

The Monge Gap: A Regularizer to Learn All Transport Maps

<https://github.com/Sisha3342/MongeGap>

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1 Problem Statement

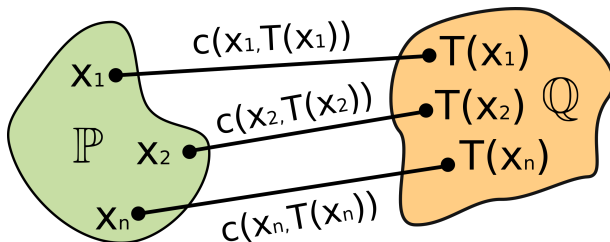
2 The Monge gap

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The Monge problem

$$W_c(\mathbb{P}, \mathbb{Q}) = \inf_{T \# \mathbb{P} = \mathbb{Q}} \int_{\Omega} c(\mathbf{x}, T(\mathbf{x})) d\mathbb{P}(\mathbf{x}).$$



Existing approaches

Recent papers consider maps $T = \nabla f_\theta$, where f_θ is an input convex neural network (ICNN), and fit θ with SGD using samples. Despite their mathematical elegance, fitting OT maps with ICNNs raises many challenges¹:

¹Alexander Korotin et al. “Do neural optimal transport solvers work? a continuous wasserstein-2 benchmark”. In: *Advances in Neural Information Processing Systems* 34 (2021), pp. 14593–14605.

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- Parameters initialization.

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- Some of their parameters must be non-negative.
- Parameters initialization.
- Min-max minimization problem.
- Relevance of the imposed constraints.

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Key contributions

A new paper proposes a radically different approach: the Monge gap², which introduces a regularizer to solve the OT problem. It has the following advantages:

²Théo Uscidda and Marco Cuturi. “The Monge Gap: A Regularizer to Learn All Transport Maps”. In: *arXiv preprint arXiv:2302.04953* (2023).

Key contributions

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- No architecture constraints.

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Key contributions

A new paper proposes a radically different approach: the Monge gap², which introduces a regularizer to solve the OT problem. It has the following advantages:

- Generalizes to arbitrary costs.
- No architecture constraints.
- Simple minimization algorithm.

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The Monge Gap

$$\mathcal{M}_\rho^c(T) = \int_{\Omega} c(\mathbf{x}, T(\mathbf{x})) d\rho(\mathbf{x}) - W_c(\rho, T\# \rho).$$

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Properties:

- For any vector field T , $\mathcal{M}_\rho^c(T) \geq 0$.

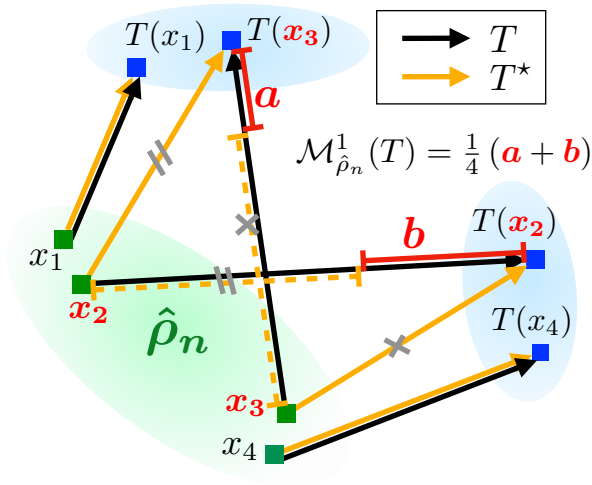
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$$\mathcal{M}_\rho^c(T) = \int_{\Omega} c(\mathbf{x}, T(\mathbf{x})) d\rho(\mathbf{x}) - W_c(\rho, T\#\rho).$$

Properties:

- For any vector field T , $\mathcal{M}_\rho^c(T) \geq 0$.
- T is a c -OT map between ρ and $T\#\rho \leftrightarrow \mathcal{M}_\rho^c(T) = 0$.

Geometrical intuition



Minimization problem: generic costs

We directly parametrize T as a neural network T_θ and solve the optimization problem:

Loss for generic costs

$$\min_{\theta} \mathcal{L}(\theta) = \Delta(T_\theta \# \mu, \nu) + \lambda_{\text{MG}} \mathcal{M}_\mu^c(T).$$

Minimization problem: structured costs

For structured costs, i.e., $c(\mathbf{x}, \mathbf{y}) = h(\mathbf{x} - \mathbf{y})$ with h being strictly convex, the proposed method can be modified.

OT map for structured costs

$$T_\theta : \mathbf{x} \mapsto \mathbf{x} - \nabla h^* \circ F_\theta(\mathbf{x}).$$

³Chen-Hao Chao et al. “Quasi-Conservative Score-based Generative Models”. In: *arXiv preprint arXiv:2209.12753* (2022).

