all $x \in B$

$\tilde{R}_{B,\tau} \leftarrow \tau$ -tilted loss (2) on minibatch B

$\tilde{R}_{g,\tau} \leftarrow \frac{1}{\tau} \log \left((1 - \lambda) e^{\tau \tilde{R}_{g,\tau}} + \lambda e^{\tau \tilde{R}_{B,\tau}} \right)$

$w_{\tau,x} \leftarrow e^{\tau f(x;\theta) - \tau \tilde{R}_{g,\tau}}$

$\theta \leftarrow \theta - \frac{\alpha}{|B|} \sum_{x \in B} w_{\tau,x} \nabla_{\theta} f(x; \theta)$

end

Contents

Mitigating Noisy Outliers $t < 0$

- Robust regression
- Robust classification
- Low-quality annotators

Robust regression

- Label noise

objectives	test RMSE (Drug Discovery)		
	20% noise	40% noise	80% noise
ERM	1.87 (.05)	2.83 (.06)	4.74 (.06)
L_1	1.15 (.07)	1.70 (.12)	4.78 (.08)
Huber (Huber, 1964)	1.16 (.07)	1.78 (.11)	4.74 (.07)
STIR (Mukhoty et al., 2019)	1.16 (.07)	1.75 (.12)	4.74 (.06)
CRR (Bhatia et al., 2017)	1.10 (.07)	1.51 (.08)	4.07 (.06)
TERM	1.08 (.05)	1.10 (.04)	1.68 (.03)
Genie ERM	1.02 (.04)	1.07 (.04)	1.04 (.03)

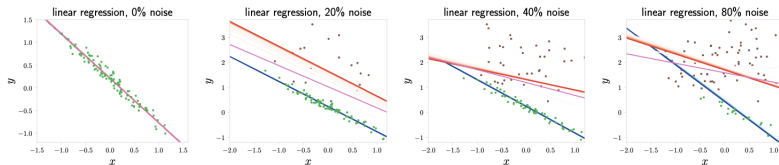
Robust regression

- Label and feature noise

objectives	test RMSE (cal-housing)		test RMSE (abalone)	
	clean	noisy	clean	noisy
ERM	0.766 (0.023)	239 (9)	2.444 (0.105)	1013 (72)
L_1	0.759 (0.019)	139 (11)	2.435 (0.021)	1008 (117)
Huber (Huber, 1964)	0.762 (0.009)	163 (7)	2.449 (0.018)	922 (45)
CRR (Bhatia et al., 2017)	0.766 (0.024)	245 (8)	2.444 (0.021)	986 (146)
TERM	0.745 (0.007)	0.753 (0.016)	2.477 (0.041)	2.449 (0.028)
Genie ERM	0.766 (0.023)	0.766 (0.028)	2.444 (0.105)	2.450 (0.109)

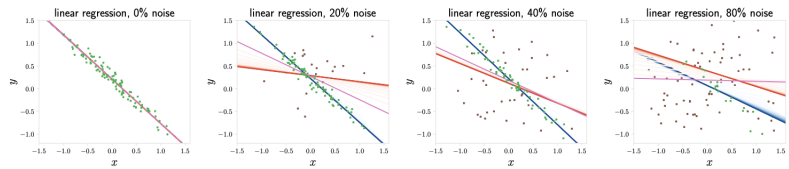
Robust regression

- Unstructured random v.s. adversarial noise.



