# **Value Iteration Convergence Proof**

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### 1 Introduction

While studying **Reinforcement Learning** by Sutton and Barto, I came across the value iteration algorithm for finite state and action spaces and pondered at the proof that it converges to the optimal value function. This took me on a rich and deep journey featuring a fantastic review of analysis. This writeup derives the proof for the convergence of the value iteration algorithm from barebones first principles  $^1$ . We take definitions of sequences (and notion of bounded sequences), limits, and continuity along with the least upper bound property of  $\mathbb R$  and basic set theory for granted  $^2$ .

#### 1.1 Value Iteration Algorithm

We use the same notation as the Sutton and Barto text. The Value Iteration Algorithm is an iterative algorithm that refines value functions  $V_k : \mathcal{S} \to \mathbb{R}$  until they near the optimal value function  $V_*$ . The Bellman optimal state-value function states (with discounting  $\gamma \in (0,1)$ ):

$$V_*(s) = \max_{a \in \mathcal{A}(s)} \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r|s, a) \left[ r + \gamma V_*(s') \right]; \forall s \in \mathcal{S}$$

The iterative algorithm for value iteration sets:

$$V_{k+1}(s) = \max_{a \in \mathcal{A}(s)} \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r | s, a) \left[ r + \gamma V_k(s') \right]; \forall s \in \mathcal{S}$$

With  $V_0(s)$  defined arbitrarily.

<sup>&</sup>lt;sup>1</sup>Got a lot of help from Wikipedia along the way, which I used to verify intermediate proofs

<sup>&</sup>lt;sup>2</sup>Principles of Mathematical Analysis by Rudin has more in depth coverage of everything - I reference this a ton

**Theorem 1.1.** The Value Iteration Algorithm converges to a unique optimal value function:

$$\lim_{k \to \infty} V_k(s) = V_*(s); \forall s \in \mathcal{S}$$

This is the main theorem we want to prove.

# 2 Necessary Analysis Definitions and Theorems

In this section, we provide definitions and theorems (with proof) from analysis that are all necessary to prove **Thm 1.1**.

#### 2.1 Main Definitions

**Defn 2.1.** A Metric Space is a pair (X, d) of a set X and "distance" function  $d: X \times X \to \mathbb{R}$  with the following properties:

- 1.  $\forall x, y \in X, d(x, y) > 0 \iff x \neq y, \forall x \in X, d(x, x) = 0$
- 2.  $\forall x, y \in X, d(x, y) = d(y, x)$
- 3.  $\forall x, y, z \in X, d(x, z) \le d(x, y) + d(y, z)$

**Defn 2.2.** Given a metric space (X,d), a <u>Cauchy Sequence</u> is an infinite sequence  $\{x_n\}_{n\in\mathbb{Z}_+}$  such that,  $\forall \epsilon > 0$ ,  $\exists N \in \mathbb{Z}_+$ ,  $\forall m, n > N$ ,  $d(x_m, x_n) < \epsilon$ .

**Defn 2.3.** A <u>Complete Metric Space</u> is a metric space (X,d) if for all Cauchy sequences  $\{x_n\}_{n\in\mathbb{Z}_+}$ ,  $\lim_{n\to\infty} x_n \frac{1}{exists} \frac{1}{exis$ 

**Defn 2.4.** Given a metric space (X, d), a contraction mapping is a mapping  $f: X \to X$  such that  $\exists q \in (0, 1), \forall x, y \in X, d(f(x), f(y)) < q\overline{d(x, y)}$ .

q is called the Lipschitz constant.

### **2.2** $\mathbb{R}^k$ with $l_{\infty}$ Distance Metric is a Complete Metric Space

This is a critical thing to prove to lead us to **Thm 1.1**. We start with some building block theorems to work up to this. When we specify  $\mathbb{R}$ , we mean the metric space defined by  $(\mathbb{R}, d)$  where d(x, y) = |x - y|.

**Theorem 2.1.** *Monotone Convergence Theorem:* Any infinite sequence of  $\mathbb{R}$  that is monotonic and bounded converges.

