

University Dortmund

FACULTY OF ELECTRICAL ENGINEERING COMPUTER ENGINEERING INSTITUTE



Scheduling Problems and Solutions

Uwe Schwiegelshohn

CEI University Dortmund Summer Term 2004



Textbook

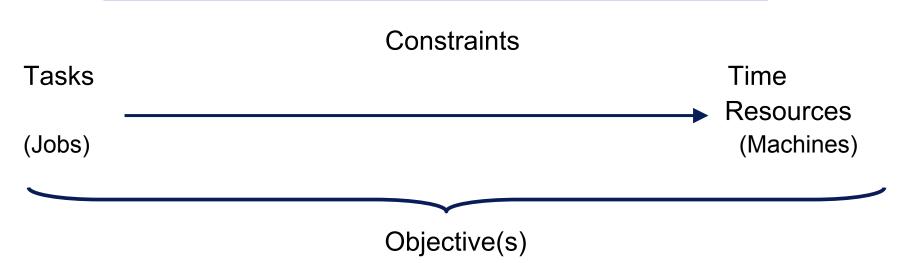


- Scheduling Theory, Algorithms, and Systems Michael Pinedo
 2nd edition, 2002
 Prentice-Hall Inc.
 Pearson Education
- The lecture is based on this textbook.
- These slides are an extract from this book. They are to be used only for this lecture and as a complement to the book.



Scheduling Problem





Areas:

- Manufacturing and production
- Transportations and distribution
- Information processing



Example 1

Paper Bag Factory



- different types of paper bags
- 3 production stages
 - printing of the logo
 - gluing of the side
 - sewing of one or both ends
- several machines for each stage
 - differences in speed and function
 - processing speed and processing quantity
 - setup time for a change of the bag type
- due time and late penalty
- minimization of late penalties, setup times



Example 2 Gate Assignments at Airport



- different types of planes (size)
- different types of gates (size, location)
- flight schedule
 - randomness (weather, take off policy)
- service time at gate
 - deplaning of passengers
 - service of airplane
 - boarding of passengers
- minimization of work for airline personnel
- minimization of airplane delay



Example 3

Tasks in a CPU

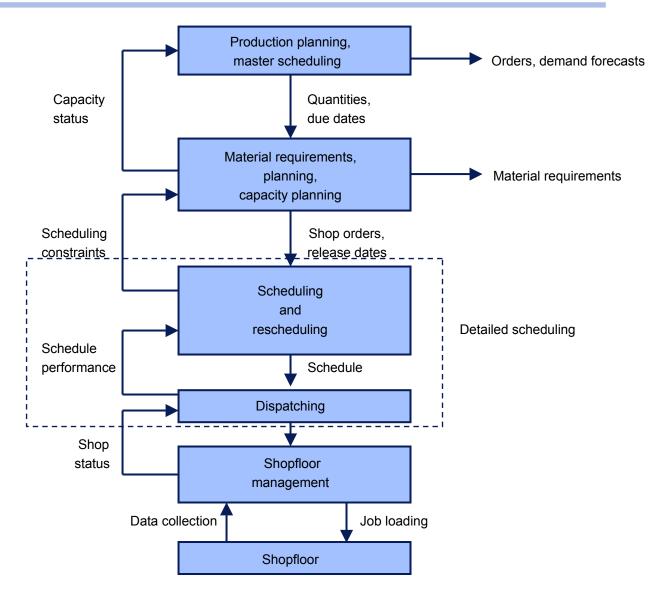


- different applications
 - unknown processing time
 - known distributions (average, variance)
 - priority level
- multitasking environment
 - preemption
- minimization of the sum of expected weighted completion times



Information Flow Diagram in a Manufacturing System

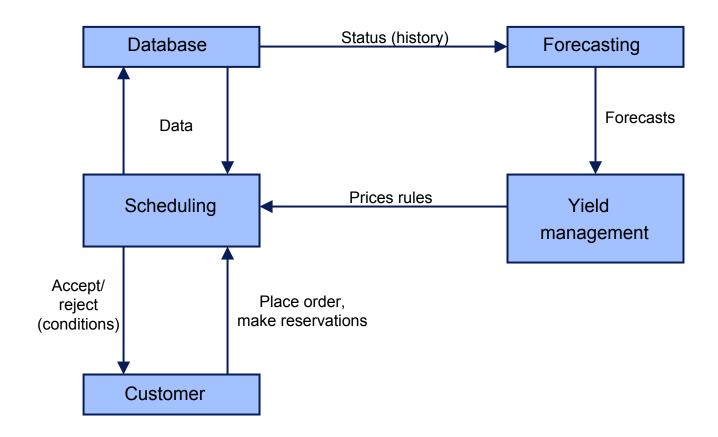






Information Flow Diagram in a Service System







Job Properties



Pij: processing time of job j on machine i

(p_j: identical processing time of job j on all machines)

r: release data of job j (earliest starting time)

d_j: due date of job j (completion of job j after d_j results in a late penalty)

dj: deadline (dj must be met)



Machine Environment (1)



I : single machine

P_m: **m** identical machines in parallel

Q_m: **m** machines in parallel with different speeds

R_m: **m** unrelated machines in parallel

F_m: flow shop with **m** machines in series

- each job must be processed on each machine using the same route.
- queues between the machines

FIFO queues, see also permutation flow shop

FF_c: flexible flow shop with **c** stages in series and several identical machines at each stage, one job needs processing on only one (arbitrary) machine at each stage.



Machine Environment (2)



 J_{m} : job show with **m** machines with a separate predetermined route for each job. A machine may be visited more than once by a job. This is called *recirculation*.

 FJ_c : flexible job shop with \boldsymbol{c} stages and several identical machines at each stage, see FF_c

 O_m : Open shop with \boldsymbol{m} machines

Each job must be processed on each machine.



Restrictions and Constraints (1)



- release dates, see also job properties
- sequence dependent setup times
 - → S_{ijk}: setup time between job j and job k on machine i
 - → (S_{jk}: identical setup times for all machines)
 - → (S_{0j}: startup for job j)
 - \rightarrow (S_{i0}: cleanup for job j)
- preemption (prmp)
 - → The processing of a job can be interrupted and later resumed (on the same or another machine).
- precedence constraints (prec)
 - Certain jobs must be completed before another job can be started.
 - representation as a directed acyclic graph (DAG)



Restrictions and Constraints (2)



- machine breakdowns (brkdwn)
 - → machines are not continuously available: For instance, m(t) identical parallel machines are available at time t.
- machine eligibility restrictions (M_i)
 - → M_j denotes the set of parallel machines that can process job j (for P_m and Q_m).
- permutation (prmu), see F_m
- blocking (block)
 - → A completed job cannot move from one machine to the next due to limited buffer space in the queue. Therefore, it blocks the previous machine (F_m, FF_c)



Restrictions and Constraints (3)



- no wait (nwt)
 - → A job is not allowed to wait between two successive executions on different machines (F_m, FF_c).
- recirculation (recirc)



Objective Functions (1)



- Completion time of job j: C_j
- Lateness of job j: L_j = C_j d_j
 - → The lateness may be positive or negative.
- Tardiness: $T_j = max(L_j, 0)$

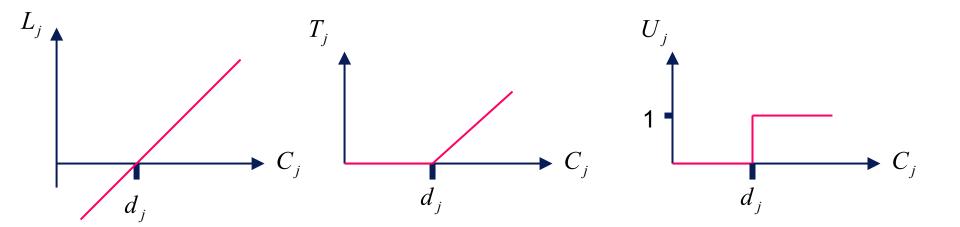
Number of late jobs: U_i =

1 if
$$C_j > d_{j,}$$



Objective Functions (2)





- Makespan: C_{max} = max (C₁,...,C_n)
 - completion time of the last job in the system
- Maximum lateness: L_{max} = max (L₁,..., L_n)



Objective Functions (3)

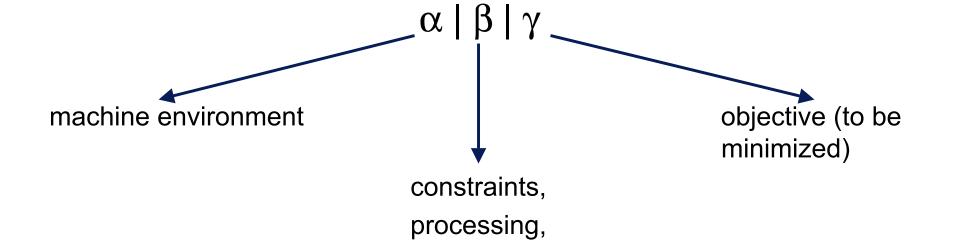


- lacksquare Total weighted completion time: Σ w_j C_j
- Total weighted flow time: $(\sum w_j (C_j r_j)) = \sum w_j C_j \sum w_j r_j$
- Discounted total weighted completion time:
 - → $(\Sigma w_j (1 e^{-rC_j}))$ 0<r<1
- Total weighted tardiness: Σ w_j T_j
- Weighted number of tardy jobs: $\sum w_j U_j$
- Regular objective functions:
 - → non decreasing in C₁,...,C_n
 - → Earliness: E_i = max (-L_i, 0)
 - non increasing in C_j
- $\Sigma E_j + \Sigma T_j$, Σw_j , $E_j + \Sigma w_j$, $T_j \longrightarrow$ not regular obj. functions



Description of a Scheduling Problem





characteristics

Examples:

- Paper bag factory
- Gate assignment
- Tasks in a CPU
- Traveling Salesman

$$\begin{aligned} & \text{FF3} \mid r_j \mid \Sigma \ w_j \ T_j \\ & P_m \mid r_j \ , \ M_j \mid \Sigma \ w_j \ T_j \\ & \text{I} \mid r_j \ \text{prmp} \mid \Sigma \ w_j \ C_j \\ & \text{I} \mid s_{jk} \mid C_{max} \end{aligned}$$



Classes of Schedules



- Nondelay (greedy) schedule
 - → No machine is kept idle while a task is waiting for processing.

An optimal schedule need not be nondelay!

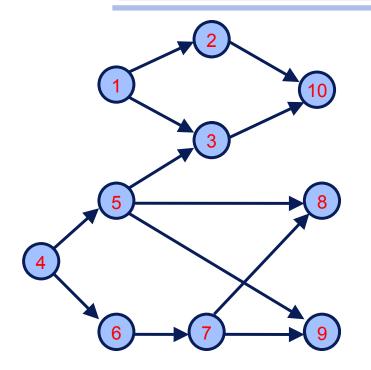
Example: P2 | prec | C_{max}

jobs	1	2	3	4	5	6	7	8	9	10
pj	8	7	7	2	3	2	2	8	8	15



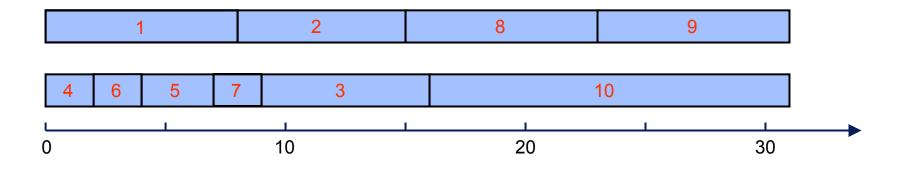
Precedence Constraints Original Schedule





jobs	1	2	3	4	5	6	7	8	9	10
pj	8	7	7	2	3	2	2	8	8	15

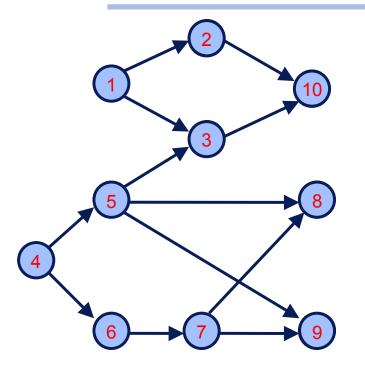






Precedence Constraints Reduced Processing Time

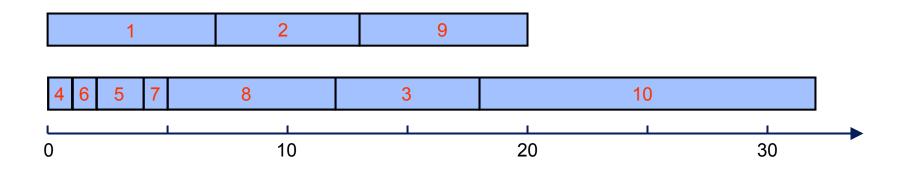




jobs	1	2	3	4	5	6	7	8	9	10
pj	7	6	6	1	2	1	1	7	7	14



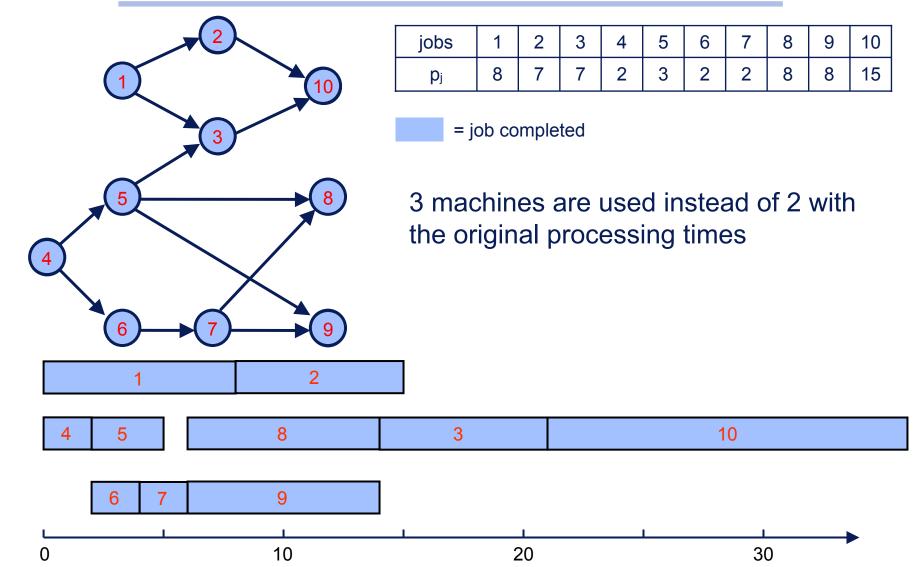
The processing time of each job is reduced by 1 unit.





