

## 0.1 Basics

**Topological space:** defined as a set of points, along with a set of neighborhoods.

Satisfy a set of axioms relating the points and the neighborhood.

Motivation: most general notion of a mathematical space that allows for

- continuity,
- connectedness,
- convergence

Extension: manifolds, metric spaces, etc

Commonly used: defined in terms of open sets.

More intuitive: neighborhoods.

$X$  a set, together with  $\mathbf{N} : X \mapsto 2^{2^X}$ ,  $N \in \mathbf{N}(x)$  is a neighborhood of  $x$ , satisfying

1. Point in its own neighborhood;
2. Superset of neighborhood is a neighborhood,  $N \subseteq M \implies M \in \mathbf{N}(x)$ ;
3. Intersection of neighborhoods is a neighborhood,  $\forall N, M \in \mathbf{N}(x), N \cap M \in \mathbf{N}(x)$
4.  $\forall N \in \mathbf{N}(x) \exists M, s.t. y \in M \implies N \in \mathbf{N}(y)$

Open sets:  $x \in U \implies U \in \mathbf{N}(x)$

Equivalent definition with respect to open sets:

$(X, \tau), \tau \subseteq 2^{2^X}$ , satisfying:

1.  $\emptyset, X \subseteq \tau$
2.  $N_i \in \tau, \bigcup_i N_i \in \tau$
3.  $N_i \in \tau, \bigcap_i N_i \in \tau, i$  finite

These are called open sets.

**Continuous:** the inverse image of every open set is an open set.

**Homotopy:** Intuitively from the idea of continuous deformation; is strictly weaker than homeomorphism.

## 0.2 Homology

Intuitive view:

**Path:** continuous map  $[0, 1] \mapsto X$ ;  $x \sim y$  if  $\gamma(0) = x, \gamma(1) = y$ .

This is clearly an equivalence relation. Therefore, the path connected components of  $X$  are equivalence classes under  $\sim$ .

### 0.2.1 Simplicial Complexes

General idea is that simplicial complexes extend the notion of graph to include higher dimensional components in it.

Turn simplicial complexes to topological spaces: "embed" it into Euclidean space.

Embedding: map points to coordinates and all points affinely independent.

Induced map:  $\hat{f} : K \rightarrow 2^{\mathbb{R}^d}, \{v_0, v_1, \dots, v_r\} \mapsto \text{Conv}(f(v_0), \dots, f(v_r))$

All embeddings  $f : K \rightarrow \mathbb{R}^d, g : K \rightarrow \mathbb{R}^{d'}, \hat{f}$  and  $\hat{g}$  are homeomorphic.