

Testing of Automotive Systems (Part I)

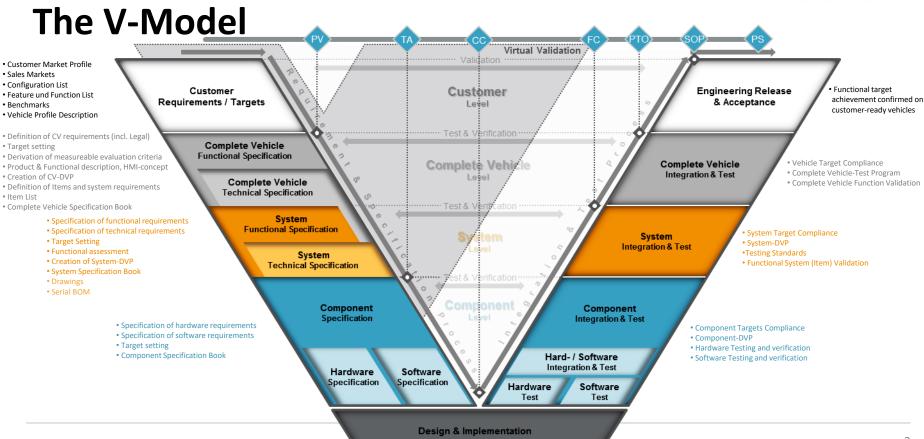
Module 9 – Integration Testing

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FRS Function Release Step

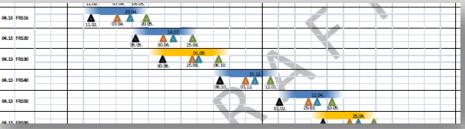






The Art of Integration – Function Release Steps

- FRS are iterative steps
- Each FRS realizes an exactly defined function increase
- Several FRS can be nested into each other
- To serve the highly individual requirements of the project landscape
- FRS have no exactly predefined duration
- The overall numbers of FRS is not limited
- There is no "typical function increase" for each FRS
- Integration team leader is the owner of the FRS process





The goal of the FRS is ...

... to identify the strength and the weakness of the system and functions, not only error finding with a defined package (Verbund)

... to support upcoming build phases or special events (winter/summer testing) with a tested and frozen HW/SW

package

 \dots to provide an overview of the actual status of mechatronic function implementation (system and

customer

functions)

... to report an error status of the mechatronic customer and system functions

... to confirm the vehicle built from E/E perspective

The goal of the FRS is NOT ...

... to provide a complete vehicle status report

... to provide a full function parametrization and validation report



FRS - Timing



FRS with function increase

- Implementation of clearly defined list of functions by system suppliers and validation by MAGNA STEYR
- The goal of the FRS is function increase
- FRS with function increase start with end of concept phase (FRSCC) and end with FRS100 (typ. C-Samples)



Bug fix FRS

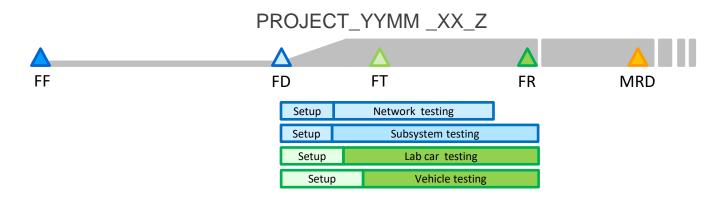
 Individually short term planned for implementation of corrections

Data FRS PS

- Check of data packages
- No function increase
- Data FRS usually planned in last quarter of serial development

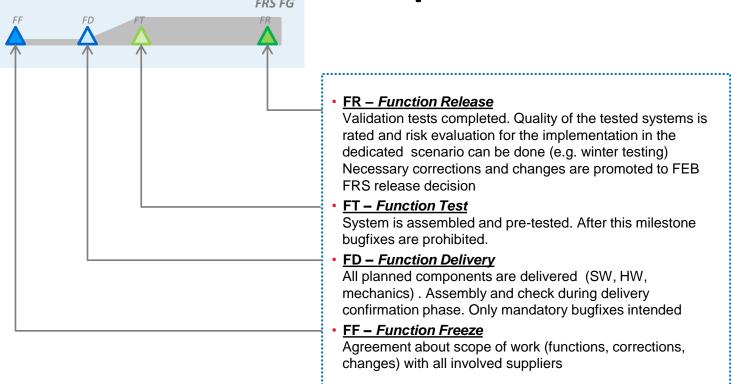


Generic FRS – test sequence



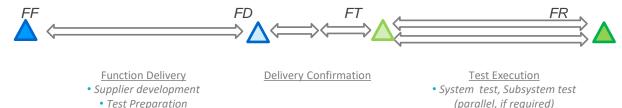


Generic Function Release Step - Milestones





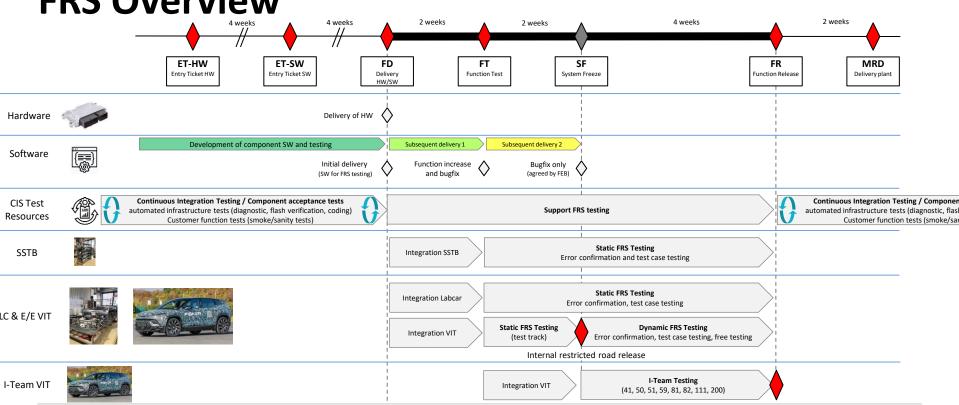
FRS- The Phases



- Basically each phase is flexible in duration, overall FRS highly dependent on OEM and development task
- During function delivery the supplier's development process is tracked by means of metrics
- Delivery confirmation between FD und FT can be realized individually based on the implementation volume
- Step by step (first subsystem, then system) or
- Only one of both steps (depending on validation goal)
- Test Execution combines different types of integration testing
- Subsystem test (including variants)
- Network Test bench Test
- Lab car test
- VIT (Vehicle intensive test)



FRS Overview





Function release Step - Milestones

FT – Function Test	 integration to test resources by MAGNA (Component acceptance test). Function increase and bugfix possible until FT if confirmed in FEB meeting. The system under test is pre-tested and first start up of system is finished. Start of main test execution phase. Bugfix delivery only possible when necessary and aligned with project.
SF – System Freeze	Start of complete system testing.
FR – Function Release	Complete system release from complete vehicle based on test results of I-Teams (41, 50 51, 59, 81, 82, 111, 140, 200) is done. Risks and limitation for build and complete vehicle testing process are described. Problem landscape is presented.
MRD – Material required Date	Hardware and software must be available for vehicle build process.