Precedence Constraints Use of 3 Machines







Active Schedule



It is not possible to construct another schedule by changing the order of processing on the machines and having at least one task finishing earlier without any task finishing later.

There is at least one optimal and active schedule for $J_m||\gamma|$ if the objective function is regular.

Example:

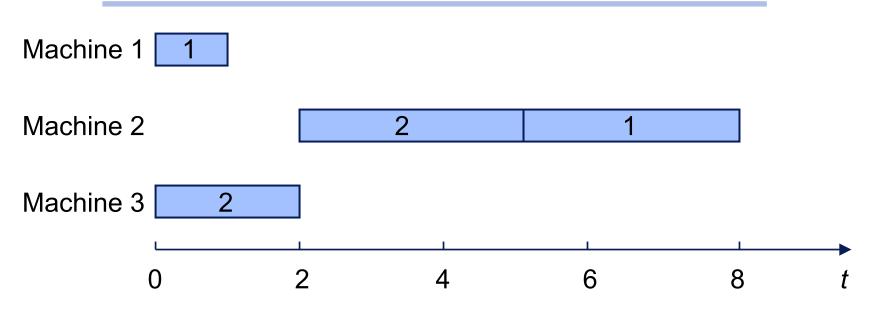
Consider a job shop with three machines and two jobs.

- Job 1 needs 1 time unit on machine 1 and 3 time units on machine 2.
- Job 2 needs 2 time units on machine 3 and 3 time units on machine 2.
- Both jobs have to be processed last on machine 2.



Example of an Active Schedule





It is clear that this schedule is active as reversing the sequence of the two jobs on machine 2 postpones the processing of job 2. However, the schedule is neither nondelay nor optimal. Machine 2 remains idle until time 2 while there is a job available for processing at time 1.



Semi – active Schedule



No task can be completed earlier without changing the order of processing on any one of the machines.

Example:

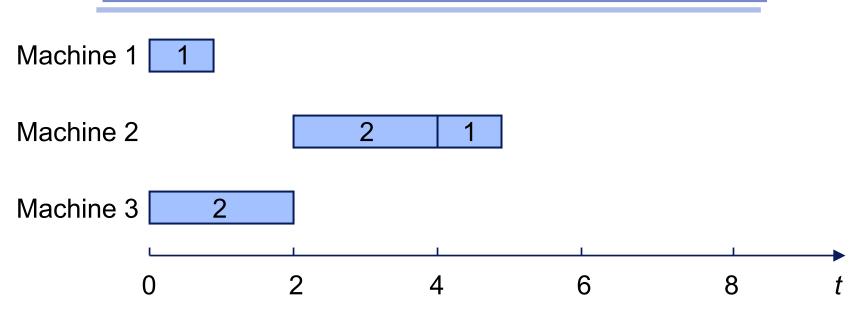
Consider again a schedule with three machines and two jobs. The routing of the two jobs is the same as in the previous example.

- The processing times of job 1 on machines 1 and 2 are both equal to 1.
- The processing times of job 2 on machines 2 and 3 are both equal to 2.



Example of a Semi – active Schedule



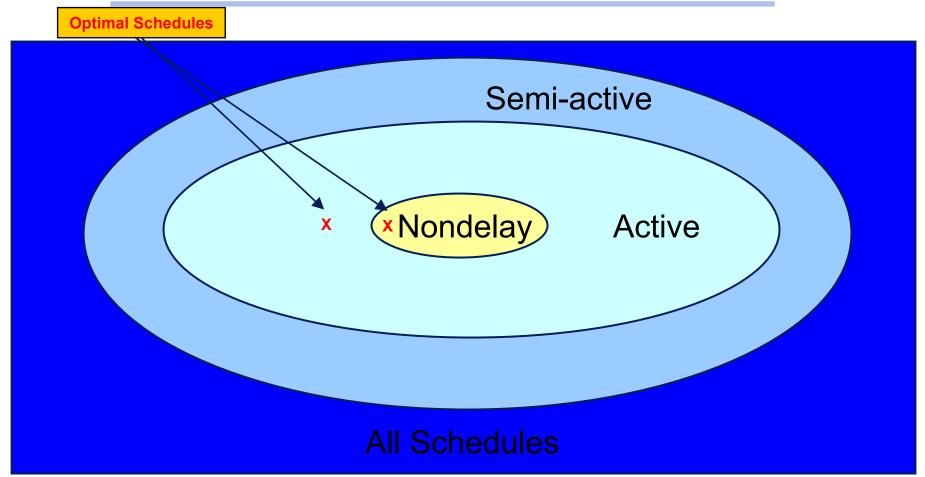


Consider the schedule under which job 2 is processed on machine 2 before job 1. This implies that job 2 starts its processing on machine 2 at time 2 and job 1 starts its processing on machine 2 at time 4. This schedule is semi-active. However, it is not active as job 1 can be processed on machine 2 without delaying the processing of job 2 on machine 2.



Venn Diagram of Classes of Schedules for Job Shops





A Venn diagramm of the three classes of nonpreemptive schedules; the nondelay schedules, the active schedules, and the semi-active schedules



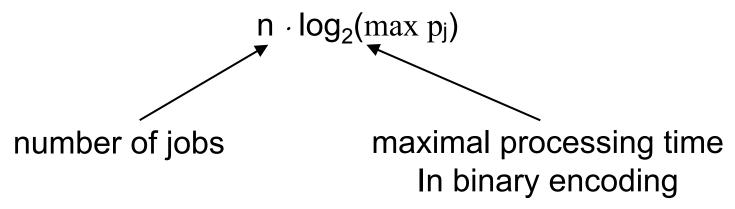
Complexity Preliminaries



- T(n)=O(f(n)) if $T(n)< c\cdot f(n)$ holds for some c>0 and all $n>n_0$.
- Example

$$1500 + 100n^2 + 5n^3 = O(n^3)$$

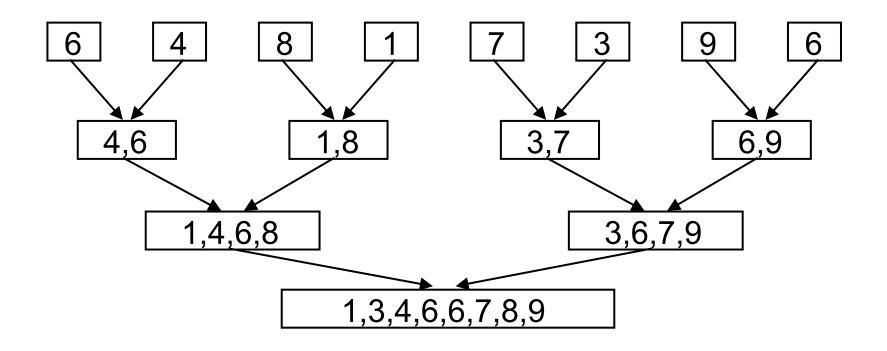
Input size of a simple scheduling problem





Mergesort





n input values at most $n \cdot \log_2 n$ comparison steps

time complexity of mergesort: $O(n \cdot \log n)$



Complexity Hierarchies of Deterministic Scheduling Problems



Some problems are special cases of other problems:

Notation:
$$\alpha_1 \mid \beta_1 \mid \gamma_1 \propto \text{(reduces to)} \quad \alpha_2 \mid \beta_2 \mid \gamma_2$$

Examples:

$$1 \mid\mid \Sigma C_j \propto 1 \mid\mid \Sigma w_j C_j \propto P_m \mid\mid \Sigma w_j C_j \propto Q_m \mid prec \mid \Sigma w_j C_j$$

Complex reduction cases:

$$\alpha \mid \beta \mid L_{max} \propto \alpha \mid \beta \mid \sum U_{j}$$

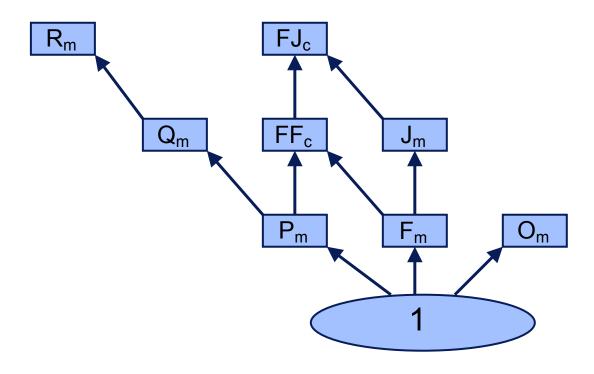
 $\alpha \mid \beta \mid L_{max} \propto \alpha \mid \beta \mid \sum T_{i}$

Variation of di and logarithmic search



Machine Environment

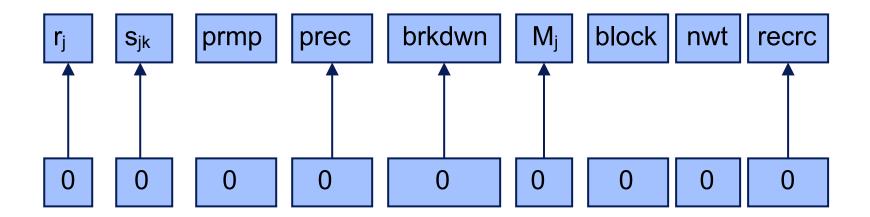






Processing Restrictions and Constraints

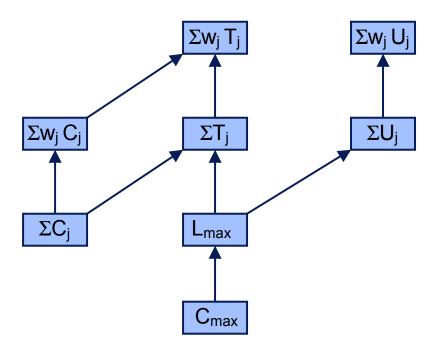






Objective Functions







Time Complexity of Algorithms

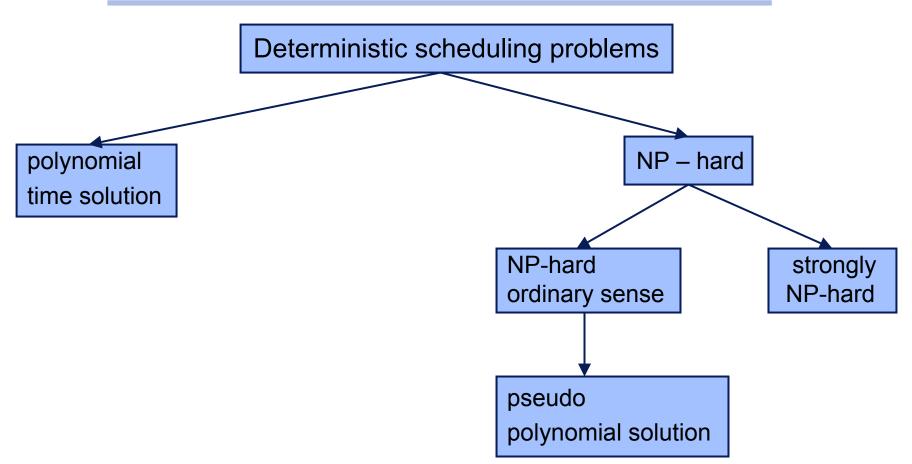


- Easy (polynomial time complexity): There is an algorithm that optimally solves the problem with time complexity O((n · log(max p_i))^k) for some fixed k.
- NP-hard in the ordinary sense (pseudo polynomial time complexity): The problem cannot be optimally solved by an algorithm with polynomial time complexity but with an algorithm of time complexity O((n · max p_i)^k).
- NP-hard in the strong sense: The problem cannot be optimally solved by an algorithm with pseudo polynomial complexity.



Problem Classification







Partition



Given positive integers a_1, \dots, a_t and $b = \frac{1}{2} \sum_{j=1}^t a_j$,

do there exist two disjoint subsets S₁ and S₂ such that

$$\sum_{j \in S_i} a_j = b$$

for i=1,2?

Partition is NP-hard in the ordinary sense.



3-Partition



Given positive integers a₁,..., a_{3t}, b with

$$\frac{b}{4} < a_j < \frac{b}{2}$$
, j = 1,..., 3t,

and

$$\sum_{j=1}^{3t} a_j = tb$$

do there exist t pairwise disjoint three element subsets $S_i \subset \{1, ..., 3t\}$ such that

$$\sum_{j \in S_i} a_j = b \qquad \text{for i=1,..., t?}$$

3-Partition is strongly NP-hard.



Proof of NP-Hardness

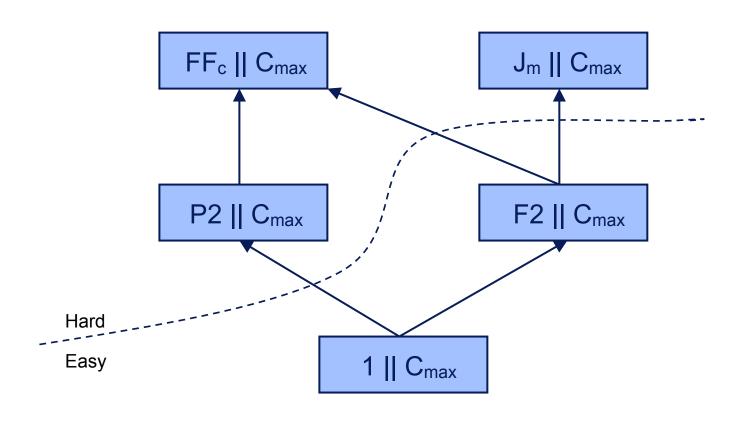


- A scheduling problem is NP-hard in the ordinary sense if
 - → partition (or a similar problem) can be reduced to this problem with a polynomial time algorithm and
 - → there is an algorithm with pseudo polynomial time complexity that solves the scheduling problem.
- A scheduling problem is strongly NP-hard if
 - → 3-partition (or a similar problem) can be reduced to this problem with a polynomial time algorithm.



