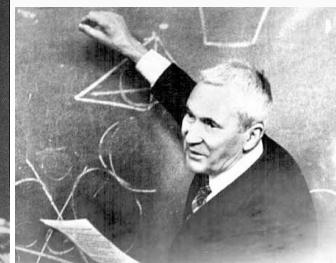
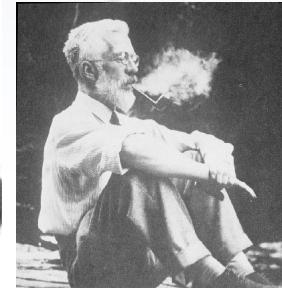
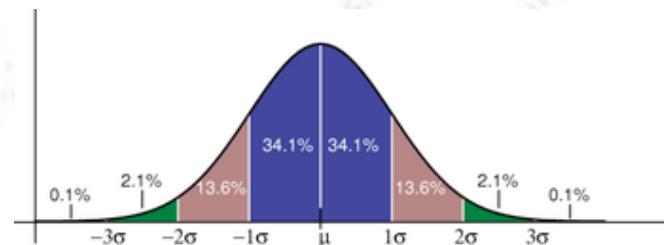


# Applied Statistics

## Mean and Width



Troels C. Petersen (NBI)



*“Statistics is merely a quantisation of common sense”*

# Mean & Width

## Applied Statistics

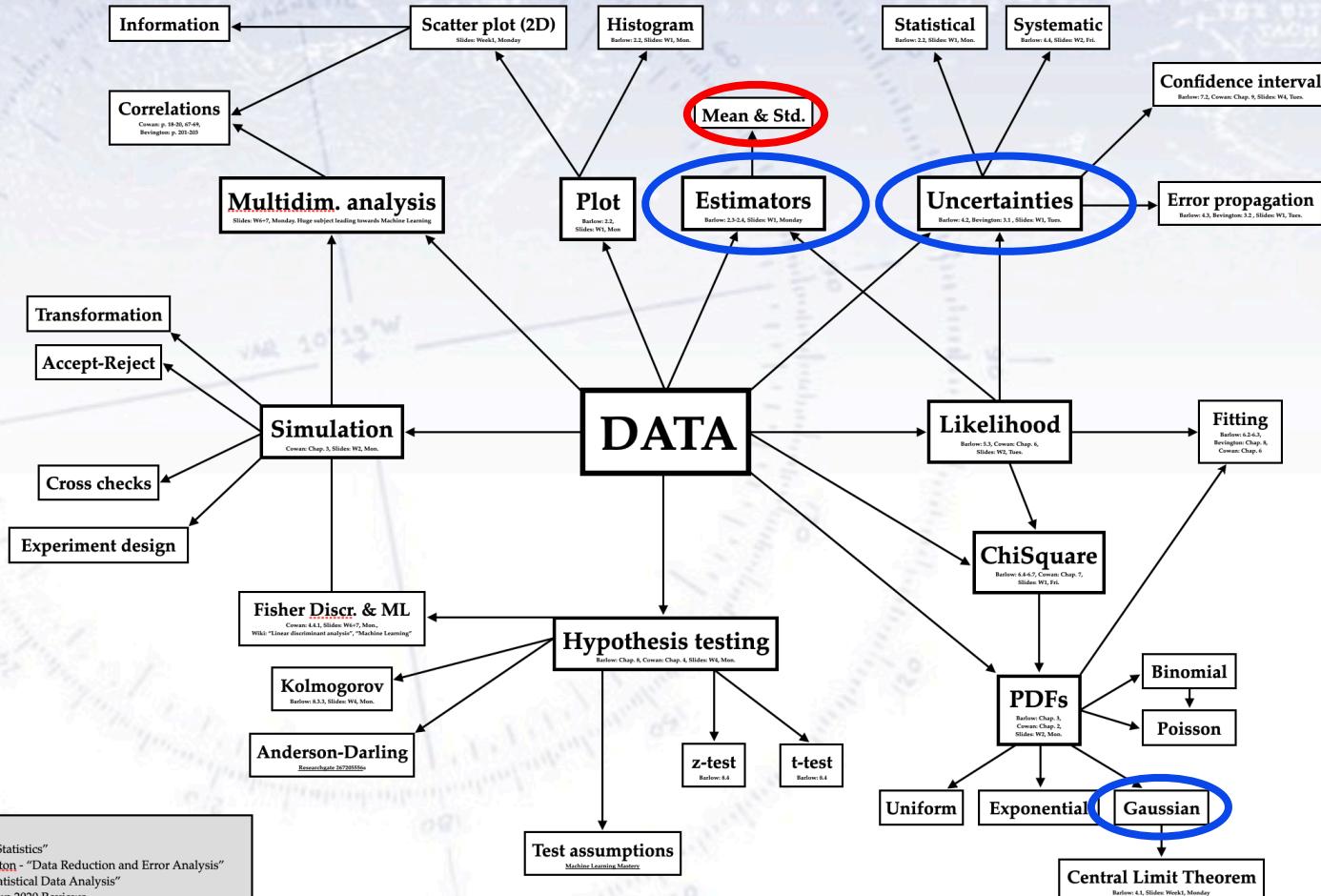
Describe data (Quantify & Visualise)

