
Ocean Drift Simulation and Trajectory Prediction: A Survey

www.surveyx.cn

Abstract

Ocean drift simulation and trajectory prediction are pivotal in understanding marine environments, leveraging mathematical models to predict movements influenced by ocean currents, wind patterns, and geographical coordinates. This survey highlights the integration of diverse scientific techniques, such as high-resolution ocean modeling and innovative simulation approaches, to enhance environmental monitoring and maritime operations. High-resolution models like SLIM have identified significant pathways critical for ecosystem resilience, while fuzzy-based methods have improved uncertainty propagation in trajectory predictions. The OpenDrift framework exemplifies robust trajectory modeling across applications, underscoring the importance of integrating diverse data sources for precise simulations. Challenges remain in model parameterization, data integration, and scalability, necessitating advancements in real-time data processing and standardization. Future research should focus on refining model accuracy through comprehensive datasets and standardized benchmarks. Overall, these efforts contribute to a deeper understanding of ocean dynamics, supporting effective environmental management and sustainable ocean governance.

1 Introduction

1.1 Overview of Ocean Drift Simulation and Trajectory Prediction

Ocean drift simulation and trajectory prediction are crucial for understanding marine environments and optimizing maritime operations. These techniques utilize mathematical models and computational tools to forecast the movement of objects or substances in oceanic waters, influenced by ocean currents, wind patterns, and geographical coordinates. Their significance spans various applications, including environmental monitoring through geospatial analysis and IoT integration, maritime navigation via advanced trajectory prediction and clustering techniques, and pollution tracking using real-time data from sensing technologies [1, 2, 3, 4, 5].

The complexity of accurately predicting vessel trajectories in cluttered maritime environments necessitates precise future intent forecasting, vital for safe navigation [6]. Moreover, integrating trajectory prediction with task planning, particularly in satellite task scheduling, reveals challenges in decoupling these processes, often leading to suboptimal outcomes [7]. This analogy is pertinent to ocean studies, where coupling trajectory prediction with operational planning can significantly enhance maritime activity efficacy.

Recent surveys have highlighted a gap in comprehensive reviews and systematic evaluations of distance-based vessel trajectory clustering methods, underscoring the need for a synthesized understanding of these techniques [2]. This evolution in the field necessitates continuous advancements in modeling and analytical approaches to address the dynamic nature of oceanic systems. Consequently, ocean drift simulation and trajectory prediction are integral to marine environment studies and management, providing insights crucial for both scientific research and practical applications.

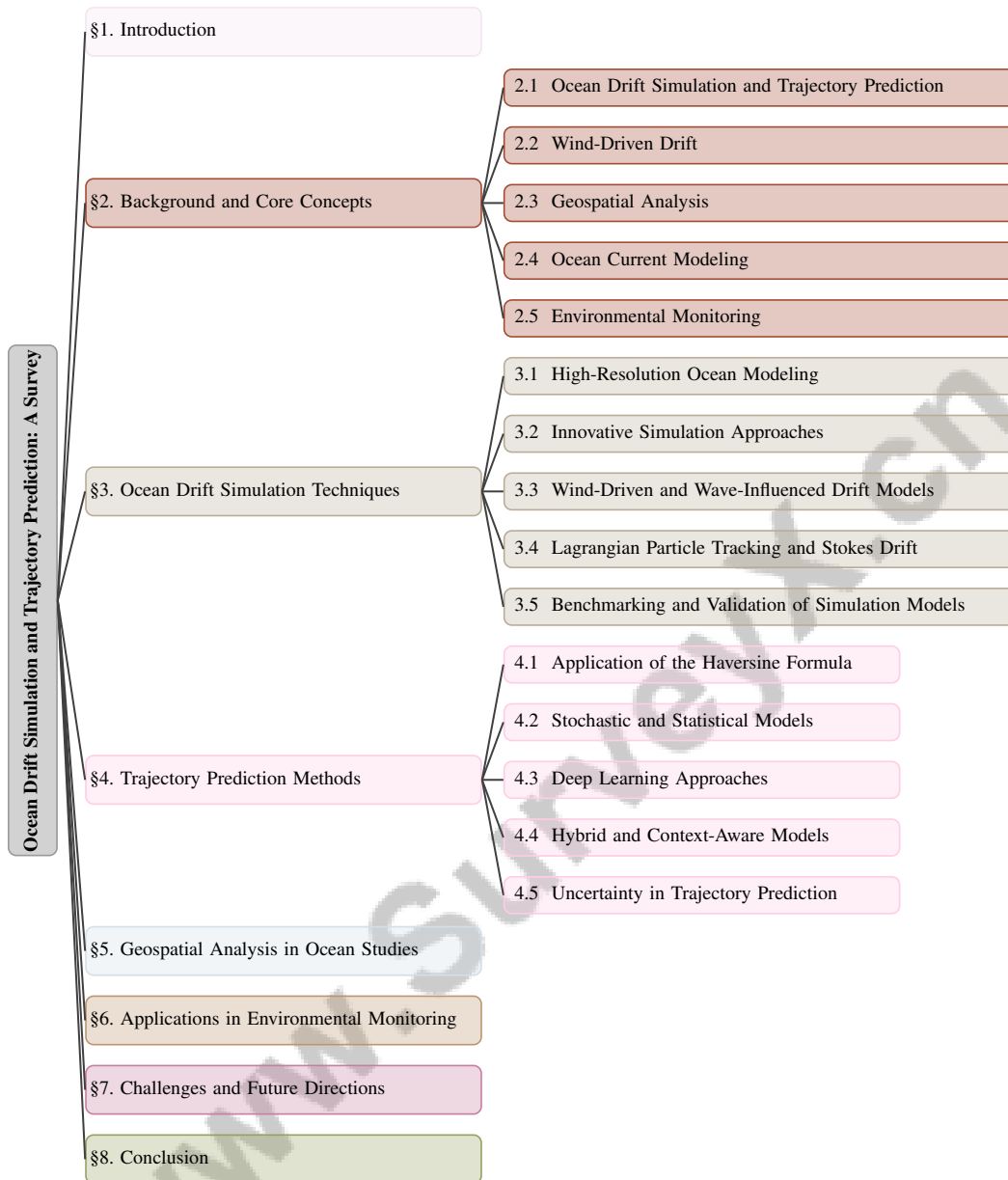


Figure 1: chapter structure

1.2 Relevance and Importance

Ocean drift simulation and trajectory prediction are vital for environmental and maritime contexts, offering essential insights into marine dynamics and facilitating effective oceanic activity management. Predicting the movement of objects or substances in the ocean is critical for addressing environmental issues, such as marine pollution. The prevalence of pelagic microplastics, especially in regions like the North Pacific, highlights the necessity for accurate prediction models to understand and mitigate the impacts of these pollutants [8]. These models are essential for tracking the dispersion and removal processes of microplastics in the upper ocean, which exhibit non-conservative behavior due to their complex interactions with oceanic processes.

In the maritime sector, ocean drift simulations enhance shipping efficiency and safety. The absence of a systematic approach to quickly locate nearby expedition services poses significant challenges, potentially leading to delays and inefficiencies in shipping processes [5]. Enhanced accuracy in

trajectory predictions through these simulations facilitates improved planning and resource allocation, ultimately optimizing shipping routes and minimizing operational disruptions.

Furthermore, the establishment of standardized benchmarks, such as those provided by Automatic Identification System (AIS) databases, is crucial for advancing maritime trajectory learning and prediction [9]. These benchmarks enable the comparative evaluation of various methods and algorithms, fostering innovation and enhancing predictive model reliability. As ocean circulation models evolve, they present new opportunities for understanding complex ocean dynamics, addressing challenges identified in recent surveys [10]. Integrating these models with trajectory prediction techniques is essential for advancing our understanding of oceanic systems and enhancing maritime operations, thereby contributing to sustainable ocean management and environmental stewardship.

1.3 Structure of the Survey

This survey on ocean drift simulation and trajectory prediction is organized into several key sections that systematically explore the multifaceted aspects of the field. The paper begins with an introduction that outlines ocean drift simulation and trajectory prediction, emphasizing their relevance in understanding ocean dynamics and improving maritime operations.

Following the introduction, Section 2 delves into the background and core concepts, providing a detailed explanation of fundamental ideas such as wind-driven drift, geospatial analysis, ocean current modeling, and environmental monitoring, thereby setting the foundation for the methodologies discussed in subsequent sections.

Section 3 focuses on ocean drift simulation techniques, reviewing various methodologies and models, including high-resolution ocean modeling and innovative simulation approaches. This section examines the intricate dynamics of ocean surface processes by integrating wind-driven currents and wave-influenced behaviors, particularly through Lagrangian particle tracking and Stokes drift analysis. It underscores the critical need for benchmarking and validating simulation models, emphasizing the importance of accurately accounting for the vertical profiles of drift currents and the uncertainties in parameterizations of wind and wave interactions to enhance trajectory prediction precision for buoyant objects in marine environments [11, 12, 13].

In Section 4, the discussion shifts to trajectory prediction methods, exploring approaches such as the haversine formula, stochastic and statistical models, deep learning techniques, and hybrid models, while addressing the challenges posed by uncertainty in trajectory prediction.