Complexity of Makespan Problems

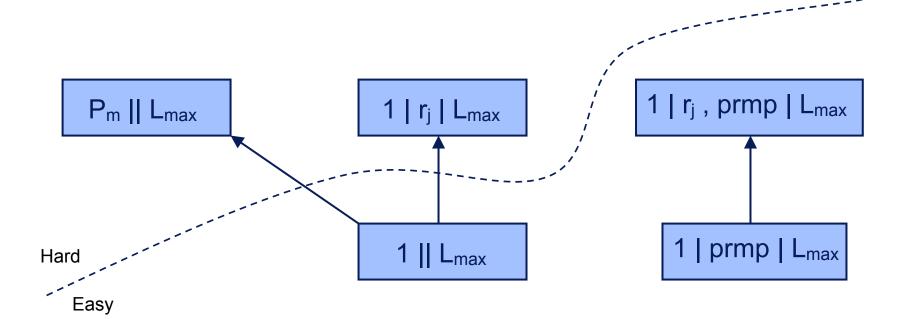






Complexity of Maximum Lateness Problems







Total Weighted Completion Time (1)



1 ||
$$\sum w_j C_j$$
: Schedule the jobs in Smith order $\frac{w_j}{p_j}$.

The Weighted Shortest Processing Time first (WSPT) rule is optimal for $1 \parallel \Sigma w_j C_{j.}$

Proof by contradiction and localization:

If the WSPT rule is violated then it is violated by a pair of neighboring task h and k.

$$S_1$$
: $\sum w_j C_j = ... + w_h(t+p_h) + w_k(t+p_h+p_k)$



Total Weighted Completion Time (2)





$$S_2$$
: $\sum w_j C_j = ... + w_k(t+p_k) + w_h(t+p_k+p_h)$

Difference between both schedules S₁ und S₂:

 $w_k p_h - w_h p_k > 0$ (improvement by exchange)

$$\iff \frac{W_k}{p_k} > \frac{W_h}{p_h}$$

The complexity is dominated by sorting \implies O (n log(n))



Total Weighted Completion Time (3)



Use of precedence constraints: $1 | \text{prec} | \Sigma w_j C_j$ Only independent chains are allowed at first!

Chain of jobs 1, ..., k

I* satisfies

$$\frac{\sum\limits_{j=1}^{l^*} w_j}{\text{of this}} = \max_{1 \le l \le k} \left(\frac{\sum\limits_{j=1}^{l} w_j}{\sum\limits_{j=1}^{l} p_j} \right)$$

I* determines the δ -factor of the chain 1, ..., k



Total Weighted Completion Time with Chains



Whenever the machine is available, select among the remaining chains the one with the highest δ -factor.

Schedule all jobs from this chain without interruption until the job that determines the δ -factor.

Proof concept

There is an optimal schedule that processes all jobs 1, ..., I* in succession + Pairwise interchange of chains



Example: Total Weighted Completion Time with Chains (1)



Consider the following two chains:

$$1 \rightarrow 2 \rightarrow 3 \rightarrow 4$$

and

$$5 \rightarrow 6 \rightarrow 7$$

The weights and processing times of the jobs are given in the following table.

jobs	1	2	3	4	5	6	7
Wj	6	18	12	8	8	17	18
pj	3	6	6	5	4	8	10



Example: Total Weighted Completion Time with Chains (2)



• δ -factor of first chain $(6+18)/(3+6) = \frac{24}{9}$ \rightarrow

- Job 2
- δ -factor of second chain $\frac{(8+17)}{(4+8)} = \frac{25}{12} < \frac{24}{9}$ → Jobs 1 and 2 are scheduled first.
- δ -factor of remaining part of first chain $\frac{12}{6} < \frac{25}{12}$ → Job 3 → Jobs 5 and 6 are scheduled next.
- $\frac{w_7}{p_7} = \frac{18}{10} < \frac{12}{6}$ → Job 3 is scheduled next.
- $\frac{w_4}{p_4} = \frac{8}{5} < \frac{18}{10}$ → Job 7 is scheduled next and finally job 4



Other Total Completion Time Problems



- 1 | prec | Σ w_j C_j is strongly NP hard for arbitrary precedence constraints.
- 1 | r_j , prmp | Σ w_j C_j is strongly NP hard.
 - → The WSPT (remaining processing time) rule is not optimal. <u>Example:</u> Select another job that can be completed before the release date of the next job.
- $1 \mid r_j$, prmp $\mid \Sigma C_j$ is easy.
- $1 \mid r_j \mid \Sigma C_j$ is strongly NP hard.
- 1 || Σ w_j (1 e -r^Cj) can be solved optimally with the Weighted Discounted Shortest Processing Time first (WDSPT) rule:

$$\frac{1}{1-e^{-rp_j}}$$



Maximum Cost



- General problem: 1 | prec | h_{max}
 - → h_j (t): nondecreasing cost function
 - → $h_{max} = max (h_1 (C_1), ..., h_n (C_n))$
- Backward dynamic programming algorithm
 - \rightarrow makespan $C_{max} = \sum p_i$
 - → J: set of all jobs already scheduled (backwards) in

$$[C_{max} - \sum_{i \in J} p_j, C_{max}]$$

- \rightarrow J^c = {1, ..., n} \ J: set of jobs still to be scheduled
- \rightarrow J' \subseteq J^c: set jobs that can be scheduled under consideration of precedence constraints.



Algorithm: Minimizing Maximum Cost



Step 1

Set $J = \emptyset$, let $J^c = \{1, ..., n\}$ and J' be the set of all jobs with no successors.

Step 2

Let $j^* \in J'$ be such that

$$h_{j*}\left(\sum_{j\in J^c} p_j\right) = \min_{j\in J'}\left(h_j\left(\sum_{k\in J^c} p_k\right)\right)$$

Add j* to J.

Delete j* from J^c.

Modify J' to represent the new set of schedulable jobs.

• Step 3 If $J^c = \emptyset$ then STOP otherwise go to Step 2.

This algorithm yields an optimal schedule for 1 | prec | h_{max}.



Minimizing Maximum Cost: Proof of Optimality (1)

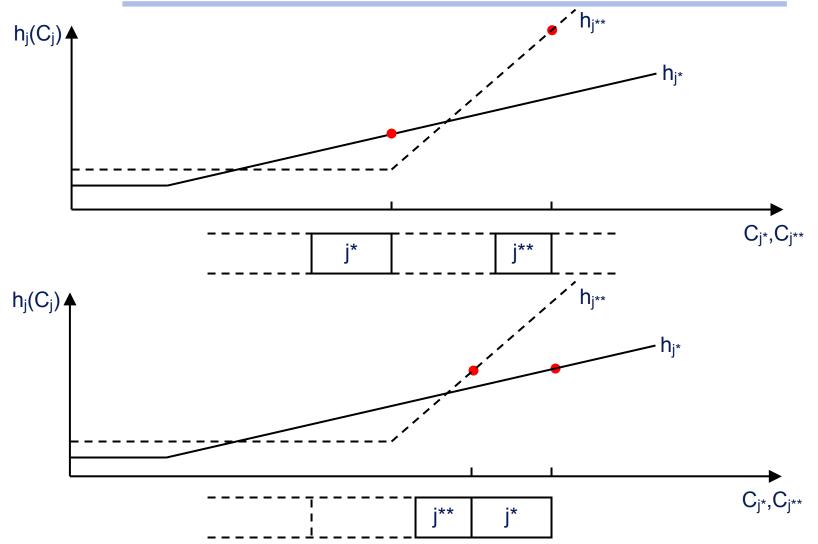


- Assumption: The optimal schedule S_{opt} and the schedule S of the previous algorithm are identical at positions k+1,..., n.
- At position k with completion time t, there is job j** in S_{opt} and job j* with $h_{j**}(t) \ge h_{j*}(t)$ in S.
 - → Job j* is at position k' < k in S_{opt}.
- Create schedule S' by removing job j* in S_{opt} and putting it at position k.
 - \rightarrow h_j(C_j) does not increase for all jobs {1, ..., n} \ {j*}.
 - → $h_{j^*}(t) \le h_{j^{**}}(t)$ ') $\le h_{max}(S_{opt})$ holds due to the algorithm.
- Therefore, schedule S' is optimal as h_{max}(S')≤h_{max}(S_{opt}) holds.
 - → An optimal schedule and schedule S are identical at positions k, k+1, ..., n.



Minimizing Maximum Cost: Proof of Optimality (2)







Minimizing Maximum Cost: Example



jobs	1	2	3	
p _j	2	3	5	
$h_j(C_j)$	1 + C _j	1.2 C _j	10	

$$C_{\text{max}} = 2+3+5 = 10$$

- $h_3(10) = 10 < h_1(10) = 11 < h_2(10) = 12$ → Job 3 is scheduled last.
- $h_2(10 p_3) = h_2(5) = 6 = h_1(5)$
 - → Optimal schedules 1,2,3 and 2,1,3



Maximum Lateness (1)



- 1 || L_{max} is a special case of 1 | prec | h_{max}.
 - → $h_j = C_j d_j$ → Earliest Due Date first
- 1 | r_j | L_{max} is strongly NP complete.

Proof:

Reduction of 3-Partition to $1 | r_j | L_{max}$

integers
$$a_1, \dots, a_{3t}, b$$
 $\frac{b}{4} < a_j < \frac{b}{2}$ $\sum_{j=1}^{3t} a_j = t \cdot b$ \Rightarrow n = 4t -1 jobs

$$\begin{aligned} r_j &= j \cdot b \, + \, (j \, -1), & p_j &= \, 1, & d_j &= \, j \cdot b \, + \, j, & \forall \, j &= \, 1,, \, t \, -1 \\ r_j &= \, 0, & p_j &= \, \alpha_{j-t+1}, & d_j &= \, t \cdot b \, + \, (t-1), \, \forall \, j \, = \, t,, \, 4t-1 \end{aligned}$$

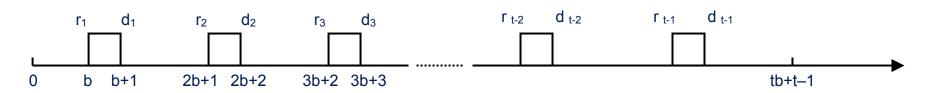


Maximum Lateness (2)



 $L_{max} = 0$ if every job $j \in \{1,..., t-1\}$ can be processed from r_j to $r_j + p_j = d_j$ and all other jobs can be partitioned over t intervals of length b.

→ 3 – Partition has a solution.



 $1 \mid r_j \mid L_{max}$ is strongly NP – hard.



Optimal Solution for $1 | r_j | L_{max}(1)$



Optimal solution for 1 | r_j | L_{max}: Branch and bound method

- → Tree with n+1 levels
- Level 0: 1 root node
- Level 1: n nodes:
 A specific job scheduled at the first position of the schedule.
- Level 2: n·(n-1) nodes: from each node of level 1 there are n – 1 edges to nodes of level 2: a second specific job scheduled at the second position of the schedule.
 - n!/k! nodes at level k: each node specifies the first k positions of the schedule.



Optimal Solution for $1 | r_j | L_{max}(2)$



Assumption:
$$r_{j_k} \ge \min_{l \in J} (\max(t, r_l) + p_l)$$

J: jobs that are not scheduled at the father node of level k – 1

t: makespan at the father node of level k – 1

Job j_k need not be considered at a node of level k with this specific father at level k-1.

Finding bounds:

If there is a better schedule than the one generated by a branch then the branch can be ignored.

- $1 \mid r_j$, prmp | L_{max} can be solved by the preemptive *Earliest Due Date* (EDD) *first* rule.
 - → This produces a nondelay schedule.
 - → The resulting schedule is optimal if it is nonpreemptive.



Branch and Bound Applied to Minimizing Maximum Lateness (1)



jobs	1	2	3	4
p _j	4	2	6	5
r _j	0	1	3	5
d _j	8	12	11	10

- Level 1 (1, ?, ?, ?) (2, ?, ?, ?) (3, ?, ?, ?) (4, ?, ?, ?)
 - → Disregard (3, ?, ?, ?) and (4, ?, ?, ?) as job 2 can be completed at r₃ and r₄ at the latest.
- Lower bound for node (1, ?, ?, ?):

Lower bound for node (2, ?, ?, ?):



Branch and Bound Applied to Minimizing Maximum Lateness (2)



- Lower bound for node (1, 2, ?, ?):
 - \rightarrow 1, 2, 3, 4 (nonpreemptive, L_{max} = 6)
 - → Disregard (2, ?, ?, ?).
- Lower bound for node (1, 3, ?, ?):
 - → 1, 3, 4, 2 (nonpreemptive, $L_{max} = 5$) ← optimal
 - → Disregard (1, 2, ?, ?).
- Lower bound for node (1, 4, ?, ?):
 - \rightarrow 1, 4, 3, 2 (nonpreemptive, L_{max} = 6)

A similar approach can be used for $1 \mid r_j$, prec $\mid L_{max}$.

→ The additional precedence constraints may lead to less nodes in the branch and bound tree.



Number of Tardy Jobs: $1 \parallel \Sigma U_j$



- The jobs are partitioned into 2 sets.
 - set A: all jobs that meet their due dates
 - → These jobs are scheduled according to the EDD rule.
 - set B: all jobs that do not meet their due dates
 - These jobs are not scheduled!
- The problem is solved with a forward algorithm.
 - J: Jobs that are already scheduled
 - Jd: Jobs that have been considered and are assigned to set B
 - J^c: Jobs that are not yet considered



Algorithm for Solving 1 || ΣU_j



■ Step 1 Set
$$J = \emptyset$$
, $J^d = \emptyset$, and $J^c = \{1, ..., n\}$.