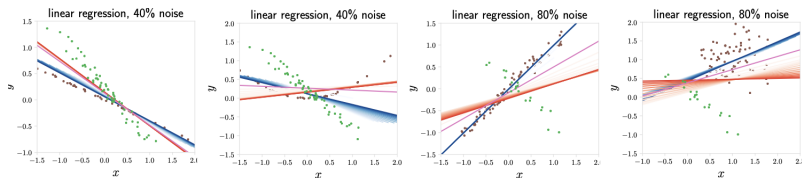
Robust regression

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Robust regression

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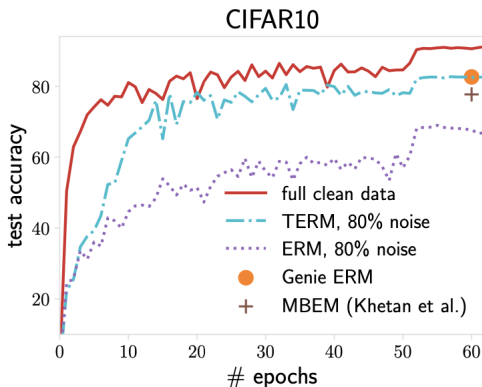


Robust Classification

objectives	test accuracy (CIFAR10, Inception)		
	20% noise	40% noise	80% noise
ERM	0.775 (.004)	0.719 (.004)	0.284 (.004)
RandomRect (Ren et al., 2018)	0.744 (.004)	0.699 (.005)	0.384 (.005)
SelfPaced (Kumar et al., 2010)	0.784 (.004)	0.733 (.004)	0.272 (.004)
MentorNet-PD (Jiang et al., 2018)	0.798 (.004)	0.731 (.004)	0.312 (.005)
GCE (Zhang and Sabuncu, 2018)	0.805 (.004)	0.750 (.004)	0.433 (.005)
TERM	0.795 (.004)	0.768 (.004)	0.455 (.005)
Genie ERM	0.828 (.004)	0.820 (.004)	0.792 (.004)

Robust regression

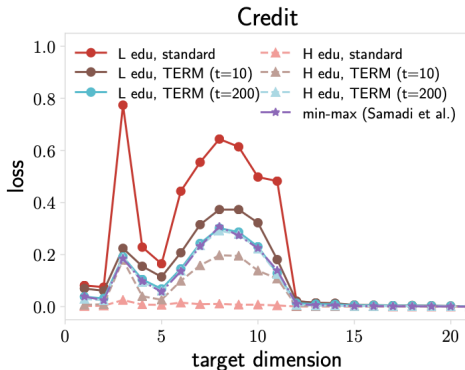
- Low-Quality Annotators



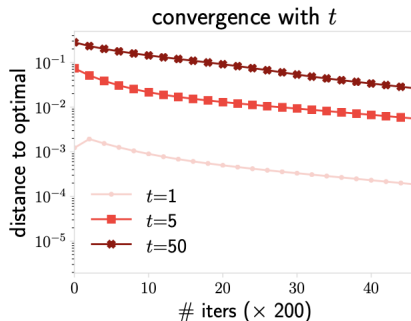
Solving Hierarchical TERM $t > 0$

In this section, we show that positive values of t in TERM can help promote fairness via learning fair representations and enforcing fairness during optimization, and offer variance reduction for better generalization.

Fair Principal Component Analysis (PCA)



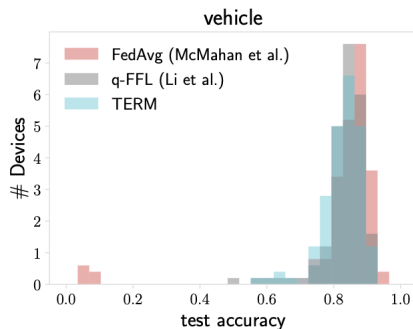
Fair Principal Component Analysis (PCA)



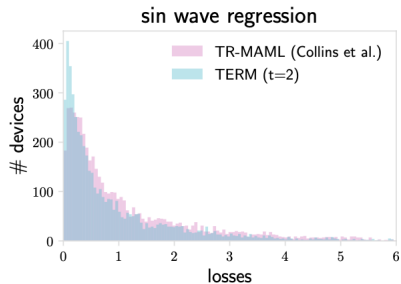
Fair Federated Learning

objectives	test accuracy		
	average	worst 10%	stdev
FedAvg	0.853 (.078)	0.421 (.007)	0.173 (.001)
q -FFL ($q = 5$)	0.862 (.029)	0.704 (.033)	0.064 (.005)
TERM ($t = 0.1$)	0.853 (.027)	0.707 (.009)	0.061 (.003)

