

# Algorithms I

## Definition

An **algorithm** is a *well defined* computation procedure that takes a set of values as input and produces a set of values as output.

Note: the term *well defined* is itself, not well defined.

## Definitions

- **Problems** have specific inputs and outputs, input must be finite and not a stream of data.
- **Problem instances** is a specific set of inputs for a problem. A problem can have a Big-O but not a problem instance.
- A program is **correct** if for every input instance, it terminates with the correct output.

## Note

- Randomised algorithms is a branch of incorrect algorithms.
- Some algorithms produce incorrect outputs with a probability (e.g. quantum computing)
- Some algorithms loops infinitely for some inputs, but runs a lot faster than an algorithm that guarantees termination for cases where it terminates. It might be possible to determine whether it will terminate for a specific input before running it.
- Some algorithms gives an output within a margin of error (e.g. A\* vs Dijkstra)

# Notation

## Arrays

- $A[1]$  is the first item
- $A[1..n]$  is an array of length  $n$
- $A.length$  is the number of items in the array

We write pseudocode that is

- Imperative
- Block structured
- Fixed form (indentation matters)
- Parameters are passed by values, objects are passed by pointers
- Loop induction (for loops) increments after the final loop

```
for i=1 to 10
    // do stuff
```

After this loop, consider  $i=11$

## Sorting

Each **key** may have attached payloads.

## Insertion Sort

```
for j = 2 to A.length
    Key = A[j]
    i = j - 1
    while i > 0 && A[i] > Key
        A[i + 1] = A[i]
        i = i - 1
    A[i + 1] = Key
```

Use proof by induction for algorithms:

- **Initialisation:** find a property that is true at the start of the program

$P$ : at the start of each loop,  $A[1\dots j - 1]$  contains the  $1\dots j - 1$  items in sorted order.

At the start of the first loop, that is just  $[a_1]$ , true.

#### Note

Define “the start of the loop” as: after assigning the value of  $j$ , but before running the first line of code in the loop.

- **Maintenance:** show that the property is maintained as the program is running.
- **Termination:** when the program terminates, show the output is correct.

After the last loop,  $A[1\dots A.length]$  would have been containing all the items  $1\dots A.length$  in order.

And then we can also show the program terminates as it only needs to complete the loop  $A.length$  items.

#### Note

Which is the same as the following Hoare logic proof.

Let  $P, Q$  be pre and post-conditions,  $B$  be body of the loop,  $C$  be condition for the loop.

Given:

1.  $\{P\} B \{P\}$
2.  $P \wedge \neg C \implies Q$

Then  $\{P\}$  while  $C$  do  $B \{Q\}$

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## Analysis

### Definition

**Analysis** is about predicting the resources (CPU, memory, disk operations) for input instances we haven’t ran our algorithm on.

Input measurement	Description
$A.length$	Common for every day scenarios, but may be incorrect if each item in array can have variable size (e.g. big integer)
no. of bits/bytes	Useful for algorithm that operates on some bit/byte value.
$2^{A.length}$	Overestimates the size in most cases, but can be used for search lists.

### Definition

The **running time** of a program is the number of **basic operations**. (as they all cost 1)

Basic operation	Cost
Indexing an array $A[i]$	1
Arithmetic operation	1
Comparisons	1

Basic operation	Cost
Assignment to variables	1

One basic operation might not be equal to one clock cycle, if you change the cost of the basic operations, the running time changes.

### Note

Comparisons (numbers) is usually done by subtracting one from another, then compare with 0.

## Order of Growth

- $\Theta(g(n))$  is the **asymptotic tight bound** for  $g(n)$

$$f(n) \in \Theta(g(n)) \implies \exists c_1, c_2, n_0 \in \mathbb{R}^+ : (\forall n \geq n_0 : c_1 g(n) \leq f(n) \leq c_2 g(n))$$

- $O(g(n))$  is the **asymptotic tight upper bound** for  $g(n)$

$$f(n) \in O(g(n)) \implies \exists c, n_0 \in \mathbb{R}^+ : (\forall n \geq n_0 : f(n) \leq cg(n))$$