## Overview of subjects

Version 1.2, 6. Nov. 2020

Simulate data (Design & Cross Check)

Model data (Predict & Understand)



References:

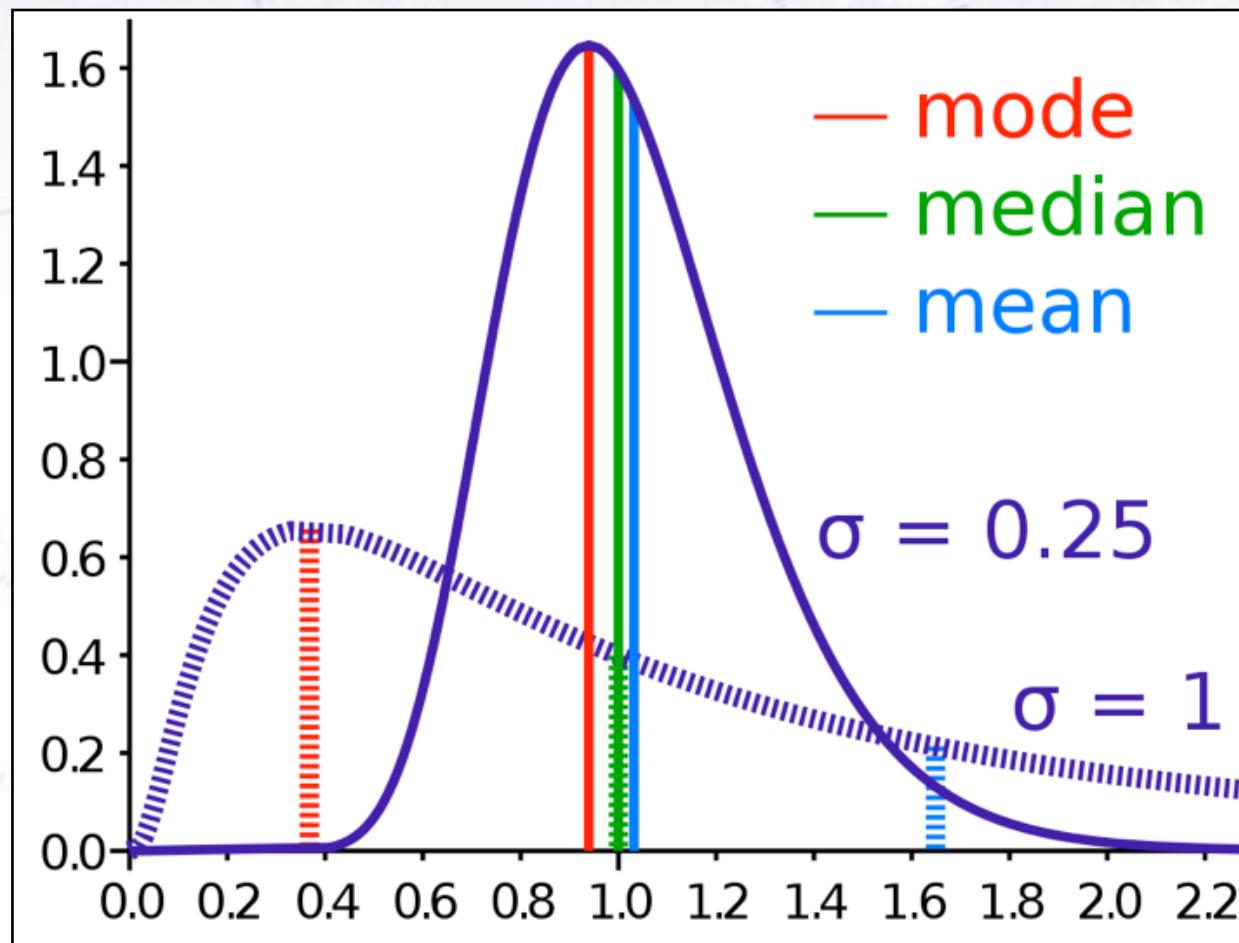
- Barlow: R. J. Barlow - "Statistics"
- Bevington: P. H. Bevington - "Data Reduction and Error Analysis"
- Cowan: G. Cowan - "Statistical Data Analysis"
- PDG: Particle Data Group 2020 Reviews
- Slides: T. C. Petersen - "Applied Statistics 2020" course (W = Week)
- Wiki: Good reference for ALL subjects (only specified when essential)
- SciPy: SciPy Statistical Functions and (very brief) documentation

