



EfficientNet: Rethinking Model Scaling for Convolutional Neural Networks

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BACKGROUND

EVOLUTION OF CNNs



AlexNet (2012)

First winner of the ImageNet challenge based on a CNN

VGGNet (2014)

Depth is critical in CNN design

ResNet (2015)

Residual blocks skip connection

GoogLeNet (2014)

Reduce parameter count, memory usage, and computation

ZFNet (2013)

Change in hyper parameter



EfficientNet

EVOLUTION OF CNNs



Observation 1:

More sophisticated architecture

Larger scale

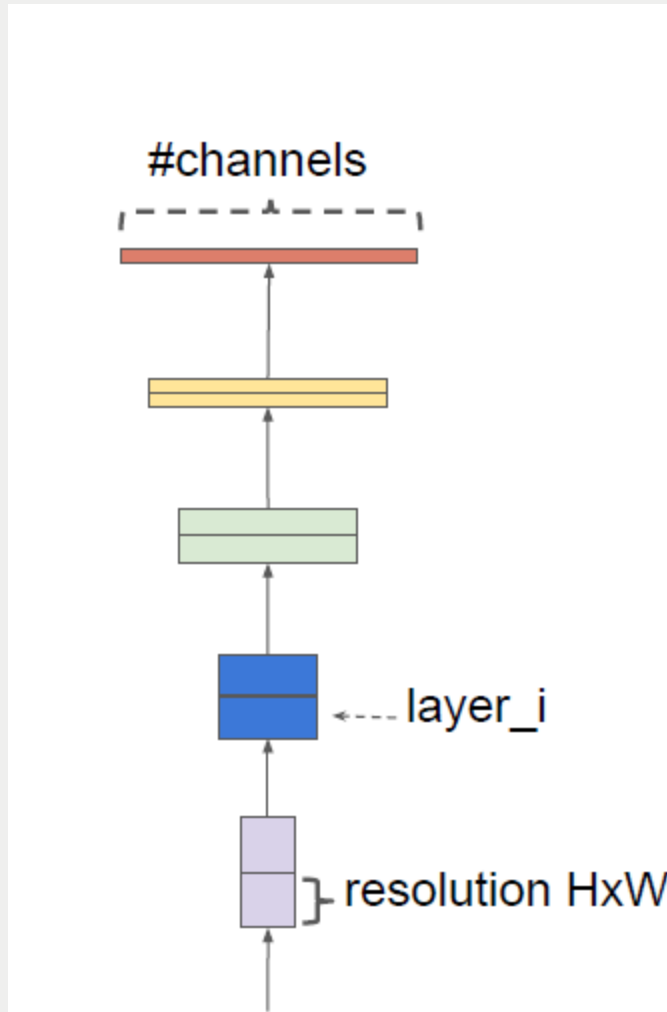


Better performance



MOTIVATION

SCALING UP CNNs

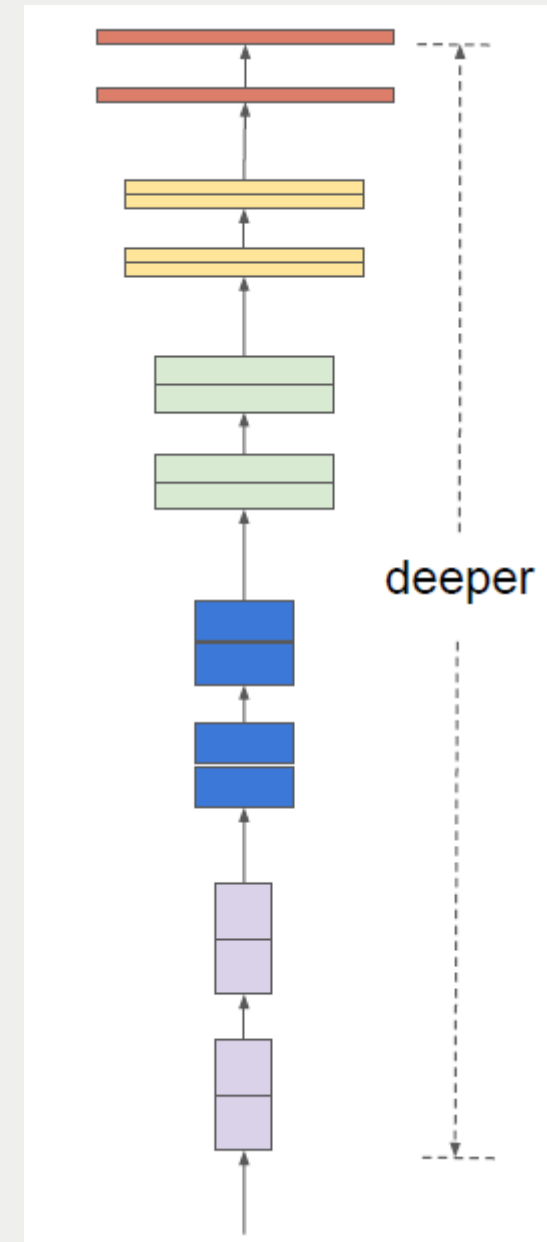


Baseline

Add more layers



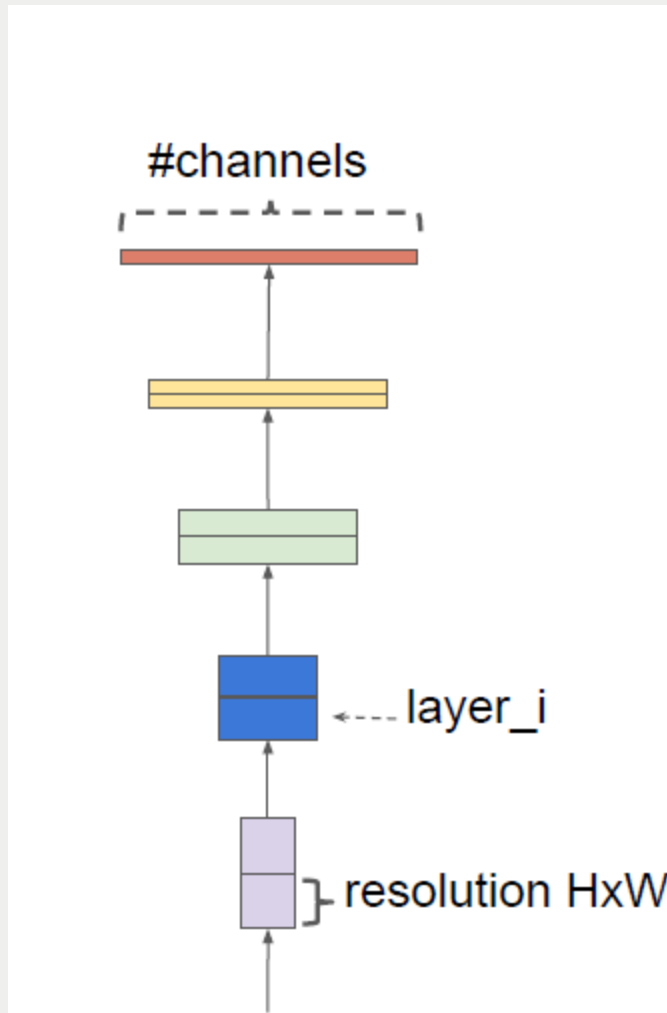
Depth coefficient: d
(In this case, $d=2$)



