

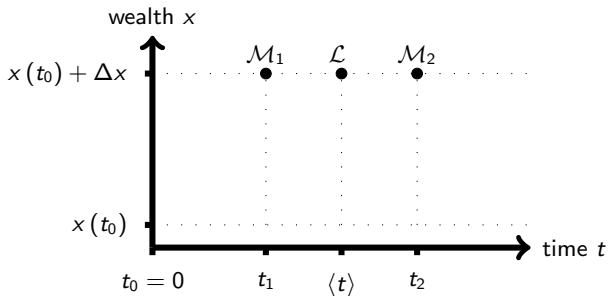


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Commercial Break : Risk Preferences in Time Lotteries

Full paper at: bit.ly/TimeLotteries

- Known payment amount: Δx
- Two possible payment times
earlier t_1
later $t_2 (> t_1)$
- Probability $0 \leq p \leq 1$ to
receive Δx earlier at t_1
($1 - p$ later at t_2)
- Every time lottery L defines a
unique timed payment \mathcal{L} : Δx
is received with certainty at the
expected payment time
 $\langle t \rangle = pt_1 + (1 - p)t_2$



↪ Growth-optimal preferences vs EDUT preferences

What are we weighting for?

A mechanistic model for probability weighting

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Full paper at bit.ly/lml-pw-r1

Live paper at bit.ly/lml-pw

Erich-Schneider-Seminar Economics Department, CAU Kiel

02 November 2020





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Main result

Main Result

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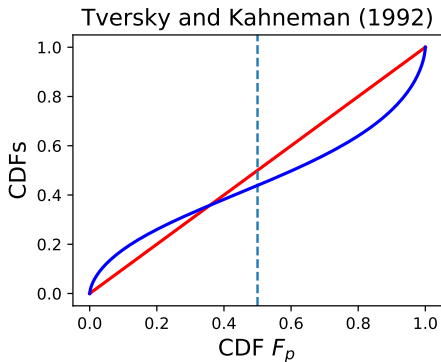
Functional Form

Fitting Functions

Ergodicity
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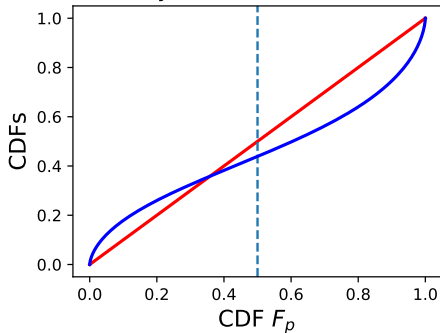
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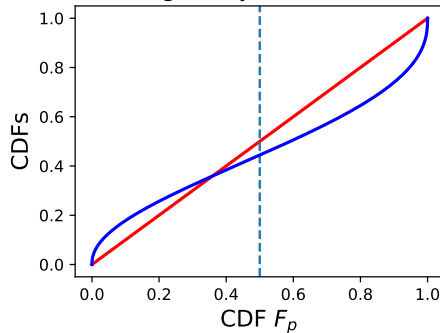
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Tversky and Kahneman (1992)



Ergodicity Economics





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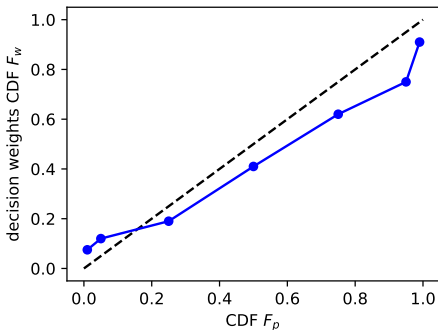
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Definition of Probability Weighting (PW)



(Preston and Baratta 1948, p. 188, Fig. 1, relabelled axes)

“The existence [...] a scale of *psychological probability* and its functional relationship to the scale of *mathematical probability*” (p. 186)

- empirical pattern: inverse-S shape
- important component in behavioural economics (Cumulative Prospect Theory)

Classical interpretation of PW:

- maladaptive irrational cognitive bias

- How does this pattern emerge?
- Can we derive a functional form (rather than fit a function)?