Section 5 provides an in-depth analysis of the significance of geospatial analysis in ocean studies, categorizing various methodologies and exploring their integration with WebGIS systems. This integration enhances data visualization and accessibility, facilitating effective communication of complex geospatial data related to oceanic environments. Additionally, it discusses challenges and innovations in geospatial analytics, particularly concerning the Internet of Things (IoT) and environmental informatics, illustrating how these technologies can improve our understanding of marine ecosystems [14, 1, 4, 5, 15].

Section 6 delves into the diverse applications of ocean drift simulation and trajectory prediction in environmental monitoring, highlighting specific case studies that demonstrate the effectiveness of these techniques in tracking pollutants and predicting oil spill trajectories. This section also discusses the integration of IoT technologies in environmental research, showcasing how real-time data enhances monitoring efforts. Furthermore, it examines the role of autonomous underwater gliders in collecting valuable oceanographic data, thereby improving the accuracy and reliability of trajectory predictions and environmental assessments [16, 11].

The survey concludes with Section 7, which identifies and elaborates on current challenges and future directions in geospatial analysis and visualization. It discusses critical issues such as model parameterization, the integration of diverse data sources, scalability of analytical frameworks, and the pressing need for standardization and validation of geospatial models. This section highlights complexities arising from model heterogeneity and the importance of developing robust frameworks for effective model integration and management, as well as the role of emerging technologies like the IoT in enhancing geospatial analytics [15, 4, 3, 1].

This structured approach offers an in-depth analysis of methodologies and advancements in ocean drift simulation and trajectory prediction, emphasizing their essential contributions to marine science

and environmental management. By integrating various factors such as wind-driven drift currents, iceberg dynamics, and microplastic distribution, it highlights the complexities involved in accurately modeling the movement of buoyant objects and the implications for ecological health and maritime activities [11, 17, 18, 13, 19]. The following sections are organized as shown in Figure 1.

2 Background and Core Concepts

2.1 Ocean Drift Simulation and Trajectory Prediction

Ocean drift simulation and trajectory prediction are crucial for understanding marine dynamics, employing mathematical and computational models to forecast the movement of objects or substances influenced by ocean currents, wind, and environmental factors. These simulations focus on the upper ocean layer, significantly impacting shipping routes, pollutant dispersion, and maritime safety. Recent studies using passive optical sensing highlight the complexities of these currents, which differ from deeper flows and are influenced by wind stress, underscoring the need for precise transport estimation [20, 21].

High-resolution models, such as SLIM, are essential for connectivity pathways in conservation efforts, like coral reef protection [22]. Incorporating remotely sensed winds improves model accuracy [23], while predicting wave heights in areas like Monterey Bay requires rapid methodologies [24]. In navigation, predicting vessel intent is vital for collision avoidance, with AIS databases setting benchmarks for anomaly detection [9].

Wind-driven drift significantly influences surface flow and air-sea momentum exchanges [25]. However, practical methods for vertical wind-driven drift profiles in particle tracking are lacking, affecting buoyant object path predictions [11]. Innovative approaches, such as fuzzy data representations, offer new prediction avenues [13]. Additionally, trajectory prediction in extreme weather, like hurricanes, illustrates these techniques' broader applications [26].

Challenges in large eddy simulations, particularly error propagation in data-driven models, highlight the complexity of trajectory prediction [27]. Robust models integrating environmental factors are needed for comprehensive upper-ocean transport insights [20]. Understanding ocean climate models is crucial for predicting global circulation and its climate implications [28].

These methodologies are vital for marine science, offering insights into buoyant object behavior under various transport mechanisms, including geostrophic and wind-driven currents. Depth-dependent corrections for wind-driven drift enhance prediction accuracy, and frameworks quantifying drift prediction uncertainties refine understanding, crucial for navigation and environmental management [11, 13].

2.2 Wind-Driven Drift

Wind-driven drift is central to ocean current dynamics, affecting surface water flow and momentum exchange at the air-sea interface. Accurate surface wind characterization, benchmarked against ASCAT observations, is essential for model bias identification and enhancement [29]. The shift to big data applications in modeling necessitates real-time processing across time horizons, facing challenges like varying data rates and noise, complicating trajectory prediction [3, 2].

Understanding the vertical structure of drift currents, crucial for simulating buoyant object pathways, poses significant challenges [11]. Depth-dependent variations are critical for modeling substances like oil slicks, where drag coefficient changes are often overlooked, leading to trajectory inaccuracies [30]. Surface water motion dynamics, particularly during wave breaking, are crucial for understanding flow transitions [25].

Remotely sensed winds are vital for marine applications, though affected by environmental factors like precipitation [23]. Error amplification in predictions necessitates robust models accounting for autoregressive error growth [27]. Advancements in data processing, understanding vertical drift structures, and precise environmental measurements are essential for improving model accuracy and reliability, particularly for wind-driven drift's influence on surface object trajectories [11, 18, 31, 32].

2.3 Geospatial Analysis

Geospatial analysis enhances ocean drift simulation and trajectory prediction accuracy by integrating spatial data and models essential for simulating geographic processes [15]. These models examine spatial relationships and patterns, crucial for understanding ocean currents and object movement. Challenges include extensive data processing and complex computations, requiring sophisticated techniques for accurate simulations [15]. Model heterogeneity complicates integration and collaboration, highlighting the need for standardized data formats and protocols for better interoperability and model integration [15].

Advancements in GIS and remote sensing offer tools for spatial data visualization and analysis. Integrating geospatial analysis with IoT technologies allows researchers to combine diverse data sources, facilitating sophisticated models incorporating various environmental variables. This synergy addresses geographic data processing complexities, creating predictive models for complex ecological interactions and phenomena, leading to informed environmental decision-making [1, 4, 3, 15, 33].

2.4 Ocean Current Modeling

Ocean current modeling is fundamental for understanding water mass movement and interactions, forming the backbone of ocean drift simulation. These models integrate dynamics like circulation patterns, temperature, salinity, and biogeochemical processes to predict object distribution within marine environments, enhancing our understanding of their behavior and ecological impacts [19, 23, 17].

High-resolution models, such as MITgcm, evaluate sea ice conditions and influencing factors, emphasizing atmospheric data integration for comprehensive modeling [34]. In the Arctic, detailed ocean dynamics analysis is crucial for model accuracy. The Wave-modified mixing-length model (WMM) incorporates wave effects into near-surface wind drift modeling, offering a realistic representation of wind-wave interactions [32].

Challenges in ocean climate modeling include simulating complex interactions, requiring a thorough understanding of physical processes and their numerical representation [28]. Benchmarking and validation are integral for model development, with benchmarks incorporating atmospheric adjustments enhancing simulation reliability [29].

These methodologies are essential for simulating ocean drift, incorporating transport mechanisms like Stokes drift and wind-induced currents, influencing buoyant object trajectories. By integrating depth-dependent corrections and accounting for vertical drift profiles, these models improve marine dynamics understanding and predictions, supporting applications from environmental monitoring to navigation [11, 18, 32, 17].

2.5 Environmental Monitoring

Environmental monitoring through ocean drift simulation and trajectory prediction assesses ecological impacts and marine ecosystem dynamics. Factors like wind-driven drift currents and depth-dependent variations influence buoyant object movement, crucial for climate regulation and navigation [11, 17]. These techniques provide insights into pollutant distribution, such as microplastics, within oceans. High-resolution modeling improves Arctic Ocean simulations, aiding climate change response understanding.

Quantifying microplastic distribution enhances ecological impact understanding, validated by experimental studies [8]. Numerical simulations improve microplastic pathway knowledge, crucial for assessing long-term marine ecosystem effects and informing pollution reduction policies [19].

Geospatial data and visualization tools enable spatial pattern analysis, integrating diverse data for comprehensive environmental change assessments [4]. Fuzzy frameworks quantify uncertainties in drifting object trajectories, enhancing prediction reliability and environmental management [13].

Surface drift currents, influenced by mechanical and wind waves, are critical for environmental monitoring. Reliable measurement methods improve drift current understanding, aiding pollutant transport and dispersion assessments, contributing to effective environmental management strategies [21].

3 Ocean Drift Simulation Techniques

Category	Feature	Method
High-Resolution Ocean Modeling	Detailed Ocean Dynamics	GSSK[35]
Innovative Simulation Approaches	Attention and Representation	STA-JTPF[6], TAS[36], GT[26], VTPF[37], MSTFormer[38]
	Diffusion and Uncertainty Reduction	DT[39]
	Unsupervised and Clustering Techniques	NPC[40]
	Surrogate Modeling	MLFWCF[24]
Wind-Driven and Wave-Influenced Drift Models	Experimental Simulations	WWTE[25]
	Wind-Driven Current Calculations	EWSM[30]
	Adaptive Drift Modeling	SVR-PM[16]
	Modeling Ocean Dynamics	WMM[32]
Lagrangian Particle Tracking and Stokes Drift	Combined Trajectory Prediction	OD[41]
Benchmarking and Validation of Simulation Models	Error Analysis	EADCM[27]

Table 1: This table provides a comprehensive overview of various methodologies employed in ocean drift simulation. It categorizes these methods into high-resolution ocean modeling, innovative simulation approaches, wind-driven and wave-influenced drift models, Lagrangian particle tracking and Stokes drift, and benchmarking and validation processes. Each category highlights specific features and the corresponding techniques, illustrating the diverse strategies utilized to enhance the accuracy and reliability of ocean drift predictions.