Depth scaling



SCALING UP CNNs

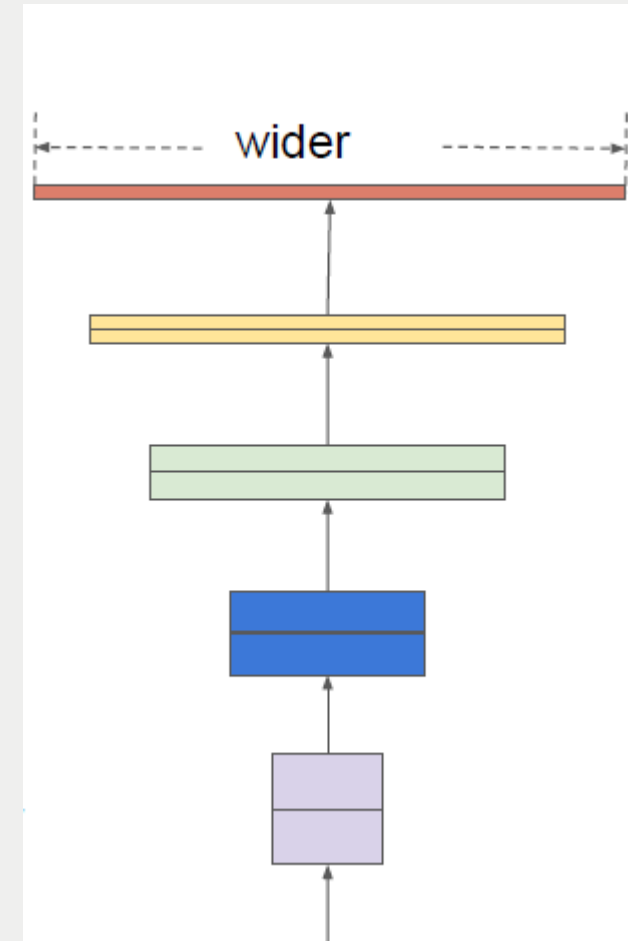


Baseline

Add more channels

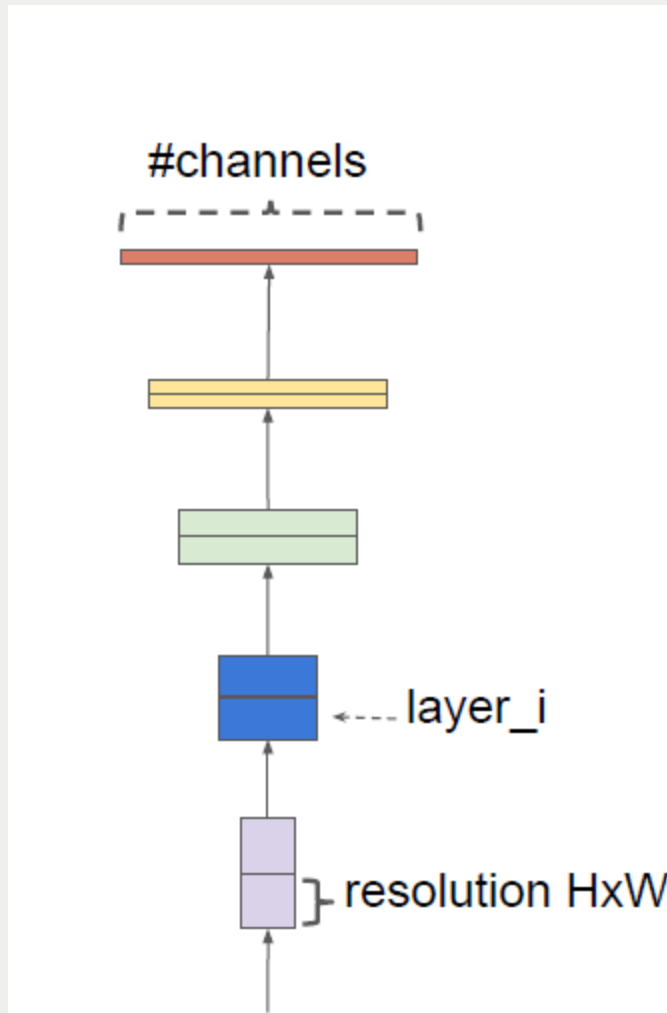


Width coefficient: w



Width scaling

SCALING UP CNNs

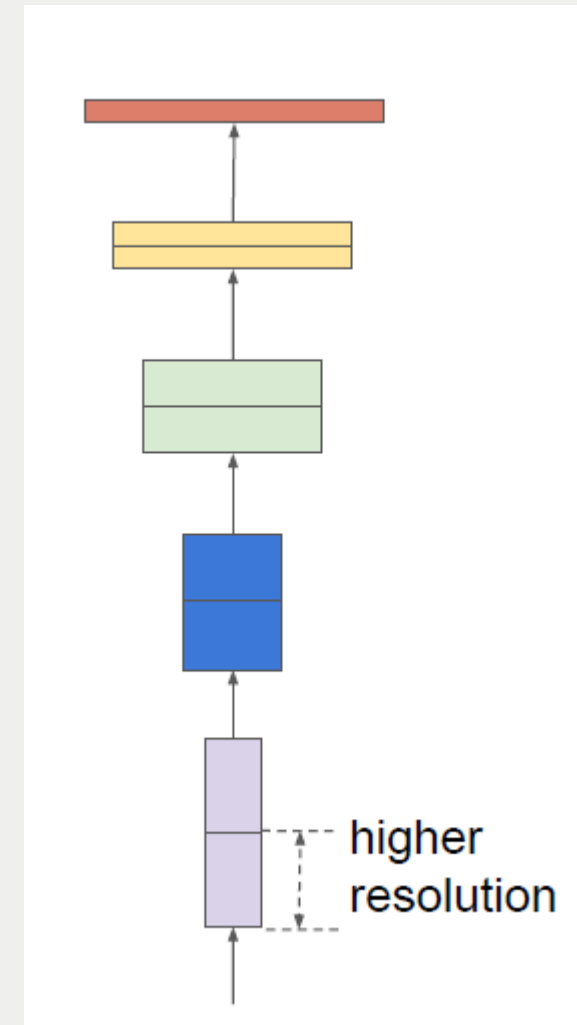


Baseline

Higher resolution
of input image



Resolution
coefficient: r

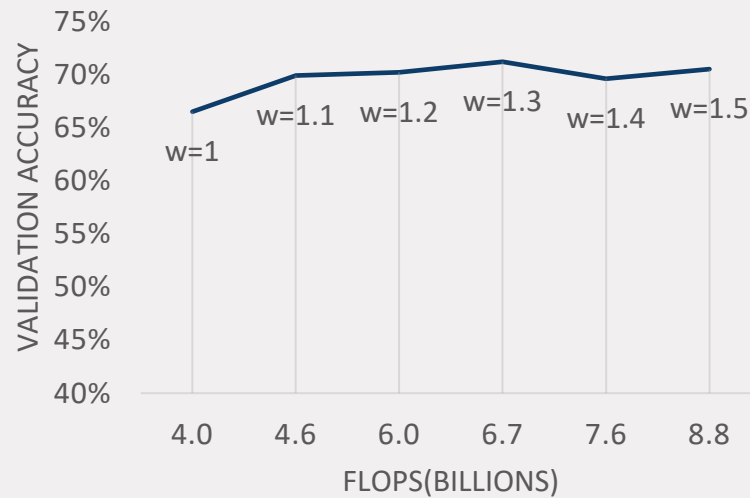


Resolution scaling

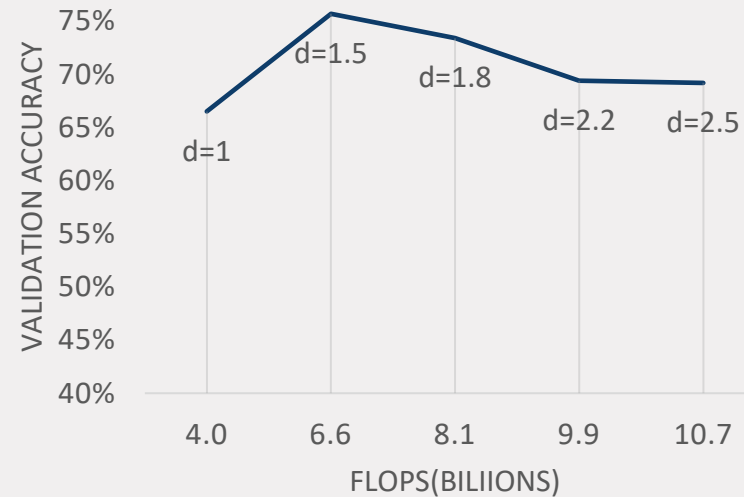
EMPIRICAL STUDY



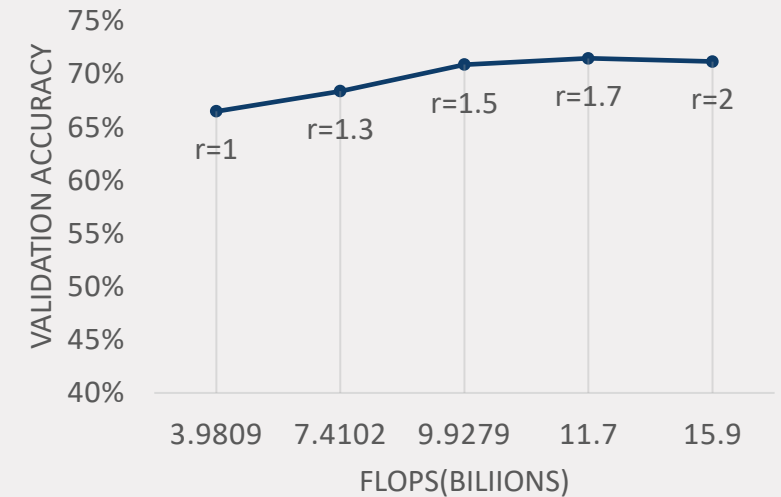
Change in Width



Change in Depth



Change in Resolution



Experiment setting:

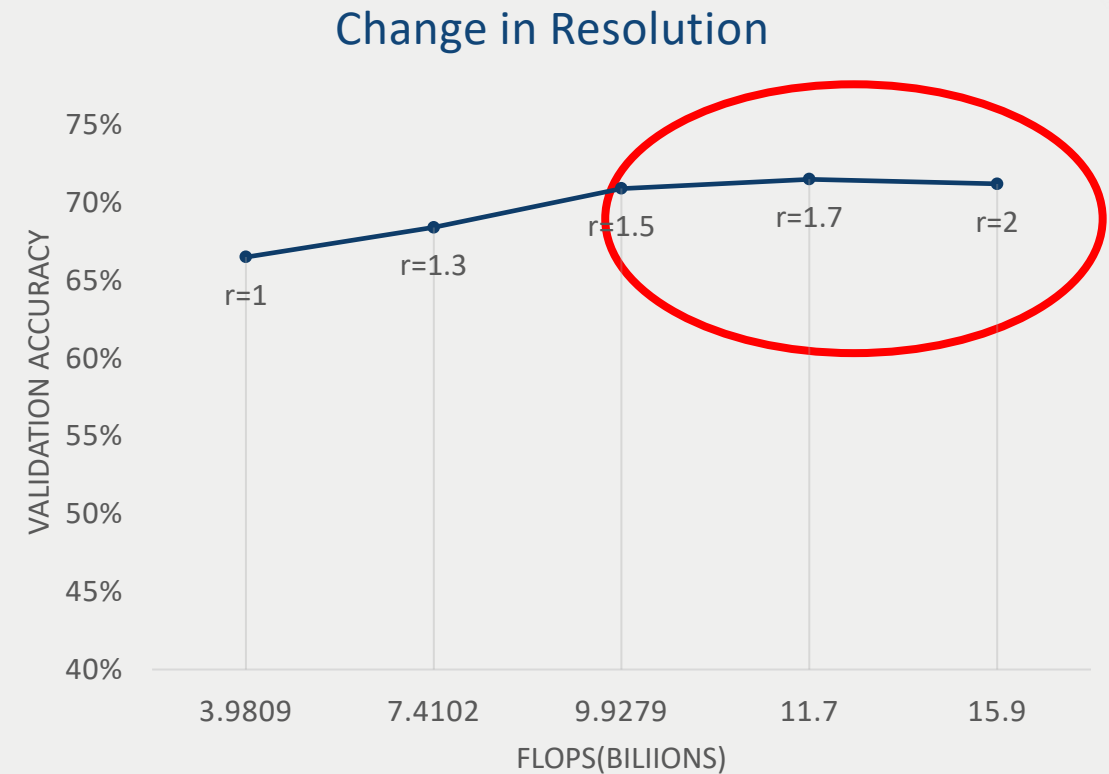
- Baseline: EfficientNet-B0 (Structure will be detailed discussed later)