Software maturity Function implementation planning



FRS Maturity

0	Open, Not implemented									
	Functionality is available as backup to enable first testing (e.q to									
В	enable Mule testing)									
	Firstly implemented. Test at test bench should be possible,									
	vehicle tests may be possible.									
	Generally functionality should be 100% available but smaller									
	deviations can occur. Functional restrictions shall be agreed with									
F	Integration teams.									
	100% functionality is available for prototype vehicle tests. Basic									
	parameterization available. Functional restrictions shall be									
P	agreed with Integration teams.									
	100% functionality is available, parameters are defined and									
	verified.Parametrization process finished and customer maturity									
С	is achieved.									

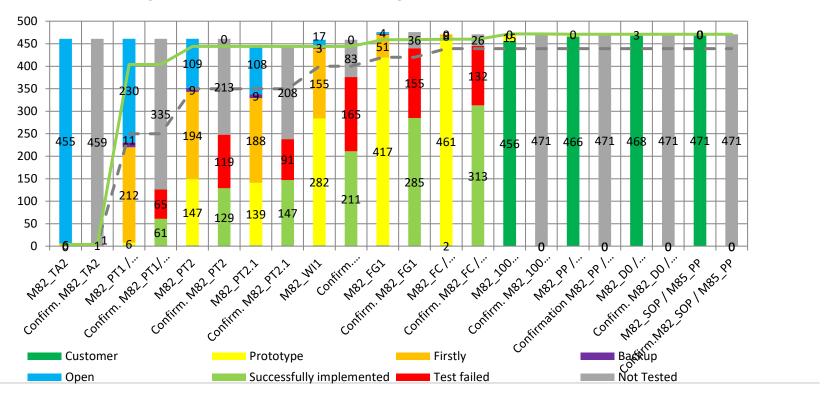


FRS- Function implementation plan

Function List ID	Feature ID (Customer from ALM Function Req ID in ALM)	ECU	Name	EE - Responsible	Option	M82_1803_TA1	M82_1803_TA15up	MB2_1803_TA2	MB2_1803_TA⊠up	MB2_1803_PT1	M82_1803_PT15up	M82_1803_PT2	M82_1803_PT⊠up	MB2_1803_WI1	M82_1803_WI1Sup	M82_1803_FG1	MB2_1803_FG15up	MB2_1803_FC	M82_1803_FCSupp	MB2_1803_100	M82_1803_100Sup	M82_1803_PP	M82_1803_PPSupp	MB2_1803_D0	M82_1803_D0Supp	M82_1803_SOP	M82_1803_SOPSup	TC Responsible
1.1	14211		Safety - Crash mitigation		Customer																							
1.1.1.1			Driver Airbag (1 stage) - Firing Driver Airbag	Grinschgl	Customer	0	0	0	F	F	F I	P	Р	P F	, ,	P F	,	Р	Р	С	С	С	С	С	С	С	С	Baumgartner
	5463; 5467; 549	ACM	activation driver airbag	Wilfling		0	0	0	F	F	F I	Р	Р	P F	, ,	P F	,	P	Р	С	С	С	С	С	С	С	С	
	5463; 5467; 550	ACM	send crash detected (hardwired)	Wilfling		F	В	Р	F	Р	P I	Р	Р	P F	,	P F	•	P	Р	С	С	С	С	С	С	С	С	
	3349	SESAM	send terminal status (CAN)	Fuchs		F	F	Р	Р	P	P I	P	Р	P F	, ,	P F		Р	Р	С	С	С	С	С	С	С	С	
	1219	BCM	Gateway	Zatsch		F	0	Р	F	Р	P I	Р	Р	P F)	P F	,	P	Р	С	С	С	С	С	С	С	С	
1.1.2.1			Passenger Airbag (1 stage) - Firing Passenger Airbag	Grinschgl	Customer	0	0	0	F	F	F I	P	Р	P F	, ,	P I	,	Р	P	С	С	С	С	С	С	С	С	Baumgartner
	5463; 5467; 549	ACM	activation passenger airbag	Wilfling		0	0	0	F	F	F I	Р	Р	P F	, ,	P F	,	Р	Р	С	С	С	С	С	С	С	С	
	5463; 5501; 550		send crash detected (CAN)	Wilfling		F	0	Р	F	Р	P I	P	Р	P F	, ,	P I	,	Р	Р	С	С	С	С	С	С	С	С	
	5463; 5467; 550		send crash detected (hardwired)	Wilfling		F	В	Р	F	Р	P I	P	Р	P F	, ,	P F	,	Р	Р	С	С	С	С	С	С	С	С	
	3349	SESAM	send terminal status (CAN)	Fuchs		F	F	Р	Р	P	P I	P	Р	P F	, ,	P I	,	Р	Р	С	С	С	С	С	С	С	С	
	1219	BCM	Gateway	Zatsch		F	0	Р	F	Р	P I	P	Р	P F	, ,	P I	,	Р	Р	С	С	С	С	С	С	С	С	
1.1.3.1			Curtain Airbag for driver and passenger - Activation Curtain Airbag	Grinschgl	Customer	0	0	0	F	F	F	P	P I	P F	, ,	P I	•	Р	Р	с	С	С	С	С	С	С	С	Baumgartner
	5463; 5467; 549	ACM	activation curtain airbag driver	Wilfling		0	0	0	F	F	F I	P	P	P F	, ,	P F	,	P	Р	С	С	С	С	С	С	С	С	
	5463; 5467; 549	ACM	activation curtain airbag passenger	Wilfling		0	0	0	F	F	F I	Р	Р	P F	, ,	P F	•	P	P	С	С	С	С	С	С	С	С	
	5463; 5501; 550	EACM	send crash detected (CAN)	Wilfling		F	0	P	F	P	P I	P	P I	P F	, ,	P F	,	P	P	С	С	С	С	С	С	С	С	
	5463; 5467; 550	ACM	send crash detected (hardwired)	Wilfling		F	В	Р	F	P	P I	Р	Р	P F	, ,	P F	,	P	Р	С	С	С	С	С	С	С	С	
	3349	SESAM	send terminal status (CAN)	Fuchs		F	F	P	P	P	P I	Р	P	P F)	P F		P	P	С	С	С	С	С	С	С	С	
	1219	BCM	Gateway	Zatsch		F	0	P	F	P	P I	P	P	P F	, ,	P F	,	P	P	С	С	С	С	С	С	С	С	
1.1.4.1			Side airbag for driver and passenger - Activation of side airbag		Customer	0	0	0	F	F	F I	Р	Р	P F	, ,	P I	•	Р	Р	С	С	С	С	С	С	С	С	Baumgartner
	5463; 5467; 549		activation side airbag driver	Wilfling		0	0	0	F	F	F I	Р	P	P F	, ,	P I	,	Р	Р	С	С	С	С	С	С	С	С	
	5463; 5467; 549		activation side airbag passenger	Wilfling		0	0	0	F	F	F I	Р	P	P F	, 1	P F	•	P	P	С	С	С	С	С	С	С	С	
	5463; 5501; 550		send crash detected (CAN)	Wilfling		F	0	P	F	P	P I	Р	P I	P F	, ,	P F	,	P	Р	С	С	С	С	С	С	С	С	
	5463; 5467; 550		send crash detected (hardwired)	Wilfling		F	В	Р	F	P	P I	Р	Р	P F	, ,	P F	•	Р	Р	С	С	С	С	С	С	С	С	
	3349	SESAM	send terminal status (CAN)	Fuchs		F	F	P	Р	P	P I	Р	Р	P F	, 1	P F	•	Р	P	С	С	С	С	С	С	С	С	
	1219	BCM	Gateway	Zatsch		F	0	Р	F	P	P I	Р	Р	P F	, ,	P I	,	P	Р	С	С	С	С	С	С	С	С	
1.1.5.1	, in the second		Airbag failure warning light - Indication of airbag failures in IC		Customer	0	0	F	F	Р	P I	Р	Р	P F	, ,	P I		Р	Р	С	С	С	С	С	С	С	С	Baumgartner
	5463	ACM	send indication of airbag failures to IC (CAN)	Wilfling		F	0	Р	В	Р	P	Р	Р	P F)	P I)	Р	Р	С	С	С	С	С	С	С	С	
		SESAM	send terminal status (CAN)	Fuchs		F	F	Р	Р	Р	P I	Р	Р	P F)	P I	,	Р	Р	С	С	С	С	С	С	С	С	
		BCM	Gateway	Zatsch		F	0	Р	F	P	P I	Р	Р	P F)	P I	,	Р	Р	С	C	С	С	С	С	С	С	
	3149	IPC	indication of airbag failures in IC (info to customer)	Müller		0	0	F	F	P	P I	Р	Р	P F) [P I	•	P	Р	С	C	С	С	С	С	С	С	