Exploring ocean drift simulation techniques requires a comprehensive understanding of foundational methodologies for accurate modeling. Table 1 presents a detailed classification of ocean drift simulation methodologies, showcasing the diverse approaches and techniques applied to improve the precision of oceanic process modeling. Additionally, Table 5 presents a comprehensive comparison of different ocean drift simulation techniques, illustrating the various methodologies employed to improve the precision of ocean modeling. This section discusses various approaches developed for simulating ocean drift, starting with high-resolution ocean modeling, which is vital for capturing the intricate dynamics of oceanic processes and enhancing the understanding of marine environments.

3.1 High-Resolution Ocean Modeling

High-resolution ocean modeling significantly improves the accuracy of simulating ocean drift by capturing fine-scale features often missed by lower-resolution models. For instance, a high-resolution model with a 4.5 km spatial resolution has demonstrated notable improvements in representing the Atlantic Water layer, reducing biases compared to a 24 km model [34]. Models like SLIM, achieving approximately 100 meters spatial resolution, facilitate the simulation of complex flow patterns and improve estimates of connectivity pathways crucial for understanding substance and organism movement [28]. Such models are invaluable for conservation efforts, enabling accurate predictions of critical ecological connectivity pathways.

Advancements in analytical methods have further enhanced high-resolution models. Computationally efficient techniques for simulating iceberg trajectories have improved understanding of iceberg dynamics and their impact on ocean currents [35]. Innovative measurement techniques, such as Polarimetric Slope Sensing (PSS), enable non-intrusive measurement of near-surface currents, capturing high-resolution images of wave slopes to derive current profiles without disturbing the water surface [23]. Controlled experiments, like wind-wave-current tank studies, provide insights into surface current evolution and turbulence, contributing to more accurate models [29].

High-resolution ocean modeling is indispensable for simulating ocean drift, offering detailed insights into marine environment dynamics. These models support applications ranging from environmental monitoring to maritime navigation, providing robust frameworks for understanding and predicting ocean current behaviors. Continuous development of numerical methods and parameterizations is vital for addressing unresolved processes in ocean simulations, ultimately enhancing the precision and reliability of high-resolution models [2].

3.2 Innovative Simulation Approaches

Innovative simulation approaches in ocean drift modeling leverage advanced machine learning and data-driven techniques to enhance predictive accuracy and efficiency. Integrating deep learning architectures with spatial and temporal attention mechanisms is crucial for capturing complex

Method Name	Modeling Techniques	Attention Mechanisms	Predictive Frameworks
STA-JTPF[6]	Lstm-based Architecture	Spatial And Temporal	Sta-JTPF
VTPF[37]	Lstm Networks	Attention Mechanisms	Vtpf
MSTFormer[38]	Cnn	Dynamic-aware Self-attention	Mstformer
TAS[36]	Data-driven Techniques	Spatial And Temporal	Self-attention
DT[39]	Transformer-based Conditional	Spatiotemporal Dependencies	Stochastic Vessel Trajectory
GT[26]	Graph Neural Networks	Transformer Architectures	Graphtransformer Framework
NPC[40]	-	-	-
MLFWCF[24]	Matrix Operations	-	Self-attention

Table 2: Overview of various innovative simulation approaches in ocean drift modeling, detailing the modeling techniques, attention mechanisms, and predictive frameworks employed by each method. These methods leverage advanced machine learning architectures and data-driven techniques to enhance predictive accuracy and efficiency in marine environments.

interactions within marine environments, such as predicting vessel intent based on past interactions and positions [6]. The Vessel Trajectory Prediction Framework (VTPF) exemplifies this innovation by utilizing attention mechanisms and high-level intention information to improve prediction accuracy [37].

The MSTFormer model showcases advancements in trajectory prediction with its Multi-headed Dynamic-aware Self-attention mechanism and knowledge-inspired loss function, enhancing its capacity to learn and predict long-term trajectories [38]. The TrAISformer network captures the multimodal nature of vessel movements through a classification-based approach, allowing for multiple future trajectory representations [36]. Similarly, the DiffuTraj framework employs a guided diffusion process to reduce uncertainty in vessel motion predictions [39].

Graph neural networks integrated with transformer architectures enhance predictive capabilities by effectively modeling spatial relationships, as demonstrated in hurricane trajectory predictions [26]. Methodologies like the NPC method use unsupervised clustering-based trajectory reconstruction to predict vessel trajectories without requiring a training set [40]. Machine learning as a surrogate model in ocean drift simulations can achieve accuracy comparable to physics-based models at a fraction of the computational cost [24].

Table 2 provides a comprehensive summary of the innovative simulation approaches discussed, highlighting the specific modeling techniques, attention mechanisms, and predictive frameworks utilized in each method to advance ocean drift modeling. These innovative approaches are transforming ocean drift modeling by integrating cutting-edge machine learning techniques and data-driven models. Advancements in numerical modeling and simulation techniques significantly improve marine environmental assessments' accuracy and effectiveness, supporting informed decision-making in environmental management and maritime operations [42, 35, 17, 23, 19].

3.3 Wind-Driven and Wave-Influenced Drift Models

Method Name	Model Components	Technological Advancements	Application Areas
WWTE[25]	Wind-water Tunnel	Laboratory Experiments	Marine Pollution Transport
EWSM[30]	Effective Wind Speed	Wind Speed Retrieval	Oil Spill Trajectory
WMM[32]	Wave Effects	Wave-correction Factor	Oil Spill Tracking
SVR-PM[16]	Wind Drift Factor	Machine Learning Applications	Oil Spill Simulations

Table 3: Overview of wind-driven and wave-influenced drift models, highlighting their core components, technological advancements, and application areas. The table presents four methods, each contributing uniquely to the understanding and simulation of oceanographic processes, particularly in the context of marine pollution and oil spill management.

Wind-driven and wave-influenced drift models are critical for simulating the interactions between atmospheric and oceanic processes that dictate surface current dynamics. These models consider the vertical profile of drift currents, including Stokes drift and wind-induced shear, and the influence of varying wind conditions on buoyant object trajectories. By integrating multiple transport mechanisms, such as geostrophic and tidal currents, and utilizing depth-dependent corrections, these models enhance particle tracking precision [32, 11, 31, 13, 18]. Table 3 provides a comprehensive summary of various wind-driven and wave-influenced drift models, illustrating their methodological components, technological innovations, and specific application domains in oceanographic research.

Significant advancements include wind-water tunnel experiments, which simulate and measure the transition of wind-driven surface flow and its relation to wave breaking [25]. The introduction of effective wind speed as a factor for modeling wind-driven currents in oil-affected areas marks a departure from traditional methods [30]. Incorporating wave effects into momentum balance through empirical parameters improves near-surface current representation [32]. Machine learning techniques, such as the Support Vector Regression-Parameterization Model (SVR-PM), derive a variable wind drift factor that adapts to changing conditions [16].

The development of wind-driven and wave-influenced drift models represents a significant advancement in oceanographic simulations. By integrating advanced numerical modeling techniques and thoroughly examining wind and wave dynamics interactions, these models yield essential insights into surface current behavior, enhancing environmental management strategies and optimizing maritime operations [19, 30, 20, 17].

3.4 Lagrangian Particle Tracking and Stokes Drift

Lagrangian particle tracking and Stokes drift are essential methodologies in ocean simulations, providing insights into buoyant objects' trajectories influenced by oceanic and atmospheric forces. These techniques account for complex transport mechanisms, including wind-driven shear currents and depth-dependent drift profiles. By integrating Stokes drift with Lagrangian tracking, researchers can enhance predictions of surface drifter behavior, improving simulation accuracy in ecological modeling and pollution dispersion studies [43, 11, 18, 32].

Lagrangian particle tracking involves following individual particles' paths through the ocean, offering a detailed representation of their trajectories. The OpenDrift framework exemplifies Lagrangian particle tracking capabilities, facilitating trajectory modeling with diverse forcing data [41]. Stokes drift represents the net movement of fluid particles caused by wave motion, playing a crucial role in surface materials transport. Studies indicate that simulations incorporating windage and Stokes drift align more closely with observed drifter paths [18].

The integration of Lagrangian particle tracking with Stokes drift models, enhanced by a depth-dependent correction for wind-driven drift currents, offers a comprehensive framework for simulating pollutants, biological organisms, and other materials' transport in marine environments. This approach improves predictions regarding buoyant objects' trajectories, supporting effective environmental management and maritime operations [11, 18, 13].

3.5 Benchmarking and Validation of Simulation Models

Benchmark	Size	Domain	Task Format	Metric
OMIP[44]	1,000,000	Ocean Biogeochemistry	Tracer Simulation	Root Mean Square Error, Mean Absolute Error
AISDB[9]	403,599	Maritime Navigation	Trajectory Prediction	Mean Absolute Error, Root Mean Square Error
BSHcmod+W[18]	6	Oceanography	Trajectory Simulation	Mean Absolute Error, Root Mean Square Error
SDC-BM[21]	42	Oceanography	Drift Current Measurement	$U_d / U_{St}, U_{dw} / u^*$
MPB[8]	19,600	Marine Pollution	Abundance Prediction	Weight Concentration, Total Particle Count
PENACC.E.[45]	1,000,000	Oceanography	Model Evaluation	Taylor Diagram, Cost Function
OpenTraj[46]	76,866	Human Trajectory Prediction	Trajectory Prediction	Conditional Entropy, Number of Clusters
ERA5-ASCAT[29]	1,000,000	Oceanography	Wind Field Comparison	rms wind vector difference

Table 4: This table presents a comprehensive overview of representative benchmarks utilized in the field of ocean drift simulation model validation. It details the various datasets, including their size, domain, task format, and the specific metrics employed to evaluate model performance, thereby highlighting the diversity and scope of current benchmarking efforts.