- Step 2 Let j* denote the job that satisfies d_{j*} = min (d_j). Add j* to J.
 Delete j* from J^c.
 Go to Step 3.
- Step 3 If $\sum_{j \in J} p_j \le d_{j^*}$ then go to Step 4, otherwise let k^* denote the job which satisfies $p_{k^*} = \max_{j \in J} (p_j)$. Delete k^* from J. Add k^* to J^d .
- Step 4 If $J^c = \emptyset$ then STOP, otherwise go to Step 2.



1 || Σ U_j: Proof of Optimality (1)



The computational complexity is determined by sorting O(n·log(n)).

We assume that all jobs are ordered by their due dates.

- \rightarrow $d_1 \le d_2 \le ... \le d_n$
- J_k is a subset of jobs $\{1, ..., k\}$ such that
 - (I) it has the maximum number N_k of jobs in $\{1, ..., k\}$ completed by their due dates,
 - (II) of all sets with N_k jobs in $\{1, ..., k\}$ completed by their due dates J_k is the set with the smallest total processing time.
 - → J_n corresponds to an optimal schedule.



1 || Σ U_j: Proof of Optimality (2)



Proof by induction

The claim is correct for k=1.

- We assume that it is correct for an arbitrary k.
- 1. Job k+1 is added to set J_k and it is completed by its due date.
 - \rightarrow $J_{k+1} = J_k \cup \{k+1\}$ and $|J_{k+1}| = N_k + 1 = N_{k+1}$.
- 2. Job k+1 is added to set J_k and it is not completed on time.
 - The job with the longest processing time is deleted
 - \rightarrow $N_{k+1} = N_k$
 - \rightarrow The total processing time of J_k is not increased.
 - → No other subset of {1, ..., k+1} can have N_k on-time completions and a smaller processing time.



1 || Σ U_i: Example



jobs	1	2	3	4	5
p _j	7	8	4	6	6
d _j	9	17	18	19	21

Job 1 fits:

 $J_1 = \{1\}$

Job 2 fits:

 $J_2 = \{1, 2\}$

Job 3 does not fit:

 $J_3 = \{1, 3\}$

Job 4 fits:

 $J_4 = \{1, 3, 4\}$

Job 5 does not fit:

 $J_5 = \{3, 4, 5\}$

→ schedule order

3, 4, 5, (1, 2)

 $\Sigma U_i = 2$

- $1 \parallel \Sigma w_j U_j$ is NP-hard in the ordinary sense.
 - \rightarrow This is even true if all due dates are the same: 1 $|d_i=d| \sum w_i U_i$
 - > Then the problem is equivalent to the knapsack problem.



1 || Σ w_jU_j: Example



Heuristic approach: Jobs are ordered by the WSPT rule (w_j / p_j).

→ The ratio
$$\frac{\sum w_j U_j(WSPT)}{\sum w_j U_j(OPT)}$$
 may be very large.

■ Example: WSPT: 1, 2, 3 $\Sigma w_j U_j = 89$

OPT: 2, 3, 1 $\Sigma w_j U_j = 12$

jobs	1	2	3
p _j	11	9	90
Wj	12	9	89
d _j	100	100	100



Total Tardiness (1)



- 1 || ΣT_j : NP hard in the ordinary sense.
 - → There is a pseudo polynomial time algorithm to solve the problem.

Properties of the solution:

- 1. If $p_j \le p_k$ and $d_j \le d_k$ holds then there exists an optimal sequence in which job j is scheduled before job k.
 - This is an Elimination criterion or Dominance result.

A large number of sequences can be disregarded. ⇒ New precedence constraints are introduced. ⇒ The problem becomes easier.



Total Tardiness (2)



2 problem instances with processing times p₁, ..., p_n

First instance: d₁, ..., d_n

C'_k: latest possible completion time of job k in an optimal sequence (S')

Second instance:

 $d_1, ..., d_{k-1}, max\{d_k, C'_k\} d_{k+1}, ..., d_n$

S": an optimal sequence

C_j": completion time of job j in sequence S"

2. Any sequence that is optimal for the second instance is optimal for the first instance as well.



Total Tardiness (3)



- Assumption: $d_1 \le ... \le d_n$ and $p_k = max (p_1, ..., p_n)$
- → kth smallest due date has the largest processing time.
- 3. There is an integer δ , $0 \le \delta \le n k$ such that there is an optimal sequence S in which job k is preceded by all other jobs j with $j \le k+\delta$ and followed by all jobs j with $j > k+\delta$.
 - An optimal sequence consists of
 - 1. jobs 1, ..., k-1, k+1, ..., k+ δ in some order
 - 2. job k
 - 3. jobs k+ δ +1, ..., n in some order The completion time of job k is given by $C_k(\delta) = \sum_{i < k + \delta} p_i$.



Minimizing Total Tardiness (1)



- J(j, l, k): all jobs in the set {j, ..., l} with a processing time ≤ p_k but job k is not in J(j, l, k).
- V(J(j, l, k), t) is the total tardiness of J(j, l, k) in an optimal sequence that starts at time t.

Algorithm: Minimizing Total Tardiness

Initial conditions: $V(\emptyset, t) = 0$

 $V({j}, t) = max (0, t + p_j - d_j)$

Recursive relation:

 $V(J(j,l,k),t) = \min_{\delta} \left(V(J(j,k'+\delta,k'),t) + \max(0,C_{k'}(\delta) - d_{k'}) + V(J(k'+\delta+1,l,k'),C_{k'}(\delta)) \right)$

where k' is such that $p_{k'} = \max(p_{j'}|j' \in J(j,l,k))$

Optimal value function V({1, ..., n},0)



Minimizing Total Tardiness (2)



- At most $O(n^3)$ subsets J(j, l, k) and Σp_j points in t
 - \rightarrow O(n³· Σ p_j) recursive equations
- Each recursion takes O(n) time
 - \rightarrow Running time $O(\underline{n}^4 \cdot \Sigma_{\mathbf{j}} p_j)$

polynomial in n

pseudo polynomial

Algorithm PTAS Minimizing Total Tardiness



Minimizing Total Tardiness Example (1)



jobs	1	2	3	4	5
p _j	121	79	147	83	130
d _j	260	266	266	336	337

■ k=3 (largest processing time) \Rightarrow 0 \leq δ \leq 2 = 5 - 3

$$V(\{1, 2, ..., 5\}, 0) = \min \begin{cases} V(J(1, 3, 3), 0) + 81 + V(J(4, 5, 3), 347) \\ V(J(1, 4, 3), 0) + 164 + V(J(5, 5, 3), 430) \\ V(J(1, 5, 3), 0) + 294 + V(\emptyset, 560) \end{cases}$$

- V(J(1, 3, 3), 0) = 0 for sequences 1, 2 and 2, 1
- V(J(4, 5, 3), 347) = 347 + 83 336 + 347 + 83 + 130 337 = 317 for sequence 4, 5



Minimizing Total Tardiness Example (2)



- V(J(1, 4, 3), 0) = 0 for sequences 1, 2, 4 and 2, 1, 4
- V(J(5, 5, 3), 430) = 430 + 130 337 = 223
- V(J(1, 5, 3), 0) = 76 for sequences 1, 2, 4, 5 and 2, 1, 4, 5

$$\rightarrow$$
 V({1, ..., 5}, 0) = min $\left\{ \begin{array}{l} 0 + 81 + 317 \\ 0 + 164 + 223 \\ 76 + 294 + 0 \end{array} \right\} = 370$

1, 2, 4, 5, 3 and 2, 1, 4, 5, 3 are optimal sequences.



Total Weighted Tardiness



- 1 || Σ w_jT_j is strongly NP complete.
 - → Proof by reduction of 3 Partition
- Dominance result
 If there are two jobs j and k with d_j ≤ d_k, p_j ≤ p_k and w_j ≥ w_k then there is an optimal sequence in which job j appears before job k.
- The Minimizing Total Tardiness algorithm can solve this problem if $w_j \le w_k$ holds for all jobs j and k with $p_j \ge p_k$.



Total Tardiness An Approximation Scheme (1)



For NP – hard problems, it is frequently interesting to find in polynomial time a (approximate) solution that is close to optimal.

Fully Polynomial Time Approximation Scheme A for $1 \parallel \Sigma T_j$:

$$\sum T_{j}(A) \leq (1+\varepsilon) \sum T_{j}(OPT)$$
optimal schedule

The running time is bounded by a polynomial (fixed degree) in n and $1/\epsilon$.



Total Tardiness An Approximation Scheme (2)



- a) n jobs can be scheduled with 0 total tardiness iff (if and only if) the EDD schedule has 0 total tardiness.
 - $T_{\max}(EDD) \le \sum T_j(OPT) \le \sum T_j(EDD) \le n \cdot T_{\max}(EDD)$

maximum tardiness of any job in the EDD schedule



Total Tardiness An Approximation Scheme (3)



- b) V(J,t): Minimum total tardiness of job subset J assuming processing starts at t.
 - → There is a time t* such that

$$V(J, t)=0$$
 for $t \le t^*$ and $V(J, t)>0$ for $t > t^*$ $\Rightarrow V(J, t^* + \delta) \ge \delta$ for $\delta \ge 0$

→ The pseudo polynomial algorithm is used to compute V(J, t) for

$$\max\{0, t^*\} \le t \le n \cdot T_{\max}(EDD)$$

→ Running time bound O(n⁵ · T_{max}(EDD))



Total Tardiness An Approximation Scheme (4)



c) Rescale $p'_j = \lfloor p_j / K \rfloor$ and $d'_j = d_j / K$ with some factor K.

S is the optimal sequence for rescaled problem.

 $\sum T_j^*(S)$ is the total tardiness of sequence S for processing times $K \cdot p'_j \le p_j$ and due dates d_j .

 $\sum T_j(S)$ is the total tardiness of sequence S for $p_j < K \cdot (p_j^* + 1)$ and d_j .

Select
$$K = \frac{2\varepsilon}{n(n+1)} \cdot T_{\text{max}} (EDD)$$

$$\rightarrow \sum T_j(S) - \sum T_j(OPT) \le \varepsilon \cdot T_{\max}(EDD)$$



PTAS Minimizing Total Tardiness



Algorithm: PTAS Minimizing Total Tardiness

Step 1 Apply EDD and determine T_{max}.

If $T_{max} = 0$, then $\sum T_i = 0$ and EDD is optimal; STOP.

Otherwise set

$$K = \left(\frac{2\varepsilon}{n(n+1)}\right) T_{max} (EDD)$$

Step 2 Rescale processing times and due dates as follows:

$$p'_{j} = \lfloor p_{j} / K \rfloor$$
 $d'_{j} = \frac{d_{j}}{K}$

Step 3 Apply Algorithm Minimizing Total Tardiness to the rescaled data.

Running time complexity: $O(n^5 \cdot T_{max}(EDD)/K) = O(n^7/\epsilon)$



PTAS Minimizing Total Tardiness Example



jobs	1	2	3	4	5
p _j	1210	790	1470	830	1300
d _j	1996	2000	2660	3360	3370

- Optimal sequence 1,2,4,5,3 with total tardiness 3700.
 - → Verified by dynamic programming
- T_{max}(EDD)=2230
 - \rightarrow If ε is chosen 0.02 then we have K=2.973.
- Optimal sequences for the rescaled problem: 1,2,4,5,3 and 2,1,4,5,3.
 - → Sequence 2,1,4,5,3 has total tardiness 3704 for the original data set.
 - $\rightarrow \sum T_j(2,1,4,5,3) \le 1.02 \cdot \sum T_j(1,2,4,5,3)$



Total Earliness and Tardiness (1)

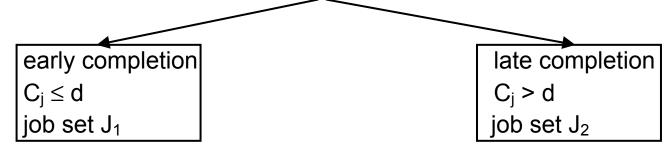


Objective $\Sigma E_j + \Sigma T_j$

- → This problem is harder than total tardiness.
- → A special case is considered with d_j = d for all jobs j.

Properties of the special case

- No idleness <u>between</u> any two jobs in the optimal schedule
 - → The first job does not need to start at time 0.
- Schedule S is divided into 2 disjoint sets





Total Earliness and Tardiness (2)



- Optimal Schedule:
 Early jobs (J₁) use Longest Processing Time first (LPT)
 Late jobs (J₂) use Shortest Processing Time first (SPT)
- There is an optimal schedule such that one job completes exactly at time d.

Proof: Job j* starts before and completes after **d**.

If $|J_1| \le |J_2|$ then
shift schedule to the left until j* completes at **d**.

If $|J_1| > |J_2|$ then
shift schedule to the right until j* starts at **d**.



Minimizing Total Earliness and Tardiness with a Loose Due Date



Assume that the first job can start its processing after t = 0 and $p_1 \ge p_2 \ge ... \ge p_n$ holds.

- Step 1 Assign job 1 to set J₁.
 - Set k = 2.
- Step 2 Assign job k to set J₁ and job k + 1 to set J₂ or vice versa.
- Step 3 If $k+2 \le n-1$, set k=k+2 and go to Step 2 If k+2=n, assign job n to either set J_1 or set J_2 and STOP.

If k+2 = n+1, all jobs have been assigned; STOP.



Minimizing Total Earliness and Tardiness with a Tight Due Date (1)



The problem becomes NP-hard if job processing must start at time 0 and the schedule is nondelay.

It is assumed that $p_1 \ge p_2 \ge ... \ge p_n$ holds.

- Step 1 Set τ_1 = d and τ_2 = Σ p_j d. Set k = 1.
- Step 2 If $\tau_1 \ge \tau_2$, assign job k to the first unfilled position in the sequence and set $\tau_1 = \tau_1 p_k$. If $\tau_1 < \tau_2$, assign job k to the last unfilled position in the sequence and set $\tau_2 = \tau_2 p_k$.
- Step 3 If k < n, set k = k + 1 and go to Step 2.</p>
 If k = n, STOP.



Minimizing Total Earliness and Tardiness with a Tight Due Date (2)



6 jobs with d = 180

jobs	1	2	3	4	5	6
p _j	106	100	96	22	20	2

Applying the heuristic yields the following results.