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OT map for structured costs

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Because F_θ is a conservative vector field, we use an additional regularizer³ to point it and optimize the following loss:

Loss for structured costs

$$\min_{\theta} \mathcal{L}(\theta) = \Delta(T_{\theta\#}\mu, \nu) + \lambda_{\text{MG}} \mathcal{M}_{\rho}^c(T_{\theta}) + \lambda_{\text{cons}} \mathcal{C}_{\rho}(F_{\theta}).$$

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Wasserstein-2 benchmark

We use the Korotin et al. 2021 benchmark for pairs of gaussian mixtures μ, ν in dimension $d \in \{2, 4, \dots, 26\}$ for which the optimal map for the squared Euclidean cost is known. We report the next metrics:

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Unexplained variance percentage

$$\mathcal{L}_2^{\text{UV}}(\hat{T}) = 100 \cdot \frac{\mathbb{E}_{\mu} \left\| \hat{T}(X) - T^*(X) \right\|_2^2}{\text{Var}_{\nu}(X)}.$$

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The Sinkhorn divergence

$$S_{\ell_{2,\epsilon}^2}(\nu, \hat{T}_{\#}\mu) = W_{\ell_{2,\epsilon}^2}(\mu, \nu) - \frac{1}{2}(W_{\ell_{2,\epsilon}^2}(\mu, \mu) + W_{\ell_{2,\epsilon}^2}(\nu, \nu)).$$

Results

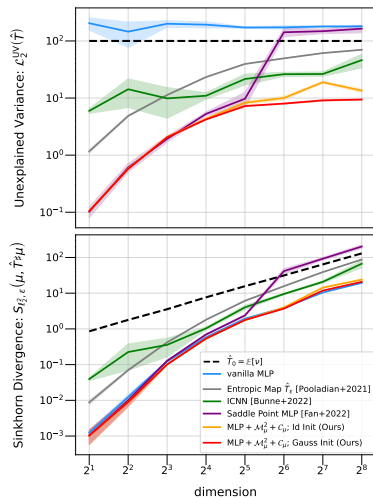


Figure: Reference

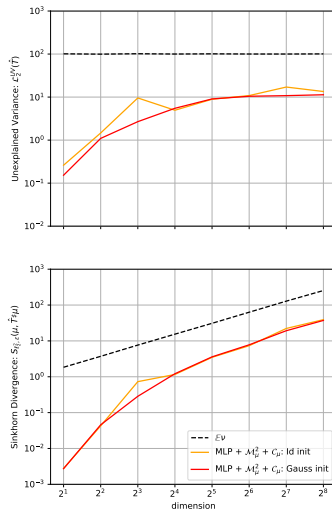
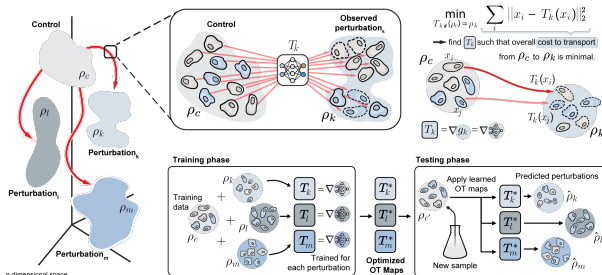


Figure: Replication

Single-cell genomics

Predicting the response of cells to a perturbation is a central question in biology. We predict responses of cells populations to cancer treatments using the proteomic dataset⁴. The dataset used can be accessed [here](#).



⁴Charlotte Bunne et al. "Learning Single-Cell Perturbation Responses using Neural Optimal Transport". In: *bioRxiv* (2021). DOI: 10.1101/2021.12.15.472775. eprint: <https://www.biorxiv.org/content/early/2021/12/15/2021.12.15.472775.full.pdf>. URL: <https://www.biorxiv.org/content/early/2021/12/15/2021.12.15.472775>.

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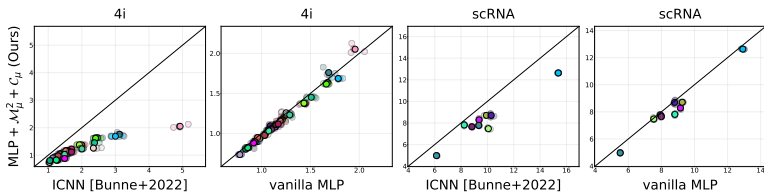


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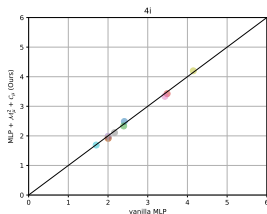


Figure: Replication

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- Studied the proposed regularization approach.
- Implemented regularizers/models and assessed their performance on selected tasks.
- Got quite close results for the \mathcal{L}_2^{UV} , while the replication's $S_{\ell_2, \epsilon}$ is worse than the original one.



Bunne, Charlotte et al. “Learning Single-Cell Perturbation Responses using Neural Optimal Transport”. In: *bioRxiv* (2021). DOI: 10.1101/2021.12.15.472775. eprint: <https://www.biorxiv.org/content/early/2021/12/15/2021.12.15.472775.full.pdf>. URL: <https://www.biorxiv.org/content/early/2021/12/15/2021.12.15.472775>.



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