Benchmarking and validation are critical for developing ocean drift simulation models, ensuring their accuracy and reliability in representing marine dynamics. These processes involve comprehensive evaluation techniques, including rigorous testing and systematic comparison of model predictions with real-world observations or established benchmarks. This approach assesses predictive models' performance and identifies specific areas for enhancement [46, 42, 17]. Table 4 provides a detailed

overview of the representative benchmarks used for evaluating the effectiveness of ocean drift simulation models, illustrating the diversity of datasets and metrics applied in this domain.

Benchmarking typically involves evaluating models against standardized tests or datasets to establish their effectiveness in simulating oceanic processes. Validation requires comparing model predictions with observational data to ensure fidelity to real-world conditions. Methods involving depth-dependent corrections to background currents in particle tracking simulations exemplify the rigorous testing required to validate model accuracy [11]. Quantifying prediction errors in flow trajectory predictions is another critical aspect of model validation, with mathematical formulations providing insights into model precision [27].

Performance metrics, including Mean Squared Error (MSE), Mean Absolute Error (MAE), and Root Mean Square Error (RMSE), are commonly employed to assess simulation models' accuracy. The use of publicly available datasets enhances benchmarking and validation efforts' robustness by providing diverse scenarios for testing model performance. Addressing challenges such as scalability, data privacy concerns, and integrating real-time data sources into predictive models is crucial for advancing ocean drift simulation models' precision and applicability in marine research and environmental management [3].

Feature	High-Resolution Ocean Modeling	Innovative Simulation Approaches	Wind-Driven and Wave-Influenced Drift Models
Resolution	100 Meters	Not Specified	Not Specified
Technique	Numerical Methods	Machine Learning	Empirical Parameters
Application	Ecological Connectivity	Predictive Accuracy	Surface Current Dynamics

Table 5: This table provides a comparative analysis of three distinct ocean drift simulation methodologies: high-resolution ocean modeling, innovative simulation approaches, and wind-driven and wave-influenced drift models. It highlights key features such as resolution, techniques employed, and specific applications, offering insights into the diverse strategies used to enhance the accuracy and applicability of oceanic process modeling.

4 Trajectory Prediction Methods

Understanding trajectory prediction methodologies is crucial for enhancing forecast accuracy and reliability. This section explores specific approaches to address trajectory prediction complexities, beginning with the Haversine formula, a fundamental tool in geospatial analysis for calculating distances between Earth surface points, crucial for predictive modeling. Figure 2 illustrates the hierarchical structure of trajectory prediction methods, highlighting key categories such as the application of the Haversine formula, stochastic and statistical models, deep learning approaches, hybrid and context-aware models, and the challenges of uncertainty in trajectory prediction. Each category is further detailed into subcategories, showcasing the diverse methodologies and their contributions to enhancing predictive accuracy and reliability in geospatial and maritime applications.

4.1 Application of the Haversine Formula

The Haversine formula is a key algorithm in geospatial analysis, calculating the shortest distance between geographical points using latitude and longitude. It is instrumental in WebGIS applications for locating private universities and marine cargo services, optimizing location-based services through precise distance measurements [47, 48, 14, 5]. By incorporating Earth's curvature, it ensures accurate distance calculations vital for environmental monitoring and maritime navigation, enhancing trajectory forecast reliability.

In vessel trajectory prediction, the Haversine formula measures distances between predicted and actual positions, serving as a critical metric for model performance evaluation [14]. Its integration with GIS optimizes routing and resource allocation by calculating distances between user locations and service providers [47]. The formula's precision aids long-term environmental predictions, such as typhoon trajectories, supporting real-time data integration for accurate path forecasting. In logistics, it determines the shortest delivery routes, improving vehicle routing efficiency [14]. The Haversine formula underpins accurate routing solutions across geospatial applications, with advanced modeling techniques and real-time data enhancing ocean drift simulations by accounting for depth-dependent drift currents and wind-induced shear effects [11, 13, 17].

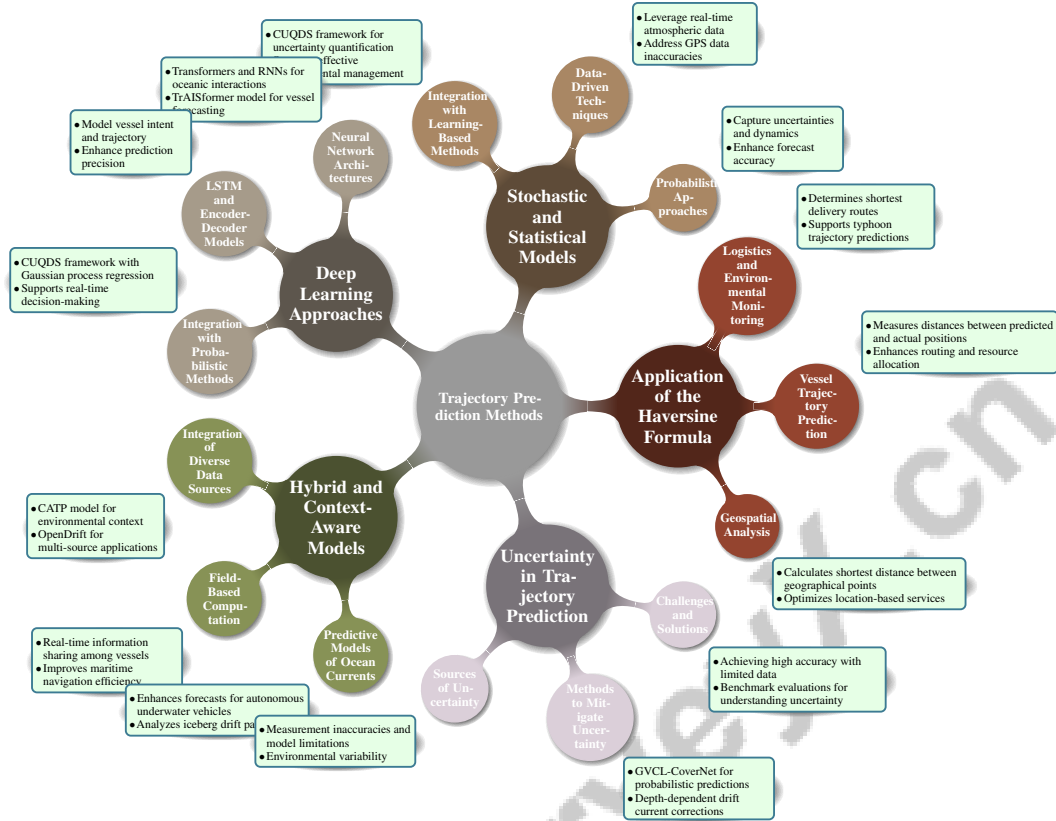


Figure 2: This figure illustrates the hierarchical structure of trajectory prediction methods, highlighting key categories such as the application of the Haversine formula, stochastic and statistical models, deep learning approaches, hybrid and context-aware models, and the challenges of uncertainty in trajectory prediction. Each category is further detailed into subcategories, showcasing the diverse methodologies and their contributions to enhancing predictive accuracy and reliability in geospatial and maritime applications.

4.2 Stochastic and Statistical Models

Stochastic and statistical models are vital in trajectory prediction, capturing the inherent uncertainties and dynamics of oceanic and atmospheric processes. These models employ probabilistic approaches to simulate movements, accommodating marine environment variability. Stochastic elements enhance forecast accuracy and reliability, particularly in complex scenarios where deterministic models may falter. Informed machine learning techniques integrate prior knowledge, facilitating robust, multi-modal predictions essential for applications like autonomous driving [42, 49, 46, 50, 3].

Stochastic models using approximate statistical moments improve prediction accuracy by capturing trajectory variability influenced by complex environmental interactions [51]. The CUQDS framework exemplifies integrating learning-based and statistical methods, enhancing uncertainty quantification and trajectory forecast reliability [52].

Data-driven approaches like the LT3P model leverage real-time atmospheric data for accurate typhoon path predictions, integrating physics-conditioned encoding with trajectory forecasting [53]. Addressing GPS data inaccuracies is crucial, as these uncertainties impact trajectory predictions [54].

Stochastic and statistical models provide methodologies for capturing uncertainty and variability in marine and atmospheric processes. By combining probabilistic modeling with data-driven techniques, these models enhance maritime vessel forecast accuracy and support effective environmental management [39, 42].

4.3 Deep Learning Approaches

Deep learning techniques have emerged as powerful tools in trajectory prediction, employing sophisticated neural network architectures like Transformers and RNNs to model intricate oceanic interactions. These approaches enhance predictive analytics for vessel trajectories and wave conditions by addressing the heterogeneous nature of AIS data [24, 42, 37, 36, 55]. For instance, the TrAISformer model excels in forecasting vessel positions up to 10 hours ahead, while deep learning methods predict hurricane trajectories and ocean wave conditions.