- $\Omega(g(n))$  is the **asymptotic tight lower bound** for  $g(n)$

$$f(n) \in \Omega(g(n)) \implies \exists c, n_0 \in \mathbb{R}^+ : (\forall n \geq n_0 : cg(n) \leq f(n))$$

- $o(g(n))$  is the **asymptotic non-tight upper bound** for  $g(n)$

$$f(n) \in o(g(n)) \implies \forall c \in \mathbb{R}^+ : (\exists n_0 \in \mathbb{R}^+ : (\forall n \geq n_0 : f(n) < cg(n)))$$

- $\omega(g(n))$  is the **asymptotic non-tight lower bound** for  $g(n)$

$$f(n) \in \omega(g(n)) \implies \forall c \in \mathbb{R}^+ : (\exists n_0 \in \mathbb{R}^+ : (\forall n \geq n_0 : cg(n) < f(n)))$$

## Properties of Orders of Growth

$$\Theta(g(n)) \subseteq O(g(n))$$

$$\Theta(g(n)) \subseteq \Omega(g(n))$$

- **Transitive:** satisfied by all 5 orders

$$f(n) \in \Theta(g(n)) \wedge g(n) \in \Theta(h(n)) \implies f(n) \in \Theta(h(n))$$

- **Reflexive:** satisfied by the tight bounds  $\Theta, O, \Omega$

$$f(n) \in \Theta(f(n))$$

- **Symmetric:** satisfied by  $\Theta$

$$f(n) \in \Theta(g(n)) \implies g(n) \in \Theta(f(n))$$

## Analysis of Insertion Sort

```

for j = 2 to A.length          // ran (n-1)+1 times
    Key = A[j]                // ran n-1 times
    i = j - 1                 // ran n-1 times
    while i > 0 && A[i] < Key // ran sum_(j=2)^n t_j times
        A[i+1] = A[i]          // ran sum_(j=2)^n (t_j - 1) times
        i = i - 1              // ran sum_(j=2)^n (t_j - 1) times
    A[i+1] = Key              // ran n-1 times

```

Where  $t_j$  is the number of times the while loop is tested on the  $j$ th cycle.

- Best case:  $t_j = 1$  then  $T(n) = pn + q$
- Worst case:  $t_j = j$  then  $T(n) = pn^2 + qn + r$
- Average case: the claim is that on average, half of the keys in  $A[1\dots j - 1]$  will be less than  $A[j]$

$$t_g = j/2 \text{ gives } T(n) \in O(n^2)$$

The worst case is useful because

- It gives the upper bound on resource
- Often the same as the average case

Insertion sort is an **incremental algorithm**: it builds up an output that satisfies some properties.

## Divide and Conquer

1. Split into 2 or more smaller subproblems.
2. call the same algorithm on each subproblem recursively.
3. Combine solutions to the subproblems to build the solution to the original problem.

### Note

Recursion will terminate because the subproblem will get smaller and smaller.

## Merge Sort

```
// we are sorting A[p..r]
if p < r
    q = floor((p + r) / 2)
    MergeSort(A, p, q)
    MergeSort(A, q + 1, r)
    Merge(A, p, q, r)
```

And Merge defined as

```
n1 = q - p + 1
n2 = r - q

L = new Array(1 .. n1 + 1)
R = new Array(1 .. n2 + 1)

L[1 .. n1] = A[p .. q]
L[n1 + 1] = infinity
R[1 .. n2] = A[q + 1 .. r]
R[n2 + 1] = infinity

i = j = 1

for k = p to r
    if L[i] <= R[j]
        A[k] = L[i]
        i = i + 1
    else
        A[k] = R[j]
        j = j + 1
```

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- If the length of the array is not a power of 2, pad  $\infty$  to the end so that it is.
- After sorting, remove the added  $\infty$  at the end of the sorted array.

The input array is modified, Merge has no return value.