Function implementation plan





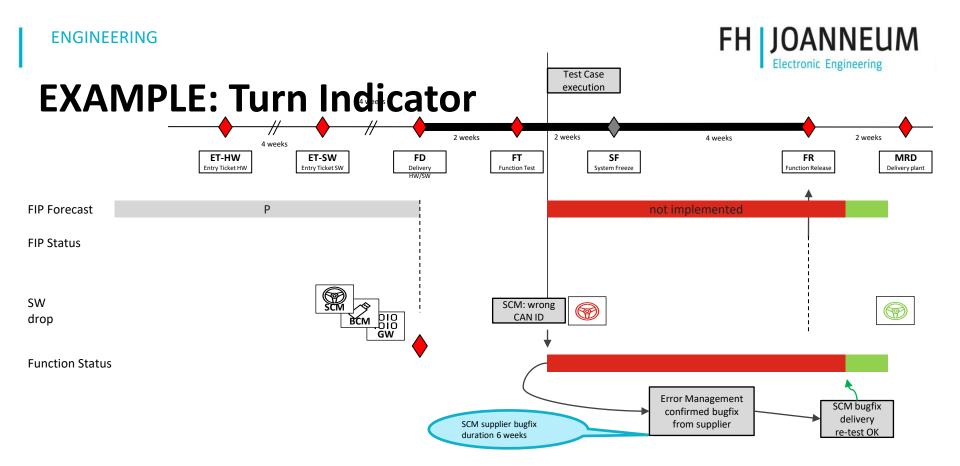
Continuous integration step (CIS)



Challenges and current situation

- Current FRS process not respected by project and supplier (SW delivery dates, test reports, ...)
- Multiple SW deliveries with bad quality, lot of redelivery's (untested) no functional check prior to FRS testing
- HW availability for FRS testing (ECU's, sensors and wiring harness)







Solution: Addition CIS

Process Solution

Implementation of CIS (continuous integration steps)

Ensure strengthen FRS milestone reporting within project and line organization

Ensure test resources for ER-C/ER-I to check SW (Component Acceptance Test, Smoke/Sanity testing)

Enhance FRS process with component test possibility

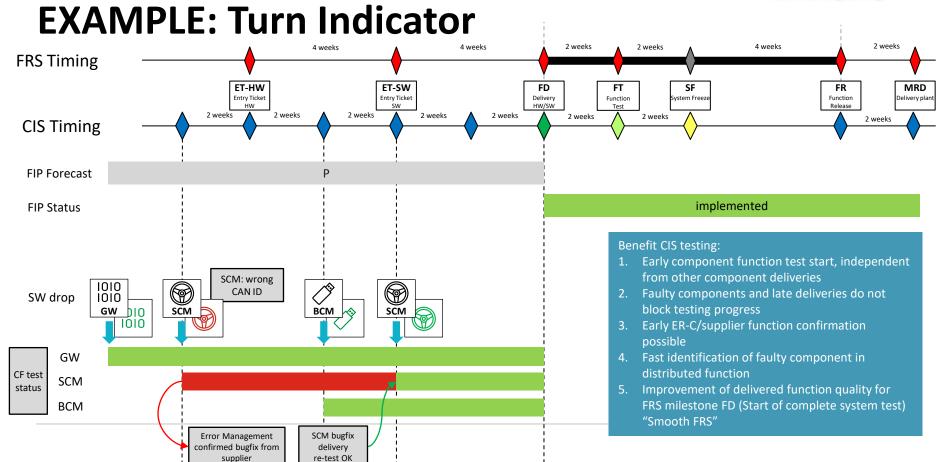
Change mindset of FRS process and release



Technical Solution

Improve Automation level especially for system tests (diagnosis, flashing, ...)
Generate generic work products (test cases, test benches reports, ...)