τ ₁	$ au_2$	Assignment	Sequence
180	166	Job 1 Placed First	1xxxxx
74	166	Job 2 Placed Last	1xxxx2
74	66	Job 3 Placed First	13xxx2
-22	66	Job 4 Placed Last	13xx42
-22	44	Job 5 Placed Last	13x542
-22	24	Job 6 Placed Last	136542



Minimizing Total Earliness and Tardiness (1)



- Objective Σ w'E_j + Σ w"T_j with d_j = d.
 - \rightarrow All previous properties and algorithms for $\Sigma E_j + \Sigma T_j$ can be generalized using the difference of w' and w".
- Objective $\sum w_j E_j + \sum w_j T_j$ with $d_j = d$.
 - → The LPT/SPT sequence is not necessarily optimal in this case.
 - WLPT and WSPT are used instead.
 - The first part of the sequence is ordered in increasing order of w_j / p_j.
 - The second part of the sequence is ordered in decreasing order of w_j / p_j.



Minimizing Total Earliness and Tardiness (2)



- Objective Σ w'E_j + Σ w'T_j with different due dates
 - → The problem is NP hard.
 - a) Sequence of the jobs
 - b) Idle times between the jobs
 - dependent optimization problems
- Objective $\sum w_j$ ' $E_j + \sum w_j$ '' T_j with different due dates
 - → The problem is NP hard in the strong sense.
 - It is more difficult than total weighted tardiness.

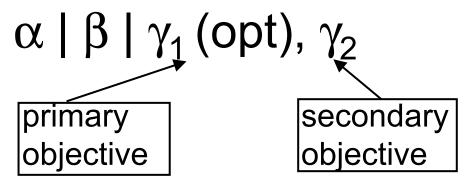
If a predetermined sequence is given then the timing can be determined in polynomial time.



Primary and Secondary Objectives



A scheduling problem is usually solved with respect to the **primary** objective. If there are several optimal solutions, the **best of those solutions** is selected according to the **secondary** objective.



- We consider the problem 1 || ΣC_j (opt), L_{max} .
 - → All jobs are scheduled according to SPT.
 - → If several jobs have the same processing time EDD is used to order these jobs.
 - SPT/EDD rule



Reversal of Priorities (1)



We consider the problem with reversed priorities:

1 ||
$$L_{max}$$
 (opt), ΣC_j

 \rightarrow L_{max} is determined with EDD.

$$\rightarrow$$
 z := L_{max}

Transformation of this problem:

$$\frac{\overline{d}_{j}}{d} = d_{j} + Z$$
new deadline old due dates



Reversal of Priorities (2)



- After the transformation, both problems are equivalent.
 - The optimal schedule minimizes Σ C_j and guarantees that each job completes by its deadline.
 - → In such a schedule, job k is scheduled last iff

$$\overline{d_k} \ge \sum_{j=1}^n p_j$$
 and

$$p_k \ge p_l$$
 for all I such that $\overline{d_l} \ge \sum_{j=1}^n p_j$ hold.

- Proof: If the first condition is not met, the schedule will miss a deadline.
 - A pairwise exchange of job I and job k (not necessarily adjacent) decreases Σ C_i if the second condition is not valid for I and k.



Minimizing Total Completion Time with Deadlines (1)



• Step 1 Set
$$k = n, \tau = \sum_{j=1}^{n} p_j, J^c = \{1, ..., n\}$$

Step 2 Find k* in J^c such that

$$d_{k^*} \geq \tau$$
 and

 $\frac{p_{k^*}}{\mathsf{d}_{\perp}} \ge p_{l}$ for all jobs I in $\mathsf{J^c}$ such that

Step 3 Decrease k by 1.

Decrease τ by p_{k^*}

Delete job k* from J^c.

■ Step 4 If $k \ge 1$ go to Step 2, otherwise STOP.

The optimal schedule is always nonpreemptive even if preemptions are allowed.



Minimizing Total Completion Time with Deadlines (2)



jobs	1	2	3	4	5
pj	4	6	2	4	2
\bar{d}_{j}	10	12	14	18	18

$$\tau = 18 \Rightarrow d_4 = d_5 = 18 \ge \tau$$
$$p_4 = 4 > 2 = p_5$$

→ Last job : 4

→
$$\tau = 18 - p_4 = 14 \Rightarrow d_3 = 14 \ge 14$$
 $d_5 = 18 \ge 14$ $p_5 = 2 = p_3$

→ Either job can go in the now last position : 3

→
$$\tau = 14 - p_3 = 12 \Rightarrow d_5 = 18 \ge 12$$
 $d_2 = 12 \ge 12$ $p_2 = 6 > 2 = p_5$

→ Next last job: 2

$$\tau$$
 = 12 − p₂ = 6 \Rightarrow d₅ = 18 ≥ 6 d₁ = 10 ≥ 12 p₁ = 4 > 2 = p₅

→ Sequence:

51234



Multiple Objectives



In a generalized approach, multiple objectives are combined in a linear fashion instead of using a priority ordering.

- Objectives: γ_1 , γ_2
- Problem with a weighted sum of two (or more) objectives:

$$1 \mid \beta \mid \Theta_1 \gamma_1 + \Theta_2 \gamma_2$$

■ The weights are normalized: $\Theta_1 + \Theta_2 = 1$



Pareto-Optimal Schedule (1)



A schedule is called pareto-optimal if it is not possible to decrease the value of one objective without increasing the value of the other.

$$\Theta_1 \rightarrow 0$$
 and $\Theta_2 \rightarrow 1$

$$\rightarrow 1|\beta|\Theta_1\gamma_1 + \Theta_2\gamma_2 \rightarrow 1|\beta|\gamma_2(opt), \gamma_1$$

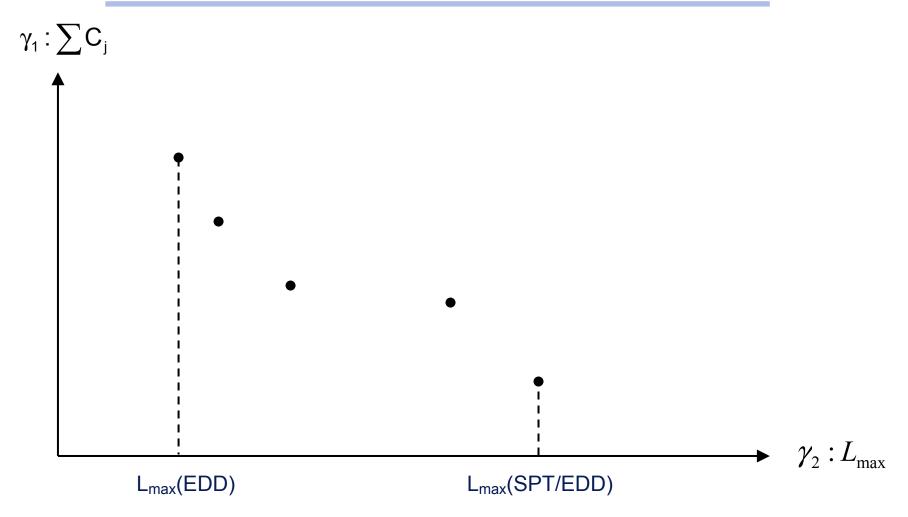
$$\Theta_1 \to 1$$
 and $\Theta_2 \to 0$

$$\rightarrow$$
 1 | β | $\Theta_1 \gamma_1 + \Theta_2 \gamma_2 \rightarrow 1$ | β | γ_1 (opt), γ_2



Pareto-Optimal Schedule (2)





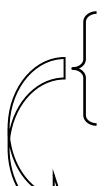


Pareto-Optimal Solutions (1)



Generation of all pareto-optimal solutions

Find a new pareto-optimal solution:



Determine the optimal schedule for L_{max} .

Determine the minimum increment of L_{max} to decrease the minimum Σ C_i .

Similar to the minimization of the total weighted completion time with deadlines

Start with the EDD schedule, end with the SPT/EDD schedule.



Pareto-Optimal Solutions (2)



Set
$$r = 1$$

Set
$$L_{max} = L_{max}(EDD)$$
 and $\overline{d}_j = d_j + L_{max}$.

Set
$$k = n$$
 and $J^c = \{1, ..., n\}$.

Set
$$\tau = \sum_{j=1}^{n} p_j$$
 and $\delta = \tau$.

Step 3

Find j* in J^c such that

$$d_{i^*} \ge \tau$$
 , and

$$p_{i^*} \ge p_i$$
 for all jobs in J^c such that $\overline{d}_i \ge \tau$.

Put job j* in position k of the sequence.

Step 4

If there is no job I such that $d_I < \tau \ \ \text{and} \ \ p_I > p_{j^*}$, go to Step 5.

Otherwise find j** such that

$$\tau - \overline{d}_{j^{**}} = \min_{l} (\tau - \overline{d}_{l})$$

for all I such that $d_I < \tau$ and $p_I > p_{I^*}$.

Set
$$\delta^{**} = \tau - d_{j^{**}}$$
.

If
$$\delta^{**} < \delta$$
 , then $\delta = \delta^{**}$.



Pareto-Optimal Solutions (3)



Step 5 Decrease k by I.

Decrease τ by p_{i^*} .

Delete job j* from J^{c.}

If $k \ge 1$ go to Step 3,

otherwise go to Step 6.

Step 6 Set $L_{max} = L_{max} + \delta$.

If $L_{max} > L_{max}(SPT/EDD)$, then STOP.

Otherwise set r = r + 1, $d_j = d_j + \delta$, and go to Step 2.

Maximum number of pareto – optimal points

$$\rightarrow$$
 n(n - 1)/2 = O(n²)

Complexity to determine one pareto – optimal schedule

- → O(n log(n))
- → Total complexity O(n³ log(n))



Pareto-Optimal Solutions (4)



jobs	1	2	3	4	5
pj	1	3	6	7	9
d _j	30	27	20	15	12

EDD sequence

$$5,4,3,2,1 \Rightarrow L_{max} (EDD) = 2$$

 $c_3 = 22$ $d_3 = 20$

SPT/EDD sequence

$$1,2,3,4,5 \Rightarrow L_{max} (SPT/EDD) = 14$$

 $c_5 = 26$ $d_5 = 12$



Pareto-Optimal Solutions (5)



Iteration r	$(\Sigma C_j, L_{max})$	Pareto – optimal schedule	current τ + δ	δ
1	96, 2	5,4,3,1,2	32 26 22 17 14	1
2	77, 3	1,5,4,3,2	33 30 23 18 15	2
3	75, 5	1,4,5,3,2	35 32 25 20 17	1
4	64, 6	1,2,5,4,3	36 33 26 21 18	2
5	62, 8	1,2,4,5,3	38 35 28 23 20	3
6	60, 11	1,2,3,5,4	41 38 31 26 23	3
7	58, 14	1,2,3,4,5	44 41 34 29 26	Stop

- 1 || Θ₁ ∑w_j C_j + Θ₂ L_{max} Extreme points (WSPT/EDD and EDD) can be determined in polynomial time.
 - → The problem with arbitrary weights Θ_1 and Θ_2 is NP hard.



Parallel Machine Models



- A scheduling problem for parallel machines consists of 2 steps:
 - → Allocation of jobs to machines
 - → Generating a sequence of the jobs on a machine
- A minimal makespan represents a balanced load on the machines.
- Preemption may improve a schedule even if all jobs are released at the same time.
- Most optimal schedules for parallel machines are nondelay.
 - \rightarrow Exception: $R_m \parallel \sum C_i$
- General assumption for all problems: $p_1 \ge p_2 \ge ... \ge p_n$



$P_m \parallel C_{max}$



The problem is NP-hard.

→ P₂ || C_{max} is equivalent to Partition.

Heuristic algorithm: Longest processing time first (LPT) rule Whenever a machine is free, the longest job among those not yet processed is put on this machine.

→ Upper bound:
$$\frac{C_{\text{max}}(LPT)}{C_{\text{max}}(OPT)} \le \frac{4}{3} - \frac{1}{3m}$$

 \rightarrow The optimal schedule $C_{max}(OPT)$ is not necessarily known but the following bound holds:

$$C_{\text{max}}(OPT) \ge \frac{1}{m} \sum_{j=1}^{n} p_j$$



Proof of the Bound (1)



- If the claim is not true, then there is a counterexample with the smallest number n of jobs.
- The shortest job *n* in this counterexample is the last job to start processing (LPT) and the last job to finish processing.
 - \rightarrow If *n* is not the last job to finish processing, then deletion of *n* does not change C_{max} (LPT) while C_{max} (OPT) cannot increase.
 - \rightarrow A counter example with n-1 jobs
- Under LPT, job n starts at time $C_{max}(LPT)-p_n$.
 - → In time interval $[0, C_{max}(LPT) p_n]$, all machines are busy.

$$C_{\max}(LPT) - p_n \le \frac{1}{m} \sum_{j=1}^{n-1} p_j$$



Proof of the Bound (2)



$$C_{\text{max}}(LPT) \le p_n + \frac{1}{m} \sum_{j=1}^{n-1} p_j = p_n (1 - \frac{1}{m}) + \frac{1}{m} \sum_{j=1}^{n} p_j$$

$$\frac{4}{3} - \frac{1}{3m} < \frac{C_{\max}(LPT)}{C_{\max}(OPT)} \le \frac{p_n(1 - 1/m)}{C_{\max}(OPT)} + \frac{\sum_{j=1}^n p_j/m}{C_{\max}(OPT)} \le \frac{p_n(1 - 1/m)}{C_{\max}(OPT)} + 1$$

$$C_{\text{max}}(OPT) < 3p_n$$

At most two jobs are scheduled on each machine. For such a problem, LPT is optimal.



