

# EE3025 IDP

## Assignment-1

Download all python codes from

[https://github.com/Sivanidevarapalli26/EE3025\\_IDP/tree/main/Assignment-1/Codes](https://github.com/Sivanidevarapalli26/EE3025_IDP/tree/main/Assignment-1/Codes)

and latex-tikz codes from

[https://github.com/Sivanidevarapalli26/EE3025\\_IDP/tree/main/Assignment-1](https://github.com/Sivanidevarapalli26/EE3025_IDP/tree/main/Assignment-1)

### 1 QUESTION

1.1. Let

$$x(n) = \left\{ \underset{\uparrow}{1}, 2, 3, 4, 2, 1 \right\} \quad (1.1.1)$$

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2) \quad (1.1.2)$$

Compute

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (1.1.3)$$

and  $H(k)$  using  $h(n)$ .

### 2 SOLUTION

2.1. When Unit impulse signal is given as input to the LTI system then its impulse response is the output of the system. So, from equation (1.1.2) we can say that the Impulse response of the system is,

$$h(n) + \frac{1}{2}h(n-1) = \delta(n) + \delta(n-2) \quad (2.1.1)$$

2.2. Given that DFT of a Input Signal  $x(n)$  is :

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (2.1.2)$$

2.3. Similarly, DFT of Impulse Response  $h(n)$  is,

$$H(k) \triangleq \sum_{n=0}^{N-1} h(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (2.1.3)$$

2.4. Python Code to compute the DFT of  $x(n)$  and  $h(n)$  is given below

[https://github.com/Sivanidevarapalli26/EE3025\\_IDP/blob/main/Assignment-1/Codes/ee18btech11012.py](https://github.com/Sivanidevarapalli26/EE3025_IDP/blob/main/Assignment-1/Codes/ee18btech11012.py)

2.5. From the above code we get the following plots.

[https://github.com/Sivanidevarapalli26/EE3025\\_IDP/tree/main/Assignment-1/figs](https://github.com/Sivanidevarapalli26/EE3025_IDP/tree/main/Assignment-1/figs)

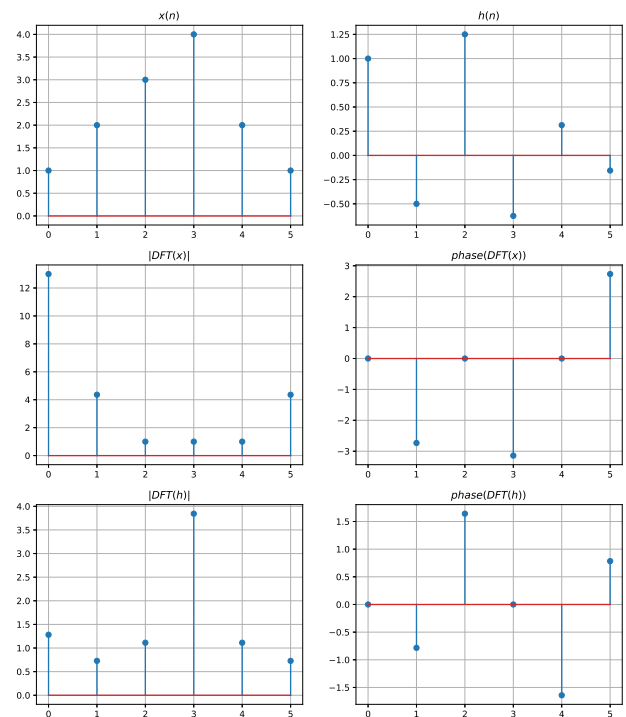


Fig. 2.1: Plots of  $x(n)$  and  $h(n)$ , their DFTs