Test hypotheses on data (Decide)

# Defining the mean

There are several ways of defining “a typical” value from a dataset:

- a) Arithmetic mean b) Mode (most probably) c) Median (half below, half above)
- d) Geometric mean e) Harmonic mean f) Truncated mean (robustness)



# Mean and Width

It turns out, that the best estimator for the **mean** is (as you all know):

$$\hat{\mu} = \frac{1}{N} \sum_i x_i = \bar{x}$$

The second (central) moment of the data is called the **variance**, defined as:

$$\hat{V} = \frac{1}{N} \sum_i (x_i - \mu)^2$$

Note the “hat”, which means “estimator”. It is sometimes dropped...

# Mean and Width

It turns out, that the best estimator for the **mean** is (as you all know):

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For the **standard deviation (Std)**, a.k.a. **width** or **RMSE**, it is:

$$\hat{\sigma} = \sqrt{\frac{1}{N} \sum_i (x_i - \mu)^2}$$

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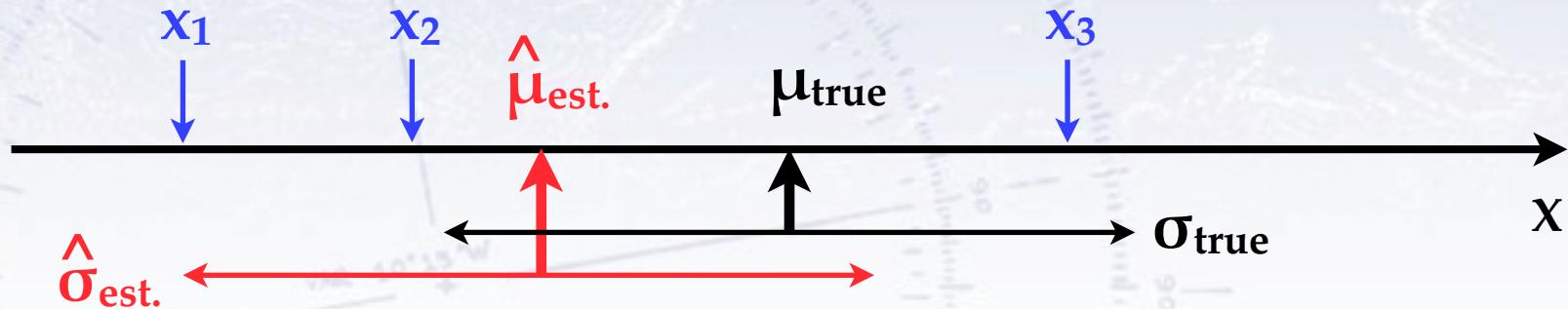
For the **standard deviation (Std)**, a.k.a. **width** or **RMSE**, it is:

$$\hat{s} = \sqrt{\frac{1}{N-1} \sum_i (x_i - \bar{x})^2}$$

Note the “hat”, which means “estimator”. It is sometimes dropped...

# Why not “just” the naive SD?

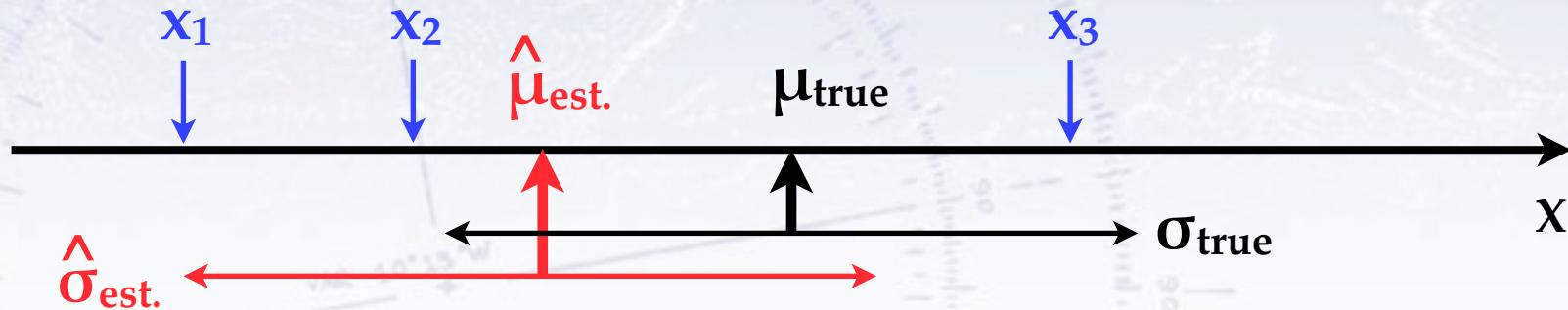
Imagine taking 3 independent measurements, and then the mean and SD:



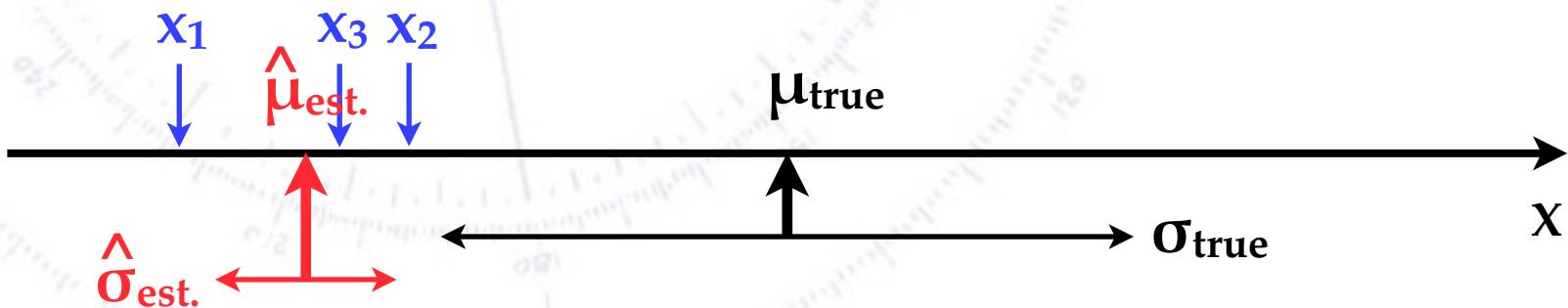
Above, all went well, because measurements were nicely distributed on both sides of the mean, and spread out according to SD.

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Imagine taking 3 independent measurements, and then the mean and RMSE:



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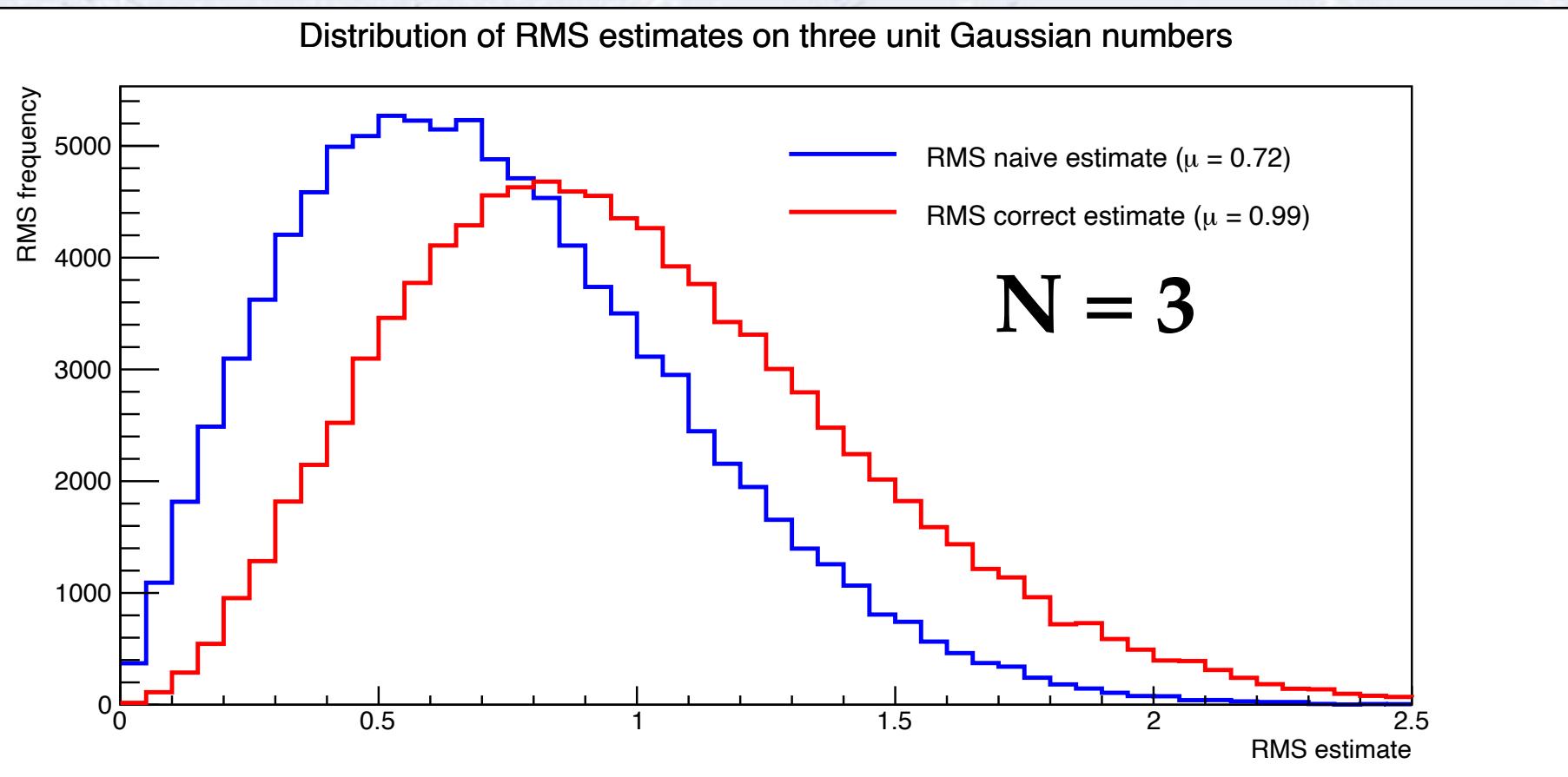