A Worst Case Example for LPT



jobs	1	2	3	4	5	6	7	8	9
pj	7	7	6	6	5	5	4	4	4

- 4 parallel machines
- $C_{max}(OPT) = 12 = 7+5 = 6+6 = 4+4+4$
- $C_{\text{max}}(LPT) = 15 = (4/3 1/(3.4)) \cdot 12$

7	4	4
7	4	
6	5]
6	5	-]



Other Makespan Results



- Arbitrary nondelay schedule $\frac{C_{max} (LIST)}{C_{max} (OPT)} \le 2 \frac{1}{m}$
- P_m | prec | C_{max} with $2 \le m < \infty$ is strongly NP hard even for chains.
- Special case m ≥ n: p_∞ | prec | C_{max}
- a) Start all jobs without predecessor at time 0.
- b) Whenever a job finishes, immediately start all its successors for which all predecessors have been completed.
 - Critical Path Method (CPM)
 - Project Evaluation and Review Technique (PERT)



Heuristics Algorithms



- Critical Path (CP) rule
 - → The job at the head of the longest string of jobs in the precedence constraints graph has the highest priority.
 - \rightarrow P_m | p_i = 1, tree | C_{max} is solvable with the CP rule.
- Largest Number of Successors first (LNS)
 - → The job with the largest total number of successors in the precedence constraints graph has the highest priority.
 - → For intrees and chains, LNS is identical to the CP rule
 - → LNS is also optimal for $P_m | p_j = 1$, outtree $| C_{max}$.
- Generalization for problems with arbitrary processing times
 - → Use of the total amount of processing remaining to be done on the jobs in question.



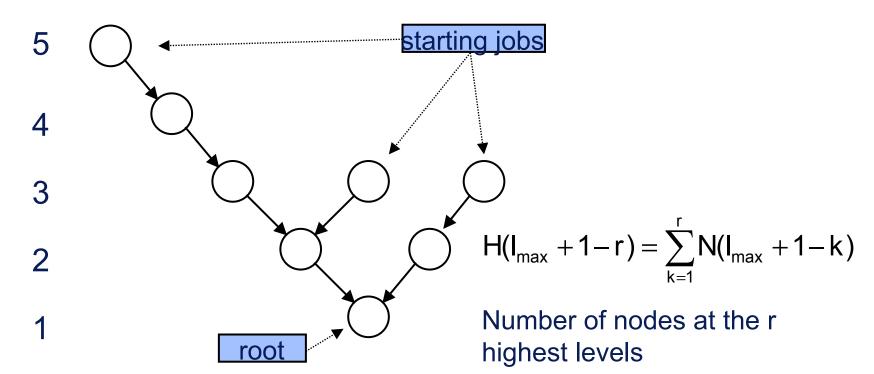
$P_m \mid p_j = 1$, tree $\mid C_{max} \mid$



Level

highest level I_{max}

N(I) number of jobs at level I



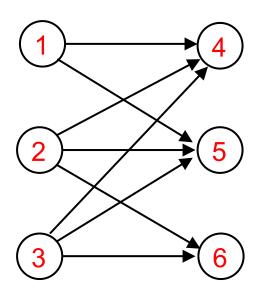


CP for $P_2|p_j=1$, $prec|C_{max}$



$$\frac{C_{\max}(CPM)}{C_{\max}(OPT)} \le \frac{4}{3}$$

for two machines



almost fully connected bipartite graph

1

1

5

2

1

5

2

(2)

(3)

(4)

 $\left(6\right)$

(3)

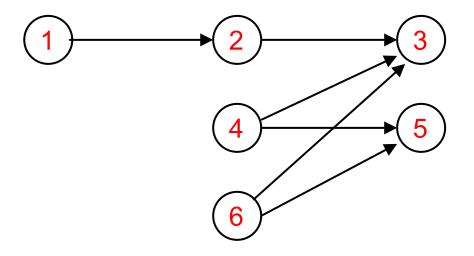
6

 $\overline{4}$



LNS for $P_2|p_j=1$, prec $|C_{max}|$





1

4

 $\left(\mathbf{1}\right)$

2

3)

(1)

2

(3)

2

 $\left(\mathbf{6}\right)$

(5

<u>(4</u>

 $\left(\mathbf{6}\right)$

5

$P_{m} | p_{j} = 1, M_{j} | C_{max}(1)$



A job can only be processed on subset M_i of the m parallel machines.

Here, the sets M_i are nested.

→ Exactly 1 of 4 conditions is valid for jobs j and k.

 \rightarrow M_i is equal to M_k $(M_i=M_k)$

 \rightarrow M_i is a subset of M_k $(M_i \subset M_k)$

 \rightarrow M_k is a subset of M_i $(M_i \supset M_k)$

 \rightarrow M_i and M_k do not overlap. $(M_i \cap M_k = \emptyset)$

Every time a machine is freed, the job is selected that can be processed on the smallest number of machines.

- → Least Flexible Job first (LFJ) rule
- → LFJ is optimal for $P_2 \mid p_j = 1$, $M_j \mid C_{max}$ and for $P_m \mid p_j = 1$, $M_j \mid C_{max}$ when the M_j sets are nested (pairwise exchange).

$P_{m} | p_{j} = 1, M_{j} | C_{max}(2)$



• Consider $P_4 \mid p_j = 1$, $M_j \mid C_{max}$ with eight jobs. The eight M_j sets are:

$$\rightarrow$$
 M₁ = {1,2}

$$\rightarrow$$
 M₂ = M₃ = {1,3,4}

$$\rightarrow M_{4} = \{2\}$$

$$\rightarrow$$
 $M_5 = M_6 = M_7 = M_8 = \{3,4\}$

Machines	1	2	3	4
LFJ	1	4	5	6
	2		7	8
	3			
optimal	2	1	5	7
-	3	4	6	8

LFM (Least Flexible Machine) and LFM-LFJ do not guarantee optimality for this example either.

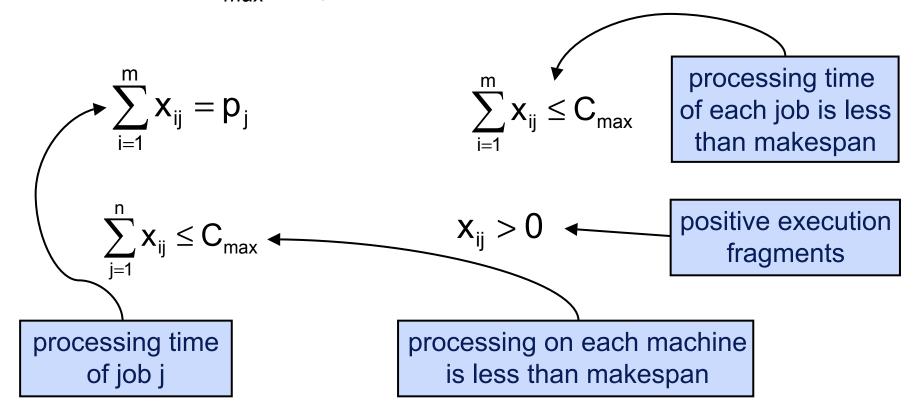


Makespan with Preemptions (1)



Linear programming formulation for P_m | prmp | C_{max} The variable x_{ii} represents the total time job j spends on machine i.

Minimize C_{max} subject to





Makespan with Preemptions (2)



- The solution of a linear program yields the processing of each job on each machine.
 - → A schedule must be generated in addition.
- Lower bound: $C_{\text{max}} \ge \max \left\{ p_1, \sum_{j=1}^n p_j / m \right\} = C *_{\text{max}}$

Algorithm Minimizing Makespan with Preemptions

- Nondelay processing of all jobs on a single machine without preemption ⇒ makespan ≤ m • C*_{max}
- 2. Cutting of this schedule into m parts
- 3. Execution of each part on a different machine



LRPT Rule



Longest Remaining Processing Time first (LRPT)

- → Preemptive version of Longest Processing Time first (LPT)
- → This method may generate an infinite number of preemptions.

Example: 2 jobs with $p_1 = p_2 = 1$ and 1 machine

The algorithm uses the time period ε .

 \rightarrow Time ε after the previous decision the situation is evaluated again.

The makespan of the schedule is 2 while the total completion time is $4 - \epsilon$.

→ The optimal (non preemptive) total completion time is 3.

The following proofs are based on a discrete time framework.

→ Machines are only preempted at integer times.



Vector Majorization



Vector of remaining processing times at time t $(p_1(t), p_2(t), \dots, p_n(t)) = p(t)$.

A vector $\overline{p}(t)$ majorizes a vector $\overline{q}(t)$, $\overline{p}(t) \ge_m \overline{q}(t)$, if

$$\sum_{j=1}^{k} p_{(j)}(t) \ge \sum_{j=1}^{k} q_{(j)}(t) \text{ holds for all } k = 1, ..., n.$$

 $p_i(t)$ is the jth largest element of p(t).

Example

Consider the two vectors $\overline{p}(t) = (4, 8, 2, 4)$ and $\overline{q}(t) = (3, 0, 6, 6)$.

Rearranging the elements within each vector and putting these in decreasing order results in vectors (8, 4, 4, 2) and (6, 6, 3, 0).

It can be easily verified that $p(t) \ge_m q(t)$.



LRPT Property



If $p(t) \ge_m q(t)$ then LRPT applied to p(t) results in a larger or equal makespan than obtained by applying LRPT to q(t).

Induction hypothesis: The lemma holds for all pairs of vectors with total remaining processing time less than or equal to $\sum_{j=1}^{n} p_j(t) - 1$ and $\sum_{j=1}^{n} q_j(t) - 1$, respectively.

Induction base: Vectors 1, 0, ..., 0 and 1, 0, ... 0.

After LRPT is applied for one time unit on p(t) and q(t), respectively, then we obtain at time t+1 the vectors p(t+1) and q(t+1) with

$$\sum_{j=1}^{n} p_{j}(t+1) \leq \sum_{j=1}^{n} p_{j}(t) - 1 \text{ and } \sum_{j=1}^{n} q_{j}(t+1) \leq \sum_{j=1}^{n} q_{j}(t) - 1.$$

If $\overline{p}(t) \ge_m \overline{q}(t)$, then $\overline{p}(t+1) \ge_m \overline{q}(t+1)$.



Result of the LRPT Rule



LPRT yields an optimal schedule for $P_m \mid prmp \mid C_{max}$ in discrete time.

We consider only problems with more than m jobs remaining to be processed.

Induction hypothesis: The lemma holds for any vector p(t) with $\sum_{j=1}^{n} p_{j}(t) \le N-1$.

We consider a vector $\mathbf{p}(t)$ with $\sum_{j=1}^{n} p_{j}(t) = N$.

If LRPT is not optimal <u>for</u> p(t), then another rule R must be optimal. R produces vector q(t+1) with $q(t+1) \ge_m p(t+1)$.

From time t+1 on, R uses LRPT as well due to our induction hypothesis.

Due to the LRPT property, R cannot produce a smaller makespan than LRPT.



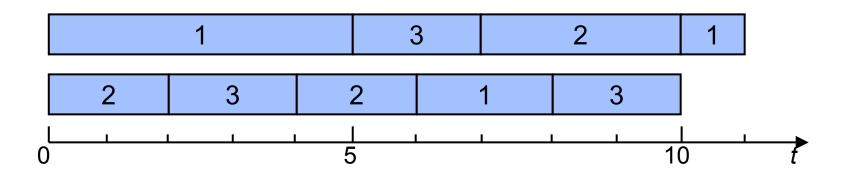
LRPT in Discrete Time



Consider two machines and three jobs 1, 2 and 3, with processing times 8, 7, and 6.

$$C_{max}(LRPT)=C_{max}(OPT)=11.$$

Remember: Ties are broken arbitrarily!





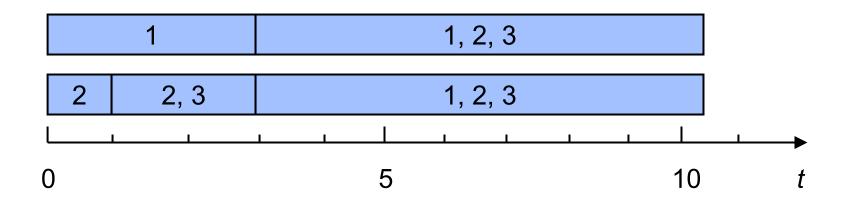
LRPT in Continuous Time



Consider the same jobs as in the previous example.
As preemptions may be done at any point in time, processor sharing takes place.

$$C_{\text{max}}(LRPT)=C_{\text{max}}(OPT)=10.5.$$

To prove that LRPT is optimal in continuous time, multiply all processing times by a very large integer K and let K go to ∞.





Lower Bound for Uniform Machines



$$Q_m \mid prmp \mid C_{max}$$

note n!

$$C_{\max} \ge \max \left(\frac{p_1}{v_1}, \frac{p_1 + p_2}{v_1 + v_2}, \frac{\sum_{j=1}^{m-1} p_j}{\sum_{j=1}^{m-1} v_j}, \frac{\sum_{j=1}^{n} p_j}{\sum_{j=1}^{m} v_j} \right) \quad \text{for } v_1 \ge v_2 \ge ... \ge v_m$$

Comparison:
$$P_{m} \mid prmp \mid C_{max}$$
 $C_{max} \ge max \left\{ p_{1}, \sum_{j=1}^{n} p_{j} / m \right\}$



LRPT-FM



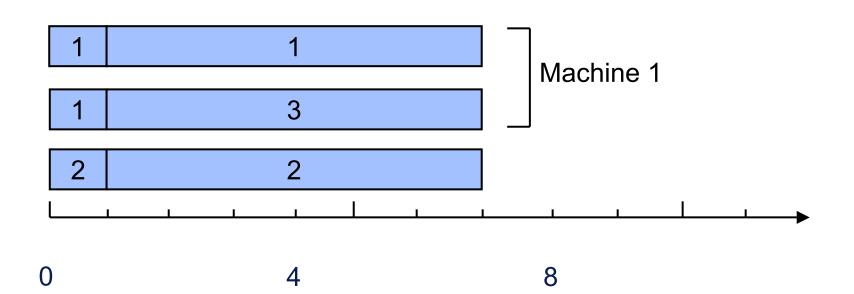
- Longest Remaining Processing Time on the Fastest
 Machine first (LRPT FM) yields an optimal schedule with infinitely many preemptions for Q_m | prmp | C_{max} :
 - → At any point in time the job with the largest remaining processing time is assigned to the fastest machine.
- Proof for a discrete framework with respect to speed and time
 - → Replace machine j by v_i machines of unit speed.
 - → A job can be processed on more than one machine in parallel, if the machines are derived from the same machine.
- Continuous time:
 - → All processing times are multiplied by a large number K.
 - → The speeds of the machines are multiplied by a large number V.
- The LRPT-FM rule also yields optimal schedules if applied to Q_m | r_i, prmp | C_{max}.