- no motivation of the functional form of weighting curve other than fit
- origin of PW preferences? no stable mappings (Stewart et al. [2015](#))
- experimental design is a key confounder → description-experience gap, *i.e.* less (even under-) overweighting in decisions-from-experience (Hertwig et al. [2004](#); Hertwig and Erev [2009](#))
- meta-analyses find all possible weighting curves (Ungemach et al. [2009](#); Wulff et al. [2018](#), Tab. 9)

Statistical explanations

- PW due to biased estimation (Fox and Hadar [2006](#))
- PW is optimal in sequential learning problems (Seo et al. [2019](#))
- PW heuristic as an approximate Bayesian solution for the inference problem (Martins [2006](#))

⇨ reproducibility, context dependence, (mal)adaptive

No *truth*, only difference in models of uncertainty

Task: model payout, x , of a gamble as a random variable.

Disinterested Observer (DO)



DO assigns PDF $p(x)$
 \hookrightarrow CDF $F_p(x)$

$$F_p(x) = \int_{-\infty}^x p(s) ds$$

Decision Maker (DM)



DM assigns different PDF $w(x)$
 \hookrightarrow CDF $F_w(x)$

$$F_w(x) = \int_{-\infty}^x w(s) ds$$



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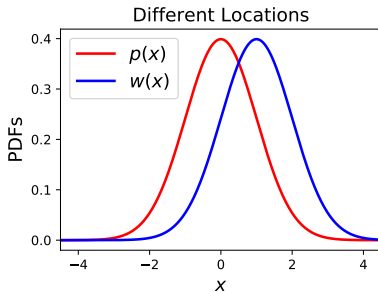
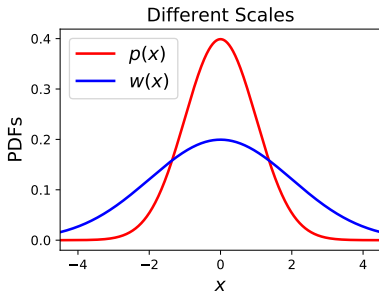
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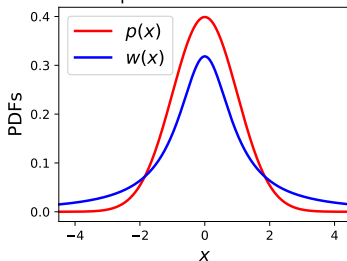
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Scales, Locations, Shapes



Different Shapes: Gaussian and t -distribution





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Thought Experiment: DM assumes greater scale

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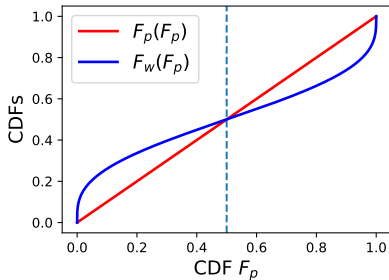
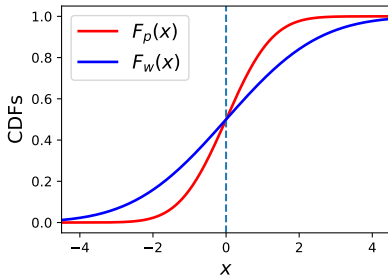
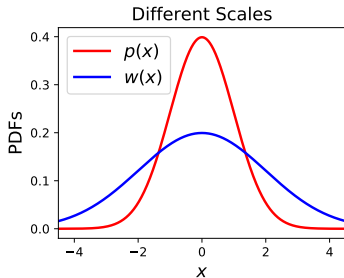
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Asymmetric Inverse-S = diff. in uncertainty + diff. in locations

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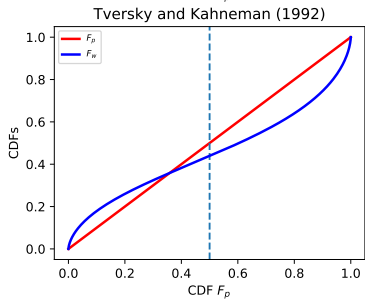
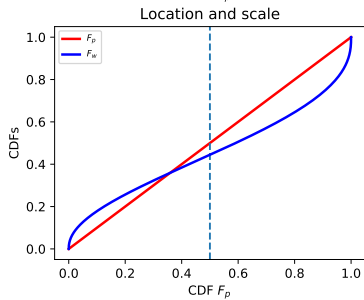
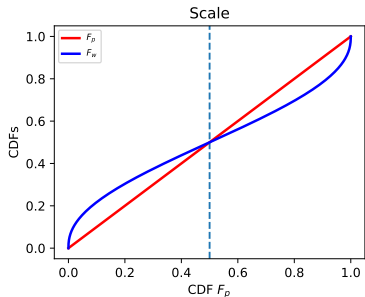
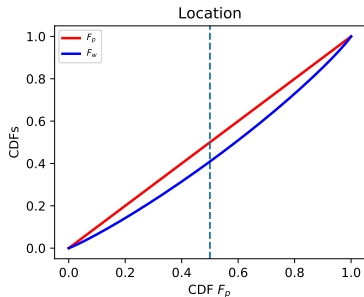
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Numerically feasible for arbitrary distributions:

- 1 list values of DO's CDF, $F_p(x)$, at set x_i
- 2 list values of DM's CDF, $F_w(x)$, at same x_i
- 3 plot $F_w(x)$ vs. $F_p(x)$



Functional form of the weighting function

Gaussian case with different scale:

$$w(p) = p^{\frac{1}{\alpha^2}} \underbrace{\frac{(2\pi\sigma^2)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha}}_{\text{normalisation factor}}, \quad (1)$$

where

- DO's scale is σ , $X \sim \mathcal{N}(\mu, \sigma^2)$
- DM's scale is $\alpha\sigma$, $X \sim \mathcal{N}(\mu, (\alpha\sigma)^2)$
- DO uses greater uncertainty $\alpha < 1 \rightarrow$ S shape
- DM uses greater uncertainty $\alpha > 1 \rightarrow$ inverse-S shape
- uncertainty measured by the standard deviation



Tversky and Kahneman (1992, $\gamma = 0.68$)

$$F_w^{TK}(F_p; \gamma) = (F_p)^\gamma \frac{1}{[(F_p)^\gamma + (1 - F_p)^\gamma]^{1/\gamma}} \quad (2)$$

Lattimore et al. (1992)

$$F_w^L(F_p; \delta, \gamma) = \frac{\delta F_p^\gamma}{\delta F_p^\gamma + (1 - F_p)^\gamma} \quad (3)$$

Gaussian case with greater DM scale $\alpha\sigma$

$$w(p) = p^{\frac{1}{\alpha^2}} \frac{(2\pi\sigma^2)^{\frac{1-\alpha^2}{2\alpha^2}}}{\alpha}, \quad (4)$$

which is a power law in p with a pre-factor to ensure normalisation



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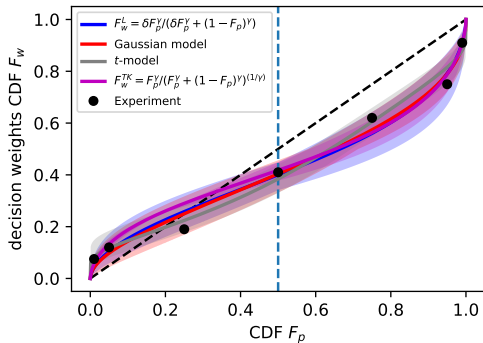
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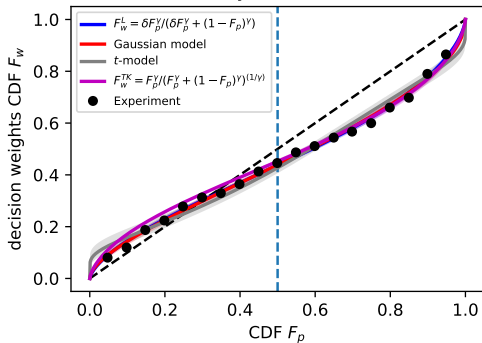
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Preston & Baratta (1948)



Tversky & Fox (1995)





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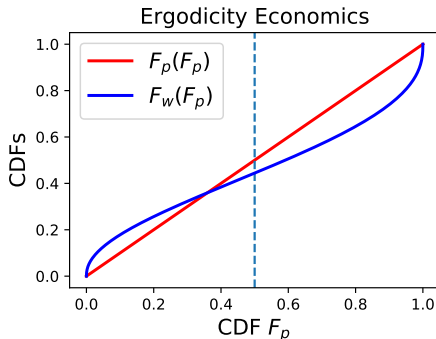
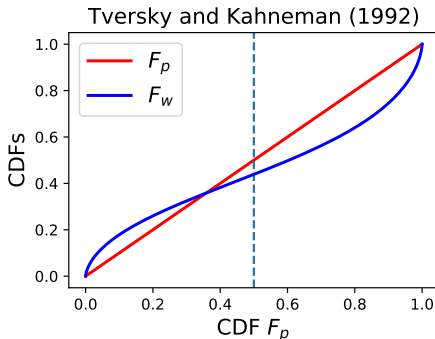
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Interim conclusion



- DM's greater scale gives inverse-S shape (unimodal distributions)
- difference in locations gives asymmetry
- reproduces observations of probability weighting

Job done. Thank you for your attention ;)



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The Ergodicity Question



Typical DO concern

What happens on average to
the **ensemble** of subjects?

