Control Systems

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1 Feedback circuits

Abstract—This manual is an introduction to control systems in feedback circuits. Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/control/feedback/codes

1 FEEDBACK CIRCUITS

1.0.1. Consider an op amp having a single pole open loop response $G_o = 10^5$ and $f_p = 10$ Hz.Let op amp be ideal connected in non-inverting terminal with a nominal low frequency of closed loop gain of 100 and wired as a unity gain buffer.

Find the frequency at which |GH| = 1 and What is its corresponding phase margin **Solution:** For a single-pole amplifier, open loop transfer function is

$$G(s) = \frac{G_o}{1 + \frac{s}{\omega_n}} \tag{1.0.1.1}$$

Given that $f_p = 10$ Hz and $G_o = 10^5$

$$G(s) = \frac{G_o}{1 + \frac{s}{2\pi f_o}} \implies \frac{10^5}{1 + \frac{s}{2\pi . 10}}$$
 (1.0.1.2)

So,the open-loop gain of the op amp is

$$G(s) = \frac{10^5}{1 + \frac{s}{2\pi 10}}$$
 (1.0.1.3)

For a unity-gain buffer, the feedback factor is

$$H = 1$$
 (1.0.1.4)

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Thus,

$$G(j\omega)H = \frac{10^5.1}{1 + \frac{j\omega}{2\pi.10}}$$
 (1.0.1.5)

To find the frequency at which $|G(j\omega)H| = 1$, we write

$$\left|\frac{10^5.1}{1 + \frac{J\omega}{2\pi.10}}\right| = 1\tag{1.0.1.6}$$

$$1 + \frac{\omega_1^2}{2\pi \cdot 10} = 10^{10} \tag{1.0.1.7}$$

Thus

$$\omega_1 = 6.283 Mrad/sec \implies f_1 = \frac{\omega_1}{2\pi} = 1 MHz$$

$$(1.0.1.8)$$

From definition of phase margin $\alpha = 180^{\circ} + \phi$ where ϕ is the phase of $G(j\omega_1)H$

$$\phi = -\tan^{-1}\left(\frac{\omega_1}{2\pi \ 10}\right) \tag{1.0.1.9}$$

At $\omega_1 = 2\pi . 10^6 rad/sec$

$$\phi = -\tan^{-1}\left(2\pi.10^6 2\pi.10\right) \tag{1.0.1.10}$$

$$\implies \phi = -90^{\circ}(approx) \qquad (1.0.1.11)$$

Therefore, the phase margin is

$$\alpha = 180 + \phi \implies \alpha = 180^{\circ} - 90^{\circ} \implies \alpha = 90^{\circ}$$

$$(1.0.1.12)$$

Hence for frequency f = 1MHz Hz, |GH| = 1 and phase margin is 90°

1.0.2. The following is the code for bode plot of the given system

1.0.3. Verification using Bode plot

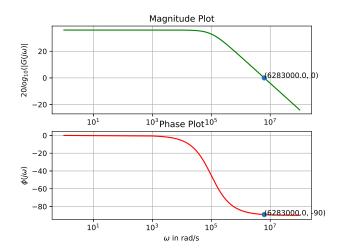


Fig. 1.0.3