Fair Federated Learning



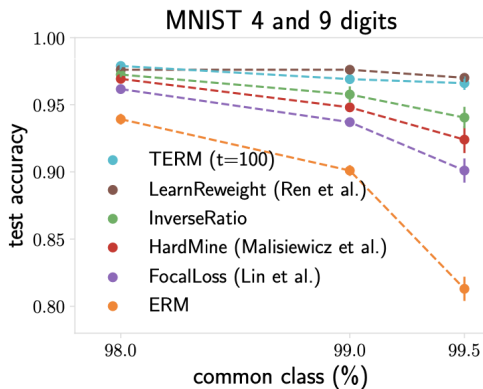
Fair Meta Learning



Fair Meta Learning

methods	mean	std	max	worst 10%
MAML	1.23	1.63	19.1	5.16
TR-MAML	1.25	1.51	14.31	4.85
TERM ($t = 2$)	1.14	1.33	13.59	4.29

Handling Class Imbalance



Class Imbalance and Random Noise

objectives	test accuracy (HIV-1)							
	clean data				30% noise			
	1:4		1:20		1:4		1:20	
	Y = 0	overall	Y = 0	overall	Y = 0	overall	Y = 0	overall
ERM	0.822 (.009)	0.934 (.003)	0.503 (.013)	0.888 (.006)	0.656 (.014)	0.911 (.006)	0.240 (.018)	0.831 (.011)
CVaR (Rockafellar et al., 2000)	0.844 (.013)	0.937 (.003)	0.621 (.011)	0.906 (.005)	0.651 (.015)	0.909 (.006)	0.252 (.014)	0.834 (.010)
GCE (Zhang and Sabuncu, 2018)	0.822 (.009)	0.934 (.003)	0.503 (.013)	0.888 (.006)	0.732 (.021)	0.925 (.005)	0.324 (.017)	0.849 (.008)
LearnReweight (Ren et al., 2018)	0.841 (.014)	0.934 (.004)	0.800 (.022)	0.904 (.003)	0.721 (.034)	0.856 (.008)	0.532 (.054)	0.856 (.013)
RobustRegRisk (Duchi et al., 2019)	0.844 (.010)	0.939 (.004)	0.622 (.011)	0.906 (.005)	0.634 (.014)	0.907 (.006)	0.051 (.014)	0.792 (.012)
FocalLoss (Lin et al., 2017)	0.834 (.013)	0.937 (.004)	0.806 (.020)	0.918 (.003)	0.638 (.008)	0.908 (.005)	0.565 (.027)	0.890 (.009)
HAR (Cao et al., 2021)	0.842 (.011)	0.936 (.004)	0.817 (.013)	0.926 (.004)	0.870 (.010)	0.915 (.004)	0.800 (.016)	0.867 (.012)
TERM _{sc}	0.840 (.010)	0.937 (.004)	0.836 (.018)	0.921 (.002)	0.852 (.010)	0.924 (.004)	0.778 (.008)	0.900 (.005)
TERM _{ca}	0.844 (.014)	0.938 (.004)	0.834 (.021)	0.918 (.003)	0.846 (.015)	0.933 (.003)	0.806 (.020)	0.901 (.010)

Contents

Related Approaches

- Alternate aggregation schemes
- Alternate loss functions
- Sample re-weighting schemes

Contents

Future Works

- Use TERM in semi-supervised learning
- Define experiment with pseudo label and TERM
- Read more about other loss functions

References

- On Tilted Losses in Machine Learning: Theory and Applications: Tian Li
Ahmad Beirami Maziar Sanjabi Virginia Smith