Application of LRPT-FM



- 2 machines with speed $v_1 = 2$, $v_2 = 1$
- 3 jobs with processing times 8, 7, and 6





$\sum C_i$ without Preemptions (1)



Different argument for SPT for total completion time without preemptions on a single machine

p_(i): processing time of the job in position j on the machine

$$\sum C_{j} = n \cdot p_{(1)} + (n-1) \cdot p_{(2)} + \dots + 2 \cdot p_{(n-1)} + p_{(n)}$$

 $p_{(1)} \le p_{(2)} \le p_{(3)} \le \dots \le p_{(n-1)} \le p_{(n)}$ must hold for an optimal schedule.



$\sum C_i$ without Preemptions (2)



SPT rule is optimal for $P_m \parallel \sum C_j$

- The proof is based on the same argument as for single machines.
- Jobs with processing time 0 are added until n is a multiple of m.
 - → The sum of the completion time has n additive terms with one coefficient each:

m coefficients with value n/m m coefficients with value n/m - 1

•

m coefficients with value 1

The SPT schedule is not the only optimal schedule.



∑w_iC_i without Preemptions



jobs	1	2	3
p _j	1	1	3
Wj	1	1	3

- 2 machines and 3 jobs
- With the given values any schedule is WSPT.
- If w₁ and w₂ are reduced by ε
 - → WSPT is not necessarily optimal.
- Tight approximation factor

$$\frac{\sum_{j} w_{j} C_{j}(WSPT)}{\sum_{j} w_{j} C_{j}(OPT)} \leq \frac{1}{2} (1 + \sqrt{2})$$

 \blacksquare $P_m || \sum w_j C_j$ is NP hard.



$P_{m} \mid prec \mid \sum C_{j}$



- \blacksquare P_m | prec | Σ C_i is strongly NP-hard.
- The CP rule is optimal for $P_m | p_j = 1$, outtree $| \sum C_j$.
 - → The rule is valid if at most m jobs are schedulable.
 - → t₁ is the last time the CP rule is not applied but rule R.
 - String 1 is the longest string not assigned at t₁
 - String 2 is the shortest string assigned at t₁
 - C₁' is the completion time of the last job of string 1 under R
 - C₂' is the completion time of the last job of string 2 under R
 - If C₁'≥C₂'+1 and machines are idle before C₁' 1, then CP is better than R, otherwise CP is as good as R.
- However, the CP rule is not always optimal for intrees.



Other ∑C_j Problems



- The LFJ rule is optimal for $P_m|p_i=1,M_i|\sum C_i$ when the M_i sets are nested.
- The $R_m||\sum C_i$ problem can be formulated as an integer program
 - → Although linear integer programming is NP-hard this program has a special structure that allows a solution in polynomial time.
 - → x_{iki}=1 if job j is scheduled as the kth to last job on machine i.
 - x_{iki} are 0-1 integer variables.

Minimize
$$\sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{n} k p_{ij} x_{ikj}$$
 subject to
$$\sum_{i=1}^{m} \sum_{k=1}^{n} x_{ikj} = 1 \qquad j = 1, ..., n$$

$$\sum_{i=1}^{n} x_{ikj} \le 1 \qquad i = 1, ..., m \text{ and } k = 1, ..., n$$

$$x_{ikj} \in \{0,1\} \qquad i = 1, ..., m, k = 1, ..., n, and j = 1, ..., n$$

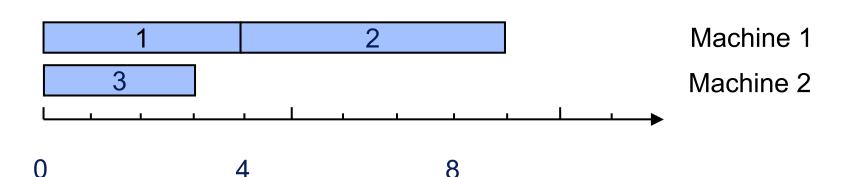


Example R_m||∑C_i



jobs	1	2	3
P _{1j}	4	5	3
p_{2j}	8	9	3

- 2 machines and 3 jobs
- The optimal solution corresponds to $x_{121}=x_{112}=x_{213}=1$. All other x_{iki} are 0. The optimal schedule is not nondelay.





$\sum C_j$ with Preemptions (1)



The nonpreemptive SPT rule is also optimal for $P_m|prmp|\sum C_j$.

 $Q_m|prmp|\sum C_j$ can be solved by the **Shortest Remaining Processing Time on the Fastest Machine** (SRPT-FM) rule.

- → Useful lemma: There is an optimal schedule with $C_j \le C_k$ when $p_j \le p_k$ for all j and k. (Proof by pairwise exchange)
- → Under SRPT-FM, we have $C_n \le C_{n-1} \le ... \le C_1$.
- → Assumption: There are n machines.
 - If there are more jobs than machines, then machines with speed 0 are added.
 - If there are more machines than jobs, then the slowest machines are not used.



$\sum C_i$ with Preemptions (2)



$$\begin{aligned} v_1 C_n &= p_n \\ v_2 C_n + v_1 (C_{n-1} - C_n) &= p_{n-1} \\ v_3 C_n + v_2 (C_{n-1} - C_n) + v_1 (C_{n-2} - C_{n-1}) &= p_{n-2} \\ &\vdots \\ v_n C_n + v_{n-1} (C_{n-1} - C_n) + v_1 (C_1 - C_2) &= p_1 \end{aligned}$$

Adding these equations yields

$$\begin{aligned} v_1 C_n &= p_n \\ v_2 C_n + v_1 C_{n-1} &= p_n + p_{n-1} \\ v_3 C_n + v_2 C_{n-1} + v_1 C_{n-2} &= p_n + p_{n-1} + p_{n-2} \\ &\vdots \\ v_n C_n + v_{n-1} C_{n-1} + \dots + v_1 C_1 &= p_n + p_{n-1} + \dots + p_1 \end{aligned}$$



$\sum C_i$ with Preemptions (3)



Let S' be an optimal schedule with $C'_n \le C'_{n-1} \le ... \le C'_1$ (see the lemma). Then we have $C'_n \ge p_n/v_1 \implies v_1C'_n \ge p_n$.

The amount of processing on jobs n and n –1 is upper bounded by

$$\leq (v_1 + v_2)C'_n + v_1(C'_{n-1} - C'_n). \Rightarrow v_2C'_n + v_1C'_{n-1} \geq p_n + p_{n-1}$$

Similarly, we obtain

$$v_kC'_n + v_{k-1}C'_{n-1} + ... + v_1C'_{n-k+1} \ge p_n + p_{n-1} + ... + p_{n-k+1}$$

This yields

$$\begin{split} v_1 C'_n &\geq v_1 C_n \\ v_2 C'_n + v_1 C'_{n-1} &\geq v_2 C_n + v_1 C_{n-1} \\ &\vdots \\ v_n C'_n + v_{n-1} C'_{n-1} + \ldots + v_1 C'_1 &\geq v_n C_n + v_{n-1} C_{n-1} + \ldots + v_1 C_1 \end{split}$$



$\sum C_i$ with Preemptions (4)



We want to transform this system of inequalities into a new system such that

- \rightarrow inequality i is multiplied by $\alpha_i \ge 0$ and
- → the sum of all those transformed inequalities yields $\sum C_i \ge \sum C_i$.
- \rightarrow The proof is complete, if those α_i exists.
- $\rightarrow \alpha_i$ must satisfy

$$v_{1}\alpha_{1} + v_{2}\alpha_{2} + ... + v_{n}\alpha_{n} = 1$$
 $v_{1}\alpha_{2} + v_{2}\alpha_{3} + ... + v_{n-1}\alpha_{n} = 1$
 \vdots
 $v_{1}\alpha_{n} = 1$

Those α_i exists as $v_1 \ge v_2 \ge ... \ge v_n$ holds.

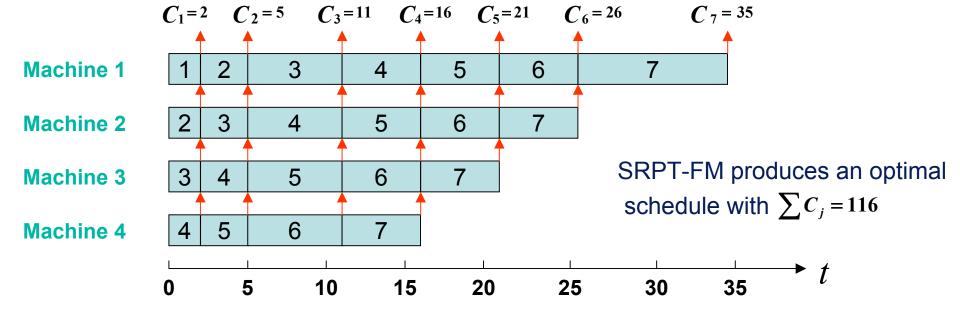


Application of the SRPT-FM Rule



	ma	chines	1	2	3	4	
		\mathbf{V}_i	4	2	2	1	
jobs	1	2	3	4	5	6	7
p_i	8	16	34	40	45	46	61

Preemptions are only allowed at integer points in time.





Due – Date Related Objectives



$$P_m \parallel C_{max} \sim P_m \parallel L_{max}$$
 (all due dates 0)

→ The problem is NP-hard.

 $Q_m \mid prmp \mid L_{max}$

Assume $L_{max} = z$

- \rightarrow $C_j \le d_j + z$
- \rightarrow set $d_j = d_i + z$ (hard deadline)
- → Hard deadlines are release dates in the reversed problem.
- → Finding a schedule for this problem is equivalent to solving Q_m | r_j, prmp | C_{max}
- → If all jobs in the reverse problem "finish" at a time not smaller than 0, then there exists a schedule for Q_m | prmp | L_{max} with $L_{max} \le z$.
- → The minimum value for z can be found by a simple search.



Example P2 | prmp | L_{max}



jobs	1	2	3	4
d _j	4	5	8	9
p _j	3	3	3	8

Is there a feasible schedule with $L_{max} = 0$? $(\overline{d}_j = d_j)$

jobs	1	2	3	4
r _j	5	4	1	0
p _j	3	3	3	8

Is there a feasible schedule with $C_{max} \le 9$?



Flow Shops



- Each job must follow the same route.
 - → There is a sequence of machines.
- There may be limited buffer space between neighboring machines.
 - → The job must sometimes remain in the previous machine: Blocking.
- The main objective in flow shop scheduling is the makespan.
 - → It is related to utilization of the machines.
- If the First-come-first-served principle is in effect, then jobs cannot pass each other.
 - Permutation flow shop



Unlimited Intermediate Storage



Permutation Schedule $j_1, j_2, ..., j_n$

$$C_{i,j_1} = \sum_{l=1}^{i} p_{l,j_1} \qquad i = 1, \dots, m$$

$$C_{1,j_k} = \sum_{l=1}^{k} p_{1,j_l} \qquad k = 1, \dots, n$$

$$C_{i,j_k} = \max(C_{i-1,j_k}, C_{i,j_{k-1}}) + p_{i,j_k}$$

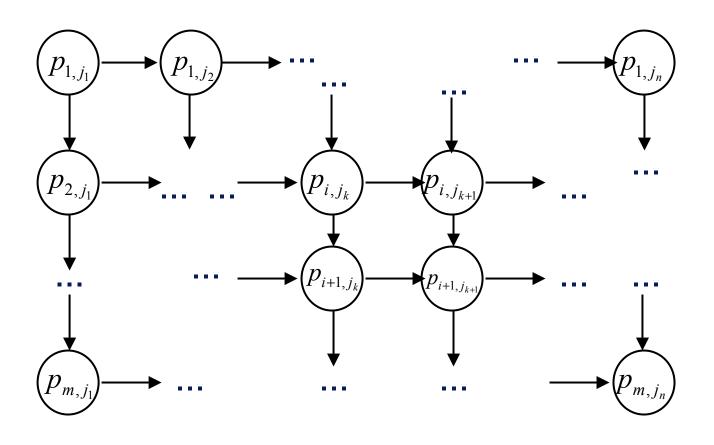
$$i = 2, \dots, m \qquad k = 2, \dots, n$$

- There is always an optimal schedule without job sequence changes in the first two and last two machines.
 - → F2|| C_{max} and F3|| C_{max} do not require a job sequence change in some optimal schedule.



Directed Graph for F_m|prmu|C_{max}







Example F4|prmu|C_{max}



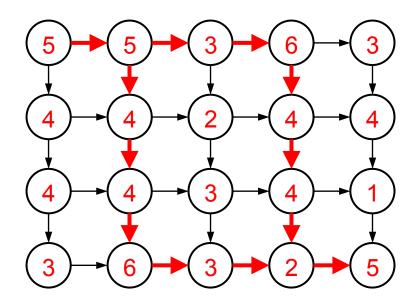
5 jobs on 4 machines with the following processing times

jobs	j ₁	j ₂	j ₃	j ₄	j ₅
p_{1,j_k}	5	5	3	6	3
p_{2,j_k}	4	4	2	4	4
p_{3,j_k}	4	4	3	4	1
p_{4,j_k}	3	6	3	2	5



Directed Graph in the Example



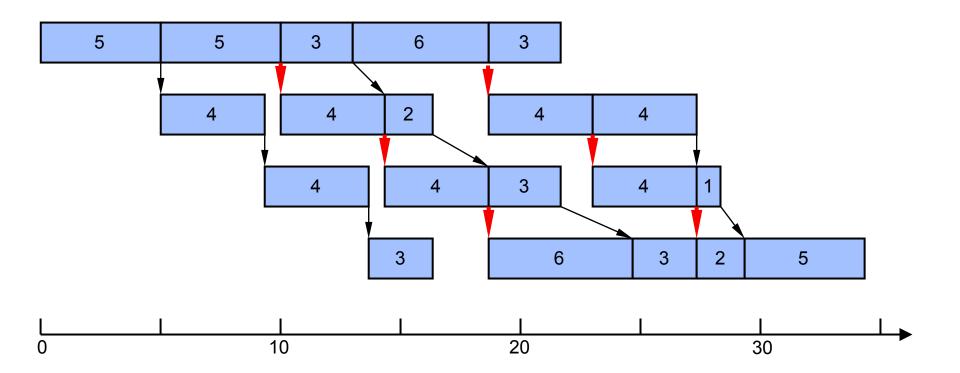


Critical path



Gantt Chart in the Example







Reversibility



Two *m* machine permutation flow shops with *n* jobs are considered with $p_{ii}^{(1)} = p^{(2)}_{m+1-i,i}$.