- Dataset: CIFAR-10 with only 3 classes (cat, deer and dog),
15k~ training samples, 3k~ testing samples
- Epochs: 40

EMPIRICAL STUDY



Observation 2:

Scaling up any dimension of network width, depth, or resolution improves accuracy, but the degree of benefit diminishes as the models grow larger.



MOTIVATION



But different scaling dimensions are **not independent**.

They are **interrelated**.

MOTIVATION



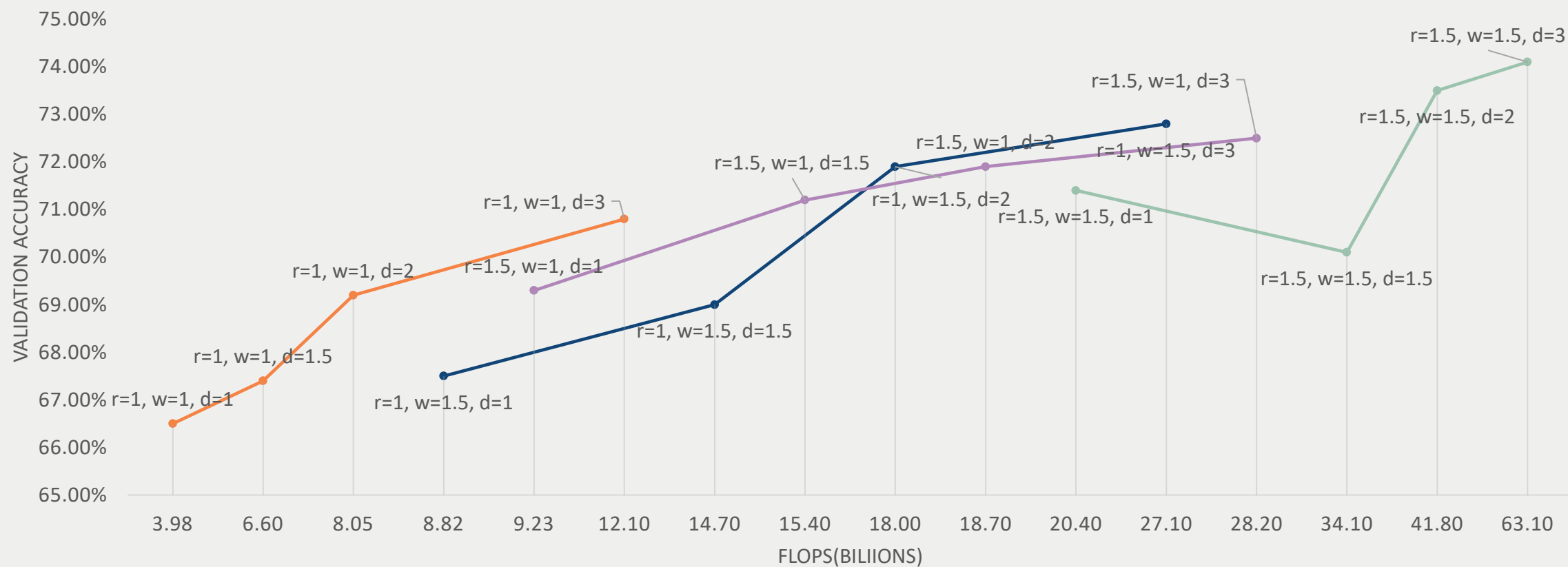
So.....

Uniformly scaling up the coefficients!

Compound Scaling



Compound Scaling



Compound Scaling



Observation 3:

In order to pursue better accuracy and efficiency, it is critical to balance all dimensions of network width, depth, and resolution during ConvNet scaling.

