homework_12_matrix_factorization_Yiman Li

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0.1 Exporting the results to PDF

Once you complete the assignments, export the entire notebook as PDF and attach it to your homework solutions. The best way of doing that is 1. Run all the cells of the notebook. 2. Export/download the notebook as PDF (File -> Download as -> PDF via LaTeX (.pdf)). 3. Concatenate your solutions for other tasks with the output of Step 2. On linux, you can use pdfunite, there are similar tools for other platforms, too. You can only upload a single PDF file to Moodle.

Make sure you are using nbconvert version 5.5 or later by running jupyter nbconvert --version. Older versions clip lines that exceed page width, which makes your code harder to grade.

1 Matrix Factorization

```
[20]: import time
import scipy.sparse as sp
import numpy as np
from scipy.sparse.linalg import svds
from sklearn.linear_model import Ridge

import matplotlib.pyplot as plt
%matplotlib inline
```

1.1 Restaurant recommendation

The goal of this task is to recommend restaurants to users based on the rating data in the Yelp dataset. For this, we try to predict the rating a user will give to a restaurant they have not yet rated based on a latent factor model.

Specifically, the objective function (loss) we wanted to optimize is:

$$\mathcal{L} = \min_{P,Q} \sum_{(i,x) \in W} (M_{ix} - \mathbf{q}_i^T \mathbf{p}_x)^2 + \lambda \sum_{x} \|\mathbf{p}_x\|^2 + \lambda \sum_{i} \|\mathbf{q}_i\|^2$$

where W is the set of (i, x) pairs for which the rating M_{ix} given by user i to restaurant x is known. Here we have also introduced two regularization terms to help us with overfitting where λ is hyper-parameter that control the strength of the regularization.

Hint 1: Using the closed form solution for regression might lead to singular values. To avoid this issue perform the regression step with an existing package such as scikit-learn. It is advisable to use ridge regression to account for regularization.

Hint 2: If you are using the scikit-learn package remember to set fit_intercept = False to only learn the coefficients of the linear regression.

1.1.1 Load and Preprocess the Data (nothing to do here)

```
[21]: ratings = np.load("exercise_12_matrix_factorization_ratings.npy")
[22]: # We have triplets of (user, restaurant, rating).
     ratings
[22]: array([[101968,
                        1880,
                                   1],
             [101968,
                                   5],
                        284,
            [101968,
                        1378,
                                   2],
            [72452,
                                   4],
                        2100,
            [72452,
                        2050,
                                   5],
            [ 74861,
                        3979,
                                   5]], dtype=int64)
```

Now we transform the data into a matrix of dimension [N, D], where N is the number of users and D is the number of restaurants in the dataset. We store the data as a sparse matrix to avoid out-of-memory issues.

[23]: <337867x5899 sparse matrix of type '<class 'numpy.int64'>'
with 929606 stored elements in Compressed Sparse Row format>

To avoid the cold start problem, in the preprocessing step, we recursively remove all users and restaurants with 10 or less ratings.

Then, we randomly select 200 data points for the validation and test sets, respectively.

After this, we subtract the mean rating for each users to account for this global effect.

Note: Some entries might become zero in this process – but these entries are different than the 'unknown' zeros in the matrix. We store the indices for which we the rating data available in a separate variable.

```
Returns
_____
matrix
           : sp.spmatrix, shape [N', D']
              The pre-processed matrix, where N' \le N and D' \le D
print("Shape before: {}".format(matrix.shape))
shape = (-1, -1)
while matrix.shape != shape:
    shape = matrix.shape
   nnz = matrix>0
    row_ixs = nnz.sum(1).A1 > min_entries
   matrix = matrix[row_ixs]
   nnz = matrix>0
    col_ixs = nnz.sum(0).A1 > min_entries
    matrix = matrix[:,col_ixs]
print("Shape after: {}".format(matrix.shape))
nnz = matrix>0
assert (nnz.sum(0).A1 > min_entries).all()
assert (nnz.sum(1).A1 > min_entries).all()
return matrix
```