*Proof.* Assume  $\{x_n\}_{n\in\mathbb{Z}_+}$  is monotonically non-decreasing. By the least upper bound property of  $\mathbb{R}$  and since  $\{x_n\}$  is bounded,  $x^*=\sup\{x_n\}$  exists,  $x^*\in\mathbb{R}$ . See that,  $\forall \epsilon>0, \exists x_N, x_N>x^*-\epsilon$ . Now,  $\forall n>N$ , we know  $x_n\geq x_N$ , so  $|x_n-x^*|=x^*-x_n\leq x^*-x_N<\epsilon$ . Therefore,  $\lim_{n\to\infty}x_n=x^*$ .

Similarly, now assume that  $\{x_n\}_{n\in\mathbb{Z}_+}$  is monotonically non-increasing. We know  $x^*=\inf\{x_n\}$  exists,  $x^*\in\mathbb{R}$ . See that,  $\forall \epsilon>0, \exists x_N, x_N< x^*+\epsilon$ . Now,  $\forall n>N$ , we know  $x_n\leq x_N$ , so  $|x_n-x^*|=x_n-x^*\leq x^N-x^*<\epsilon$ . Therefore,  $\lim_{n\to\infty}x_n=x^*$ .

Therefore, in both cases, we have the monotonic and bounded sequences converge.

**Theorem 2.2.** Bolzano-Weierstrass Theorem for  $\mathbb{R}$ : Any bounded sequence in  $\mathbb{R}$  has a convergent subsequence.

*Proof.* We first state and prove this Lemma:

**Lemma 2.3.** Any infinite sequence in  $\mathbb{R}$  has an infinite monotonic subsequence.

*Proof.* Define "peak" index n be such that  $\forall m > n, x_m \leq x_n$ . Define  $\mathcal{N} = \{n_1, n_2, \ldots\} \subseteq \mathbb{Z}_+$  be the set of all peak indices.

Case 1:  $\mathcal{N}$  is infinite. In that case, we can order  $x_{n_1} \geq x_{n_2} \geq x_{n_3} \cdots$  for an infinite  $n_i \in \mathcal{N}$ . Therefore, we have an infinite monotonically non-increasing subsequence.

Case 2:  $\mathcal{N}$  is finite. In that case, let  $N = \begin{cases} 0 & \mathcal{N} = \emptyset \\ \max(\mathcal{N}) & \mathcal{N} \neq \emptyset \end{cases}$ . Repeat the following process: choose  $x_{N+1}$ . Since N+1 is not a peak index,  $\exists n > N+1, x_n \geq x_{N+1}$ . Add that  $x_n$ . n is not a peak

 $x_{N+1}$ . Since w+1 is not a peak index,  $\exists n \geq w+1, x_n \geq x_{N+1}$ . Add that  $x_n$ . v is not a peak index, so find the next max  $m > n, x_m \geq x_n$ . We can continue this infinitely many times to form an infinite monotonically non-decreasing subsequence.

Now, by **Lemma 2.3**, any bounded sequence in  $\mathbb{R}$  has an infinite monotonic subsequence. By **Thm 2.1**, this infinite monotonic subsequence (which is also bounded) converges.

We're now set to show:

**Theorem 2.4.**  $\mathbb{R}$  *is a complete metric space.* 

*Proof.* We first prove this Lemma:

**Lemma 2.5.** A Cauchy sequence on any metric space is bounded.

*Proof.* Let (X, d) be a metric space, and  $\{x_n\}_{n \in \mathbb{Z}_+}$  be a Cauchy sequence. We will show that  $\{x_n\}$  is bounded.

Let  $\epsilon=1$ .  $\exists N\in\mathbb{Z}_+, \forall m,n>N, d(x_m,x_n)<1$ . Define  $C=\max_{m,n\leq M}d(x_m,x_n)$  which is defined and finite. Let  $B=\max\{C,1\}$ . It is thus true that,  $\forall m,n,d(x_m,x_n)< B$ , therefore the Cauchy sequence is bounded.