MOTIVATION

Based on *observation 2* & 3 —

Observation 2:

Scaling up any dimension of network improves accuracy, but the degree of benefit diminishes as the models grow larger.

Observation 3:

We need to balance all dimensions of network during ConvNet scaling.



MOTIVATION

Based on *observation 2 & 3* —



Question:

How to balance the three dimensions of neural networks?

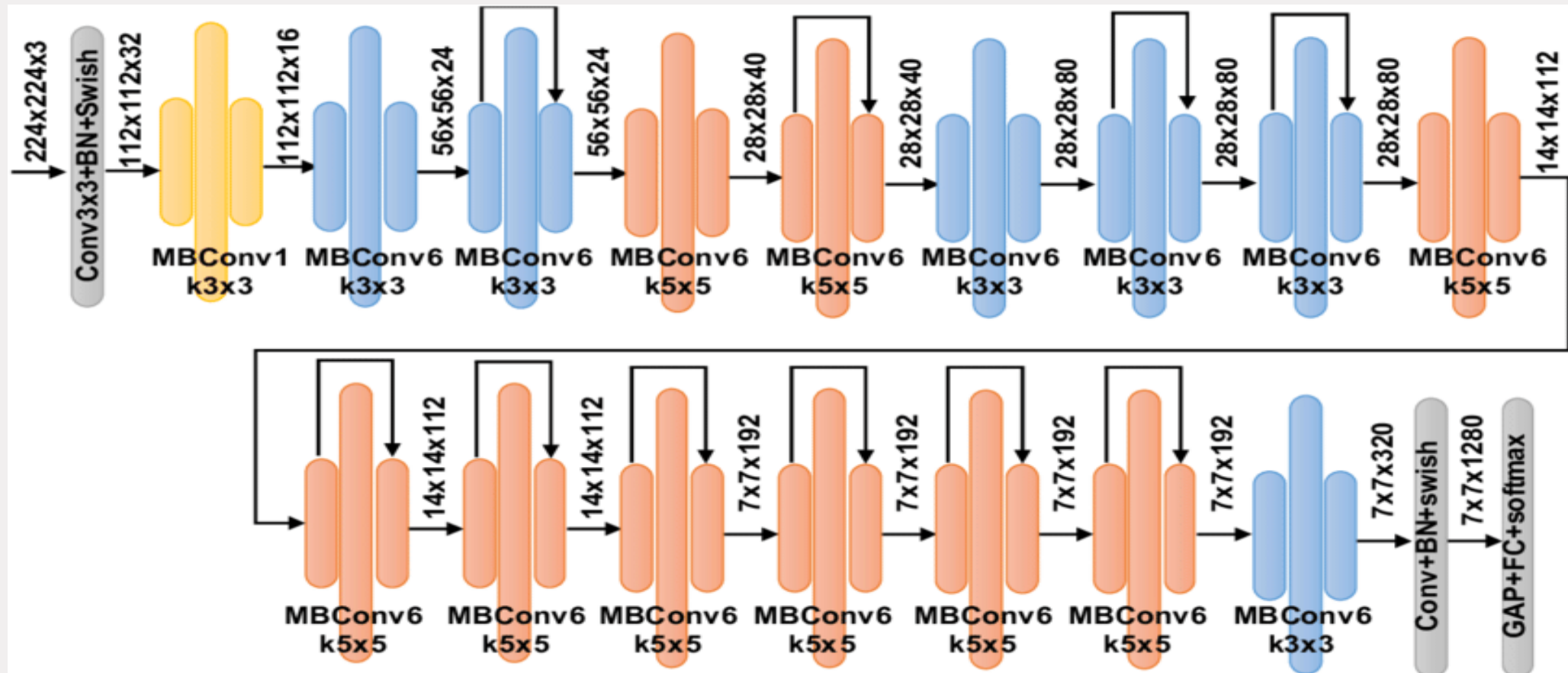


REPRODUCTION



EFFICIENTNET B0 ARCHITECTURE

Before talking about result, go through the general architecture of EfficientNet B0 (Baseline).



EFFICIENTNET REPRODUCTION

To conclude, there are two main parts for our reproduction:

1. To determine the optimal combination of depth, width, and resolution for specific computation resources.

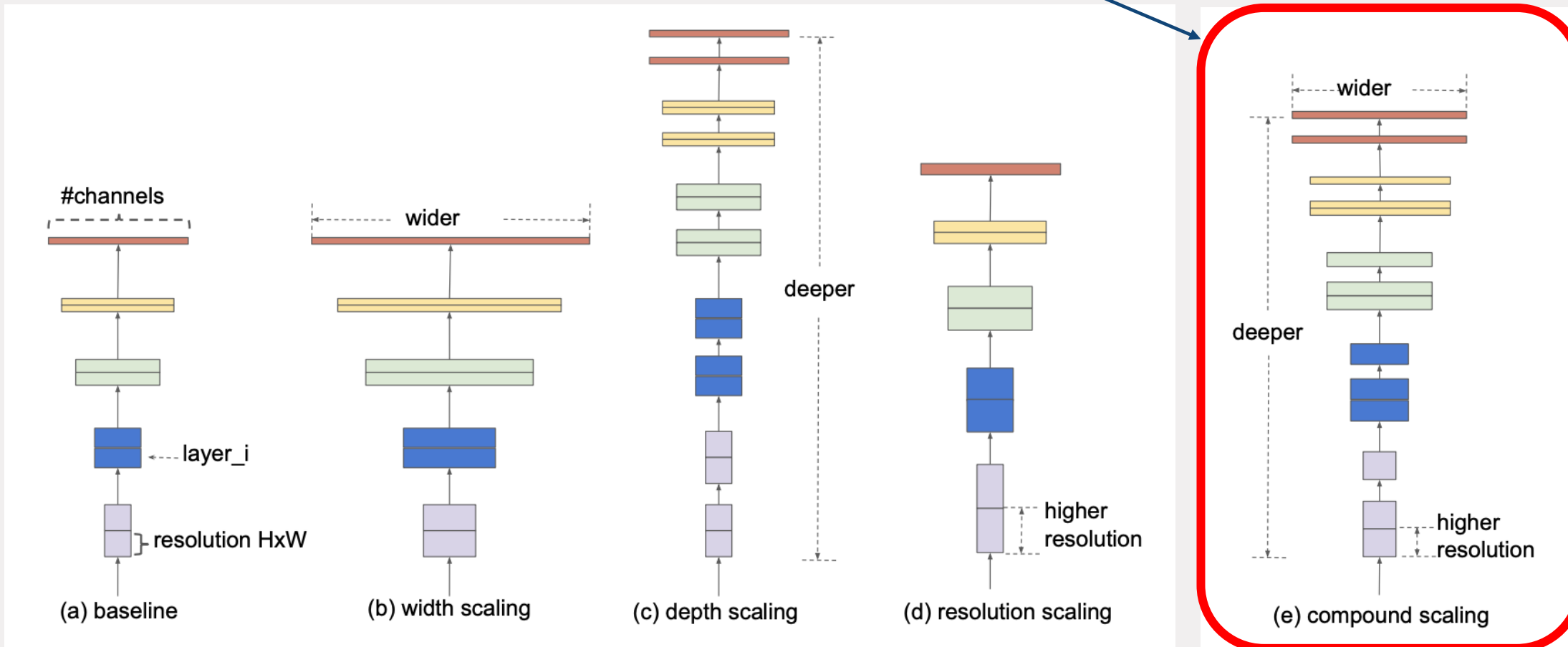
2. Compare the performance of EfficientNet with other convolutional neural network (CNN) architectures.