However, now the mean is off (not terribly so) and the SD way off (terribly so!). If we had used the true mean in the formula, it would not have been a problem.

# How incorrect is the naive SD?

Such questions can most easily be answered by a small simulation...

Produce  $N=3$  numbers from a unit Gaussian, and calculate the SD estimate:

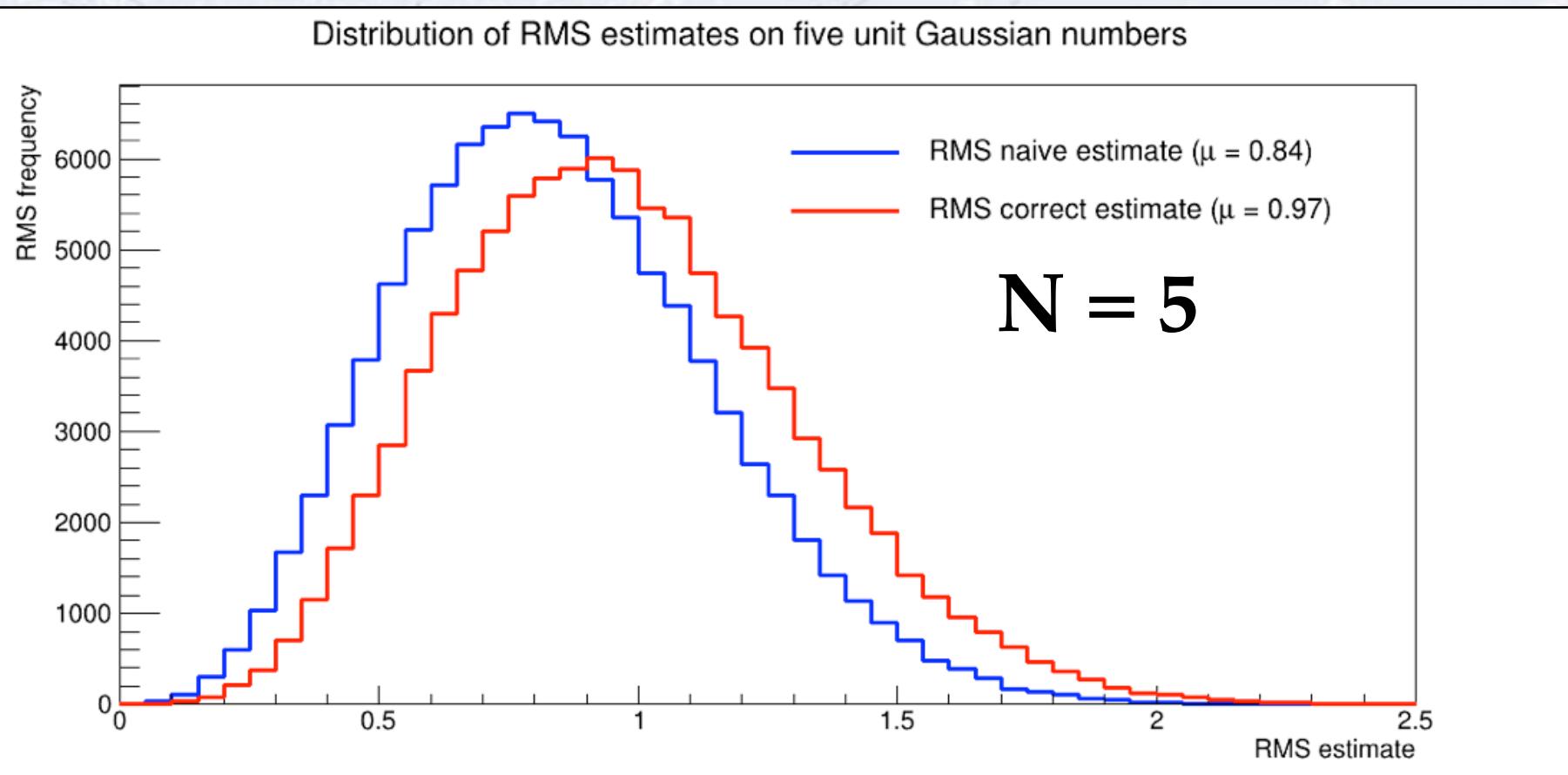


So, the “naive” SD underestimates the uncertainty significantly...

