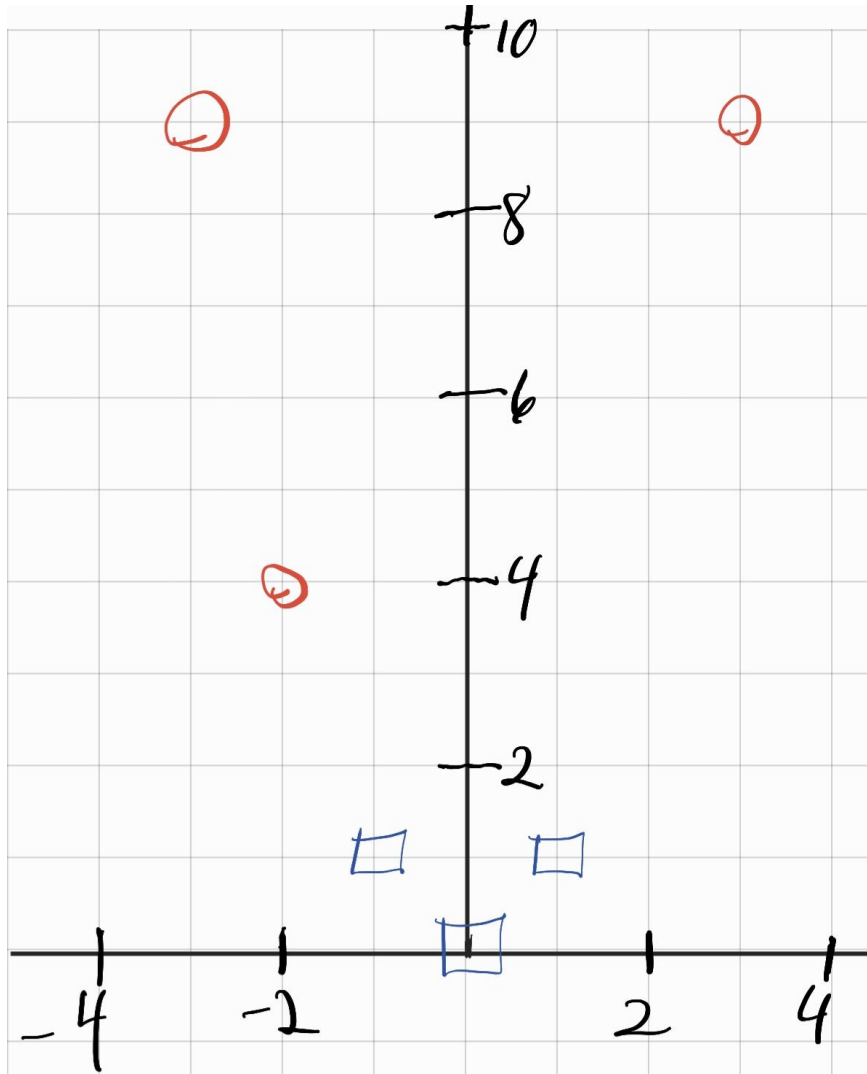