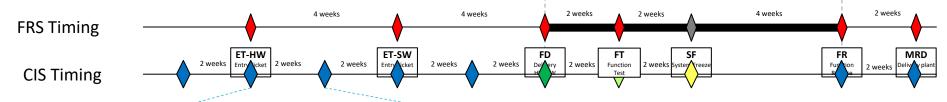


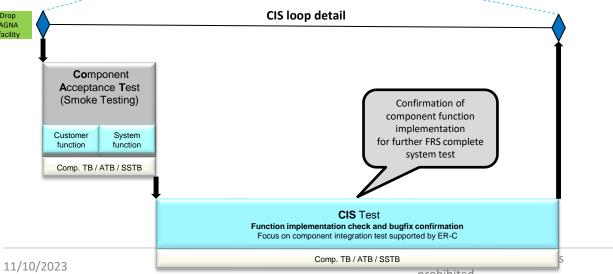
ENGINEERING

SW Drop @MAGNA Test facility

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CIS - Timing





- Regular CIS delivery (changes tested by supplier)
- FRS delivery (fully tested)
- Subsequent delivery 1 (feature & bugfix)
 - Subsequent delivery 2 (bugfix only)

prohibited

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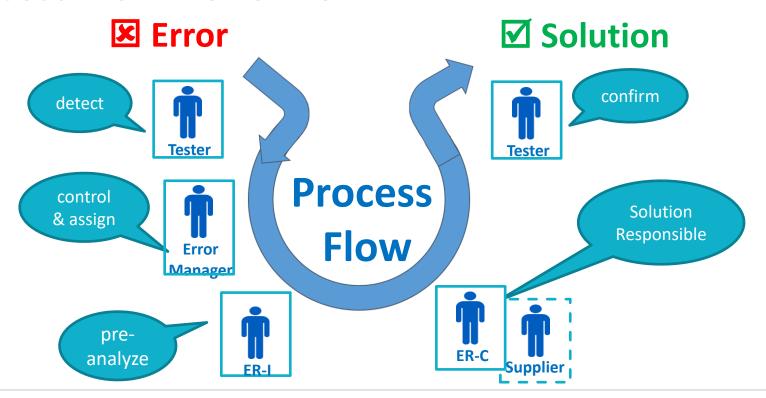
CIS, FRS Interaction 4 weeks 2 weeks 2 weeks 4 weeks 2 weeks FRS Timing ET-HW ET-SW MRD FD Entry Ticket Entry Ticket Delivery Function System Freeze Function Delivery plant SW HW/SW Release Test Early ER-C / supplier function Faulty components and Early component SW delivery confirmation late deliveries do not drop enables early test start of possible block FRS testing component test on Component **SW Drop** progress Testbench, ATB and SSTB, **FRS** independent from other components (e.g. simulated). **CIS** pretested Fast identification of and bug fixed faulty component in **SW Drop** distributed function Improvement of CIS delivered function quality for FRS milestone FD (Start of complete system test) "Smooth **Bugfix Bugfix** FRS" 2 weeks 2 weeks 2 weeks 2 weeks 2 weeks 2 weeks **CIS Timing**



Error management

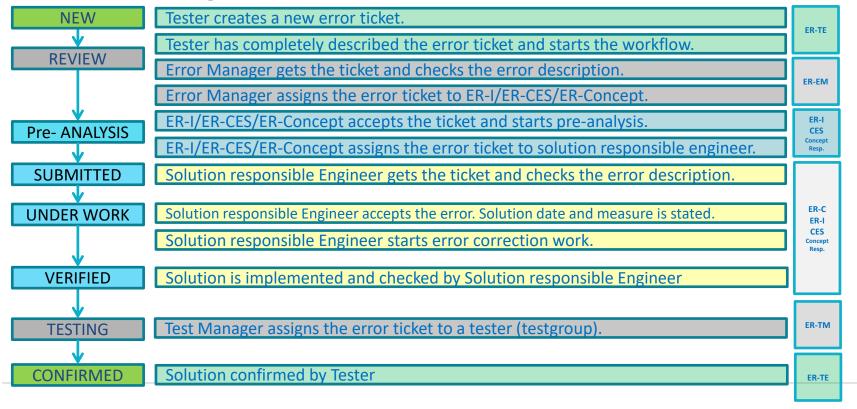


Process Flow - Overview





Error management workflow





Role Tester (ER-TEE)

ER-TEE

Rights:

- Create new error tickets
- Add attachments to existing tickets
- Reject suggested solutions ("error not confirmed")

- Describe the error clearly with all necessary information (traces, pictures, videos)
- Upfront information and clarification with CRE, ER-I if necessary is preferred.
- Observe error tickets "under observation"
- Test error solutions
- Confirm announced error tickets



Role Error Manager (ER-EM)

ER-EM

Rights:

- Assign new tickets to ER-I for pre-ANALYSIS or to Solution Responsible to start the corrective action.
- Reject new error tickets
- Assign the status OBSERVATION, CANCELLED, CLOSED or QUALITY
- Interfere during each error ticket workflow
- Reject suggested solutions ("solution not accepted")

- Assign a Solution responsible for each error ticket
- Check new error tickets regarding its information, sense and completeness.
- Decide further measures for rejected error tickets
- Observe the progress during each error ticket workflow
- Evaluate the error solving process and report it



Role Item-, CES-, Concept - Responsible

ER-I CES Resp. Concept Resp.

Rights:

- Assign the status UNDER WORK and VERIFIED
- Reject assigned error tickets ("error description", "no error" and "not reproducible")

- Accept the ticket and start pre-analysis
- Clearly identify affected component and ITEM function
- Assign ticket to Solution responsible
- Check correctness of Test case
- Assign ticket to test case writer for correction and review result
- Check and correct requirement definition of Item function and Distributed function



Role Solution Responsible (Supplier, ER-C, ER-I, CES Responsible)

ER-C Supplier ER-I, CES-Resp

Rights:

- Assign the status UNDER WORK and VERIFIED
- Reject assigned error tickets ("error description", "no error", "not responsible" and "not reproducible")
- Create new error tickets
- Add attachments to existing tickets

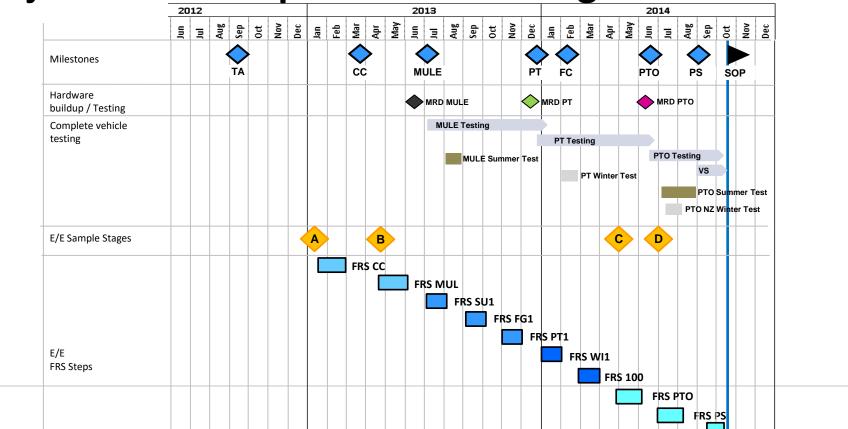
- Inform, Lead and support the supplier during the error solving process.
- Present a solution for the assigned error ticket within time limit.
- Check assigned error tickets regarding its information, sense and completeness.
 Contact and support Tester if error behaviour needs further analysis.
- Detailed error root cause analysis has to be done by supplier, not by Tester.