EFFICIENTNET REPRODUCTION

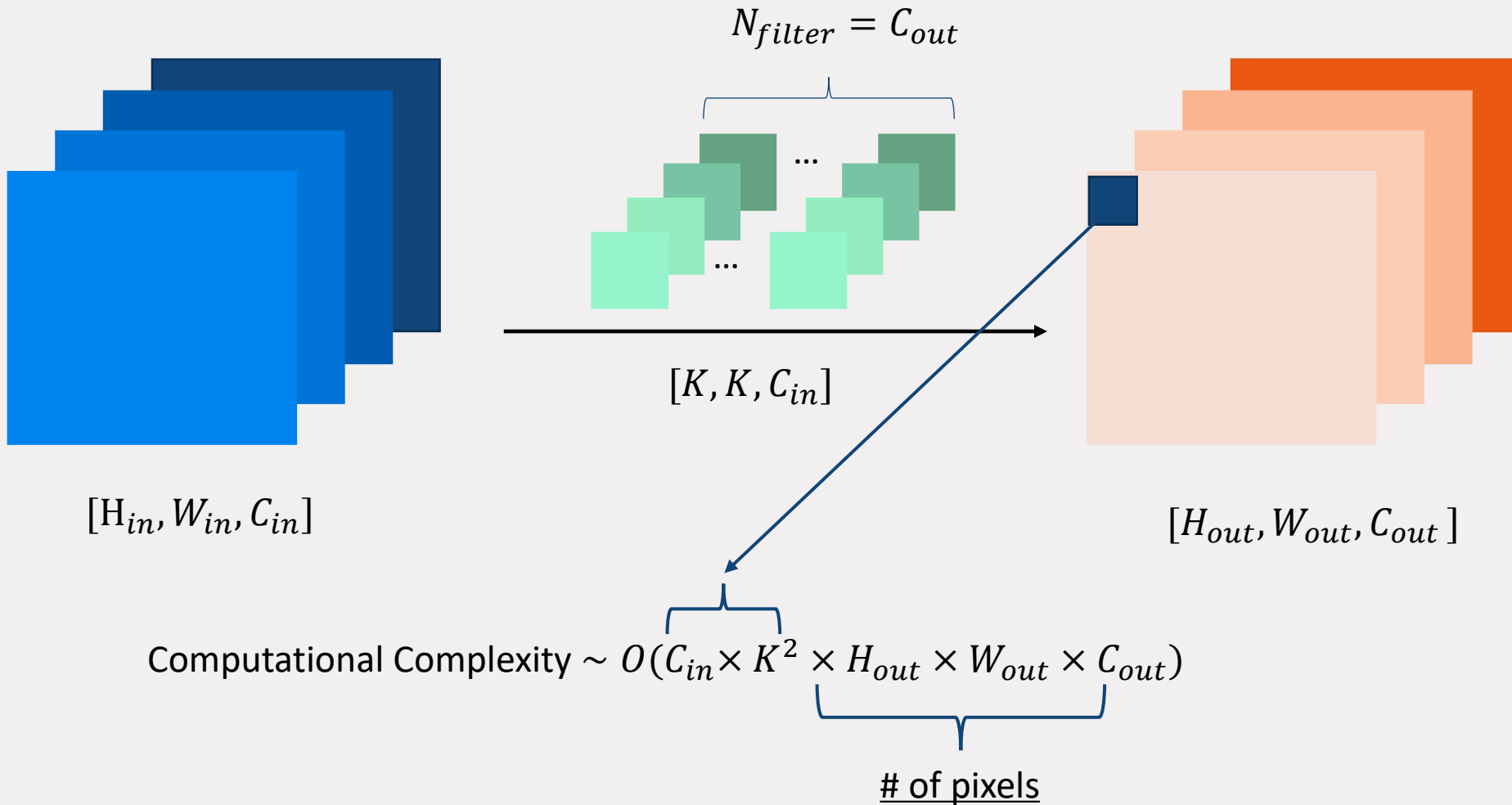
First part: Determine combination of depth, width, resolution

Efficient Net proposes 'Compound Scaling' Scheme to determine the optimal scaling factors.



EFFICIENTNET REPRODUCTION

First part: Determine combination of depth, width, resolution



EFFICIENTNET REPRODUCTION

First part: Determine combination of depth, width, resolution



Result: Computational Complexity $\sim O(C_{in} \times K^2 \times H_{out} \times W_{out} \times C_{out})$

Scaling factor: β	\longleftrightarrow	Width: w	\longleftrightarrow	(C_{in}, C_{out})
Scaling factor: γ	\longleftrightarrow	Resolution: r	\longleftrightarrow	(H_{out}, W_{out})

Conclusion1: if we enlarge width by β and resolution by γ , then the computational costs will be proportional to $(\beta^2 \cdot \gamma^2)$ times.

Scaling factor: α	\longleftrightarrow	Depth: d	\longleftrightarrow	$(\# \text{ of convolution modules})$
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Conclusion2: if we enlarge depth by α , then the computational costs will be proportional to α times.

Conclusion3: if we enlarge 3 factors by (α, β, γ) respectively, then the computational costs will be **proportional to $(\alpha \cdot \beta^2 \cdot \gamma^2)$ times.**

EFFICIENTNET REPRODUCTION

First part: Determine combination of depth, width, resolution



'Compound Scaling' Scheme:

Question: if now, our resources are N times larger, how to allocate for these 3 scaling factors?

- Step 1: Assume twice more resources are available, as we illustrate in the previous slide, we are required to solve:

$$\begin{cases} \max_{\{\alpha, \beta, \gamma\}} : validation_accuracy(\alpha, \beta, \gamma) \\ s.t: \quad \alpha \cdot \beta^2 \cdot \gamma^2 \approx 2 \end{cases}$$



Grid Search!

EFFICIENTNET REPRODUCTION

First part: Determine combination of depth, width, resolution



Grid Search Result:

Comparison between Different Grid Search Combinations

index	α	β	γ	best_train_accuracy	best_val_accuracy
<u>1</u>	<u>1.2</u>	<u>1.1</u>	<u>1.15</u>	<u>86.02%</u>	<u>93.17%</u>
2	1.2	1.15	1.1	84.85%	92.40%
3	1.3	1.05	1.15	85.10%	92.12%
4	1.3	1.15	1.05	84.21%	92.03%
5	1.15	1.1	1.2	85.07%	92.26%
6	1.1	1.2	1.15	84.71%	92.52%

$$\underline{s.t \alpha \times \beta^2 \times \gamma^2 \approx 2}$$

Experiment setting:

- Baseline: EfficientNet-B0
- Dataset: CIFAR-10 with 10 classes
- Epochs: 100

EFFICIENTNET REPRODUCTION

First part: Determine combination of depth, width, resolution



'Compound Scaling' Scheme:

Question: if now, our resources are N times larger, how to allocate for these 3 scaling factors?

- Step 1: Assume twice more resources are available, as we illustrate in the previous slide, we are required to solve:

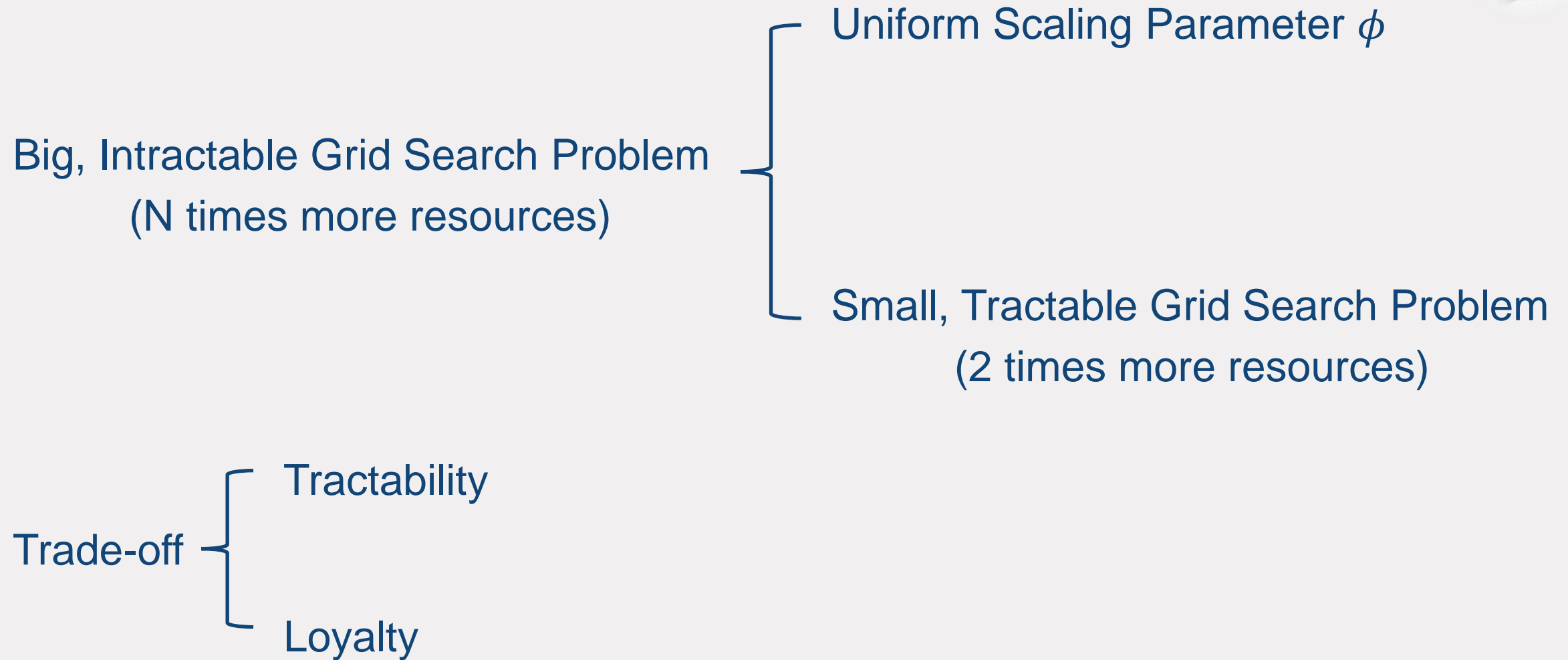
$$\begin{cases} \max_{\{\alpha, \beta, \gamma\}} : \text{validation_accuracy}(\alpha, \beta, \gamma) \\ s.t: \quad \alpha \cdot \beta^2 \cdot \gamma^2 \approx 2 \end{cases}$$

- Step 2: Now we achieve the optimal $(\hat{\alpha}, \hat{\beta}, \hat{\gamma})$ and in the question, we have N times more computation resources. In this setting, the optimal scaling factors $(\alpha^*, \beta^*, \gamma^*)$ can be determined as follows:

$$\begin{cases} \alpha^*, \beta^*, \gamma^* = \hat{\alpha}^\phi, \hat{\beta}^\phi, \hat{\gamma}^\phi \\ \phi = \log_2 N \end{cases} \longrightarrow \begin{cases} d^* = d_0 \cdot \alpha^* \\ w^* = w_0 \cdot \beta^* \\ r^* = r_0 \cdot \gamma^* \end{cases}$$

EFFICIENTNET REPRODUCTION

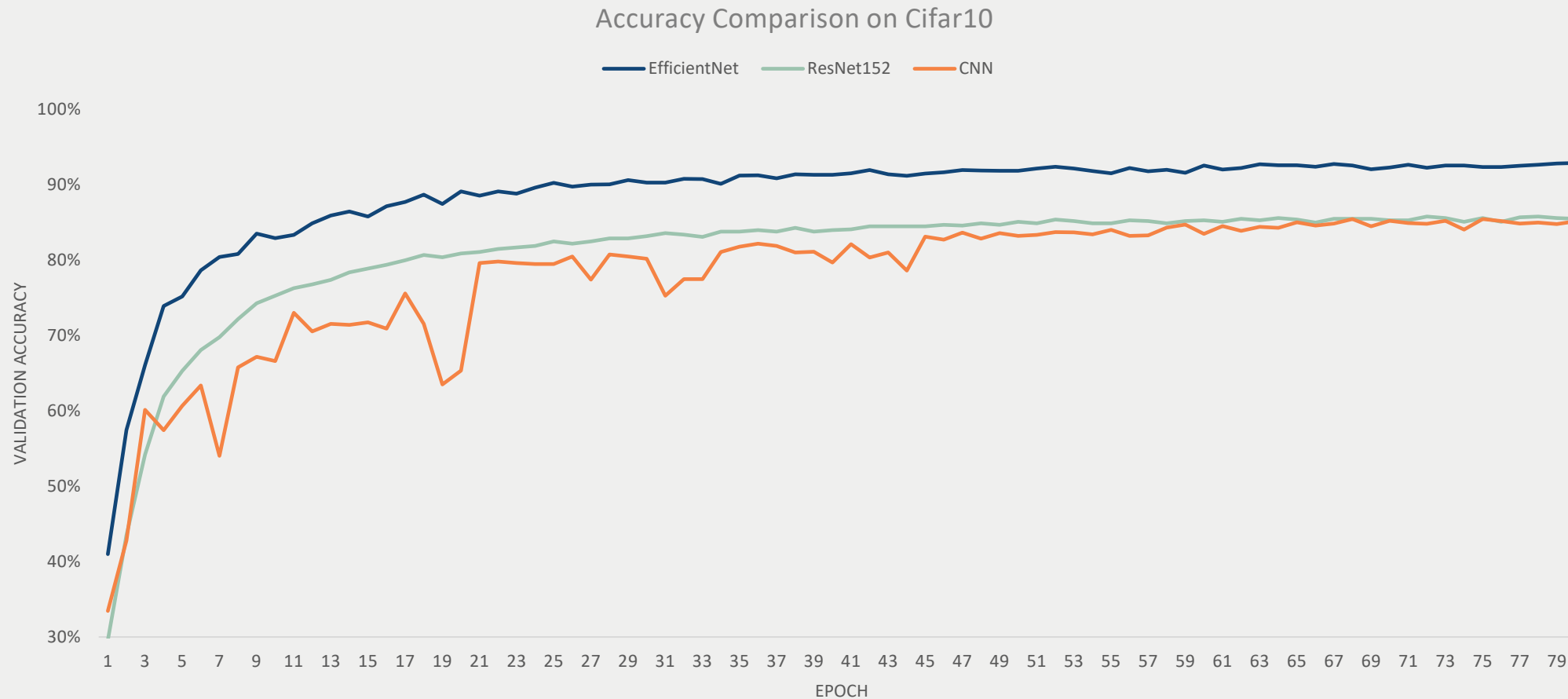
First part: Determine combination of depth, width, resolution



EFFICIENTNET REPRODUCTION

Second Part: Comparison between EfficientNet and other Network Architectures

Compare between EfficientNet and other CNN architectures including the CNN given in our lecture and famous ResNet152 on CIFAR10 Dataset.





EXTENSION

EXTENSION



Two possible directions of extension:

1

Apply EfficientNet on CIFAR100 dataset

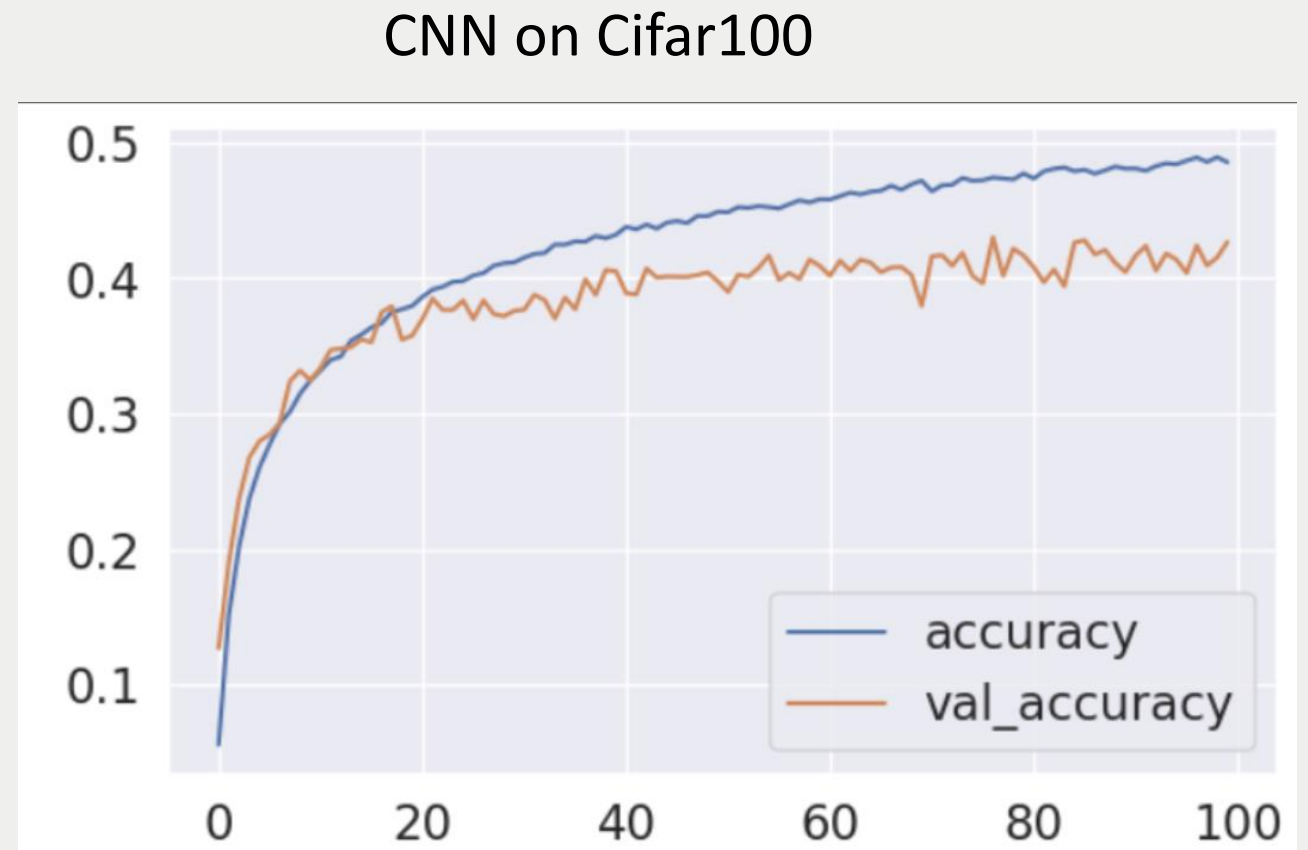
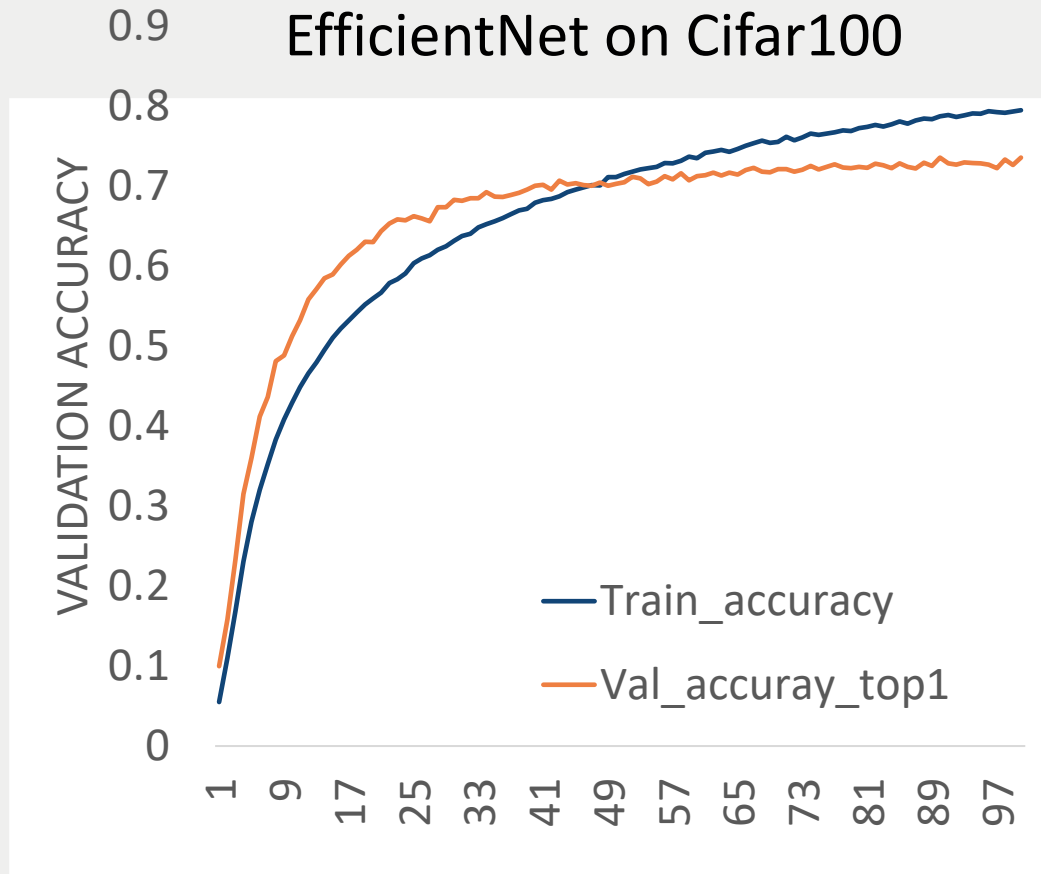
2

Improve the EfficientNet Architecture

EFFICIENTNET EXTENSION

First part: Apply EfficientNet on CIFAR100 Dataset

Compare between EfficientNet and the CNN given in our lecture on CIFAR100 Dataset.



EFFICIENTNET EXTENSION

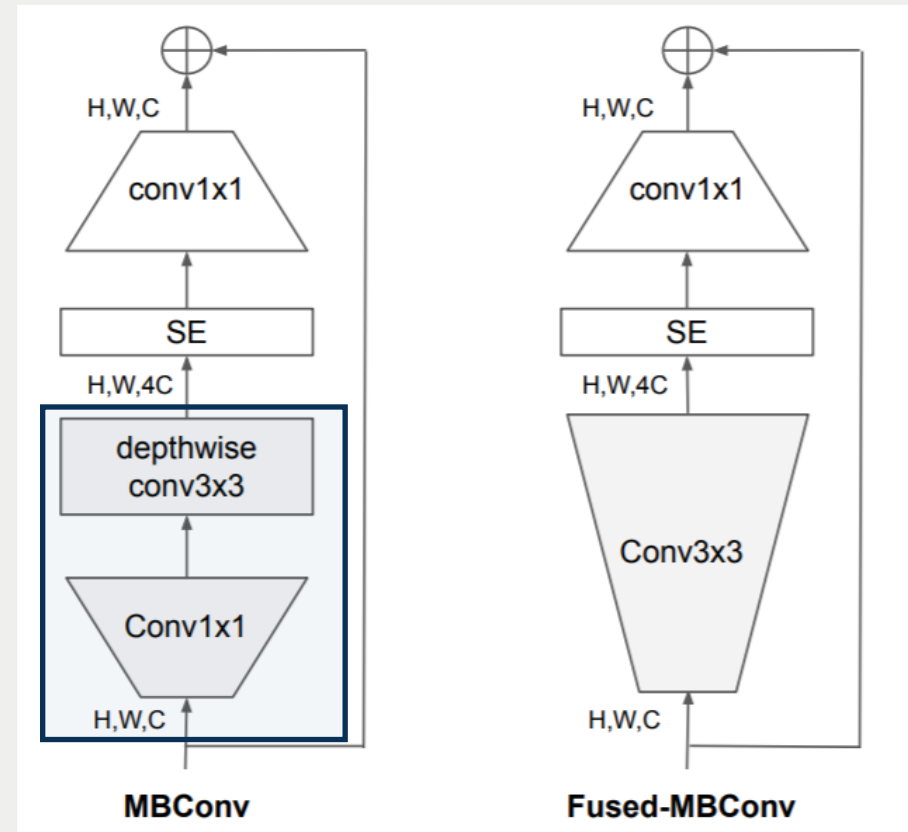
Second part: Improve EfficientNet Architecture



Limitations of the EfficientNet architecture,

1. Training with very large image sizes is slow
2. Depthwise convolutions are slow in early layers

To overcome these limitations, we try to replace the depthwise 3x3 convolution and expansion 1x1 convolution in MBConv in EfficientNet with a regular 3x3 convolution.