LSTM-based architectures effectively model vessel intent by focusing on relevant spatial and temporal features, enhancing prediction precision [37]. Encoder-decoder models with LSTM networks enable future trajectory predictions from past AIS observations, providing a robust framework for accurate forecasts [42].

The MSTFormer model exemplifies deep learning capabilities in trajectory prediction by integrating dynamics knowledge into its architecture to forecast long-term vessel trajectories [38]. Transformers, such as the TrAISformer network, combine novel AIS data representations with classification-based approaches to model vessel movements, addressing uncertainty in predicting vessel paths [36]. Additionally, the CUQDS framework enhances prediction reliability by integrating Gaussian process regression with a conformal P control module [52].

The CATP method employs competition symbiosis, optimizing trajectory predictions based on contextual performance [33]. Informed priors, as seen in the GVCL-CoverNet method, refine predictions by incorporating prior knowledge of drivable areas using existing map data [50].

Deep learning techniques advance trajectory prediction by modeling complex patterns in oceanic systems. By integrating advanced neural network architectures with probabilistic and statistical methods, these approaches enhance vessel trajectory prediction accuracy and reliability based on historical AIS data. This capability supports effective environmental management and maritime operations by providing precise forecasts and quantifying prediction uncertainties, enabling informed decision-making in real-time [56, 42, 40, 37].

4.4 Hybrid and Context-Aware Models

Hybrid and context-aware models significantly advance trajectory prediction by integrating diverse data sources and contextual information, enhancing predictive accuracy and adaptability. The CATP model employs a "manager-worker" framework, optimizing predictions based on environmental cues influencing behaviors, such as migratory birds [3, 57, 33, 50]. These models combine deterministic, stochastic, and machine learning approaches for comprehensive trajectory forecasting.

The CATP model dynamically selects the most appropriate prediction strategy according to environmental context [33]. OpenDrift provides a flexible framework that integrates various forcing fields from multiple sources, supporting applications ranging from oil drift to search and rescue operations, enabling more precise trajectory predictions [41].

Field-based computation techniques allow ships to adjust trajectories based on real-time information shared among vessels, enhancing maritime navigation efficiency and safety [58]. Integrating predictive models of ocean currents into control algorithms demonstrates the potential of hybrid approaches, improving forecasts for autonomous underwater vehicles like gliders [35].

Hybrid and context-aware models offer robust frameworks for trajectory prediction, combining diverse methodologies and real-time data to enhance forecast adaptability and precision. These models facilitate various applications in marine navigation and environmental monitoring, providing insights into oceanic dynamics by analyzing factors such as iceberg drift patterns influenced by size, current velocity, and wind conditions [35, 23, 17].

4.5 Uncertainty in Trajectory Prediction

Uncertainty in trajectory prediction presents significant challenges in ocean drift simulations, arising from measurement inaccuracies, model limitations, and environmental variability. Uncertainties can stem from wind drag parameterization based on drifting object geometry and the influence of vertical profiles of wind-driven drift currents, including Stokes drift and wind-induced shear currents. Studies emphasize incorporating observed ocean currents and winds to mitigate uncertainties linked to

physical processes, rather than relying solely on atmospheric and hydrodynamic models. Innovative frameworks and depth-dependent correction factors aim to enhance prediction accuracy and deepen understanding of buoyant object dynamics at the ocean surface [11, 13].

Measurement inaccuracies, particularly in GPS data, significantly impact trajectory predictions, necessitating robust methods to address these uncertainties [54]. The dependency on high-quality historical data underscores the importance of data quality for reliable predictions [37].

Model limitations contribute to uncertainty, especially in scenarios with sparse datasets, highlighting the need for models capable of efficient operation with limited data [37]. The computational intensity of existing multi-step prediction models poses challenges, as they often rely on iterative inference processes that can be inefficient [49].

Environmental variability introduces additional uncertainty, as oceanic conditions can change rapidly. The challenge of obtaining comprehensive data across all ocean regions complicates modeling efforts [8]. This variability emphasizes the need for adaptable models that can respond to changing conditions without extensive retraining [57].

Several methods have been proposed to mitigate uncertainty in trajectory prediction. The GVCL-CoverNet method enables a probabilistic representation of predictions, facilitating handling of uncertainty and multi-modal outputs [50]. Integrating depth-dependent drift current corrections significantly improves particle tracking simulation accuracy, underscoring the importance of environmental factors in practical applications [11]. Additionally, the MDP approach enhances robustness to trajectory uncertainties, yielding more reliable tasking plans compared to conventional methods [7].

Achieving high accuracy predictions without extensive retraining is crucial for real-time applications where data availability may be limited [42]. Benchmark evaluations focusing on predictability, regularity, and context complexity are essential for understanding and addressing uncertainty in trajectory prediction [46].

5 Geospatial Analysis in Ocean Studies

5.1 Categorization of Geospatial Analysis Methods

Geospatial analysis methods are integral to ocean studies, facilitating the integration of spatial data and enhancing ocean drift simulations and environmental monitoring. These methods are categorized to assist researchers in selecting appropriate techniques for marine applications [4]. An innovative development is the use of containerized service-based integration frameworks like GeoCSIF, which streamline the integration of heterogeneous geospatial-analysis models by encapsulating them into standardized service packages, thereby improving efficiency and scalability [15]. This is crucial for managing complex geospatial data and ensuring seamless integration across platforms.

The synergy between Internet of Things (IoT) technologies and geospatial analysis further expands capabilities in environmental informatics. IoT devices enable real-time data collection, essential for monitoring dynamic ocean processes. This integration emphasizes the importance of data transmission standards and measurement reliability in enhancing environmental assessments [1]. The use of IoT technologies allows for high-resolution data acquisition, supporting precise ocean dynamics modeling.

Predictive models, such as the Regional Ocean Modeling System (ROMS), play a pivotal role in simulating oceanic processes and improving ocean drift simulation accuracy [35]. These models provide a comprehensive framework for understanding environmental interactions, enabling accurate predictions of ocean currents and substance movements within marine environments.

The categorization of geospatial analysis methods in ocean studies highlights innovative approaches that leverage advanced technologies, including IoT, to enhance marine environment modeling and visualization. This diversity is exemplified by various geospatial analysis techniques used in IoT initiatives, collectively improving ecological dynamics understanding and facilitating effective environmental research and decision-making [15, 4, 1]. By integrating containerized frameworks, IoT technologies, and predictive models, researchers can enhance the precision and reliability of geospatial analyses, supporting effective environmental management and marine research.

5.2 Integration with WebGIS Systems

Integrating geospatial analysis with WebGIS systems significantly advances oceanographic data visualization and accessibility. This integration enhances the modeling and understanding of complex geographic processes through improved visualization techniques and IoT technology utilization. It supports innovative environmental research approaches by leveraging diverse geospatial analysis methods and enhancing data reliability across IoT deployments [15, 4, 1]. WebGIS platforms utilize GIS and internet capabilities to provide interactive maps and spatial data analysis tools, improving marine environment understanding. By integrating geospatial data with WebGIS, researchers and decision-makers can access real-time information, visualize spatial patterns, and make informed marine management and conservation decisions.

A notable WebGIS integration application is using the Haversine formula with Google Maps to recommend the nearest private universities (PTS) based on user location [14]. This demonstrates WebGIS systems' potential to enhance spatial decision-making through accurate distance measurements and location-based services. The Haversine formula, which calculates the shortest distance between two Earth points, is valuable in WebGIS applications for ensuring precise geospatial analyses and recommendations.

Moreover, integrating geospatial analysis with WebGIS systems broadens oceanographic data dissemination to scientists, policymakers, and the public. By offering user-friendly interfaces and interactive visualization tools, WebGIS platforms empower users to explore marine data, analyze spatial trends, and assess environmental changes' impacts on ocean ecosystems. Enhanced accessibility to marine research data fosters transparency, facilitates collaboration among scientists and stakeholders, and enables informed decision-making in marine resource management and conservation strategies. This is crucial given the complexities of marine ecosystems and the challenges posed by climate change, shipping activities, and pollution, necessitating coordinated responses based on reliable, shared information [1, 17, 5, 19, 22].

WebGIS systems also support integrating diverse data sources, including satellite imagery, in-situ measurements, and IoT sensor data, providing comprehensive insights into ocean dynamics. Incorporating multiple data layers and executing spatial analyses within a WebGIS environment significantly enhances ocean drift simulations and trajectory predictions' precision and dependability. This capability is essential for addressing complex marine challenges, such as pollution tracking, habitat mapping, and resource management [1, 11, 4, 13, 15].

6 Applications in Environmental Monitoring

6.1 Pollutant Tracking and Microplastic Pathways

Pollutant tracking, including microplastic pathways, is crucial for understanding marine pollution's ecological impacts and developing effective mitigation strategies. The complexity of marine environments and the small size of microplastics pose significant challenges to tracking their distribution and pathways [19]. Ocean drift simulations are essential for predicting microplastic abundance, providing benchmarks that enhance the understanding of their distribution over time [8]. Integrating these benchmarks with long-term current measurements is vital for model validation and prediction reliability [45].

In addition to microplastics, tracking larger pollutants like oil slicks and icebergs is critical for environmental assessments. Iceberg dynamics significantly influence ocean currents and contribute to sea-level rise, making them essential for climate modeling [17]. Innovative frameworks that elucidate wind-drift currents improve navigation and environmental management applications [31]. Comprehensive datasets, such as those from the Automatic Identification System (AIS), advance maritime trajectory prediction algorithms, facilitating pollutant tracking and trajectory prediction advancements [9].