GATES

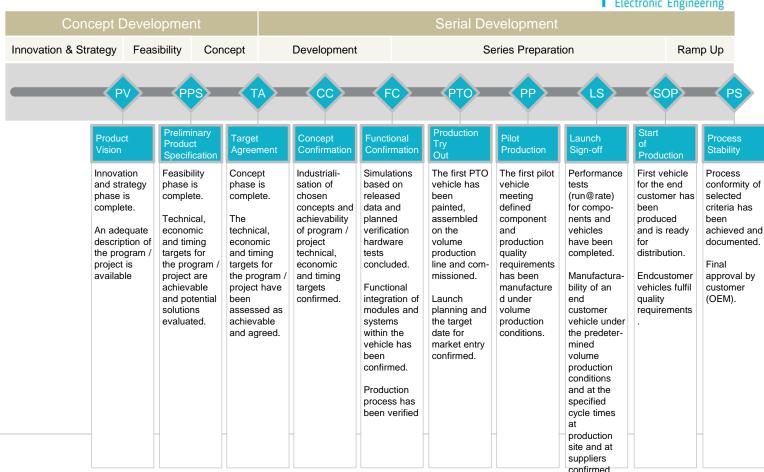


Project xx – Example Master Timing



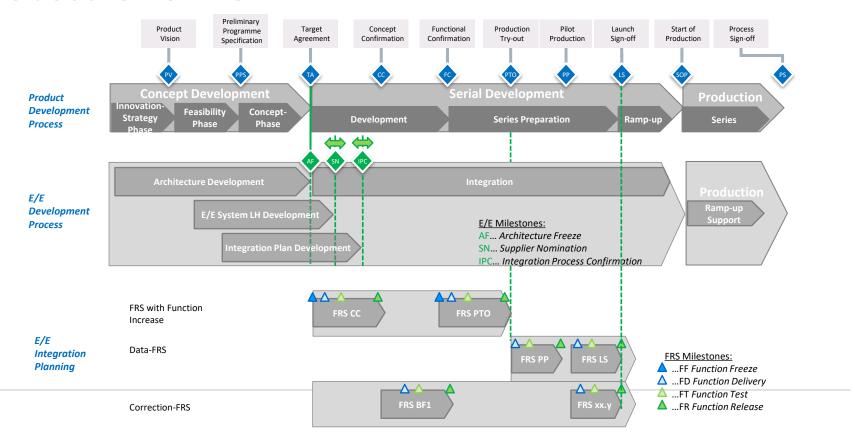
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Gates

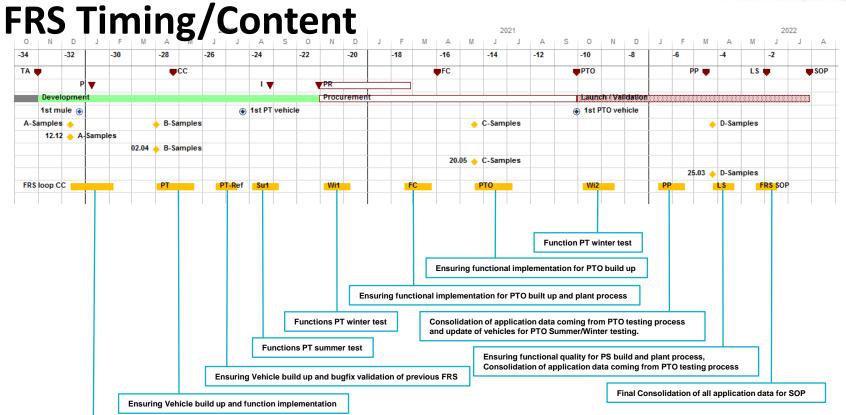




Process Overview







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FRS CC

Goal: Concept confirmation
 First build up (all ECU's, sensors and actuators)

FF

 Function Freeze
 xx.xx.20xx
 xx.xx.20xx

Function Delivery

 xx.xx.20xx

FD FT FR
Function Delivery Function Test Function Release
xx.xx.20xx xx.xx.20xx xx.xx.20xx

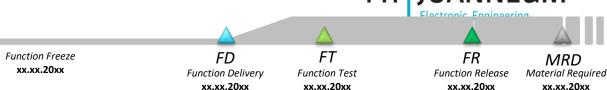
Setup Network test bench testing
Setup Subsystem testing
Setup Lab car testing

- Functional content defined in concept phase
- Testing of network functions of electrical system
- Wiring harness testing: Pinning, color mapping, connector coding, checking of fuse concept
- Confirmation of system function: network communication, bus load, clamp control

Functional confirmation of electrical system especially for new and critical

- Testing done on static test resources: lab car, network test bench and sub system test bench
- Requirements:
 - Customer functions
 - Implementation quality minimum "F" (Firstly implemented)
 - System functions:
 - Diagnostics: HW/SW identification and basic functionality like reading and deleting error memory entries should be at least possible with special supplier tools.
 - Variant coding: At least possible with special supplier tools.
 - Flash programming: At least possible with special developer tools or via CAN.
 - Energy management: Implementation of basic network functionality (Power down)
 - Required HW sample level: A-sample

FRS MUL



Setup

Setup

Setup

Network test bench testing

Subsystem testing

Lab car testing

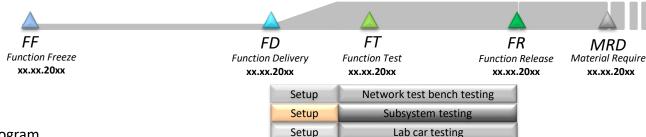
- Goal: Function testing for MULE build program
- Ensuring functional implementation for MULE build and vehicle test program
- Confirmation of system functions: network communication, bus load, clamp control
- Wiring harness testing: Pinning, color mapping, connector coding, fuse concept
- Customer function implementation: Focus on basic functionality necessary to enable a conformable dynamic vehicle test program
- Testing done on static test resources: labcar, network and subsystem test bench
- Requirements:
 - Customer functions: Implementation quality minimum "P" (Prototype testing relevant implemented) for all functions needed for MULE vehicle testing
 - System functions:

data

- Bus communication: All signals implemented according to definition in message catalog.
- Diagnostics: Basic diagnostic functionality implemented and managed by common diagnostic development tool
- Implemented diagnostic jobs must support vehicle first startup process. Provision of corresponding diagnostic description
- Variant coding: At least possible with common development tool
- Flash programming: At least possible with common development tool
- Energy management: Basic network functionality, power down functionality and quiescent current requirements must be implemented
- Required HW sample level: B-sample

