

# Object and Feature Detection

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# Overview

**Deep learning algorithms and AI rely on images and videos as input**

**Proper choice of features is key**

**Image descriptors to summarize important features**

**Denoising images before feature extraction**

**Process images to fill holes and highlight peaks**

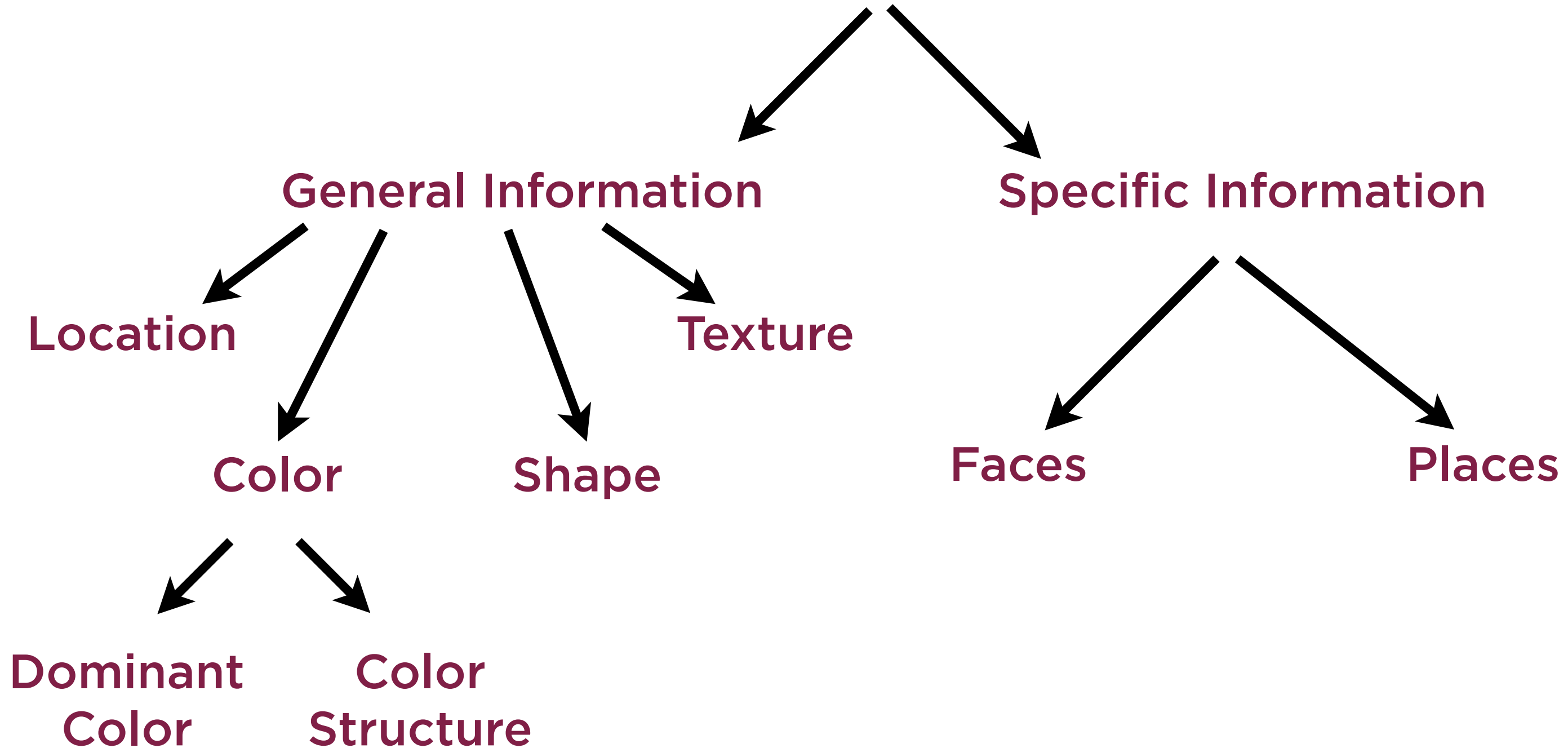
# Image Descriptor

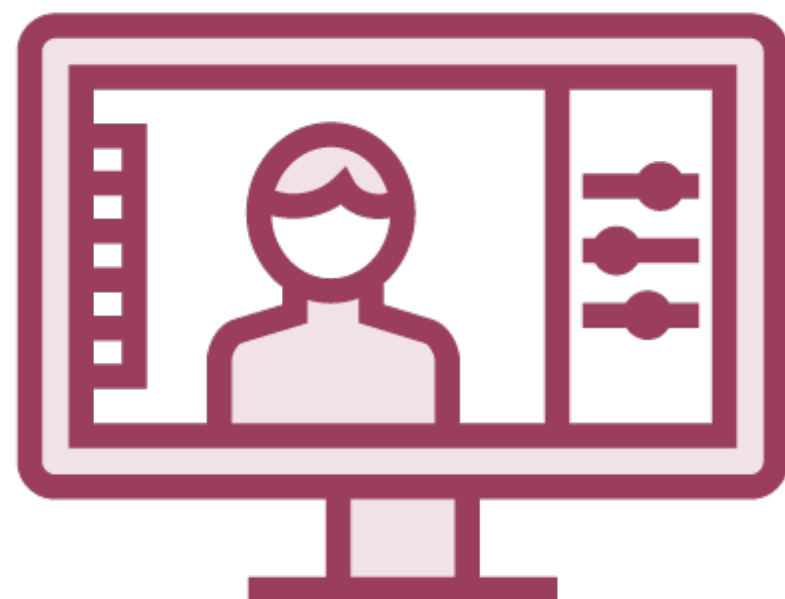
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# Image Descriptor

