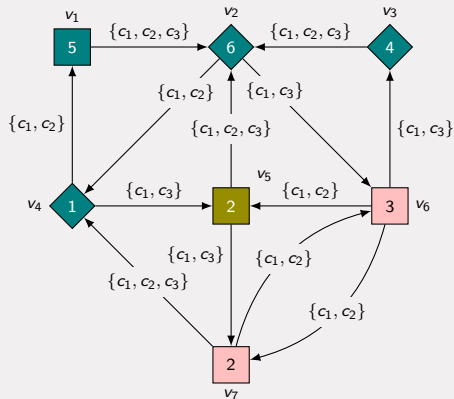


# Verifying SPLs using parity games expressing variability

Sjef van Loo

6 November, 2019



*Msc Thesis*  
*Computer Science and Engineering*  
*Supervised by T.A.C. Willemse*

# Outline

- ▶ Verification & SPLs
- ▶ Problem statement
- ▶ Variability Parity Games & algorithms
- ▶ Experimental results
- ▶ Conclusions

# Verification

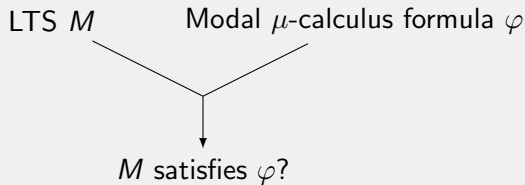
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- ▶ Mathematically *specify a requirement* (modal  $\mu$ -calculus)
- ▶ Check if the model satisfies the requirement



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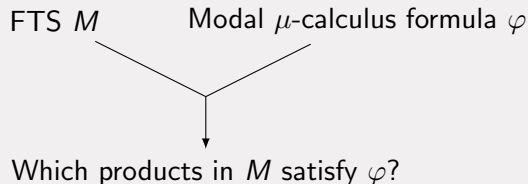
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- ▶ e.g. an elevator that can be configured to detect overload
- ▶ FTSs can be used to model the entire system using *features*
- ▶ An FTS can be transformed to an LTS given a specific feature assignment



# Problem statement

- Find all the products in an SPL that satisfy a requirement

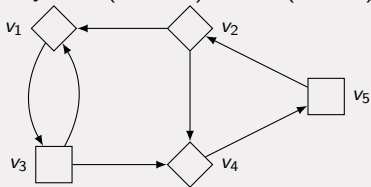


- Do so more efficiently than verifying every product independently

# Variability parity game

Parity game:  $(V, V_0, V_1, E, \Omega)$

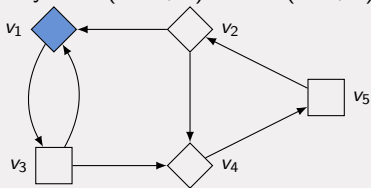
Players 0 (even,  $\diamond$ ) and 1 (odd,  $\square$ )



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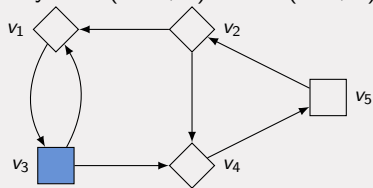
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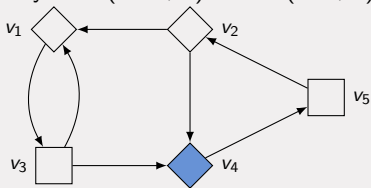
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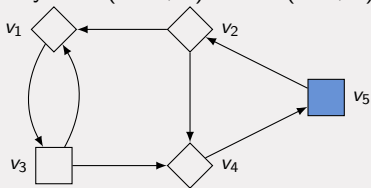
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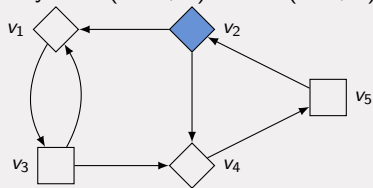
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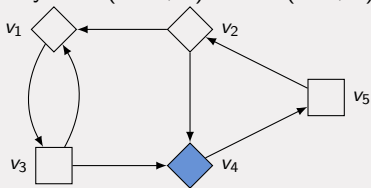
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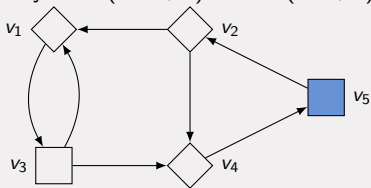