# How incorrect is the naive SD?

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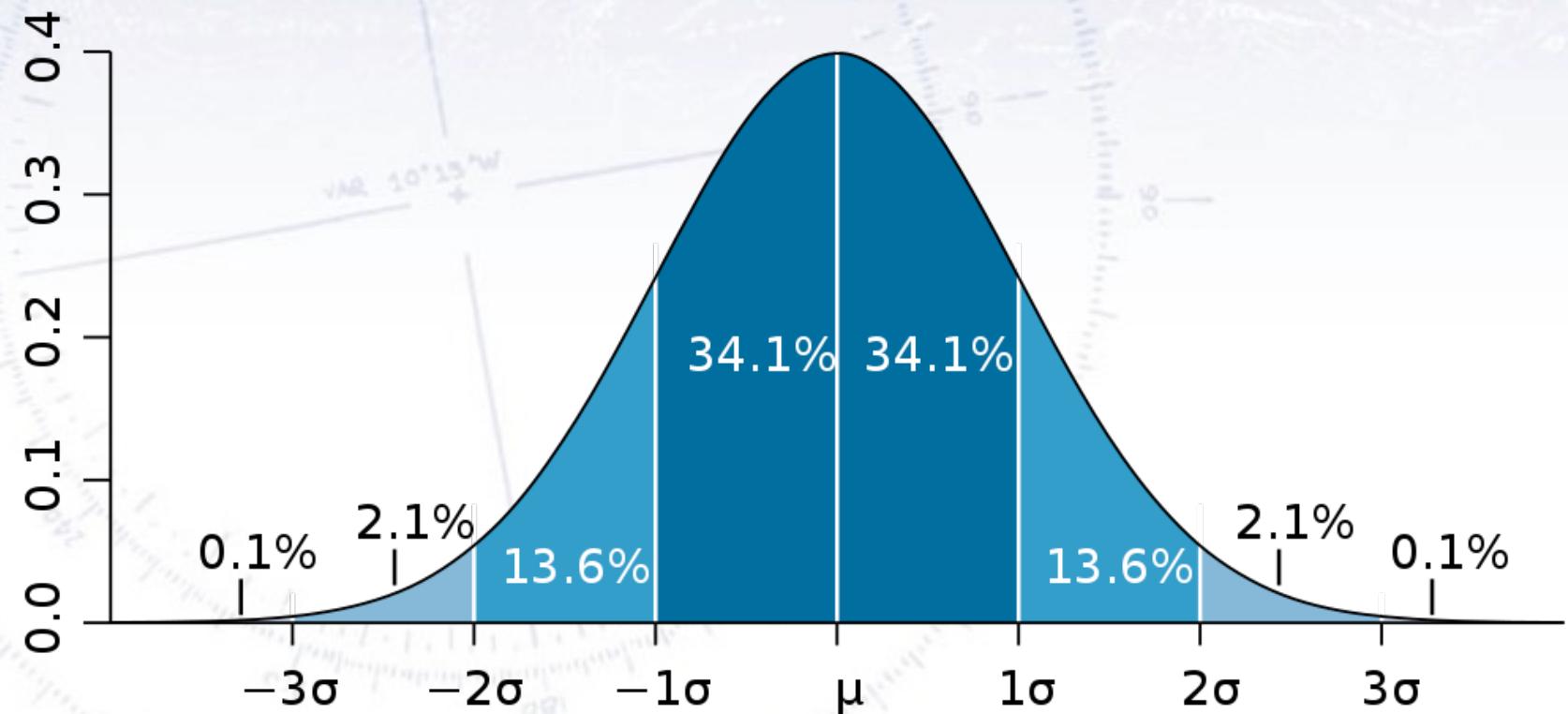
Produce  $N=5$  numbers from a unit Gaussian, and calculate the SD estimate:



Here, the “naive” SD underestimates the uncertainty a bit...

# SD and Gaussian $\sigma$ relation

When a distribution is Gaussian, the Std. corresponds to the Gaussian width  $\sigma$ :



# Mean and Width

What is the **uncertainty on the mean**? And how quickly does it improve with more data?