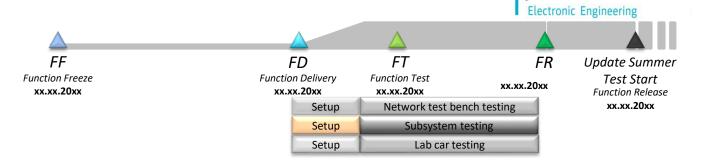


FRS PT



- Goal: Function testing for PT build program
- Testing of basic customer functionality and corresponding functions according agreed implementation planning for PT build and vehicle test program.
- Customer function implementation: Focus on basic functionality necessary to enable a conformable dynamic vehicle test program.
- Monitoring of function growth according to function implementation plan. ~90% of functions should be implemented.
- Requirements:
- Customer functions: Implementation quality minimum "P" (Prototype testing relevant implemented) for all functions needed for PT vehicle testing.
- System functions:
- Bus communication: All signals implemented according to definition in message catalog.
- Diagnostics: Implementation of all jobs necessary for variant coding and flash programming process. Realization of jobs for power down, energy saving, ECU reset needed. Usage of common development tool for Vehicle first startup process.
- Variant coding: Possible with common development tool.
- Flash programming: Possible with common development tool.
- Energy management: Basic network functionality, power down functionality and quiescent current requirements
- Required HW sample level: B-sample

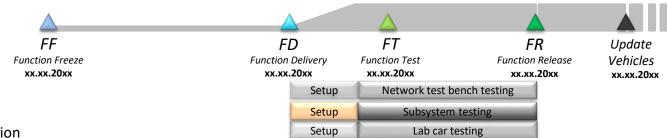
FRS SU/WI



- Goal: Ensuring function implementation and update of MULE-vehicles for Summer/Winter Testing program.
- Realization of additional functions, requested by complete vehicle departments, to ensure update of MULE-vehicles for further test program progress.
- Main testing purpose is to ensure functional growth according definition in implementation planning.
- Requirements:
- Customer functions: Implementation quality minimum "P" (Prototype testing relevant implemented) for all functions needed for MULE vehicle testing.
- System functions:
- Bus communication: All signals implemented according to definition in message catalog.
- Diagnostics: Implementation of jobs necessary for vehicle update process. Usage of common development tool for Vehicle update process.
- Variant coding: At least possible with common development tool.
- Flash programming: At least possible with common development tool.
- Energy management: Basic network functionality, power down functionality and quiescent current requirements must be implemented.
- Required HW sample level: B-sample



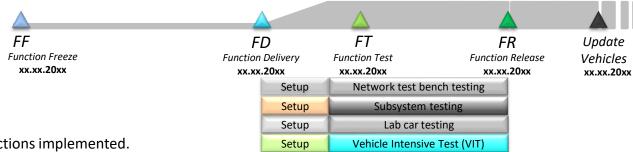
FRS FC



- Goal: Ensuring function confirmation
- Testing of basic customer functionality and corresponding functions according implementation planning for PT build and vehicle test program
- Main testing purpose is to ensure functional growth according definition in implementation planning specially with a view to upcoming PT-build program. ~80% of functions should be implemented
- Requirements:
- Customer functions: Implementation quality minimum "P" (Prototype testing relevant implemented) for all functions needed for upcoming PT vehicle testing
- System functions:
- Bus communication: All signals implemented according to definition in message catalog.
- Diagnostics: Implementation of all jobs necessary for variant coding and flash programming process. Realization of jobs for power down, energy saving, ECU reset. Usage of common development tool for Vehicle update process and upcoming first startup process in PT-build
- Variant coding: Possible with common development tool
- Flash programming: Possible with common development tool
- Energy management: Basic network functionality, power down functionality and quiescent current requirements implemented
- Required HW sample level: B-sample

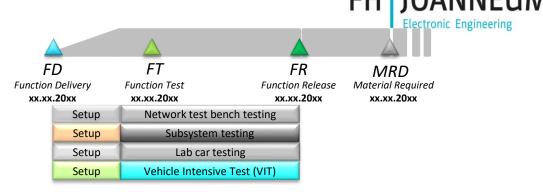
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FRS 100



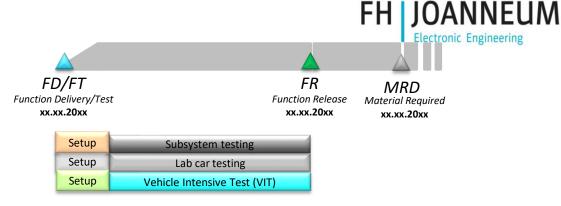
- Goal: 100% Customer and System functions implemented.
- 100% implementation oft Customer and System functions according to implementation planning to fully concentrate on error reduction process until SOP.
- 100% implementation of System functions necessary to start tool evaluation process of production facility and aftersales.
- Requirements:
- Customer functions: Implementation quality minimum "C" (Customer relevant implemented) for all functions.
- System functions:
- Bus communication: All signals implemented according to definition in message catalog.
- Diagnostics: Realization of all Diagnostic jobs (also special jobs!) for development, production and aftersales. All necessary ECU data (diagnostic-, coding- and flash description data for development, production and aftersales has to be provided.
- Variant coding: Realization with production and aftersales tool.
- Flash programming: Realization with production and aftersales tool..
- Energy management: 100% Realization
- Required HW sample level: C-sample (partly B-samples possible)

FRS PTO



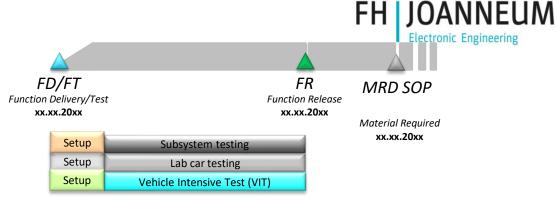
- Goal: Ensuring functional implementation for PTO build and plant process.
- 100% implementation oft Customer and System functions according to implementation planning to fully concentrate on error reduction process until SOP.
- 100% implementation of System functions necessary to start tool evaluation process of production facility and aftersales.
- Requirements:
- Customer functions: Implementation quality minimum "C" (Customer relevant implemented) for all functions.
- System functions:
- Bus communication: All signals implemented according to definition in message catalog.
- Diagnostics: Realization of all Diagnostic jobs (also special jobs!) for development, production and aftersales. All necessary ECU data (diagnostic-, coding- and flash description data for development, production and aftersales has to be provided.
- Variant coding: Realization with production and aftersales tool.
- Flash programming: Realization with production and aftersales tool..
- Energy management: 100% Realization
- Required HW sample level: C-sample (from now on only SW changes allowed!)