≠



Typical DM concern

What happens to me
on average over time?



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Why DM's greater scale?

- DM has no control over experiment
- experiment may be unclear to DM
- DM may not trust DO
- ...



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Experiencing probabilities

- “probability” is polysemous
- natural frequencies “10 out of 100” vs 10% (Gigerenzer [1991](#), [2018](#); Hertwig and Gigerenzer [1999](#))
- probabilities are not observable
- probabilities encountered as
 - known frequencies in ensemble of experiments (DO)
 - frequencies estimated over time (DM)

↪ **estimates have uncertainties – cautious DM accounts for these**

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Rare Event

- $p(x) = 0.001$
 - $T = 100$ observations
 - $\sim 99.5\%$ get 0 or 1 events
 - $\hat{p}(x) = 0$ or $\hat{p}(x) = 0.01$
- ↪ $\hat{p}(x)$ off by 1000%

Common Event

- $p(x) = 0.5$
 - $T = 100$ observations
 - $\sim 99.5\%$ get between 35 and 65 events,
 - $0.35 < \hat{p}(x) < 0.65$
- ↪ $\hat{p}(x)$ off by 30%

↪ small $p(x)$, small count \rightarrow big uncertainty



Scaling of uncertainty: small count \rightarrow big uncertainty

- 1 scaling of counts $n(x)$:

$$n(x) \sim p(x)\delta x T \iff p(x) \sim n(x)/T\delta x$$

- 2 uncertainty in Poisson-distributed counts $\sim \sqrt{n(x)}$

- 3 estimate of the asymptotic probability density

$$p(x) \approx \underbrace{\frac{n(x)}{T\delta x}}_{\text{estimate}} \pm \underbrace{\frac{\sqrt{n(x)}}{T\delta x}}_{\text{relative uncertainty}} \quad (5)$$

- 4 express the uncertainty in terms of the estimate itself

$$\varepsilon [\hat{p}(x)] \equiv \frac{\sqrt{n(x)}}{T\delta x} = \sqrt{\frac{\hat{p}(x)}{T\delta x}} \quad (6)$$

- 5 standard error $\lim_{p(x) \rightarrow 0} \sqrt{\hat{p}(x)/T\delta x}$ in \hat{p} shrinks

- 6 relative error in the estimate $\lim_{p(x) \rightarrow 0} 1/\sqrt{\hat{p}(x)T\delta x}$ grows,

- 7 $\lim_{T \rightarrow \infty} \hat{p} \rightarrow p$



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Cautionary principle : DMs don't like surprises

To avoid surprises, DMs add estimation uncertainty $\varepsilon [\hat{p}(x)]$ to every estimated probability, then normalize, s.t.

$$w(x) = \frac{\hat{p}(x) + \varepsilon [\hat{p}(x)]}{\int (\hat{p}(s) + \varepsilon [\hat{p}(s)]) ds} \quad (7)$$

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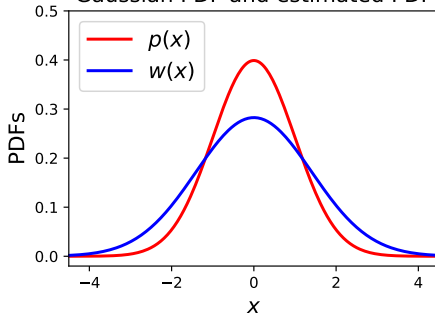


Cautionary principle : DMs don't like surprises

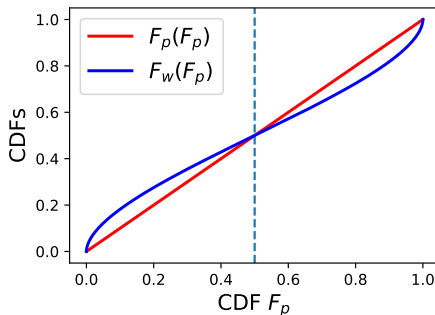
To avoid surprises, DMs add estimation uncertainty $\varepsilon [\hat{p}(x)]$ to every estimated probability, then normalize, s.t.

$$w(x) = \frac{\hat{p}(x) + \varepsilon [\hat{p}(x)]}{\int (\hat{p}(s) + \varepsilon [\hat{p}(s)]) ds} \quad (7)$$