Effectively tracking pollutants and microplastic pathways requires integrating advanced numerical modeling techniques, long-term observational data, and standardized benchmarks. These components are essential for accurately simulating microplastic distribution and dynamics, considering factors like ocean currents, wind effects, and particle interactions [19, 17, 11, 8]. Such efforts enhance envi-

ronmental management and contribute to mitigating marine pollution, promoting marine ecosystems' health and sustainability.

6.2 Oil Spill Trajectory Predictions

Oil spill trajectory predictions provide critical insights into the movement and dispersion of oil, essential for environmental monitoring and response strategies. Recent advancements in modeling techniques, such as support vector regression for real-time wind drift factor computation, enhance prediction precision by accounting for dynamic environmental conditions [16, 17, 36, 30]. Oil presence on the water surface can significantly reduce wind stress and Ekman currents, necessitating the incorporation of these effects into trajectory models for improved accuracy [30]. Dynamic models like the Support Vector Regression-Parameterization Model (SVR-PM) dynamically calculate the Wind Drift Factor (WDF) based on real-time conditions, enhancing applicability across scenarios [16].

Attention-based architectures, such as the VarLSTM, refine predictions by capturing uncertainties in vessel movements, crucial for maritime surveillance and spill response [56]. Innovative methodologies, including the wave-modified mixing-length model, highlight the importance of accurately representing wind and wave interactions in simulations [32]. Data-based models achieve significant forecasting accuracy, demonstrating competitive results compared to state-of-the-art models [55].

The application of trajectory prediction methods in forecasting oil spill movements is crucial for environmental monitoring and response. By incorporating dynamic environmental factors, employing advanced machine learning architectures, and utilizing real-time satellite data, these models significantly improve trajectory prediction accuracy, aiding in understanding spill movement and impact [16, 42, 30].

6.3 IoT in Environmental Research

Integrating Internet of Things (IoT) technologies into environmental research transforms marine ecosystem study and management, leveraging pervasive sensing infrastructure and geospatial analysis to enhance understanding, modeling, and visualization [5, 1, 42]. IoT devices, equipped with sensors and communication capabilities, enable precise monitoring of dynamic environmental processes.

IoT technologies enhance monitoring through continuous data collection from various sources, improving predictive models that simulate environmental changes. These models, integrating depth-dependent wind drift factors and advanced machine learning techniques, enhance ocean drift pattern and pollutant pathway accuracy [16, 11, 13]. High-resolution real-time data capture temporal and spatial variability, enhancing assessment accuracy and reliability.

The integration of IoT with WebGIS systems amplifies monitoring potential by providing interactive data visualization and analysis platforms. WebGIS technology enhances geographical information access, facilitating environmental monitoring through educational resources [14]. IoT technologies facilitate deploying advanced autonomous systems, such as underwater gliders and buoys, capable of operating in challenging environments. These systems function as virtual moorings, dynamically adjusting positions for optimized data collection [1, 42, 58, 40, 35]. Continuous data streams inform adaptive management strategies, allowing timely responses to environmental changes and threats.

6.4 Autonomous Underwater Gliders in Ocean Monitoring

Autonomous underwater gliders, like the Seaglider, play a pivotal role in ocean monitoring by efficiently collecting oceanographic data over extended periods and vast areas. Designed for autonomous operation, these gliders conduct long-duration missions without constant human intervention, reducing operational costs and enhancing data collection efficiency [35].

Equipped with sensors measuring oceanographic parameters, Seagliders enable high-resolution data collection essential for understanding ocean dynamics, including thermohaline circulation and biogeochemical processes [44, 23, 17]. Data collected by these gliders are invaluable for calibrating and validating ocean models, improving predictions related to ocean circulation patterns and climate variability.

These gliders are instrumental in monitoring remote ocean areas, where traditional vessels face logistical challenges. By traversing various regions, they generate continuous high-resolution data streams crucial for monitoring environmental changes and assessing marine ecosystem dynamics, enhancing climate system understanding [17, 35]. Real-time data acquisition supports adaptive management strategies, enabling timely responses to environmental threats.

Incorporating autonomous underwater gliders into monitoring programs enhances capacity for extensive assessments, as these gliders function as dynamic virtual moorings. This innovative approach reduces costs and complexities associated with traditional moorings, allowing real-time adjustments to changing conditions. By utilizing predictive models of ocean currents, these gliders maintain precise positions, enhancing data collection and understanding of oceanographic processes [58, 23, 17, 35]. Leveraging these gliders' capabilities improves understanding of oceanic processes, contributing to effective environmental management and conservation efforts.

7 Challenges and Future Directions

7.1 Model Parameterization and Physical Processes

Model parameterization and the representation of physical processes are critical challenges in ocean drift simulations, affecting model accuracy and reliability. A significant issue is the dynamic nature of environmental factors, particularly the variability of the Wind Drift Factor (WDF), often oversimplified as a constant in existing models, leading to inaccuracies in simulating oil spills and pollutants [16]. Accurately representing diapycnal mixing, turbulent flows, and mesoscale eddies is essential for realistic simulations, yet remains challenging [28]. Moreover, inadequate incorporation of wave effects into mean momentum balance complicates near-surface current predictions, increasing potential inaccuracies [32].

Current methodologies frequently rely on assumptions about drift factor calculations, which may not be valid under all conditions, affecting drift current estimations, especially in dynamic environments [11]. This reliance can lead to discrepancies in model outputs, particularly where various wave parameters influence measurements. The lack of long-term observational data with high spatial and temporal resolution is a significant barrier to validating model outputs, emphasizing the need for comprehensive datasets that capture oceanic process variability [45]. Existing benchmarks may inadequately reflect transient wind variability, especially in complex atmospheric conditions, underscoring the necessity for refined parameterizations [29].

Future research should focus on developing models that incorporate local knowledge and adaptive communication strategies to enhance navigation safety in mixed maritime environments [58]. Additionally, exploring regularizations and enhancements in models like the N-Curve, which processes variable-length sequences, will improve handling of complex oceanographic data [49]. Addressing these challenges is essential for advancing the precision and applicability of ocean drift simulations, ultimately supporting effective environmental management and maritime operations.

7.2 Data Integration and Accuracy

Data integration and accuracy pose significant challenges in ocean drift simulations, impacting the reliability of predictive models across various marine contexts. Integrating heterogeneous data sources, such as satellite observations, in-situ measurements, and IoT sensor data, is crucial for developing comprehensive models that accurately reflect ocean dynamics. However, the reliability of IoT measurements and sensor calibration is a significant challenge, affecting data accuracy. Robust data integration frameworks are necessary to harmonize disparate datasets and enhance simulation precision [28].

Frameworks like GeoCSIF address model heterogeneity through encapsulation, orchestration, and scheduling, facilitating the integration of diverse geospatial-analysis models. However, GeoCSIF may require expansion to accommodate more complex applications, highlighting the need for adaptable data integration solutions. Potential misclassifications and gaps in understanding geospatial content further complicate integration efforts, necessitating refined definitions and methodologies for comprehensive analyses [58].

Ensuring simulation model accuracy is challenging due to the inherent variability and uncertainty of oceanic processes. The complexity of ocean currents and uncertainty regarding microplastic sources and sinks exemplify difficulties in achieving accurate predictions. Additionally, reliance on specific data providers, such as AIS databases, may limit the generalizability of findings to other maritime contexts [29]. Effective uncertainty quantification methods are crucial for enhancing trajectory prediction accuracy, particularly in the face of distribution shifts and model limitations. While methods like fuzzy logic can provide valuable insights, they may overestimate uncertainty, leading to inaccuracies in applications like drift prediction, where precise environmental parameterization is critical [56, 7, 52, 5, 13].

Future research should prioritize refining model parameterizations for unresolved processes and improving the integration of various model components to enhance predictive capabilities. Expanding benchmark protocols and datasets to include diverse ocean models and conditions will be essential for improving simulation model accuracy and reliability. Addressing complexities of wind-driven drift currents, depth-dependent variations, and uncertainties in environmental modeling will significantly enhance ocean drift simulations, crucial for effective environmental management and optimizing maritime operations, particularly in tracking marine debris, predicting iceberg movements, and understanding buoyant object dynamics in the ocean [19, 11, 13, 17].

7.3 Scalability and Real-time Data Processing

Scalability and real-time data processing are pressing challenges in ocean drift simulations, impacting the ability to provide accurate and timely predictions. The unpredictable nature of ocean currents presents significant obstacles for maintaining the position of autonomous monitoring systems, such as underwater gliders, which rely on real-time data processing for effective navigation [35]. This unpredictability necessitates robust data processing frameworks capable of handling the dynamic variability of marine environments.

Enhancing sensor reliability and exploring new data transmission standards are crucial for improving real-time data accuracy in oceanographic research. Comprehensive calibration methods are vital to ensure that data collected from various sensors are reliable and precise, supporting more accurate real-time predictions [1]. Additionally, refining measurement techniques and employing advanced methods for current measurement are essential for validating benchmarks with field data, thereby enhancing their applicability in real-world scenarios [21].

Advanced machine learning techniques offer promising avenues for improving real-time data processing in trajectory predictions. By leveraging these techniques, researchers can optimize algorithms for real-time data analysis, enabling efficient processing of large datasets and enhancing prediction accuracy [54]. Future research should focus on optimizing these algorithms and integrating user feedback to refine recommendations and improve real-time data processing capabilities [47].