## Recurrence Relations

The input size is length of the region to be sorted  $n = r - p + 1$

Let  $T(n)$  be the cost of solving  $\text{MergeSort}(A, p, r)$

- If  $p = r$ ,  $T(1) = 1$
- If  $p < r$

Action	Cost
Calculate $q$	$\Theta(1)$
Calls itself on 2 subproblems	$T(n/2) \times 2$
Calls $\text{Merge}(A, p, q, r)$	$\Theta(n)$
Action	Cost
Creates 2 arrays of length $n + 2$	$\Theta(n)$
Loop $n$ iterations: assign into array and increment $i$ or $j$	$\Theta(n)$

$$T(1) = 1$$

$$\begin{aligned} T(n) &= \Theta(1) \text{ work} + 2 \cdot T\left(\frac{n}{2}\right) + \Theta(n) \text{ work} \\ &= k_1 + 2 \cdot T\left(\frac{n}{2}\right) + k_2 \cdot n \end{aligned}$$

### Definition

A **closed form solution** is not defined in terms of itself through direct or indirect recursion.

$$\begin{aligned} T(n) &= k_1 + k_2 \cdot n + 2 \cdot T\left(\frac{n}{2}\right) \\ &= k_1 + k_2 \cdot n + 2 \cdot \left( k_1 + k_2 \cdot \frac{n}{2} + 2 \cdot T\left(\frac{n}{4}\right) \right) \\ &= k_1 + k_2 \cdot n + 2 \cdot \left( k_1 + k_2 \cdot \frac{n}{2} + 2 \cdot \left( k_1 + k_2 \cdot \frac{n}{4} + 2 \cdot T\left(\frac{n}{4}\right) \right) \right) \\ &\vdots \\ &= k_1 \cdot \underbrace{(1 + 2 + 4 + \dots)}_{\log n \text{ terms}} + k_2 \cdot n \cdot \underbrace{(1 + 1 + 1 + \dots)}_{\log n \text{ times}} + 2^{\log n} \cdot T(1) \\ &= k_1 \cdot (n - 1) + k_2 \cdot n \log n + n \\ &\in \Theta(n \log n) \end{aligned}$$

### Note

We preserved the equal signs instead of saying “this term dominates” so we know  $T(n) \in \Theta(f(n))$  instead of just  $O(f(n))$

If the array length is not a power of 2

$$T(n) = T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + k_1 + k_2 \cdot n$$

Which gives the same solution.

### The Master Theorem

Let  $a \geq 1$  and  $b > 1$  be constants.

- $T(1) = 1$
- $T(n) = a \cdot T(n/b) + f(n)$

### Note

$n/b$  can be interpreted as ceil or floor, it doesn't matter.

$$f(n) \in O(n^{-\varepsilon + \log_b a}) \text{ for some } \varepsilon > 0 \implies T(n) \in \Theta(n \log_b a)$$

$$f(n) \in \Theta(n^{\log_b a}) \implies T(n) \in \Theta(n \log_b a \cdot \lg n)$$

$$f(n) \in \Omega(n^{\varepsilon + \log_b a}) \text{ for some } \varepsilon > 0 \text{ and } f(n/b) \leq c f(n)$$

$$\text{for some } c > 1 \text{ for all sufficiently large } n \implies T(n) \in \Theta(f(n))$$

### Note

There is an extended master theorem for conditions between case 2 and 3.

## Quicksort

```
QuickSort(A, p, r)
  if p < r
    q = partition(A, p, r)
    QuickSort(A, p, q - 1)
    QuickSort(A, q + 1, r)
```

```
Partition(A, p, r)
  x = A[r]
  i = p - 1
  for j = p to r - 1
    if A[j] <= x
      i = i + 1
      swap(A[i], A[j])
  swap(A[i + 1], A[r])
  return i + 1
```

The strategy: **divide** (partition array into 3 parts), **conquer** (recurse on  $L$  and  $G$ ), **combine** (no-op).

Requirements for **Partition(A, p, r)** is

- Pick any element as pivot
- Rearrange so array looks like [items  $\leq$  pivot, pivot, items  $\geq$  pivot]

$$[L, x, G]$$

## Proof

Let  $P$  be the statement:

1. If  $p \leq k \leq i$  then  $A[k] \leq x$
2. If  $i + 1 \leq k \leq j - 1$  then  $A[k] > x$
3. If  $k = r$  then  $A[k] = x$

### Note

No statements made for  $j \leq k \leq r - 1$  which is the unprocessed region.

- **Initialisation:** (1) and (2) vacuously true, (3) is true by definition.
- **Maintenance**

- Case does not enter if branch: (1) and (3) remains true, (2) is true as the new item  $> x$
- Case enters if branch: (3) remains true, (1) and (2) are true as their new items both satisfies constraint.
- The final swap ensures post-condition.