1.1.2 Task 1: Implement a function that subtracts the mean user rating from the sparse rating matrix

```
[25]: def shift_user_mean(matrix):

"""

Subtract the mean rating per user from the non-zero elements in the input

matrix.

Parameters

-----

matrix: sp.spmatrix, shape [N, D]

Input sparse matrix.

Returns

-----

matrix: sp.spmatrix, shape [N, D]

The modified input matrix.

user_means: np.array, shape [N, 1]

The mean rating per user that can be used to recover the

absolute ratings from the mean-shifted ones.

"""
```

```
# TODO: Compute the modified matrix and user_means
nnz_mask = (matrix>0)
user_means = matrix.sum(1) / nnz_mask.sum(1)
subtract_mask = sp.csr_matrix(user_means).multiply(nnz_mask)
matrix = matrix-subtract_mask

assert np.all(np.isclose(matrix.mean(1), 0))
return matrix, user_means
```

1.1.3 Split the data into a train, validation and test set (nothing to do here)

```
[26]: def split_data(matrix, n_validation, n_test):
         Extract validation and test entries from the input matrix.
         Parameters
         _____
         matrix
                       : sp.spmatrix, shape [N, D]
                           The input data matrix.
         n_validation : int
                           The number of validation entries to extract.
         n\_test
                        : int
                           The number of test entries to extract.
         Returns
         matrix_split
                        : sp.spmatrix, shape [N, D]
                           A copy of the input matrix in which the validation and
      \rightarrowtest entries have been set to zero.
                         : tuple, shape [2, n_validation]
         val_idx
                           The indices of the validation entries.
                         : tuple, shape [2, n_test]
         test\_idx
                           The indices of the test entries.
         val_values
                        : np.array, shape [n_validation, ]
                           The values of the input matrix at the validation indices.
         test\_values
                       : np.array, shape [n_test, ]
                           The values of the input matrix at the test indices.
         11 11 11
         matrix_cp = matrix.copy()
         non_zero_idx = np.argwhere(matrix_cp)
```

```
ixs = np.random.permutation(non_zero_idx)
val_idx = tuple(ixs[:n_validation].T)
test_idx = tuple(ixs[n_validation:n_validation + n_test].T)

val_values = matrix_cp[val_idx].A1
test_values = matrix_cp[test_idx].A1
matrix_cp[val_idx] = matrix_cp[test_idx] = 0
matrix_cp.eliminate_zeros()

return matrix_cp, val_idx, test_idx, val_values, test_values

[27]: M = cold_start_preprocessing(M, 20)
```

Shape before: (337867, 5899) Shape after: (3529, 2072)

```
[29]: # Remove user means.
nonzero_indices = np.argwhere(M_train)
M_shifted, user_means = shift_user_mean(M_train)
# Apply the same shift to the validation and test data.
val_values_shifted = val_values - user_means[np.array(val_idx).T[:,0]].A1
test_values_shifted = test_values - user_means[np.array(test_idx).T[:,0]].A1
```

1.1.4 Compute the loss function (nothing to do here)

```
[30]: def loss(values, ixs, Q, P, reg_lambda):

"""

Compute the loss of the latent factor model (at indices ixs).

Parameters

-----

values: np.array, shape [n_ixs,]

The array with the ground-truth values.

ixs: tuple, shape [2, n_ixs]

The indices at which we want to evaluate the loss (usually the nonzero⊔

→indices of the unshifted data matrix).

Q: np.array, shape [N, k]

The matrix Q of a latent factor model.

P: np.array, shape [k, D]

The matrix P of a latent factor model.

reg_lambda: float

The regularization strength
```

1.2 Alternating optimization

In the first step, we will approach the problem via alternating optimization, as learned in the lecture. That is, during each iteration you first update *Q* while having *P* fixed and then vice versa.

1.2.1 Task 2: Implement a function that initializes the latent factors Q and P

```
[31]: def initialize_Q_P(matrix, k, init='random'):
         Initialize the matrices Q and P for a latent factor model.
         Parameters
         _____
         matrix : sp.spmatrix, shape [N, D]
                  The matrix to be factorized.
               : int
                  The number of latent dimensions.
               : str in ['svd', 'random'], default: 'random'
                  The initialization strategy. 'svd' means that we use SVD to_{\sqcup}
      \rightarrow initialize P and Q, 'random' means we initialize
                   the entries in P and Q randomly in the interval [0, 1).
         Returns
         _____
         Q : np.array, shape [N, k]
             The initialized matrix Q of a latent factor model.
         P : np.array, shape [k, D]
             The initialized matrix P of a latent factor model.
         np.random.seed(0)
         N, D = np.shape(matrix)
         # TODO: Compute Q and P
         if init == 'svd':
```

```
U, S, V = svds(matrix, k=k)
S_x = np.diag(S)
Q = U.dot(S_x)
P = V
elif init == 'random':
Q = np.random.randn(N, k)
P = np.random.randn(k, D)
else:
    raise ValueError

assert Q.shape == (matrix.shape[0], k)
assert P.shape == (k, matrix.shape[1])
return Q, P
```