Descriptions of the key features of images.

# Image Descriptors





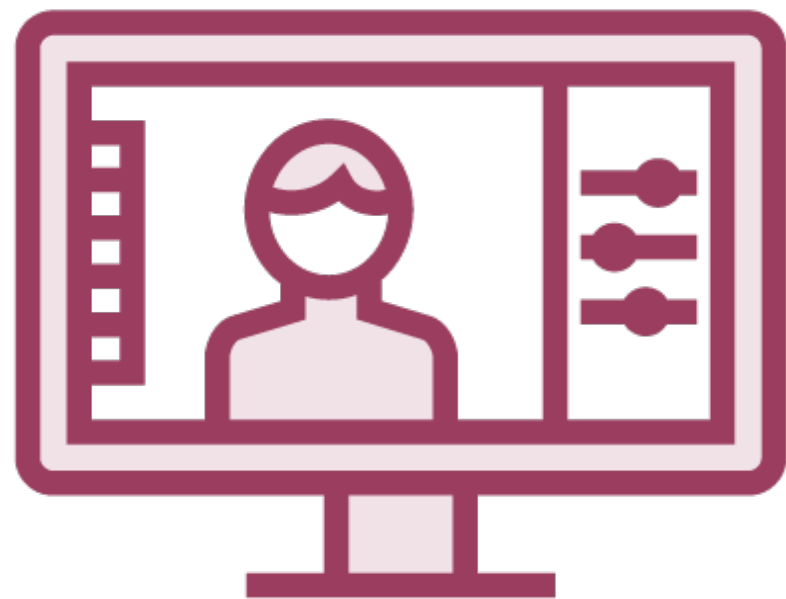
# Image Descriptors

**Scale /nvariant *Feature Transform* (SIFT)**

**DAISY descriptors**

# Scale Invariant Feature Transform (SIFT)

Feature detection algorithm used to detect and describe features in images in a manner robust to translation, scaling and rotation



# SIFT

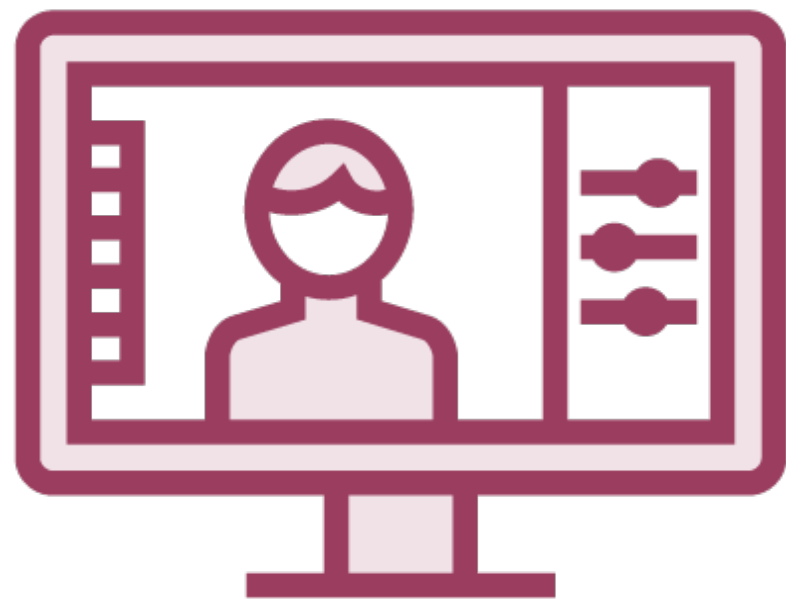
**Start with corpus of reference images**