Let  $\{x_n\}_{n\in\mathbb{Z}_+}$  be a Cauchy sequence. By **Lemma 2.5** and **Thm 2.2**, the sequence has a convergent subsequence  $\{x_{n_i}\}_{i\in\mathbb{Z}_+}$ ,  $\lim_{i\to\infty}x_{n_i}=L\in\mathbb{R}$ . We argue  $\lim_{n\to\infty}x_n=L$ .

 $\begin{array}{l} \forall \epsilon>0, \, \exists I\in \mathbb{Z}_+ \text{ such that } \forall i>I, \, |x_{n_i}-L|<\frac{\epsilon}{2}. \text{ Furthermore, } \exists N\in \mathbb{Z}_+ \text{ such that } \forall m,n>N, |x_n-x_m|<\frac{\epsilon}{2}. \text{ Take } N'=\max\{n_I,N\}. \text{ We know } \exists n_j>N'. \text{ Therefore, } \forall n>N', |x_n-L|\leq |x_n-x_{n_i}|+|x_{n_i}-L|<\epsilon. \end{array}$ 

Therefore, the Cauchy sequence  $\{x_n\}$  converges to a value in  $\mathbb{R}$ .

We are now finally ready to prove our main theorem of this section:

**Theorem 2.6.** The metric space  $(\mathbb{R}^k, d)$  with  $d(x, y) = ||x - y||_{\infty}$  is a complete metric space.<sup>3</sup>

*Proof.* Let  $\{v_n\}_{n\in\mathbb{Z}_+}$  be a Cauchy sequence. Define k sequences in  $\mathbb{R}$  as follows: for  $i=1,\ldots,k$ ,  $\{v_n^{(i)}\}_{n\in\mathbb{Z}_+}$  is the sequence such that  $v_n^{(i)}=(v_n)_i$  (the i'th element of  $v_n$ ). We argue all k of these sequences in  $\mathbb{R}$  are Cauchy as well.

 $\forall \epsilon > 0, \exists N \in \mathbb{Z}_+, \forall m, n > N, \|v_m - v_n\|_{\infty} < \epsilon. \ \|v_m - v_n\|_{\infty} = \max_i |(v_m)_i - (v_n)_i| < \epsilon, \text{ which implies } \forall i = 1, \ldots, k, |(v_m)_i - (v_n)_i| < \epsilon.$ 

Therefore, each  $\{v_n^{(i)}\}_{n\in\mathbb{Z}_+}$  is Cauchy. By **Thm 2.4**,  $\forall i, \lim_{n\to\infty} \{v_n^{(i)}\}$  exists - let's set it to  $v_i^*$ .

Thus,  $\lim_{n\to\infty} v_n = v^* \in \mathbb{R}^k$ . Therefore,  $(\mathbb{R}^k, d)$  is a complete metric space.

#### 2.3 Banach Fixed Point Theorem

We dedicate this section to the Banach Fixed Point Theorem which serves as the essence to proving Value Iteration convergence. First, we show:

**Theorem 2.7.** Every contraction mapping is uniformly continuous.

<sup>&</sup>lt;sup>3</sup>We've taken for granted earlier and here that norm distances are valid for metric spaces. This is very easy to show.

*Proof.* Let (X,d) be a metric space, and  $f:X\to X$  be a contraction mapping with Lipschitz constant  $q\in(0,1)$ .  $\forall\epsilon>0$ , let  $\delta=\frac{\epsilon}{q}>0$ . Then,  $\forall x,y\in X$  such that  $d(x,y)<\delta, d(f(x),f(y))\leq qd(x,y)< q\delta=\epsilon$ . Therefore, f is uniformly continuous.  $\Box$ 

Now, we define and prove:

**Theorem 2.8.** Banach Fixed Point Theorem: Given a complete metric space (X,d), any contraction mapping  $T: X \to X$  will have a unique fixed point  $x^* \in X$  such that  $T(x^*) = x^*$ . Furthermore, let  $x_0 \in X$  an arbitrary point. The sequence  $\{x_n\}_{n \in \mathbb{Z}_+}$  such that  $x_n = T(x_{n-1})$  converges to  $x^*$ .