FRS PP



- Goal: Ensuring functional quality for PP build and plant process. Consolidation of application data coming from PTO testing process
- 100% implementation oft Customer and System functions according to implementation planning
- Ensuring error free vehicles and build quality
- Consolidation and Validation of all application data coming from PTO testing process.
- Validation and creation oft SW data packages for Pre- series build.
- Requirements:
- Required HW sample level: D-sample

FRS SOP



- Goal: Final Consolidation of all application data for SOP.
- 100% implementation oft Customer and System functions according to implementation planning
- Last chance for parameter delivery for serial build process in plant, starting with SOP.
- Consolidation and Validation of all application data coming from VS testing process.
- Validation and creation oft SW data packages for Series build.
- Requirements:
- Completion of function application data process and final data file delivery to system integration department.



Real life example

FH JOANNEUM Electronic Engineering

Program Grenadier E

Customer: INEOS Automotive

Platform / Product: NEW BEV

Market: US EU CHN

> Timing SOP: EU 05/2026

Lifetime volume: 335.000

Production Location: MSF Graz

Magna Steyr project phases / timeline

Pre-Feasibility Phase

Feasibility Phase

Concept development

Serial development

Procurement

Launch validation

04/2022 - 09/2022 (6 months)

09/2022 - 01/2023 (5 months)

02/2023 - 09/2023 (7,5 months)

09/2023 – 05/2024 (8,5 months)

05/2024 - 04/2025 (10,5 months)

04/2025 - 05/2026 (13 months until SOP EU) / US+ 4 months / CHN +4 months





Key Specs

Unibody from Steel (No Frame)

Ground Clearance 250 mm

Curb Weight 2740kg (EU regulation)

Battery Size ~100kWh

> Range >=400km (WLTP)

Fast Charge Speed >=200kW

Electric Engines 2

> Total Power >360kW (~480hp)

> Top Speed 160km/h

Diff Locks: Front + Rear + (Mid)

Wheel Travel +-110mm (Front/Rear)

➤ Wading 650 mm

Suspension: Double Wishbone (Front)

Multi-Link (Rear)



TARGET VALUE VTS:

Approach Angle >30°

Departure Angle >33°

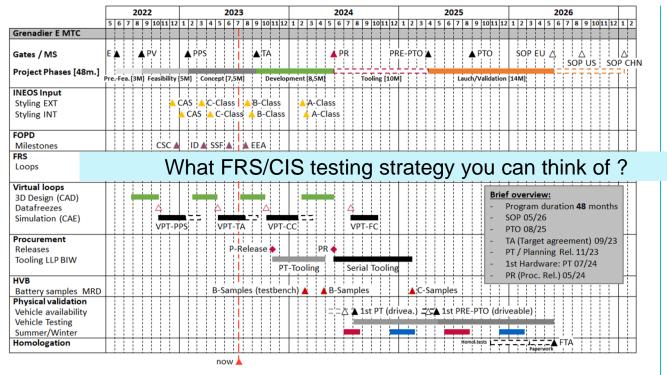
Ramp Angle >20°

ENGINEERING



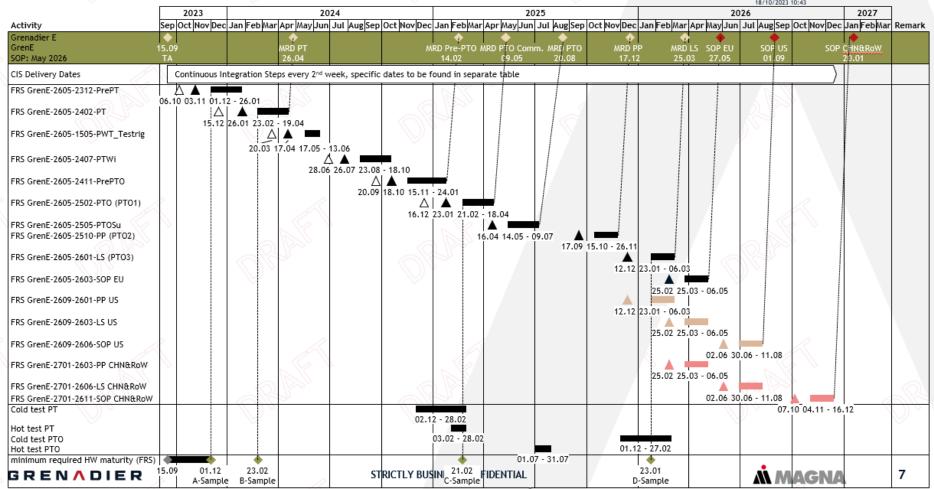


- > SOP US 09/2026
- > SOP CHN/ROW 01/2027



FRS PLAN - OVERVIEW - GRENADIER E

FRS Plan v. 1.1





Validation GrenE

Testbenches in GRENE

For FRS PrePT (01.12.2023)

following test benches planned:

1 NWTB

1 ATB

1 Body SSTB

1 HV/Powertrain

For FRS PT (23.02.2024) all test benches planned.

I-Team	Department	Amount		
140	EE_SV	1	NWTB FV	
140	EE_SV	3	ATB Automated Test Bench	
140	EE_SV	1	SSTB Body /Comfort	
140	EE_SV	1	SSTB Infotainment/HMI	
140	EE_SV	1	SSTB Chassis / ADAS	
140	EE_HV	1	SSTB HV/ Powertrain	
140	EE_SV	1	NWTB Cyber Security	
140	EE_SV	1	NWTB OTA	
140	EE_SV	2	Labcar static	
140	EE_SV	1	Labcar dynamisch	
140	EE_SV	4	VIT vehicles	VIT: PT2B_053 - M1 Lifestyle LHD EU PT2B_054 - M1 Halo Offroad RHD EU PT2B_055 - M1 Lifestyle LHD US PT2B_056 - M1 Halo Offroad LHD EU Module vehicles: PT2B_057 - M1 Lifestyle LHD China PT2B_058 - M1 Lifestyle LHD US (HU Supplier) PT2B_080 - M1 Entry LHD China PT2B_059 - M1 Lifestyle LHD US
59	EE_DF	1	SSTB ADAS (ADAS HIL)	
51	EC_FI2	1	SSTB Road to Rig	also used from I-Team 140



CIS Timing

Every 2 weeks CIS start since 15.09.2023

No ECU participation due to nomination status

Currently only residual bus simulation testing possible du to high effort on test bench frame sourcing.