**Analyze and store descriptors**

**For new images, compare to corpus**

**Find matches with corpus database**





# SIFT

**Invariant to scale and rotation**

**Robust against changes in illumination,  
noise and viewpoint**

**Highly distinctive**

**Robust to partial occlusion**

# SIFT

## Scale Invariant Feature Detection

Convert images to large  
number of feature vectors

## Cluster Identification

Given a fresh image, use Hough  
Transform to find all keys in corpus  
that this image matches

## Outlier Detection

Eliminate all feature vectors that  
are too far from original image

## Feature Matching and Indexing

Efficiently store those feature  
vectors for fast key-based lookup

## Model Verification

Minimize least square distance from  
original image and its feature  
vectors

Demo

**Feature extraction using DAISY  
descriptors**

# DAISY Descriptor

Feature selection algorithm, conceptually similar to SIFT, but faster and works with lower dimensionality feature vectors.

# DAISY Algorithm

**Also used for feature extraction**

**Dimensionality reduction**

- Robust normalization
- Followed by PCA (Principal Components Analysis)

Demo

Feature description using HOG (Histogram  
of Oriented Gradients)

# Histogram of Oriented Gradients

Feature descriptor used for object detection.

# HOG

## Image Normalization

Eliminate effects of illumination and shadows

## Compute Histograms

Group cell histograms into larger, spatially connected blocks; aggregate into HOG by voting

