# 5 Computer Organisation and Architecture

## 5.25 Internal Computer Hardware

- External components include input/output and storage devices.
- Internal components are those within the CPU.
  - Processor
  - Main memory
  - Address/control/data bus
  - I/O controllers

### The Processor

The processor **responds to and processes the instructions** that drive the computer. It contains

- The **control unit** coordinate s and controls all operations carried out by the computer. It operates by repeating the **fetch-decode-execute cycle**.
- ALU performs operations on data, such as **arithmetic operations** and **logical operations** and **shift operations**.
- Registers are **special memory cells** that operate at very high speeds. All arithmetic and logical operations take place within Registers.

#### Buses

Each bus is a **shared transmission medium**, only one device can transmit at a time..

• Control bus, a bidirectional bus to transmit command between components, and ensure the access to and use of the data and address buses by different components does not lead to conflict.

The control bus is made of **control lines**, including

- Memory read/write
- Interrupt request
- Bus request/grant
- Clock
- Reset
- Data bus, a bidirectional bus for moving data and instructions between components. The width of the data bus is a key factor in determining overall system performance.

• Address bus - specify an address to access a particular memory location.

The memory is divided into **words** handled as a unit by the processor, each word in memory has its own address. The width of the address bus determines the **maximum possible memory capacity** of the system.

## I/O Controller

An I/O controller is a device which **interfaces between and I/O device and the processor**. Each device has a **separate controller** which connects to the control bus.

The controller consists of

- An interface that allows connection of the controller to the system bus.
- A set of data, command, and status registers.
- An interface that enables connection of the controller **to the cable** connecting the device to the computer.

An **interface** is a standardised form of connection defining things such as signal, voltage levels, etc.

- The von Neumann architecture a shared memory and bus is used for both data and instructions.
- The **stored program concept** a program **must be in main memory** to be executed, and instructions are fetched from memory one at a time.
- The **Harvard architecture** physically separate memories for instructions and data. It is used in **embedded systems** as instruction can use a read-only memory.

Harvard architecture is faster than von Neumann because data and instructions can be **fetched in parallel**.

#### 5.26 The Processor

- The **ALU** perform arithmetic and logical operations on the data, as well as **shift operations** and **boolean logic operations**.
- The **control unit** controls and coordinate the activities of the CPU directing the **flow of data** between the CPU and other devices.
  - Accepts the **next instruction**.
  - Break down its processing into several sequential steps.
  - Manages its **execution**.
  - Stores the resulting data back in memory or registers.

- The system clock generates a series of signals to synchronise CPU operations.
- General-purpose registers are very fast memory, all arithmetic, logical or shift operations take place in registers.

## Dedicated registers include

- The **program counter** holds the <u>address</u> of the **next instruction** to be executed
- The current instruction register holds the current instruction being executed.
- The memory address register holds the address of the memory location from which data is to be fetched or written.
- The **memory buffer register** is used to temporarily store the data read from or written to memory.
- The status register contains bits that are set or cleared depending on the result of an instruction.

## The Fetch-Execute Cycle

This cycle is repeated over and over as each instruction of the program is executed.

#### 1. Fetch phase

The address of the next instruction is copied from PC to MAR, the address is sent via address bus to memory.

- 2. The instruction held at that address is returned along the data bus **to the MBR**. Simultaneously, the content of the **PC** is incremented so it holds the address of the next instruction.
- 3. The content of the MBR is **copied to the CIR**.

## 4. Decode phase

The instruction held in the CIR is decoded - it is split into **opcode** and **operand**.

- The opcode determine the **type of instruction** and what hardware to use to execute it.
- Additional data is fetched if necessary and passed to the registers.

### 5. Execute phase

The instruction is executed using the ALU if necessary, the results are stored in general purpose registers or memory.

#### **Processor Performance**

- Number of cores: each core is able to process a different instruction at the same time with its own fetch-execute cycle.
  - However some software may not be able to take full advantage of multiple processors.
- Cache is a very small amount of expensive, very fast memory inside the CPU. An instruction fetched from main memory is copied into the cache if it is needed again soon.

As cache fills up, unused data are replaced with more recent ones.

- Clock speed: all processor activities begin on a clock pulse. The greater the clock speed, the faster the instructions will be executed.
- Word length is the number of bits that the CPU can process simultaneously.
- The width of data bus determines how many bits can be transferred simultaneously.

The width of address bus determines the maximum memory address that can be directly referenced.

## Interrupts

An interrupt is a signal sent by a software program or a hardware device to the CPU.

- **Software interrupt** occurs when an application terminates or requests certain services from the operating system.
- Hardware interrupt occur when an I/O operation is complete or an error occurs.

When the CPU receives an interrupt signal

- 1. Suspends execution or running program.
- 2. Puts values of each register and PC onto the **system stack**.
- 3. An **interrupt service routine** is called to deal with the interrupt.
- 4. Once served, the original values of the registers are retrieved from the stack, and the fetch-execute cycle resumes.