Scalability remains a critical challenge, particularly in empirical model calibration across a wide range of wind and wave conditions. Addressing these challenges requires the development of scalable models that can efficiently process real-time data without compromising accuracy [32]. By improving empirical calibration and tackling scalability issues, researchers can enhance the precision and reliability of ocean drift simulations, ultimately supporting effective environmental management and maritime operations.

7.4 Standardization and Validation

Standardization and validation are crucial for advancing ocean drift simulation and trajectory prediction techniques, ensuring model accuracy and reliability in marine environments. The complexity and variability of oceanic processes necessitate standardized benchmarks and datasets, particularly for vessel trajectory clustering methods, to facilitate consistent evaluation and comparison of different algorithms [2]. These benchmarks are essential for addressing maritime data intricacies and enhancing predictive model precision.

Integrating standardized datasets into simulation models is vital for improving accuracy and reliability. Future work should focus on refining models by understanding the long-term implications of wind-driven sea ice variability and exploring interactions between tropical influences and Antarctic

conditions [34]. Such efforts will contribute to a comprehensive understanding of ocean dynamics and support robust simulation framework development.

Advancements in numerical modeling techniques and innovative data collection methodologies are essential for improving validation processes across scientific fields, enhancing predictive model accuracy and robustness. These improvements facilitate a better understanding of complex phenomena, such as iceberg drift dynamics and microplastic behavior in ocean currents, while supporting effective error mitigation strategies in machine learning applications, ultimately leading to more reliable insights [19, 4, 27, 17]. The exploration of sophisticated text analysis methods for better classification and understanding of geospatial content will aid in standardizing geospatial analysis methods, ensuring consistency in model assessments across studies. Additionally, refining remote sensing technologies, such as Polarimetric Slope Sensing (PSS), and integrating them with other measurement techniques will strengthen the validation of ocean drift simulations.

Future research should prioritize enhancing the integration of wave evolution and turbulence dynamics by developing advanced models that account for complex interactions at the air-sea interface. Comprehensive experimental measurements of ripple fields are crucial, as these data provide insights into the transition from wind-driven surface flows to turbulence, improving understanding of momentum and gas exchanges in oceanic environments. This focus will help validate theoretical frameworks, such as the Craik-Leibovich model, and address model sensitivity to evolving surface ripple states [12, 31, 25, 11]. These efforts will enhance simulation model accuracy and support standardized modeling approaches. Furthermore, exploring the implications of the combined Stokes drift profile on Langmuir turbulence and the Coriolis-Stokes force will contribute to establishing comprehensive modeling frameworks.

The advancement of next-generation sensors, refined calibration methods, and improved temporal and spatial resolution is crucial for accurately measuring the intricate dynamics of wind and environmental factors in marine settings, particularly in the near-surface layer where wind-driven currents significantly influence material transport and ecological interactions. These improvements will enable precise assessments of surface drift currents, including atmospheric stress effects and changes in surface roughness due to phenomena like oil spills, which can alter drag coefficients and impact ocean circulation models and pollutant trajectory predictions [30, 11, 20, 23]. Addressing these challenges will ensure the robustness and reliability of ocean drift simulations, ultimately contributing to effective environmental management and maritime operations.

8 Conclusion

The exploration of ocean drift simulation and trajectory prediction reveals the indispensable role of integrating various scientific methodologies and mathematical frameworks to deepen our comprehension of oceanic dynamics and enhance environmental monitoring. The application of high-resolution ocean models, such as the SLIM model, has been instrumental in identifying key connectivity pathways, offering critical insights into larval dispersal and strengthening coral reef resilience. This underscores the importance of detailed spatial resolution in simulating marine processes with precision.

Innovative techniques, including fuzzy-based approaches for managing uncertainty, have shown promise in accurately predicting drift trajectories, rivaling traditional methods in performance. These developments are pivotal in enhancing the dependability of predictive models, particularly in intricate marine environments where uncertainty remains a significant hurdle.

The OpenDrift framework exemplifies robust trajectory modeling capabilities across diverse applications, proving to be a versatile and efficient tool for both researchers and operational entities. Its adaptability highlights the potential benefits of integrating multiple data sources and real-time information to improve the accuracy and utility of ocean drift simulations.

Recognizing the complexity of datasets, as illustrated in benchmark studies, is crucial for refining prediction algorithms in high-throughput processing, indicating potential avenues for future research that could enhance predictive accuracy. This highlights the necessity for comprehensive datasets and standardized benchmarks to foster the development of more precise and reliable predictive models.

The advancement of ocean drift simulation and trajectory prediction relies on the integration of cutting-edge modeling techniques, uncertainty quantification, and comprehensive data frameworks.

These efforts are essential for advancing our understanding of marine dynamics, thereby facilitating effective environmental management and promoting sustainable ocean governance.

www.SurveyX.cn

References

- [1] Andreas Kamilaris and Frank Ostermann. Geospatial analysis and internet of things in environmental informatics, 2018.
- [2] Maohan Liang, Ryan Wen Liu, Ruobin Gao, Zhe Xiao, Xiaocai Zhang, and Hua Wang. A survey of distance-based vessel trajectory clustering: Data pre-processing, methodologies, applications, and experimental evaluation, 2024.
- [3] Harris Georgiou, Sophia Karagiorgou, Yannis Kontoulis, Nikos Pelekis, Petros Petrou, David Scarlatti, and Yannis Theodoridis. Moving objects analytics: Survey on future location trajectory prediction methods, 2018.
- [4] Alexander Yoshizumi, Megan M. Coffey, Elyssa L. Collins, Mollie D. Gaines, Xiaojie Gao, Kate Jones, Ian R. McGregor, Katie A. McQuillan, Vinicius Perin, Laura M. Tomkins, Thom Worm, and Laura Tateosian. A review of geospatial content in iee visualization publications, 2020.
- [5] Efriza Yunardi, Lena Magdalena, and Mesi Febima. Implementation of the haversine formula method in geographic information systems for searching the nearest sea freight expedition services in east jakarta. *Journal of Artificial Intelligence and Engineering Applications (JAIEA)*, 4(1):283–288, 2024.
- [6] Jasmine Sekhon and Cody Fleming. A spatially and temporally attentive joint trajectory prediction framework for modeling vessel intent, 2019.
- [7] Duncan Eddy and Mykel Kochenderfer. Satellite image tasking under orbit prediction uncertainty, 2019.
- [8] Atsuhiko Isobe, Shinsuke Iwasaki, Keiichi Uchida, and Tadashi Tokai. Abundance of non-conservative microplastics in the upper ocean from 1957 to 2066. *Nature communications*, 10(1):417, 2019.
- [9] Shangbo Mao, Enmei Tu, Guanghao Zhang, Lily Rachmawati, Eshan Rajabally, and Guang-Bin Huang. An automatic identification system (ais) database for maritime trajectory prediction and data mining, 2016.
- [10] Baylor Fox-Kemper, Alistair Adcroft, Claus W Böning, Eric P Chassignet, Enrique Curchitser, Gokhan Danabasoglu, Carsten Eden, Matthew H England, Rüdiger Gerdes, Richard J Greatbatch, et al. Challenges and prospects in ocean circulation models. *Frontiers in Marine Science*, 6:65, 2019.
- [11] Mirjam Van der Mheen, Charitha Pattiaratchi, Simone Cosoli, and Moritz Wandres. Depth-dependent correction for wind-driven drift current in particle tracking applications. *Frontiers in Marine Science*, 7:305, 2020.
- [12] Gregory LeClaire Wagner, Nick Pizzo, Luc Lenain, and Fabrice Veron. Transition to turbulence in wind-drift layers. *Journal of Fluid Mechanics*, 976:A8, 2023.
- [13] Hauke Blanken, Caterina Valeo, Charles Hannah, Usman T Khan, and Tamás Juhász. A fuzzy-based framework for assessing uncertainty in drift prediction using observed currents and winds. *Frontiers in Marine Science*, 8:618094, 2021.
- [14] Nurul Islam Hasanah, Somantri Somantri, and Alun Sujjada. Implementation of the haversine formula in the webgis of private universities in west java and banten. *IDEALIS: InDonEsiA journal Information System*, 7(2):178–188, 2024.
- [15] Lili Zhu, Yang Wang, Yunbo Kong, Yanfeng Hu, and Kai Huang. A containerized service-based integration framework for heterogeneous-geospatial-analysis models. *ISPRS International Journal of Geo-Information*, 13(1):28, 2024.
- [16] Darong Liu, Yan Li, and Lin Mu. Parameterization modeling for wind drift factor in oil spill drift trajectory simulation based on machine learning. *Frontiers in Marine Science*, 10:1222347, 2023.