## Object Recognition

Use histogram blocks as feature vectors in your preferred ML algorithm

## Compute Gradients

Use simple first order gradients to find contour, silhouette and texture

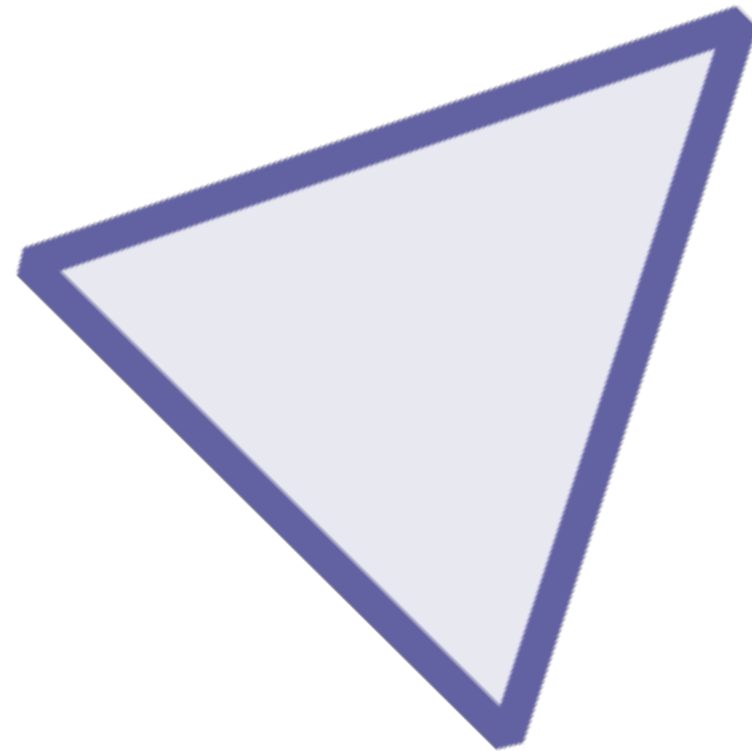
## Block Normalization

Divide each histogram block by L-1 norm or L-2 norm to normalize



Demo

**Corner detection**

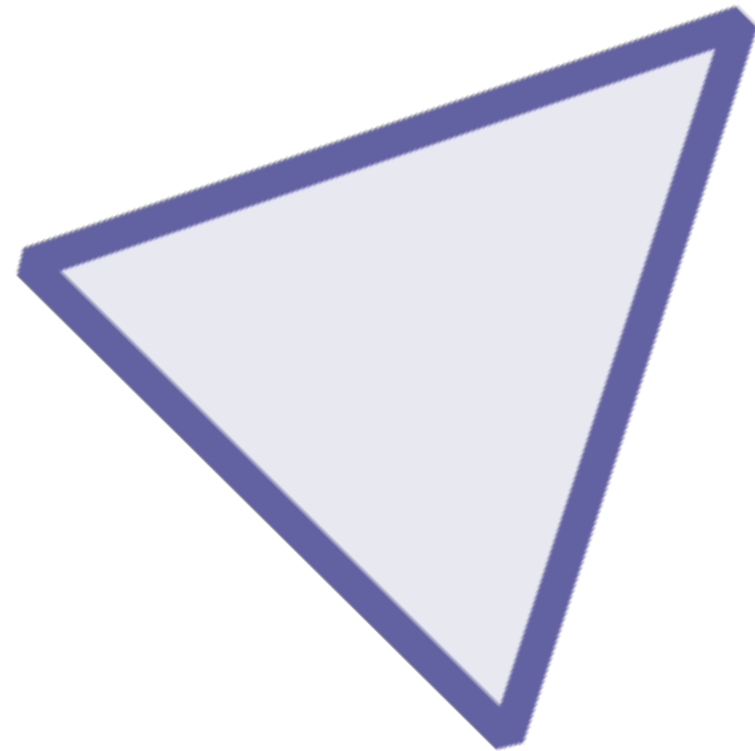


# Corner Detection

**Interest point = Point with well-defined position that can be clearly defined**

## **Types of interest points**

- Corners: Intersection of two edges
- Intensity maxima/minima
- Line endings



# Corner Detection

**Find **cornerness** measure for each pixel**

- Low self-similarity, different from nearby points

**Apply threshold to suppress weak corners**

**Remaining points are marked as corners**

# Noise

Random variations in images due to lighting variations, camera electronics, surface reflectance and lens.

# Denoising

Process of removing noise from images, usually through the use of filters.