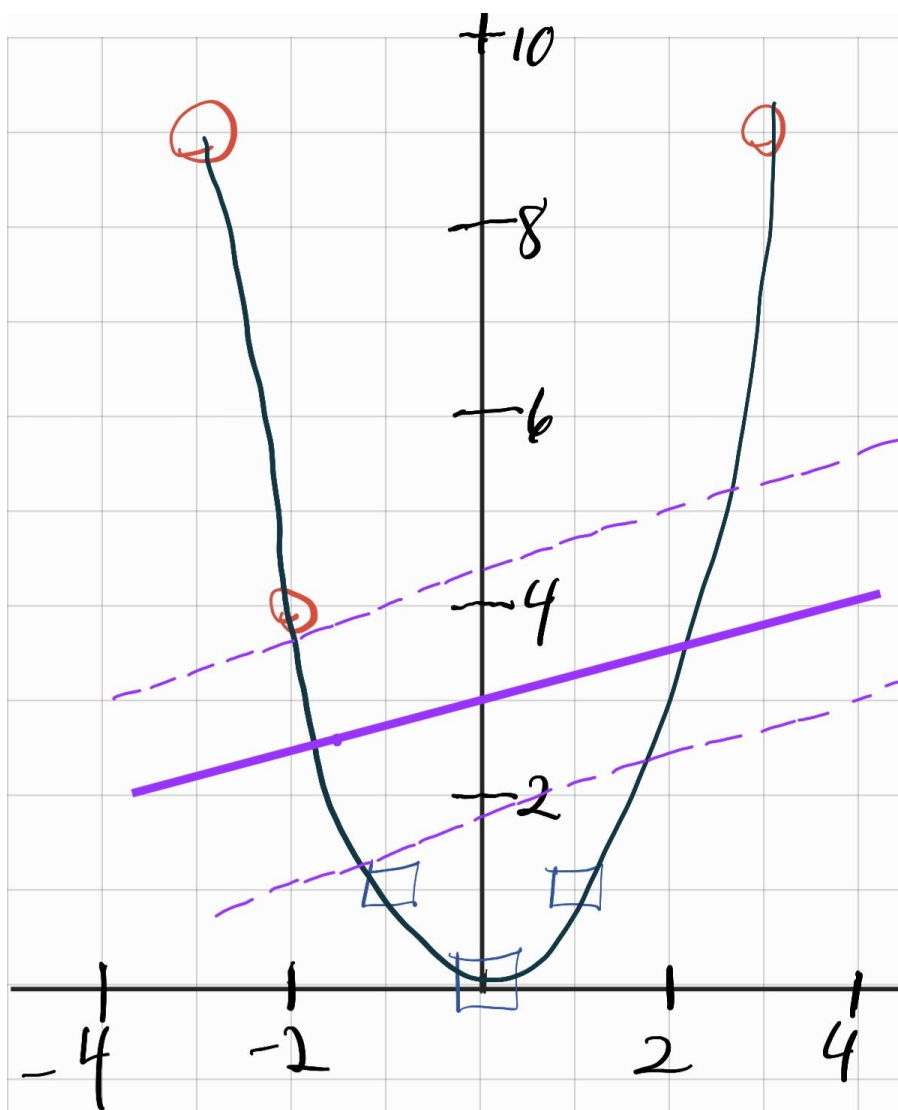