1.2.2 Task 3: Implement the alternating optimization approach

```
[32]: def latent_factor_alternating_optimization(M, non_zero_idx, k, val_idx,_
       →val_values,
                                                      reg_lambda, max_steps=100,_

→init='random',
                                                       log_every=1, patience=5,_
       →eval_every=1):
          n n n
          Perform matrix factorization using alternating optimization. Training is \Box
       \rightarrowdone via patience,
          i.e. we stop training after we observe no improvement on the validation loss \sqcup
       \hookrightarrow for a certain
          amount of training steps. We then return the best values for Q and P oberved \sqcup
       \hookrightarrow during training.
          Parameters
                               : sp.spmatrix, shape [N, D]
                                 The input matrix to be factorized.
                               : np.array, shape [nnz, 2]
          non\_zero\_idx
                                 The indices of the non-zero entries of the un-shifted \sqcup
       \hookrightarrow matrix to be factorized.
                                 nnz refers to the number of non-zero entries. Note that \sqcup
       \hookrightarrow this may be different
                                 from the number of non-zero entries in the input matrix\Box
       \hookrightarrow M, e.g. in the case
                                 that all ratings by a user have the same value.
          k
                               : int
                                 The latent factor dimension.
```

val_idx : tuple, shape [2, n_validation]

Tuple of the validation set indices.

n_validation refers to the size of the validation set.

val_values : np.array, shape [n_validation,]

The values in the validation set.

 reg_lambda : float

The regularization strength.

max_steps : int, optional, default: 100

Maximum number of training steps. Note that we will stop \Box

 \neg early if we observe

no improvement on the validation error for a specified $_{\sqcup}$

 \hookrightarrow number of steps

(see "patience" for details).

init : str in ['random', 'svd'], default 'random'

The initialization strategy for P and Q. See function \Box

 \rightarrow initialize_Q_P for details.

log_every : int, optional, default: 1

Log the training status every X iterations.

patience : int, optional, default: 5

Stop training after we observe no improvement of the

 \rightarrow validation loss for X evaluation

iterations (see eval_every for details). After we stop__

 \rightarrow training, we restore the best

observed values for Q and P (based on the validation \sqcup

 \hookrightarrow loss) and return them.

eval_every : int, optional, default: 1

Evaluate the training and validation loss every X steps. \Box

 ${\scriptscriptstyle
ightarrow} If$ we observe no improvement

of the validation error, we decrease our patience by $1,_\sqcup$

 \rightarrow else we reset it to *patience*.

Returns

 $best_Q$: np.array, shape [N, k]

Best value for Q (based on validation loss) observed

 \rightarrow during training

 $best_P$: np.array, shape [k, D]

```
Best value for P (based on validation loss) observed \sqcup
\hookrightarrow during training
   validation_losses : list of floats
                         Validation loss for every evaluation iteration, can be ⊔
\rightarrowused for plotting the validation
                        loss over time.
   train_losses
                      : list of floats
                        Training loss for every evaluation iteration, can be ...
→used for plotting the training
                        loss over time.
   converged_after : int
                        it - patience*eval\_every, where it is the iteration in_{\sqcup}
\rightarrow which patience hits 0,
                        or -1 if we hit max_steps before converging.
   11 11 11
   # TODO: Compute best_Q, best_P, validation_losses, train_losses and_
\rightarrow converged_after
   nnz_mask = sp.coo_matrix((np.ones(len(non_zero_idx)), (non_zero_idx[:
→,0],non_zero_idx[:,1])), shape=M.shape, dtype="uint8").tocsr()
   nnz_mask_col = nnz_mask.tocsc()
   cols = nnz_mask.T.tolil().rows
   rows = nnz_mask.tolil().rows
   reg = Ridge(alpha=reg_lambda, fit_intercept=False)
   Q,P = initialize_Q_P(M, k, init)
   train_losses = []
   validation_losses = []
   best_val_loss = best_Q = best_P = converged_after = -1
   train_idx = tuple(non_zero_idx.T)
   bef = -1
   times = \Pi
   for it in range(max_steps):
       if bef != -1:
           times.append(time.time()-bef)
       bef = time.time()
       if it % eval_every == 0:
           train_loss = loss(M[train_idx].A1, train_idx, Q, P, reg_lambda)
```

```
train_losses.append(train_loss)
           val_loss = loss(val_values, val_idx, Q, P, reg_lambda)
           validation_losses.append(val_loss)
           if best_val_loss < 0 or val_loss < best_val_loss:</pre>
               best_val_loss = val_loss
               best_Q = Q
               best_P = P
               current_patience = patience
           else:
               current_patience -= 1
           if current_patience == 0:
               converged_after = it - patience*eval_every
               break
       print("Iteration {}, training loss: {:.3f}, validation loss: {:.3f}".
→format(it, train_loss, val_loss))
       # fix Q and update P
       # fix Q and update P
       for rating_idx in range(M.shape[1]):
           nnz_idx = cols[rating_idx]
           res = reg.fit(Q[nnz_idx], np.squeeze(M[nnz_idx, rating_idx].
→toarray()))
           P[:, rating_idx] = res.coef_
       for user_idx in range(M.shape[0]):
           nnz_idx = rows[user_idx]
           res = reg.fit(P[:, nnz_idx].T, np.squeeze(M[user_idx, nnz_idx].
→toarray()))
           Q[user_idx, :] = res.coef_
  print("Converged after {} iterations, on average {:.3f}s per iteration".
→format(converged_after, np.mean(times)))
  return best_Q, best_P, validation_losses, train_losses, converged_after
```