# Filters for Denoising

**Total variation filter**

**Bilateral filter**

**Wavelet denoising  
filter**

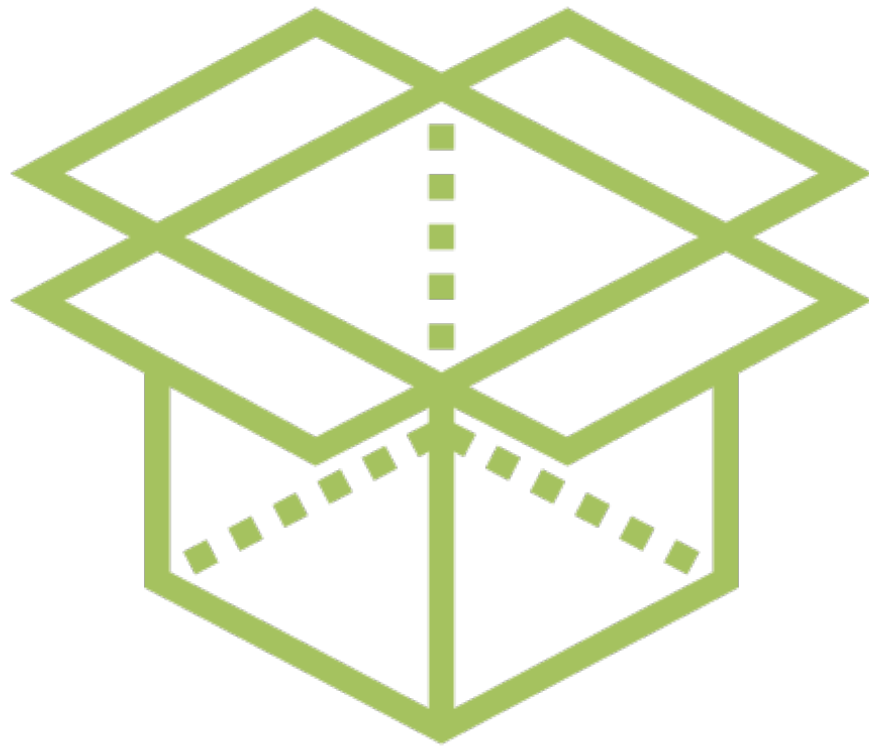


# Total Variation Filter

**Based on the principle that signals with noise have high total variation**

**Reducing total variation brings image closer to original**

# Bilateral Filter



**Edge-preserving and noise reducing filter**

**Depends on differences in color intensity, depth distance**



# Wavelet Denoising Filter



**Transform image using wavelet transform**

**Concentrates signal and image features into a few large magnitude coefficients**

**Shrinks noise, preserves important features**

**Preserves image quality**

Demo

**Image denoising**

# Morphological Reconstruction

A useful but little-known method for extracting meaningful information about shapes in an image.