*Proof.* Let the Lipschitz constant for T be  $q \in (0,1)$ . We will first argue that  $\{x_n\}$  is a Cauchy sequence.

Observe, for  $n \ge 1$ :

$$d(x_{n+1}, x_n) = d(T(x_{n+1}), T(x_n))$$

$$\leq qd(x_n, x_{n-1})$$

$$\leq q^2 d(x_{n-1}, x_{n-2})$$

$$\cdots \leq q^n d(x_1, x_0)$$

Now, take arbitrary  $m < n \in \mathbb{Z}_+$ :

$$d(x_m, x_n) \le d(x_m, x_{m+1}) + d(x_{m+1}, x_{m+2}) + \dots + d(x_{n-1}, x_n)$$

$$= \sum_{i=1}^{n-m} d(x_{m+i-1}, x_{m+i})$$

$$\le \sum_{i=1}^{n-m} q^{m+i} d(x_1, x_0)$$

$$= q^m d(x_1, x_0) \sum_{i=1}^{n-m} q^i$$

$$\le q^m d(x_1, x_0) \sum_{i=0}^{\infty} q^i$$

$$= \frac{q^m d(x_1, x_0)}{1 - q}$$

Now,  $\forall \epsilon>0, q\in (0,1)$  implies  $\exists N\in \mathbb{Z}_+$  such that  $q^N<\frac{\epsilon(1-q)}{d(x_1,x_0)}. \ \forall n>m>N,$  observe:

$$d(x_n, x_m) \le \frac{q^m d(x_1, x_0)}{1 - q} < \frac{q^N d(x_1, x_0)}{1 - q} < \epsilon$$

Therefore,  $\{x_n\}$  is Cauchy.

Thus, by **Defn 2.3**,  $\{x_n\}$  converges:  $\lim_{n\to\infty} x_n = x^*$ .

By Thm 2.7, T is continuous, therefore  $T(x^*) = \lim_{n \to \infty} T(x_n) = \lim_{n \to \infty} x_n = x^*$ , showing  $x^*$  is a fixed point.

Finally, we argue  $x^*$  is a unique fixed point. Assume on the contrary  $x^* \neq y^*$  were both fixed points such that  $T(x^*) = x^*, T(y^*) = y^*$ . Then,  $d(T(x^*), T(y^*)) = d(x^*, y^*) > qd(x^*, y^*)$  which is a contradiction. Therefore,  $x^*$  is the sole fixed point.

Therefore, T has a unique fixed point  $x^* = T(x^*)$  and any sequence with arbitrary  $x_0 \in X$ ,  $x_n = T(x_{n-1})$  will converge to  $x^*$ .

# 3 Value Iteration Convergence

We use all the previous results to prove that the Value Iteration Algorithm converges to the optimal value function.

#### 3.1 Complete Metric Space of Value Functions

**Defn 3.1.** We define a value function metric space for a given state space S as the set  $V = \{V : S \to \mathbb{R}\}$  with |S| = k finite along with the distance function  $d(V, W) = \max_{s \in S} |V(s) - W(s)|^4$ 

We show the following:

**Theorem 3.1.**  $(\mathcal{V},d)$  is isometric to the metric space  $(\mathbb{R}^k,d_\infty)$  where  $d_\infty(v,w)=\|v-w\|_\infty$ .

*Proof.* We first construct the bijective mapping  $f: \mathcal{V} \to \mathbb{R}$ . Enumerate the states as  $\mathcal{S} = \{s_1, s_2, \ldots, s_k\}$ . Let v = f(V) be such that  $v_i = V(s_i)$ . f admits an inverse  $f^{-1}(v)$  for any  $v \in \mathbb{R}$  as the value function  $V(s_i) = v_i$  for all i.

We then show that:

$$d(V, W) = \max_{s \in \mathcal{S}} |V(s) - W(s)| = \max_{i \in \{1, \dots, k\}} |V(s_i) - W(s_i)| = \max_{i \in \{1, \dots, k\}} |v_i - w_i| = ||v - w||_{\infty}$$

Where v = f(V), w = f(W).