1.2.3 Train the latent factor (nothing to do here)

```
→val_values=val_values_shifted,

→reg_lambda=1e-4, init='random',

→max_steps=100, patience=10)
```

```
Iteration 0, training loss: 15601179.586, validation loss: 21937.249
Iteration 1, training loss: 2516.317, validation loss: 753.995
Iteration 2, training loss: 540.570, validation loss: 523.066
Iteration 3, training loss: 194.908, validation loss: 513.264
Iteration 4, training loss: 95.040, validation loss: 532.319
Iteration 5, training loss: 57.519, validation loss: 548.417
Iteration 6, training loss: 40.974, validation loss: 535.613
Iteration 7, training loss: 32.765, validation loss: 534.745
Iteration 8, training loss: 28.356, validation loss: 530.761
Iteration 9, training loss: 25.839, validation loss: 527.236
Iteration 10, training loss: 24.336, validation loss: 524.362
Iteration 11, training loss: 23.395, validation loss: 521.984
Iteration 12, training loss: 22.792, validation loss: 517.433
Iteration 13, training loss: 22.386, validation loss: 511.743
Iteration 14, training loss: 22.102, validation loss: 507.319
Iteration 15, training loss: 21.895, validation loss: 504.711
Iteration 16, training loss: 21.737, validation loss: 502.432
Iteration 17, training loss: 21.613, validation loss: 500.809
Iteration 18, training loss: 21.511, validation loss: 499.392
Iteration 19, training loss: 21.425, validation loss: 498.078
Iteration 20, training loss: 21.350, validation loss: 497.056
Iteration 21, training loss: 21.283, validation loss: 495.862
Iteration 22, training loss: 21.223, validation loss: 494.797
Iteration 23, training loss: 21.167, validation loss: 493.988
Iteration 24, training loss: 21.114, validation loss: 493.125
Iteration 25, training loss: 21.065, validation loss: 492.341
Iteration 26, training loss: 21.017, validation loss: 491.748
Iteration 27, training loss: 20.972, validation loss: 491.345
Iteration 28, training loss: 20.929, validation loss: 490.784
Iteration 29, training loss: 20.887, validation loss: 490.268
Iteration 30, training loss: 20.847, validation loss: 489.816
Iteration 31, training loss: 20.807, validation loss: 489.395
Iteration 32, training loss: 20.769, validation loss: 488.989
Iteration 33, training loss: 20.732, validation loss: 488.596
Iteration 34, training loss: 20.695, validation loss: 488.198
Iteration 35, training loss: 20.659, validation loss: 487.797
Iteration 36, training loss: 20.624, validation loss: 487.379
Iteration 37, training loss: 20.590, validation loss: 486.958
Iteration 38, training loss: 20.556, validation loss: 486.527
Iteration 39, training loss: 20.523, validation loss: 486.110
```

```
Iteration 40, training loss: 20.490, validation loss: 485.691
Iteration 41, training loss: 20.458, validation loss: 485.294
Iteration 42, training loss: 20.427, validation loss: 484.889
Iteration 43, training loss: 20.396, validation loss: 484.509
Iteration 44, training loss: 20.366, validation loss: 484.115
Iteration 45, training loss: 20.336, validation loss: 483.745
Iteration 46, training loss: 20.306, validation loss: 483.358
Iteration 47, training loss: 20.277, validation loss: 482.976
Iteration 48, training loss: 20.248, validation loss: 482.730
Iteration 49, training loss: 20.220, validation loss: 482.474
Iteration 50, training loss: 20.192, validation loss: 482.170
Iteration 51, training loss: 20.164, validation loss: 481.861
Iteration 52, training loss: 20.137, validation loss: 481.542