→ p_{ij}⁽¹⁾ and p_{ij}⁽²⁾ denote the processing times of job j in the first and the second flow shop, respectively.

Sequencing the jobs according to permutation $j_1, ..., j_n$ in the first flow shop produces the same makespan as permutation $j_n, ..., j_1$ in the second flow shop.

→ The makespan does not change if the jobs traverse the flow shop in the opposite direction in reverse order (**Reversibility**).



Example Reversibility (1)



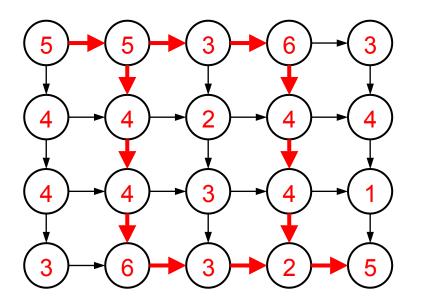
5 jobs on 4 machines with the following processing times (original processing times in parentheses)

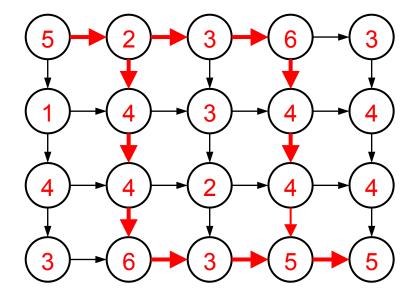
jobs	j ₁	j ₂	j ₃	j ₄	j ₅
p_{1,j_k}	3 (5)	6 (5)	3 (3)	2 (6)	5 (3)
p_{2,j_k}	4 (4)	4 (4)	3 (2)	4 (4)	1 (4)
p_{3,j_k}	4 (4)	4 (4)	2 (3)	4 (4)	4 (1)
p_{4,j_k}	5 (3)	5 (6)	3 (3)	6 (2)	3 (5)



Example Reversibility (2)







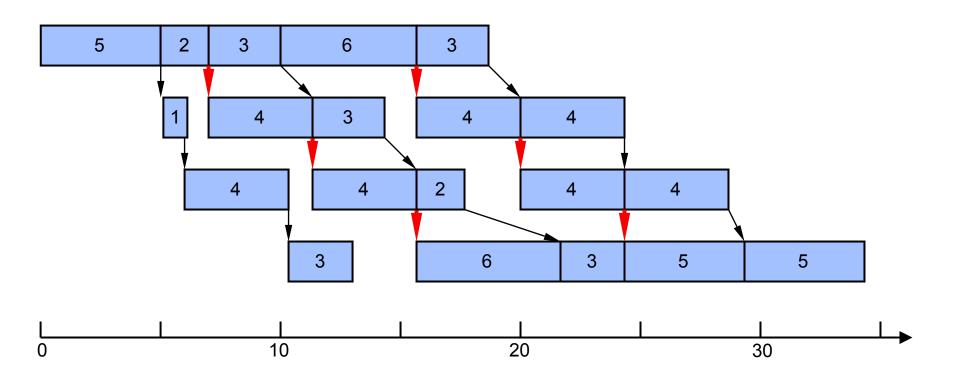
Original problem

Reverse problem



Example Reversibility (3)







F2||C_{max}



F2||C_{max} with unlimited storage in between the two machines

- → The optimal solution is always a permutation.
- Johnson's rule produces an optimal schedule.
 - The job set is partitioned into 2 sets.

Set I : all jobs with $p_{1i} \le p_{2i}$

Set II : all jobs with $p_{2i} < p_{1i}$

SPT (1) – LPT(2) schedule:

- → All jobs of Set I are scheduled first in increasing order of p_{1i} (SPT).
- → All jobs of Set II are scheduled afterwards in decreasing order of p_{2j} (LPT).
- There are many other optimal schedules besides SPT(1) – LPT(2) schedules.
 - → The SPT(1)-LPT(2) schedule structure cannot be generalized to yield optimal schedules for flow shops with more than two machines.



Proof of Johnson's Rule (1)



Contradiction: Assume that another schedule S is optimal.

- → There is a pair of adjacent jobs j followed by k such that one of the following conditions hold:
 - Job j belongs to Set II and job k to Set I; (Case 1)
 - Jobs j and k belong to Set I and p_{1i}>p_{1k}; (Case 2)
 - Jobs j and k belong to Set II and p_{2i}<p_{2k}; (Case 3)
- Sequence in schedule S: job $l \Rightarrow$ job $j \Rightarrow$ job $k \Rightarrow$ job $h \Rightarrow$

 C_{ii} : completion time of job j on machine i in schedule S

 C'_{ij} : completion time of job j on machine i in the new schedule.



Proof of Johnson's Rule (2)



- Interchange of j and k
 - → Starting time (C₁₁ + p_{1j} + p_{1k}) of job h on machine 1 is not affected Starting time of job h on machine 2:

$$\begin{split} C_{2k} &= \max \; (\; \max \; (\; C_{2l}, \; C_{1l} + p_{1j}) + p_{2j}, \; C_{1l} + p_{1j} + p_{1k}) + p_{2k} \\ &= \max \; (\; C_{2l} + p_{2j} + p_{2k}, \; C_{1l} + p_{1j} + p_{2j} + p_{2k}, \; C_{1l} + p_{1j} + p_{1k} + p_{2k}) \\ C'_{2j} &= \max \; (C_{2l} + p_{2k} + p_{2j}, \; C_{1l} + p_{1k} + p_{2k} + p_{2j}, \; C_{1l} + p_{1k} + p_{1j} + p_{2j}) \end{split}$$

- Case 1 : $p_{1j} > p_{2j}$ and $p_{1k} \le p_{2k}$
 - $ightharpoonup C_{11} + p_{1k} + p_{2k} + p_{2j} < C_{11} + p_{1j} + p_{1k} + p_{2k}$ $C_{11} + p_{1k} + p_{1j} + p_{2j} \le C_{11} + p_{1j} + p_{2j} + p_{2k}$
 - \rightarrow C'_{2j} \leq C_{2k}
- Case 2: $p_{1j} \le p_{2j}$, $p_{1k} \le p_{2k}$, and $p_{1j} > p_{1k}$

$$C_{1l} + p_{1k} + p_{2k} + p_{2j}$$

$$C_{1l} + p_{1k} + p_{1j} + p_{2j}$$

$$\leq C_{1l} + p_{1j} + p_{2j} + p_{2k}$$

Case 3 is similar to Case 2 (reversibility property).



$F_m \mid prmu \mid C_{max}$



Formulation as a Mixed Integer Program (MIP)

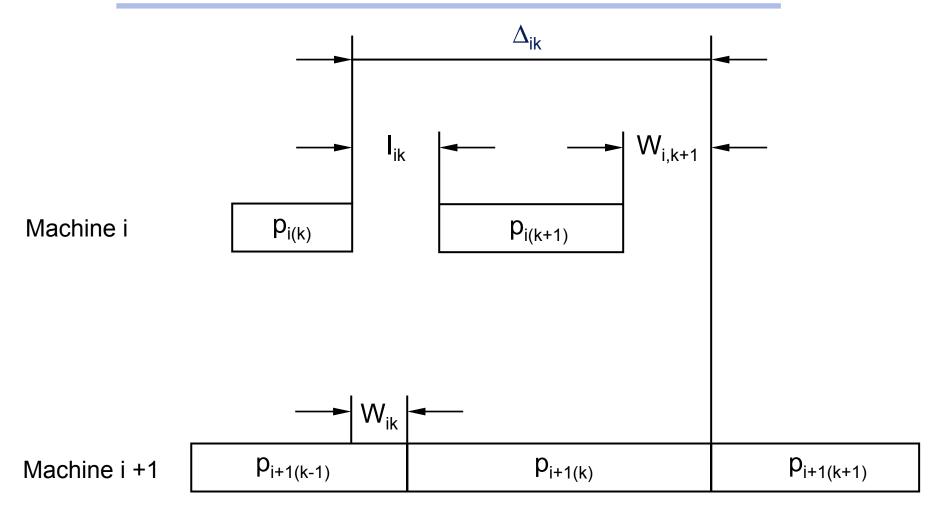
- Decision variable $x_{ik} = 1$, if job j is the k^{th} job in the sequence.
- I_{ik}: amount of idle time on machine i between the processing of jobs in position k and k+1
- W_{ik}: amount of waiting time of job in position k between machines i and i+1
- Δ_{ik} : difference between start time of the job in position k+1 on machine i+1 and completion time of the job in position k on machine i
- $\mathbf{p}_{i(k)}$: processing time of the job in position k on machine i

$$\rightarrow \Delta_{ik} = I_{ik} + p_{i(k+1)} + W_{i,k+1} = W_{ik} + p_{i+1(k)} + I_{i+1,k}$$



Graphical Description of Δ_{ik}





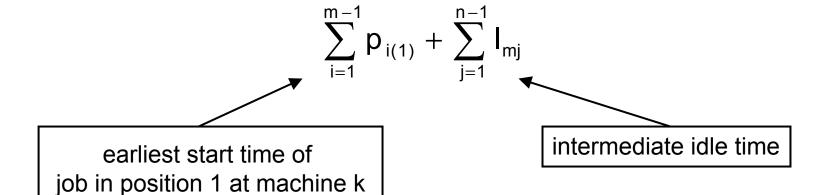
 $W_{ik} > 0$ and $I_{i+1, k} = 0$



MIP for F_m | prmu | $C_{max}(1)$



Minimizing the makespan \equiv Minimizing the idle time on machine m



- Remember: $p_{i(k)} = \sum_{j=1}^{n} x_{jk} p_{ij}$
 - → there is only one job at position k!



MIP for F_m | prmu | C_{max} (2)



$$\min\left(\sum_{i=1}^{m-1}\sum_{j=1}^{n}x_{j1}p_{ij}\right) + \sum_{j=1}^{n-1}I_{mj}$$

subject to

$$\sum_{j=1}^{n} x_{jk} = 1$$

$$\sum_{k=1}^{n} x_{jk} = 1$$

$$\sum_{jk}^{n} x_{jk} = 1$$

$$I_{ik} + \sum_{j=1}^{n} x_{j,k+1} p_{ij} + W_{i,k+1} - W_{ik} - \sum_{j=1}^{n} x_{jk} p_{i+1,j} - I_{i+1,k} = 0$$

$$W_{i1} = 0$$

$$x_{ik} \in \{0,1\}$$
 j=1, ...,n

$$I_{1k} = 0$$

$$k = 1, ..., n-1$$

$$W_{ik} \ge 0$$

$$i = 1, ..., m-1; k = 1, ..., n$$

$$I_{ik} \geq 0$$



F3||C_{max}



- F3 || C_{max} is strongly NP-hard.
 - → Proof by reduction from 3 Partition
- An optimal solution for F3 || C_{max} does not require sequence changes.
 - \rightarrow F_m | prmu | C_{max} is strongly NP hard.
- F_m | prmu, $p_{ij} = p_j | C_{max}$: proportionate permutation flow shop
 - → The processing of job j is the same on each machine.

$$\mathbf{C}_{\text{max}} = \sum_{j=1}^{n} p_j + (m-1) \max(p_1, ..., p_n)$$
 for

 F_m | prmu, $p_{ij} = p_j$ | C_{max} (independent of the sequence) This is also true for F_m | $p_{rj} = p_j$ | C_{max} .



Proportionate Flow Shop



Similarities between the single machine and the proportionate (permutation) flow shop environments

- 1. SPT is optimal for 1 || $\sum C_j$ and F_m | prmu, $p_{ij} = p_j \mid \sum C_j$.
- 2. The algorithms that produces and optimal schedule for 1 || $\sum U_j$ also results in an optimal schedule for F_m | prmu, $p_{ij} = p_j \mid \sum U_j$.
- 3. The algorithms that produces and optimal schedule for 1 || h_{max} also results in an optimal schedule for F_m | prmu, $p_{ij} = p_j$ | h_{max} .
- 4. The pseudo-polynomial dynamic programming algorithm 1 || $\sum T_j$ is also applicable to F_m | prmu, p_{ij} = p_i | $\sum T_j$.
- 5. The elimination criteria that hold for $1 || \sum w_j T$ also hold for $F_m || prmu, p_{ij} = p_j || \sum w_j T_j$.



Slope Heuristic



Slope index A_j for job j

$$A_{j} = -\sum_{i=1}^{m} (m - (2i - 1))p_{ij}$$

- Sequencing of jobs in decreasing order of the slope index
- Consider 5 jobs on 4 machines with the following processing times

jobs	j ₁	j ₂	j ₃	j ₄	j ₅
p_{1,j_k}	5	2	3	6	3
p_{2,j_k}	1	4	3	4	4
p_{3,j_k}	4	4	2	4	4
p_{4,j_k}	3	6	3	5	5

Sequences 2,5,3,1,4 and 5,2,3,1,4 are optimal and the makespan is 32.

$$A_1 = -(3 \times 5) - (1 \times 4) + (1 \times 4) + (3 \times 3) = -6$$

$$A_2 = -(3 \times 5) - (1 \times 4) + (1 \times 4) + (3 \times 6) = +3$$

$$A_3 = -(3 \times 3) - (1 \times 2) + (1 \times 3) + (3 \times 3) = +1$$

$$A_4 = -(3 \times 6) - (1 \times 4) + (1 \times 4) + (3 \times 2) = -12$$

$$A_5 = -(3 \times 3) - (1 \times 4) + (1 \times 1) + (3 \times 5) = +3$$