Therefore,  $(\mathcal{V}, d)$  is isometric to the metric space  $(\mathbb{R}^k, d_{\infty})$ .

**Corollary 3.1.1.** (V, d) is a complete metric space.

This corollary follows from **Thm 2.6**.

## 3.2 Value Iteration as a Contraction Operator on Value Functions

**Defn 3.2.** The iteration operator  $T: \mathcal{V} \to \mathcal{V}$  formalizes a step in the value iteration algorithm as:

$$(T(V))(s) = \max_{a \in \mathcal{A}(s)} \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r | s, a) \left[ r + \gamma V(s') \right]$$

**Theorem 3.2.** The iteration operator T is a contraction mapping on the metric space (V, d).

*Proof.* Let  $V, W \in \mathcal{V}$  be arbitrary value functions. For ease of notation, define:

$$Q_V(s, a) = \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r|s, a) \left[ r + \gamma V(s') \right]$$

Thus, we show:

$$\begin{split} d(T(V), T(W)) &= \max_{s \in \mathcal{S}} |(T(V))(s) - (T(W))(s)| \\ &= \max_{s \in \mathcal{S}} \left| \max_{a \in \mathcal{A}(s)} Q_V(s, a) - \max_{a \in \mathcal{A}(s)} Q_W(s, a) \right| \\ &\leq \max_{s \in \mathcal{S}} \max_{a \in \mathcal{A}(s)} |Q_V(s, a) - Q_W(s, a)| \\ &= \max_{s \in \mathcal{S}} \max_{a \in \mathcal{A}(s)} \left| \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r | s, a) \left[ r + \gamma V(s') \right] - p(s', r | s, a) \left[ r + \gamma W(s') \right] \right| \\ &= \gamma \max_{s \in \mathcal{S}} \max_{a \in \mathcal{A}(s)} \left| \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r | s, a) (V(s') - W(s')) \right| \\ &\leq \gamma \max_{s' \in \mathcal{S}} |V(s') - W(s')| \\ &= \gamma d(V, W) \end{split}$$

The second to last line follows from noting  $\sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r|s, a) = 1$ , so the weighted average is less than the maximum.

Therefore, since  $d(T(V), T(W)) \le \gamma d(V, W)$ , T is a contraction mapping with Lipschitz constant  $\gamma \in (0, 1)$ .

<sup>&</sup>lt;sup>4</sup>It is trivial to see this distance function defines a metric space by going through the properties in **Defn 2.1** 

### 3.3 Putting it Altogether: Final Proof

We now prove **Thm 1.1**.

*Proof.* Recall  $V_k = T(V_{k-1})$  as we defined. By **corollary 3.1.1**,  $(\mathcal{V}, d)$  is a complete metric space. By **Thm 3.2**, T is a contraction mapping in that metric space. Therefore, by the Banach Fixed Point Theorem 2.8,

$$\lim_{k \to \infty} V_k = V_*$$

Where  $V_*$  is a unique fixed point:

$$T(V_*) = V_*$$

Expanding this, we get  $\forall s \in \mathcal{S}$ :

$$V_*(s) = (T(V_*))(s)$$
=  $\max_{a \in \mathcal{A}(s)} \sum_{s' \in \mathcal{S}, r \in \mathcal{R}} p(s', r|s, a) [r + \gamma V_*(s')]$ 

Which is exactly the optimal state-value Bellman equation!

Therefore, the Value Iteration Algorithm as defined chooses an arbitrary  $V_0$  and constructs a sequence  $V_k = T(V_{k-1})$  which we've shown converges to the unique optimal value Bellman equation  $V_*$ .  $\square$ 

In summary, because we can write the Value Iteration Algorithm update (for discounted finite MDP setup) using an operator  $T: \mathcal{V} \to \mathcal{V}$ :  $V_{k+1} = T(V_k)$ , and since T is a contraction mapping on a complete metric space, the Value Iteration Algorithm will converge to a unique optimal  $V_*$ .