Gaussian PDF and estimated PDF



inverse-S from estimation



Interactive code at <https://bit.ly/lml-pw-count-b>



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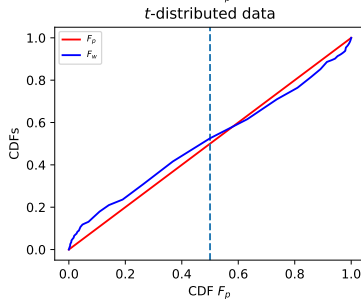
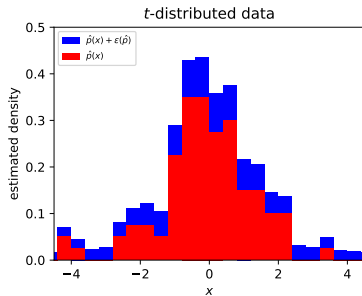
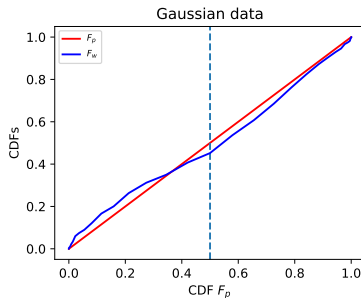
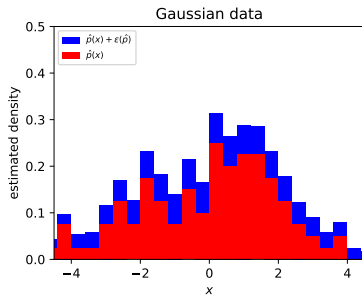
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$T = 100, \delta x = 0.4$, estimates of $\hat{p}(x)$ in red, estimates with one standard error $\hat{p}(x) + \varepsilon[\hat{p}(x)]$ in blue.



Classical interpretation of PW

- overestimation of low probability events
 - underestimation of high probability events
- ↪ maladaptive irrational cognitive bias

- testable prediction → Let's run an experiment!
- Manuscript at bit.ly/lml-pw-r1
- Interactive code at bit.ly/lml-pw-count-b

Ergodicity Economics and PW

- inverse-S shape: neutral indicator of different models of the world
 - reported observations consistent with DM's extra uncertainty
 - may arise from DM estimating probabilities over time
- ↪ Probability weighting is rational cautious behaviour under uncertainty over time



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Thank you for your attention!

I'm looking forward to the discussion
Comments & questions are very welcome, here or to

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Probability Weighting as an Estimation Issue

“It is important to distinguish [overweighting](#), which refers to a property of decision weights, from the [overestimation](#) that is commonly found in the assessment of the probability of rare events. [...] In many real-life situations, overestimation and overweighting may both operate to increase the impact of rare events.” (Kahneman and Tversky [1979](#), p. 281)

↪ distinguish between

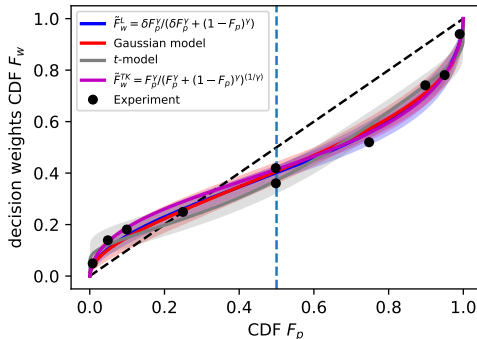
- uncertainty estimation and
- “weighting”

we analyse the former and find very good agreement with the empirical inverse-S pattern

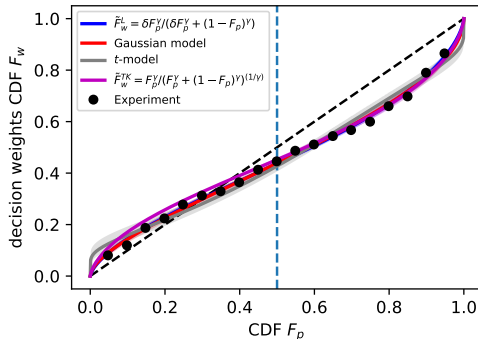
↪ How big is the residual “probability weighting” after accounting for uncertainty estimation?

Estimation Error Explains 99% of Probability Weighting

Tversky & Kahneman (1992)



Tversky & Fox (1995)



- similar fits of Gaussian & t -distributed model

→ How big is the residual “probability weighting” after accounting for estimation errors?



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