# Morphological Reconstruction

**Extract marked objects**

**Find bright regions surrounded by dark**

**Remove objects**

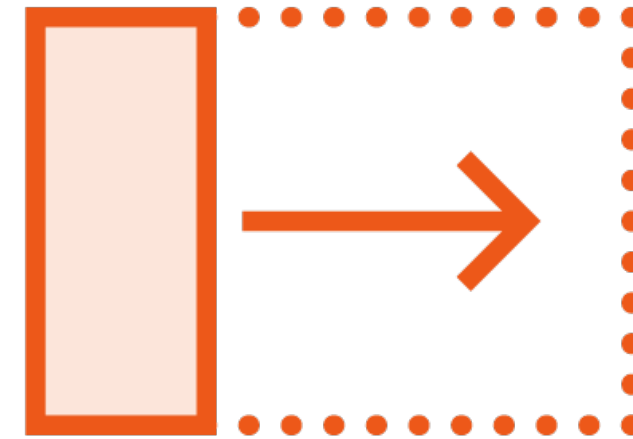
**Fill holes**

# Basic Morphological Operations



**Erosion**

Shrink connected sets

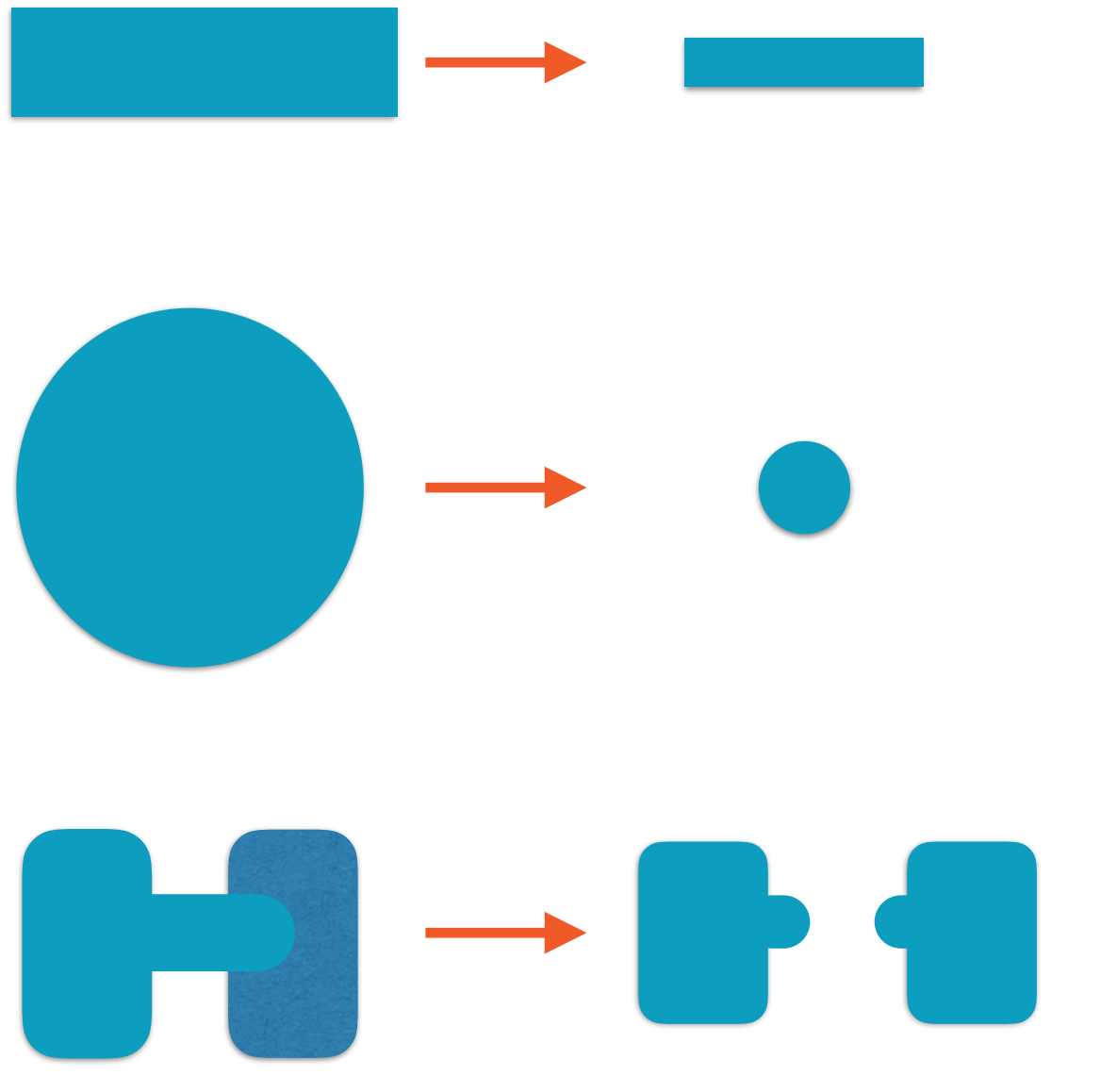


**Dilation**

Expand connected sets

Both dilation and erosion involve the use of a mask known as a  
**Structural Element**

# Erosion



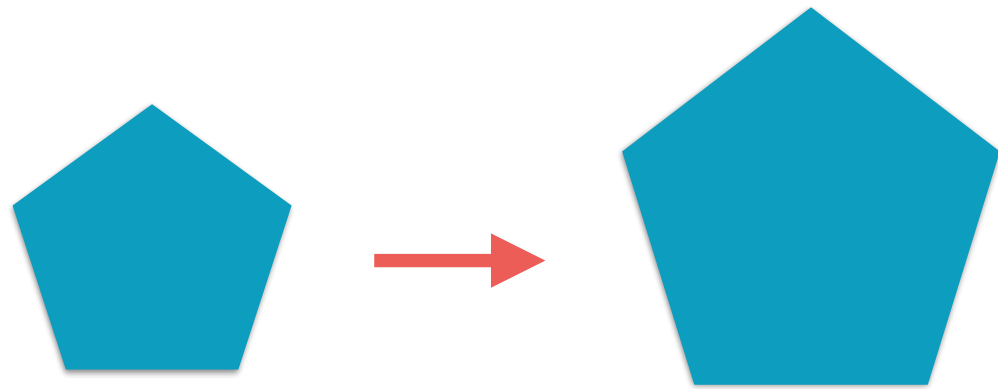
## **Shrinks objects**

- Removes pixels from boundaries

## **Can be used for**

- Shrinking features
- Removing bridges, branches, small protrusions

# Dilation

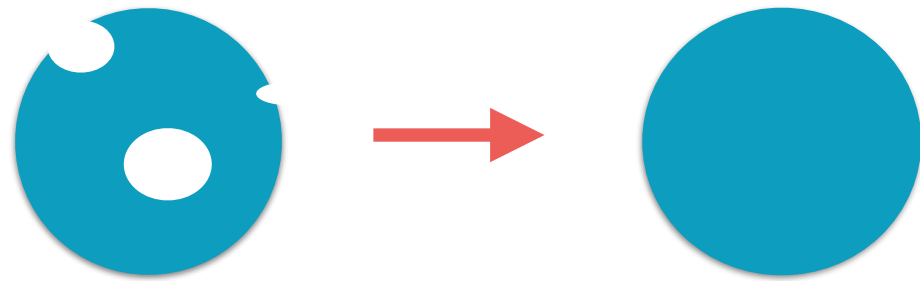


## **Expands objects**

- Adds pixels to boundaries

## **Can be used for**

- Growing features
- Filling holes and gaps



Demo

**Dilation and erosion**



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