## Performance

The number of comparisons depends on how Partition splits the array.

- **Best case:** partition splits array in half

$$T(1) = 1$$

$$T(n) = 2 \cdot T\left(\frac{n}{2}\right) + k \cdot n$$

$$T(n) \in \Theta(n \log n)$$

by master theorem.

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- **Unbalanced partition**, e.g.

$$T(1) = 1$$

$$T(n) = T\left(\frac{n}{4}\right) + T\left(\frac{3n}{4}\right) + kn$$

The **computation tree** is unbalanced.

- The shallowest node has depth  $\log_4 n$
- The deepest node has depth  $\log_{4/3} n$

Both gives  $\Theta(n \log n)$ , so any ratio split gives  $\Theta(n \log n)$

- **Worst case** when the pivot is the largest/smallest item in array.

$$\begin{aligned} T(n) &= T(n-1) + T(0) + kn \\ &= T(n-1) + kn \\ &\in \Theta(n^2) \end{aligned}$$

The probability of worst case on each split is  $2^n/n!$ , when  $n$  is small, this is quite significant.

- **Constant case** where a constant number of items are partitioned to one side. Still  $\Theta(n^2)$

## Order Statistic

### Definition

The  $i$ th order statistic is the  $i$ th smallest item in a set.

- Input: a set  $A$ , and an integer  $i$
- Output:  $x \in A$  so it is larger than exactly  $i - 1$  other elements.

- Selecting the minimum and maximum item is simple at  $O(n)$
- Selecting the  $i$ th item can be done in  $\Theta(n \lg n)$ 
  1. Sort the array
  2. Get the  $i$ th element

```
QuickSort(A, p, r, i)
  if p = r
    return A[p]
```

```

q = Partition(A, p, r)
k = q - p + 1
if i == k
    return A[q]
else if i < k
    return QuickSelect(A, p, q - 1, i)
else
    return QuickSelect(A, q + 1, r, i - k)

```

Worst case:

$$\begin{aligned}
T(1) &= 1 \\
T(n) &= T(n-1) + kn \\
&\in \Theta(n^2)
\end{aligned}$$

## Optimisations

- Randomise input data before starting
- Choose pivot at random
- Median of 3: choose the median of 3 selected items as pivot.

Hitting worst case if:

- One of the 3 element is max or minimum element
- The other median element is right next to the max/minimum element.

This has probability  $2/n^2$

- Median of medians:
  1. Consider array as groups of 5 elements.
  2. Pick the median of each group with insertion sort.
  3. Use quick select to select the median of the medians as pivot.

The final median is a median of  $\lceil n/5 \rceil$  “medians”

- Half the “medians” are greater than the median.
- Number of elements greater/smaller than the pivot is

$$\text{number of elements} \geq 3 \cdot \left\lceil \frac{1}{2} \left\lceil \frac{n}{5} \right\rceil - 2 \right\rceil \geq \frac{3n}{10} - 6$$

### Note

$-2$  removes 2 groups for worst case, includes the last group that is possibly incomplete, and the group that the pivot is in.

Worst case is  $3n/10 - 6$  on one side and  $7n/10 + 6$  on the other.

Suppose

$$T(n) = k \quad \text{if } n < 140$$

$$T(n) = T\left(\left\lceil \frac{n}{5} \right\rceil\right) + T\left(\frac{7n}{10} + 6\right) + kn \quad \text{as we are considering the worst case}$$

If we guess that  $T(n) \in \Theta(n)$ , then

$$\begin{aligned}
T(n) &\leq c \cdot \left\lceil \frac{n}{5} \right\rceil + c \cdot \left( \frac{7n}{10} + 6 \right) + kn \\
&\leq \frac{cn}{5} + c + \frac{7cn}{10} + 6c + kn \\
&= cn + \left( -\frac{cn}{10} + 7c + kn \right)
\end{aligned}$$

If  $(-cn/10 + 7c + kn) \leq 0$ , then  $T(n) \in O(n)$

- (Not in handout) Also need to check lower bound is in  $\Omega(n)$  to show  $T(n) \in \Theta(n)$

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