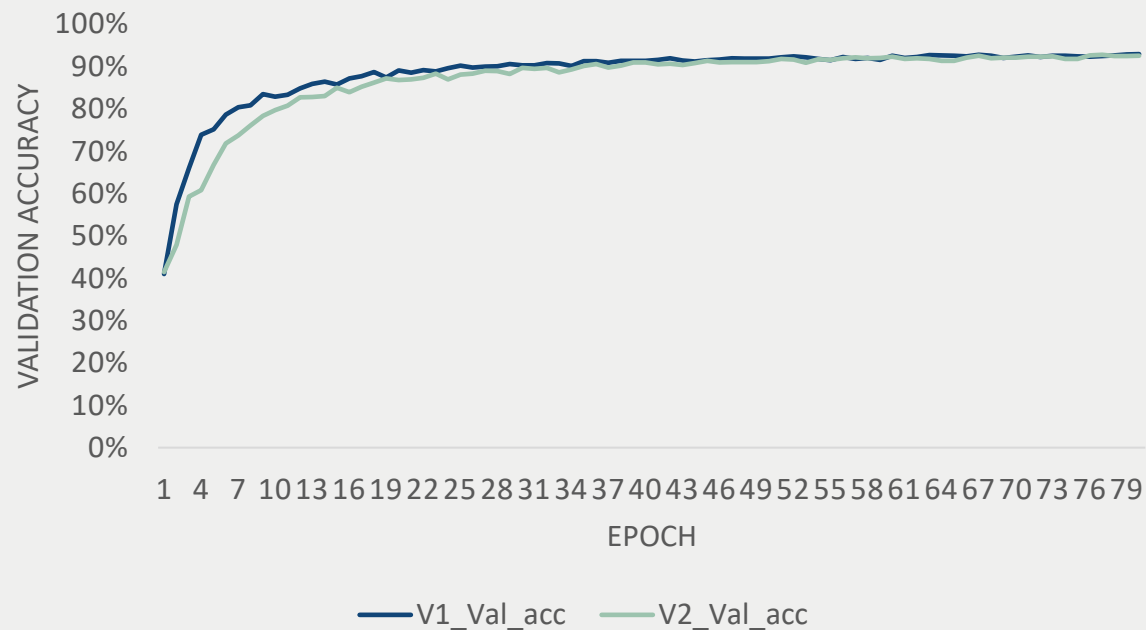
EFFICIENTNET EXTENSION

Second part: Improve EfficientNet Architecture

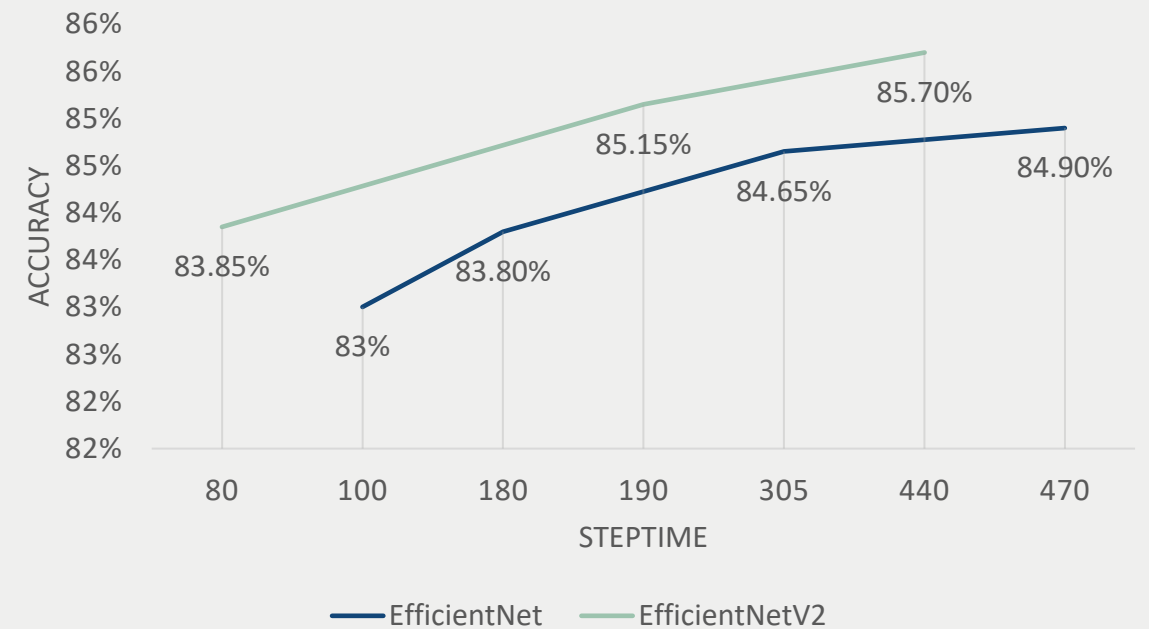


Compare between EfficientNet and EfficientNet V2 with respect to model performance (accuracy) and model efficiency (steptime).

EfficientNet Accuracy Comparison



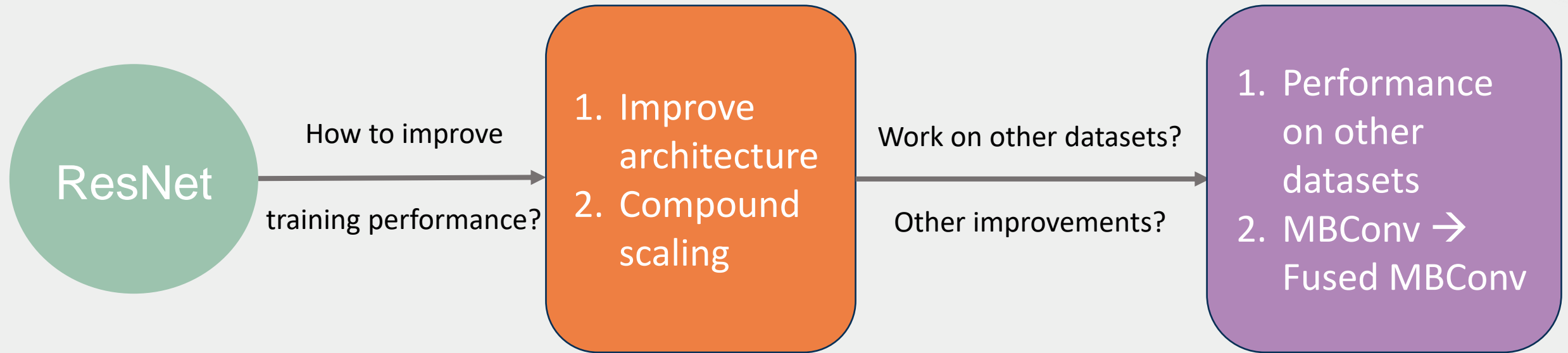
EfficientNet V.S. EfficientNet V2





CONCLUSION

SUMMARY



SUMMARY

Dataset: CIFAR-10 & CIFAR-100

Platform: Colab with GPU

Library: PyTorch

Links: <https://github.com/SizheYang512/DSA5204-2023-Group20>

Reference (paper and code):

1. ResNet, <https://arxiv.org/abs/1512.03385>
2. EfficientNet, <https://arxiv.org/abs/1905.11946>
3. EfficientNet V2, <https://arxiv.org/abs/2104.00298>
4. Code: <https://github.com/qubvel/efficientnet>
5. Code: https://github.com/WZMIAOMIAO/deep-learning-for-image-processing/tree/master/pytorch_classification/Test9_efficientNet





THANKS

HAVE A NICE DAY!