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Example:

**Cavendish Experiment**  
(measurement of Earth's density)

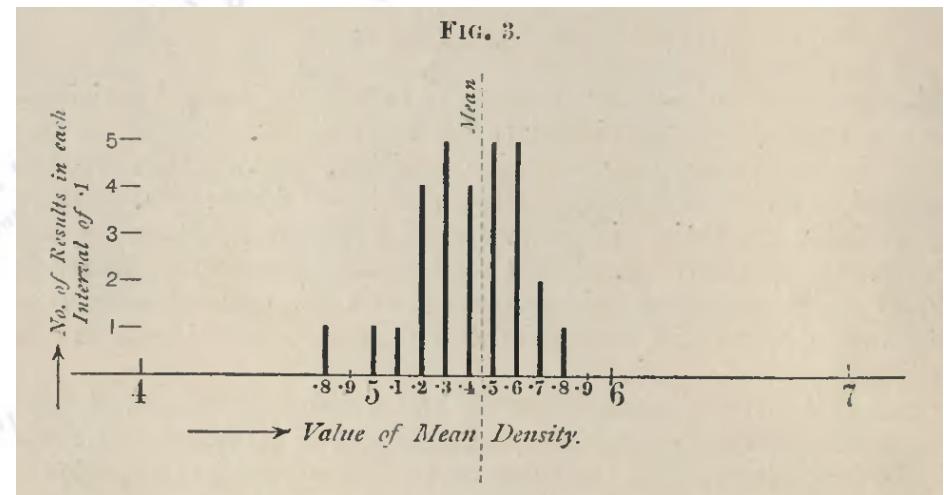
$$N = 29$$

$$\mu = 5.42$$

$$\sigma = 0.333$$

$$\sigma(\mu) = 0.06$$

$$\text{Earth density} = 5.42 \pm 0.06$$



# Mean and Width

What is the **uncertainty on the mean**? And how quickly does it improve with more data?

Please, commit  
to memory now!

Example.  
Cavendish Experiment  
(measurement of Earth's density)

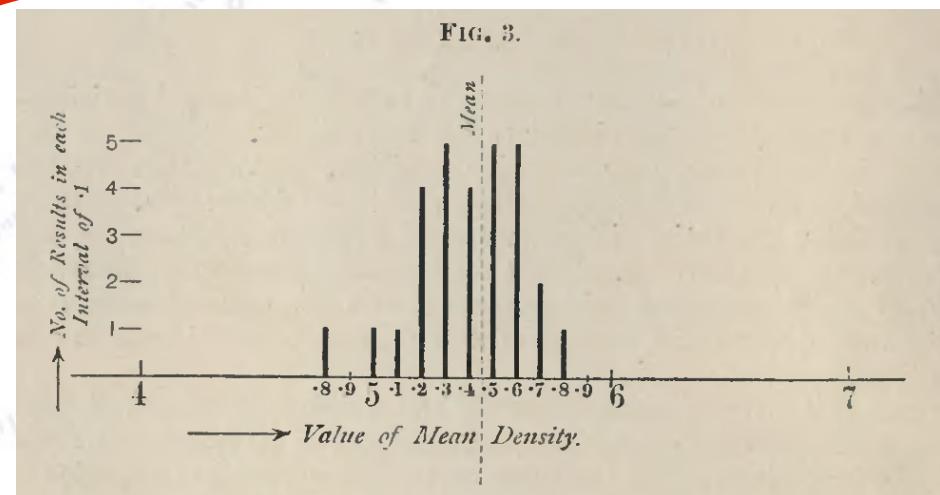
$$N = 29$$

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$$\sigma(\mu) = 0.06$$

$$\text{Earth density} = 5.42 \pm 0.06$$



# Weighted Mean

What if we are given data, which has different uncertainties?

How to average these, and what is the uncertainty on the average?

$$\hat{\mu} = \frac{\sum x_i / \sigma_i^2}{\sum 1 / \sigma_i^2}$$

For measurements with varying uncertainty, there is no meaningful SD!

The uncertainty on the mean is:

$$\hat{\sigma}_\mu = \sqrt{\frac{1}{\sum 1 / \sigma_i^2}}$$

Can be understood intuitively, if two persons combine 1 vs. 4 measurements

# Weighted Mean

What if we are given data, which has different uncertainties?

How to average these, and what is the uncertainty on the average?

$$\sum x_i / \sigma_i^2$$

Note that when doing a weighted mean,  
one should check if the measurements  
agree with each other!

For measur  
The uncerta

SD!

This can be done with a ChiSquare test.

$$\hat{\sigma}_\mu = \sqrt{\frac{1}{\sum 1/\sigma_i^2}}$$

Can be understood intuitively, if two persons combine 1 vs. 4 measurements

# Resolution using InterQuantile Range

A useful measure of resolution is the InterQuantile Range (IQR), as this is not affected by long tails.