-
- [17] Till JW Wagner, Rebecca W Dell, and Ian Eisenman. An analytical model of iceberg drift. *Journal of Physical Oceanography*, 47(7):1605–1616, 2017.
- [18] Ulrich Callies, Nikolaus Groll, Jochen Horstmann, Hartmut Kapitza, Holger Klein, Silvia Maßmann, and Fabian Schwichtenberg. Surface drifters in the german bight: model validation considering windage and stokes drift. *Ocean Science*, 13(5):799–827, 2017.
- [19] Britta D Hardesty, Joseph Harari, Atsuhiko Isobe, Laurent Lebreton, Nikolai Maximenko, Jim Potemra, Erik Van Sebille, A Dick Vethaak, and Chris Wilcox. Using numerical model simulations to improve the understanding of micro-plastic distribution and pathways in the marine environment. *Frontiers in marine science*, 4:30, 2017.
- [20] Nathan JM Laxague, Brian K Haus, David G Ortiz-Suslow, Conor J Smith, Guillaume Novelli, Hanjing Dai, Tamay Özgökmen, and Hans C Graber. Passive optical sensing of the near-surface wind-driven current profile. *Journal of Atmospheric and Oceanic Technology*, 34(5):1097–1111, 2017.
- [21] Vladislav Polnikov, Fangli Qiao, and Hongyu Ma. Surface drift currents induced by waves and wind in a large tank. *Journal of Physical Oceanography*, 50(10):3063–3073, 2020.
- [22] Charles Frys, Antoine Saint-Amand, Matthieu Le Hénaff, Joana Figueiredo, Alyson Kuba, Brian Walker, Jonathan Lambrechts, Valentin Vallaes, David Vincent, and Emmanuel Hanert. Fine-scale coral connectivity pathways in the florida reef tract: implications for conservation and restoration. *Frontiers in Marine Science*, 7:312, 2020.
- [23] Mark A Bourassa, Thomas Meissner, Ivana Cerovecki, Paul S Chang, Xiaolong Dong, Giovanna De Chiara, Craig Donlon, Dmitry S Dukhovskoy, Jocelyn Elya, Alexander Fore, et al. Remotely sensed winds and wind stresses for marine forecasting and ocean modeling. *Frontiers in Marine Science*, 6:443, 2019.
- [24] Scott C James, Yushan Zhang, and Fearghal O’Donncha. A machine learning framework to forecast wave conditions. *Coastal Engineering*, 137:1–10, 2018.
- [25] Yukun Wang, Yuji Sugihara, Yoshihiro Nakamura, and Osama Eljamal. Experimental investigation on the wind-driven surface flow associated with breaking waves. *Journal of Japan Society of Civil Engineers, Ser. B2 (Coastal Engineering)*, 76(2):I_169–I_174, 2020.
- [26] Pallavi Banerjee and Satyaki Chakraborty. Graphtransformers for geospatial forecasting of hurricane trajectories, 2023.
- [27] Dibyajyoti Chakraborty, Shivam Barwey, Hong Zhang, and Romit Maulik. A note on the error analysis of data-driven closure models for large eddy simulations of turbulence, 2024.
- [28] Stephen Griffies. *Fundamentals of ocean climate models*. Princeton university press, 2018.
- [29] Maria Belmonte Rivas and Ad Stoffelen. Characterizing era-interim and era5 surface wind biases using ascats. *Ocean Science*, 15(3):831–852, 2019.
- [30] Hui Shen, William Perrie, and Yongsheng Wu. Wind drag in oil spilled ocean surface and its impact on wind-driven circulation. *Anthropocene Coasts*, 2(1):244–260, 2019.
- [31] Vladislav Polnikov. A semi-phenomenological model for wind-induced drift currents. *Boundary-Layer Meteorology*, 172(3):417–433, 2019.
- [32] Journal of physical oceanography.
- [33] Jiang Wu, Dongyu Liu, Yuchen Lin, and Yingcai Wu. Catp: Context-aware trajectory prediction with competition symbiosis, 2024.
- [34] Zhaomin Wang, John Turner, Yang Wu, and Chengyan Liu. Rapid decline of total antarctic sea ice extent during 2014–16 controlled by wind-driven sea ice drift. *Journal of Climate*, 32(17):5381–5395, 2019.

-
- [35] Andrew Branch, Martina Troesch, Mar Flexas, AF Thompson, John Ferrara, Yi Chao, and Steve Chien. Station keeping with an autonomous underwater glider using a predictive model of ocean currents. In *Proc. 26th Int. Joint Conf. on Artificial Intelligence (IJCAI-17)*, 2017.
- [36] Duong Nguyen and Ronan Fablet. Traisformer – a transformer network with sparse augmented data representation and cross entropy loss for ais-based vessel trajectory prediction, 2024.
- [37] Samuele Capobianco, Leonardo M. Millefiori, Nicola Forti, Paolo Braca, and Peter Willett. Deep learning methods for vessel trajectory prediction based on recurrent neural networks, 2021.
- [38] Huimin Qiang, Zhiyuan Guo, Shiyuan Xie, and Xiaodong Peng. Mstformer: Motion inspired spatial-temporal transformer with dynamic-aware attention for long-term vessel trajectory prediction, 2023.
- [39] Changlin Li, Yanglei Gan, Tian Lan, Yuxiang Cai, Xueyi Liu, Run Lin, and Qiao Liu. Diffutraj: A stochastic vessel trajectory prediction approach via guided diffusion process, 2024.
- [40] Chih-Wei Chen, Charles Harrison, and Hsin-Hsiung Huang. The unsupervised method of vessel movement trajectory prediction, 2020.
- [41] Knut-Frode Dagestad, Johannes Röhrs, Øyvind Breivik, and Bjørn Ådlandsvik. Opendrift v1. 0: a generic framework for trajectory modelling. *Geoscientific Model Development*, 11(4):1405–1420, 2018.
- [42] Angelos Valsamis, Konstantinos Tserpes, Dimitrios Zissis, Dimosthenis Anagnostopoulos, and Theodora Varvarigou. Employing traditional machine learning algorithms for big data streams analysis: the case of object trajectory prediction, 2016.
- [43] A combined stokes drift profile.
- [44] James C Orr, Raymond G Najjar, Olivier Aumont, Laurent Bopp, John L Bullister, Gokhan Danabasoglu, Scott C Doney, John P Dunne, Jean-Claude Dutay, Heather Graven, et al. Biogeochemical protocols and diagnostics for the cmip6 ocean model intercomparison project (omip). *Geoscientific Model Development*, 10(6):2169–2199, 2017.
- [45] Long-term mean circulation of th.
- [46] Javad Amirian, Bingqing Zhang, Francisco Valente Castro, Juan Jose Baldelomar, Jean-Bernard Hayet, and Julien Pettre. Opentraj: Assessing prediction complexity in human trajectories datasets, 2020.
- [47] Rani Purbaningtyas, Arif Arizal, Muhammad Sholehuddin, et al. Regional leading potential recommendations: Implementation of haversine formula in sidoarjo on hands mobile applications. *Problems of Information Technology*, pages 70–76, 2019.
- [48] Dwi Arman Prasetya, Phong Thanh Nguyen, Rinat Faizullin, Iswanto Iswanto, and Edmond Febrinicko Armay. Resolving the shortest path problem using the haversine algorithm. *Journal of critical reviews*, 7(1):62–64, 2020.
- [49] Ronny Hug, Wolfgang Hübner, and Michael Arens. Modeling continuous-time stochastic processes using \mathcal{N} -curve mixtures, 2019.
- [50] Christian Schlauch, Nadja Klein, and Christian Wirth. Informed priors for knowledge integration in trajectory prediction, 2022.
- [51] Cenk Demir and Abhyudai Singh. Prediction and control of projectile impact point using approximate statistical moments, 2017.
- [52] Huiqun Huang, Sihong He, and Fei Miao. Cuqds: Conformal uncertainty quantification under distribution shift for trajectory prediction, 2025.
- [53] Young-Jae Park, Minseok Seo, Doyi Kim, Hyeri Kim, Sanghoon Choi, Beomkyu Choi, Jeongwon Ryu, Sohee Son, Hae-Gon Jeon, and Yeji Choi. Long-term typhoon trajectory prediction: A physics-conditioned approach without reanalysis data, 2024.

-
- [54] Aghus Sofwan, Yosua Alvin Adi Soetrisno, Natalia Putri Ramadhani, Amiko Rahmayani, Eko Handoyo, and M Arfan. Vehicle distance measurement tuning using haversine and micro-segmentation. In *2019 International Seminar on Intelligent Technology and Its Applications (ISITIA)*, pages 239–243. IEEE, 2019.
- [55] Rikhi Bose, Adam Pintar, and Emil Simiu. Data-based models for hurricane evolution prediction: A deep learning approach, 2021.
- [56] Samuele Capobianco, Nicola Forti, Leonardo M. Millefiori, Paolo Braca, and Peter Willett. Recurrent encoder-decoder networks for vessel trajectory prediction with uncertainty estimation, 2022.
- [57] Evangelos Psomakelis, Konstantinos Tserpes, Dimitris Zissisc, Dimosthenis Anagnostopoulos, and Theodora Varvarigou. Context agnostic trajectory prediction based on λ -architecture, 2019.
- [58] Danilo Pianini and Sven Tomforde. Towards adaptive trajectories for mixed autonomous and human-operated ships, 2024.

Disclaimer:

SurveyX is an AI-powered system designed to automate the generation of surveys. While it aims to produce high-quality, coherent, and comprehensive surveys with accurate citations, the final output is derived from the AI's synthesis of pre-processed materials, which may contain limitations or inaccuracies. As such, the generated content should not be used for academic publication or formal submissions and must be independently reviewed and verified. The developers of SurveyX do not assume responsibility for any errors or consequences arising from the use of the generated surveys.

www.SurveyX.cn