1.1 (Finite Features and SVMs)

1. In its current feature space, the dataset can not be perfectly separated by a linear separator. The data's class changes twice along the one dimension and a linear classifier in a single dimension can only separate a single class change.



- 2.
3. Yes, after being translated into 2 dimensional space, a linear separator can perfectly separate the points because there is now a clear path for a line to be drawn between the positive and negative samples.
4. In order to fully separate the data with a maximized margin, the line must pass through the midpoint between the two closest opposing points located at $(-2, 4)$ and $(-1, 1)$. The midpoint between the two points would be the point $(-3/5, 5/2)$ and the hyperplane would be perpendicular to the line formed if one were to connect the points. Because of that, the line would have a slope of $1/3$. Using the point and slope you can find that $w_1 = -1/3$, $w_2 = 1$, and $c = -3$. The margin would be half of the distance between the two points which is $\sqrt{10}/2$.



5.



6.

1.2 (Infinite Features Spaces and Kernel Magic)

1. We cannot explicitly construct $\phi_{\infty}(x)$ because it is infinite-dimensional. This would mean writing down an infinite number of basis functions which is not possible.
2. Yes, $k(a, b) = \sum_{i=1}^{\infty} \frac{e^{-a^2/2} a^i}{\sqrt{i!}} \frac{e^{-b^2/2} b^i}{\sqrt{i!}}$
 $= \exp\left[-\frac{a^2+b^2}{2}\right] \sum_{i=1}^{\infty} \left[\frac{(ab)^i}{i!}\right]$
 $= \exp\left[-\frac{a^2+b^2}{2}\right] \exp[ab]$
 $= \exp\left[-\frac{1}{2}(a^2 - 2ab + b^2)\right]$
 $= \exp\left[-\frac{1}{2}(a - b)^2\right]$
3. No, since model complexity in SVMs is not managed by feature space dimensions and instead by the number of support vectors.
4. $k(x_i + x_0, x_j + x_0) = e^{\frac{-((x_i+x_0)-(x_j+x_0))^2}{2}} = e^{\frac{-(x_i-x_j)^2}{2}} = k(x_i, x_j)$

2 (Naïve Bayes Classifier)

1.

$$P(Y = 1|Z = \text{missing}) = \frac{0.08 * \theta_{y=1}}{0.02 * (1 - \theta_{y=1}) + 0.08 * \theta_{y=1}}$$

2.

3. **Log-joint probability for a single example:**

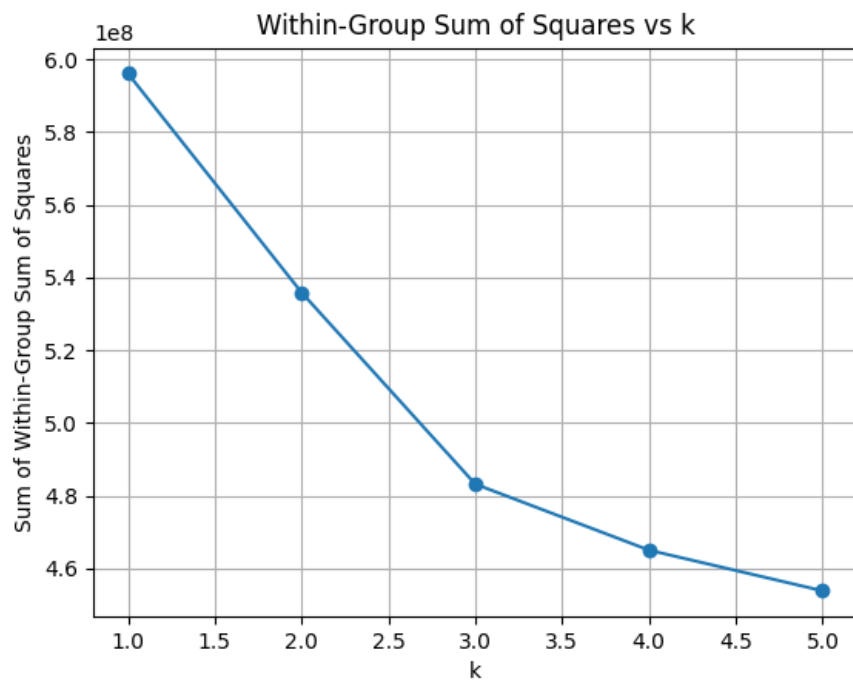
$$\log P(X_1 = x_1, X_2 = x_2, X_3 = x_3, Z = z, Y = y) = \log[p(y) \cdot p(x_1|y) \cdot p(x_2|y) \cdot p(x_3|y) \cdot P(Z = z|Y = y)]$$

For n i.i.d. examples:

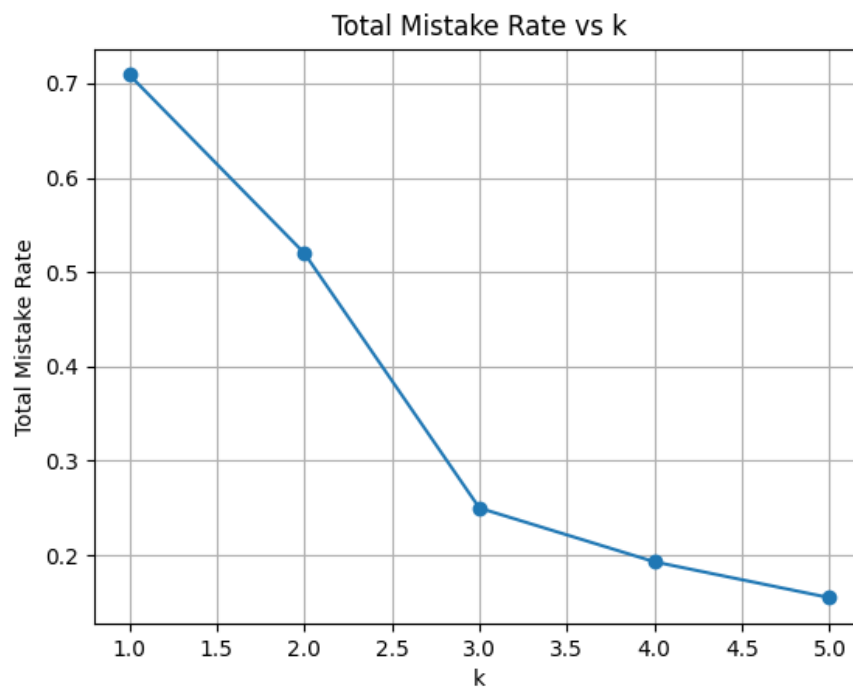
$$\log P(X, Y, Z) = \sum_{i=1}^n \log[p(y_i) \cdot p(x_{i1}|y_i) \cdot p(x_{i2}|y_i) \cdot p(x_{i3}|y_i) \cdot P(Z_i = z_i|Y_i = y_i)]$$

3 (K-means Clustering)

1.

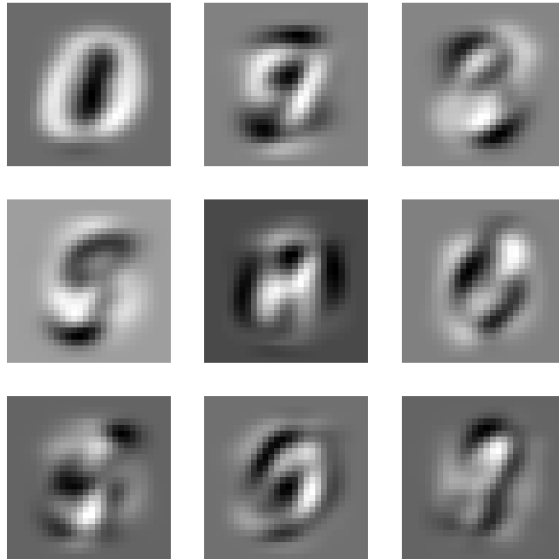


2.

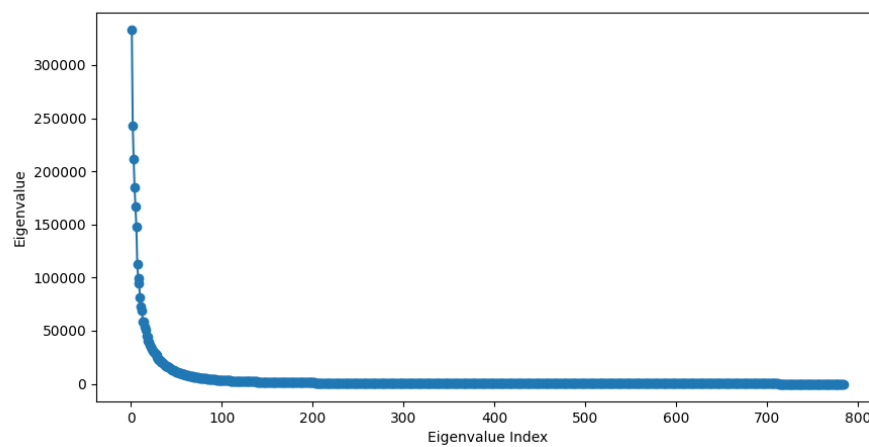


4 (Principal Components Analysis)

1.



2. ~30 eigenvectors.



3. Yes, much better.