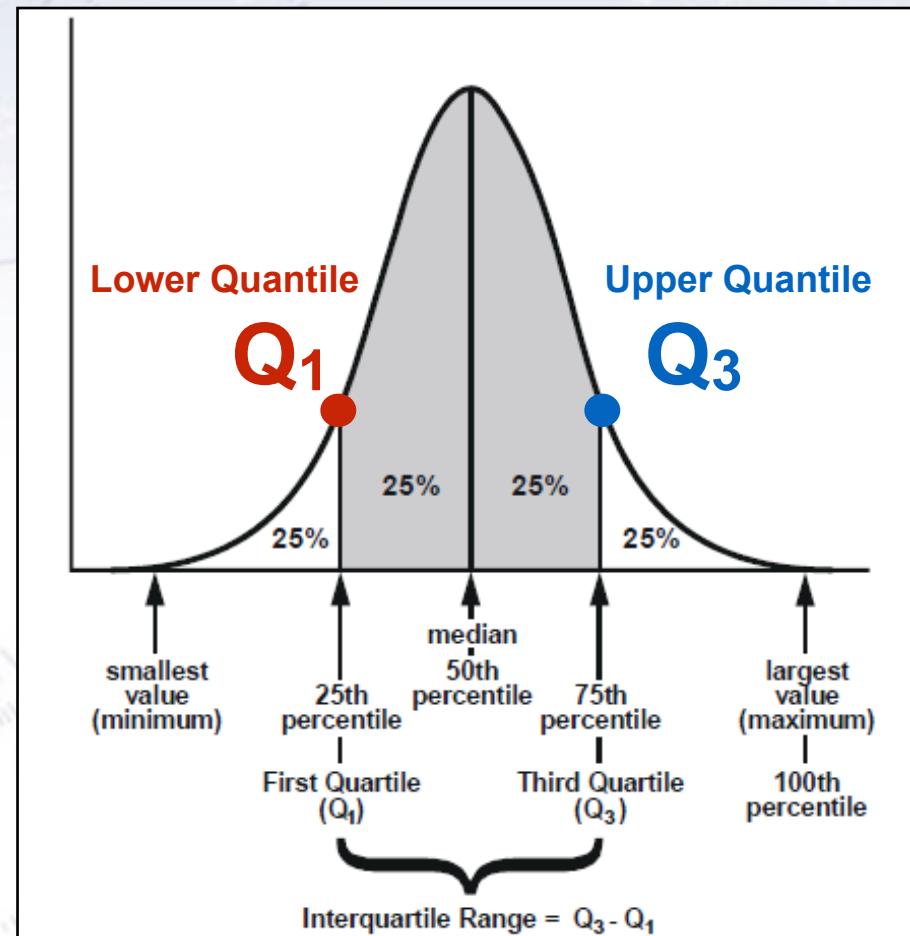
IQR measures **statistical dispersion**, calculated as the difference

$$\text{IQR} = Q_3 - Q_1$$

The InterQuantile Efficiency (IQE) is defined as:

$$\text{IQE} = \text{IQR} / 1.349$$

The factor  $1.349 = 2 \Phi^{-1}(0.75)$  ensures that  $\text{IQR} = 1$  for a unit Gaussian.



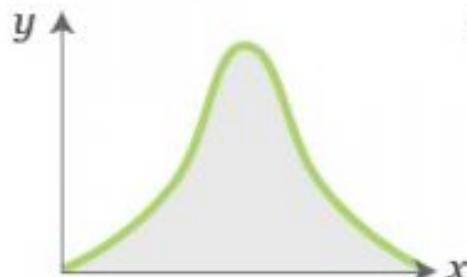
# Skewness and Kurtosis

Higher moments reveal something about a distributions asymmetry and tails:

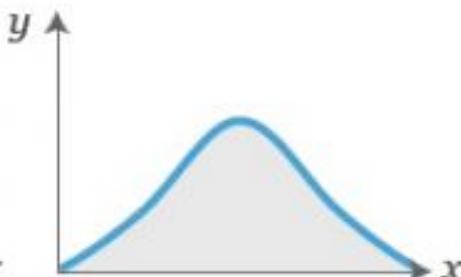


$$\gamma = \frac{\frac{1}{N} \sum_i (x_i - \bar{x})^3}{(\frac{1}{N} \sum_i (x_i - \bar{x})^2)^{3/2}}$$

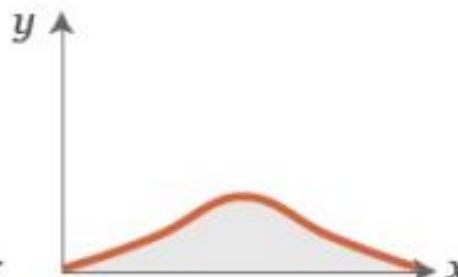
**LEPTOKURTIC**  
(thicker tails)



**MESOKURTIC**  
(normal tails)



**PLATYKURTIC**  
(thinner tails)



$$\kappa = \frac{\frac{1}{N} \sum_i (x_i - \bar{x})^4}{(\frac{1}{N} \sum_i (x_i - \bar{x})^2)^2} - 3$$