GRENADIER E - CIS TIMING									FRS Plan v. 1.1			
	Grenadier E - Name	Start Date	End Date	Grenadier E - Name	Start Date	End Date	Grenadier E - Name	Start Date	End Date	Grenadier E - Name	Start Date	End Date
	CIS 1	15.09.2023	28.09.2023	CIS 18	09.08.2024	22.08.2024	CIS 35	23.07.2025	05.08.2025	CIS 51	06.05.2026	19.05.2026
	CIS 2	29.09.2023	12.10.2023	CIS 19*	23.08.2024	05.09.2024	CIS 36	06.08.2025	19.08.2025	CIS 52	20.05.2026	02.06.2026
	CIS 3	13.10.2023	25.10.2023	CIS 20 *	06.09.2024	19.09.2024	CIS 37	20.08.2025	02.09.2025	CIS 53	03.06.2026	16.06.2026
	CIS 4	27.10.2023	09.11.2023	2605-PTWi	23.08.2024	18.10.2024	CIS 38	03.09.2025	16.09.2025	CIS 54	17.06.2026	30.06.2026
	CIS 5	10.11.2023	23.11.2023	CIS 22	18.10.2024	31.10.2024	CIS 39	17.09.2025	30.09.2025	CIS 55 *	01.07.2026	14.07.2026
	CIS 6 *	24.11.2023	07.12.2023	CIS 23	02.11.2024	15.11.2024	CIS 40	01.10.2025	14.10.2025	CIS 56 *	15.07.2026	27.07.2026
	CIS 7 *	08.12.2023	21.12.2023	CIS 24 *	16.11.2024	29.11.2024	CIS 41*	15.10.2025	28.10.2025	2609-SOP US	30.06.2026	11.08.2026
	2605-PrePT	01.12.2023	26.01.2024	CIS 25 *	30.11.2024	13.12.2024	CIS 42 *	29.10.2025	11.11.2025	CIS 57	11.08.2026	24.08.2026
	CIS 8	26.01.2024	08.02.2024	2605-PrePTO	15.11.2024	24.01.2025	2605-PP (PTO2)	15.10.2025	26.11.2025	CIS 58	25.08.2026	07.09.2026
	CIS 9	09.02.2024	22.02.2024	CIS 26	24.01.2025	06.02.2025	CIS 43	26.11.2025	09.12.2025	CIS 59	08.09.2026	21.09.2026
	CIS 10 *	23.02.2024	07.03.2024	CIS 27	07.02.2025	20.02.2025	CIS 44	10.12.2025	23.12.2025	CIS 60	22.09.2026	05.10.2026
	CIS 11 *	08.03.2024	21.03.2024	CIS 28 *	21.02.2025	06.03.2025	CIS 45	10.01.2026	23.01.2026	CIS 61	06.10.2026	19.10.2026
	2605-PT	23.02.2024	19.04.2024	CIS 29 *	07.03.2025	20.03.2025	CIS 46 *	24.01.2026	06.02.2026	CIS 62	20.10.2026	02.11.2026
	CIS 12	19.04.2024	02.05.2024	2605-PTO (PTO1)	21.02.2025	18.04.2025	CIS 47*	07.02.2026	19.02.2026	CIS 63 *	03.11.2026	16.11.2026
	CIS 13	03.05.2024	16.05.2024	CIS 30	18.04.2025	30.04.2025	2605-LS (PTO3)	23.01.2026	06.03.2026	CIS 64 *	17.11.2026	30.11.2026
	2605-PWT_testrig	17.05.2024	13.06.2024	CIS 31	02.05.2025	15.05.2025	CIS 48	06.03.2026	19.03.2026	2701-SOP CHN&RoW	04.11.2026	16.12.2026
	CIS 14	14.06.2024	27.06.2024	CIS 32 *	16.05.2025	29.05.2025	CIS 59 *	20.03.2026	02.04.2026			
	CIS 15	28.06.2024	11.07.2024	CIS 33 *	30.05.2025	12.06.2025	CIS 50 *	03.04.2026	16.04.2026			
	CIS 16	12.07.2024	25.07.2024	2605-PTOSu	14.05.2025	09.07.2025	2605-SOP EU	25.03.2026	06.05.2026			
	CIS 17	26.07.2024	08.08.2024	CIS 34	09.07.2025	22.07.2025						

^{*} Support of FRS testing (no additional function implementation allowed)



Validation GrenE

FRS GrenE-2605-2312-PrePT / FRS GrenE-2605-2402-PT

Function testing of all ECUs for PT build up.

Focus: System Functions Bus communication, Diagnose, Flashing, Coding, Energy and Network management.

FUSA and CS requirements to be implemented but show only result in a DTC entry.

FRS GRENE-2605-1505-PWT Testrig

Function testing of PWT Testrig components to ensure PT commissioning.

Focus: HVB and HV environment, VCU, ESC, EDU EPS and iBooster.

FRS GrenE-2605-2407-PTWi

Function testing of all ECUs for PT test program (e.g., cold test).

Focus: Function Growth, E2E Protection, Security Access.

FRS GrenE-2605-2411-PrePTO

Function testing of all ECUs for PTO build up. Ensure function growth.

Focus: 100% Customer and System functions implemented, SecOC, FuSa, Signature Validation, OTA.

FRS GrenE-2605-2502-PTO (PTO1)

100% Customer and System functions implemented. Ensure function growth.

Focus: 100% Customer and System functions implemented, SecOC, FuSa, Signature Validation, OTA, Downgrade protection.

FRS GrenE-2605-2505-PTOSu

Function testing of all ECUs for PTO test program (e.g., hot test).

Focus: Bugfixing, Deactivation of Security Access and Signature Validation not allowed.

FRS GrenE-2605-2510-PP (PTO2)

Ensuring functional implementation for PP build and plant process.

Focus: Bugfixing, End2End Protection, Security Access, Signature Validation, SecOC, FuSa Functions and Downgrade Protection active. SecOC with Serial Keys. (No deactivation possible anymore!)

FRS GrenE-2605-2601-LS (PTO3)

Ensuring functional quality for LS build and plant process. Consolidation of application data coming from

PTO/PP testing process.

Focus: Bugfixing

FRS GrenE-2605-2603-SOP EU

Final Consolidation of all application data for SOP EU.

Focus: Bugfixing