Iteration 53, training loss: 20.110, validation loss: 481.214
Iteration 54, training loss: 20.084, validation loss: 480.872
Iteration 55, training loss: 20.058, validation loss: 480.517
Iteration 56, training loss: 20.032, validation loss: 480.160
Iteration 57, training loss: 20.006, validation loss: 479.798
Iteration 58, training loss: 19.981, validation loss: 479.445
Iteration 59, training loss: 19.956, validation loss: 479.091
Iteration 60, training loss: 19.931, validation loss: 478.747
Iteration 61, training loss: 19.907, validation loss: 478.401
Iteration 62, training loss: 19.883, validation loss: 478.065
Iteration 63, training loss: 19.859, validation loss: 477.726
Iteration 64, training loss: 19.835, validation loss: 477.395
Iteration 65, training loss: 19.811, validation loss: 477.063
Iteration 66, training loss: 19.788, validation loss: 476.738
Iteration 67, training loss: 19.765, validation loss: 476.413
Iteration 68, training loss: 19.742, validation loss: 476.094
Iteration 69, training loss: 19.720, validation loss: 475.775
Iteration 70, training loss: 19.697, validation loss: 475.463
Iteration 71, training loss: 19.675, validation loss: 475.150
Iteration 72, training loss: 19.653, validation loss: 474.844
Iteration 73, training loss: 19.631, validation loss: 474.538
Iteration 74, training loss: 19.609, validation loss: 474.238
Iteration 75, training loss: 19.588, validation loss: 473.939
Iteration 76, training loss: 19.567, validation loss: 473.645
Iteration 77, training loss: 19.546, validation loss: 473.352
Iteration 78, training loss: 19.525, validation loss: 473.063
Iteration 79, training loss: 19.504, validation loss: 472.776
Iteration 80, training loss: 19.483, validation loss: 472.493
Iteration 81, training loss: 19.463, validation loss: 472.212
Iteration 82, training loss: 19.442, validation loss: 471.934
Iteration 83, training loss: 19.422, validation loss: 471.658
Iteration 84, training loss: 19.402, validation loss: 471.386
Iteration 85, training loss: 19.382, validation loss: 471.115
Iteration 86, training loss: 19.363, validation loss: 470.848
Iteration 87, training loss: 19.343, validation loss: 470.583
```

```
Iteration 88, training loss: 19.323, validation loss: 470.321 Iteration 89, training loss: 19.304, validation loss: 470.061 Iteration 90, training loss: 19.285, validation loss: 469.804 Iteration 91, training loss: 19.266, validation loss: 469.549 Iteration 92, training loss: 19.247, validation loss: 469.297 Iteration 93, training loss: 19.228, validation loss: 469.047 Iteration 94, training loss: 19.209, validation loss: 468.801 Iteration 95, training loss: 19.191, validation loss: 468.556 Iteration 96, training loss: 19.172, validation loss: 468.314 Iteration 97, training loss: 19.154, validation loss: 468.075 Iteration 98, training loss: 19.136, validation loss: 467.838 Iteration 99, training loss: 19.118, validation loss: 467.603 Converged after -1 iterations, on average 4.454s per iteration
```

1.2.4 Plot the validation and training losses over for each iteration (nothing to do here)

```
[34]: fig, ax = plt.subplots(1, 2, figsize=[10, 5])
    fig.suptitle("Alternating optimization, k=100")

ax[0].plot(train_loss[1::])
    ax[0].set_title('Training loss')
    plt.xlabel("Training iteration")
    plt.ylabel("Loss")

ax[1].plot(val_loss[1::])
    ax[1].set_title('Validation loss')
    plt.xlabel("Training iteration")
    plt.ylabel("Loss")

plt.show()
```

Alternating optimization, k=100