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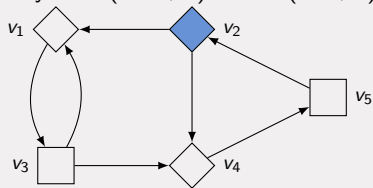
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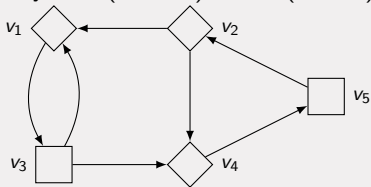
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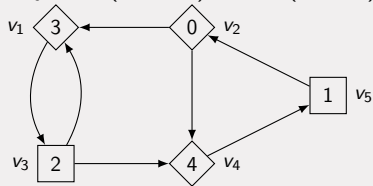


- Infinite path starting at some vertex

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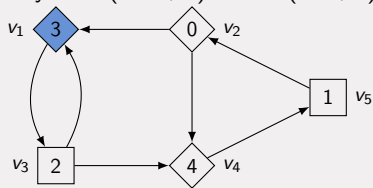


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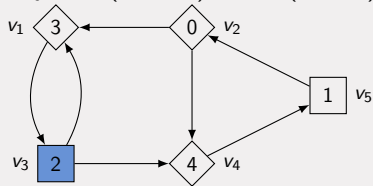


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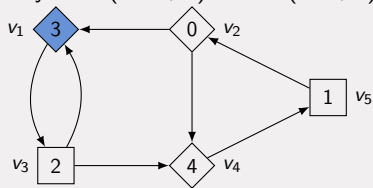


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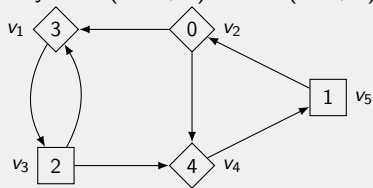


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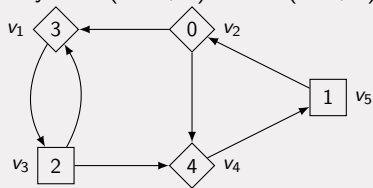
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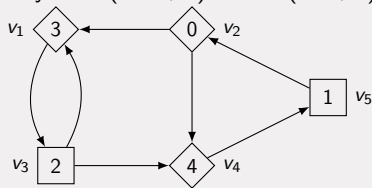


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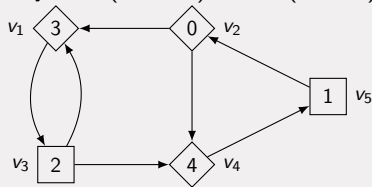


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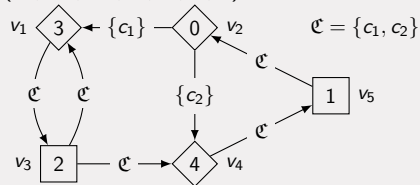
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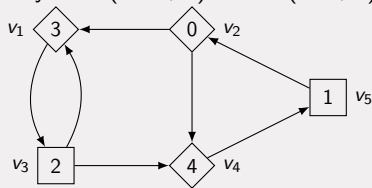


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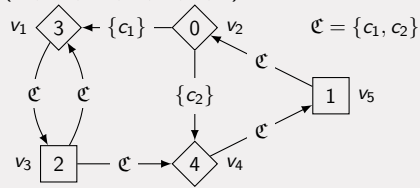
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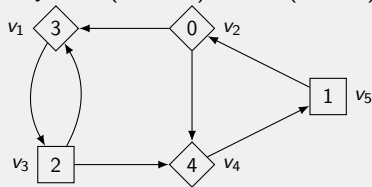


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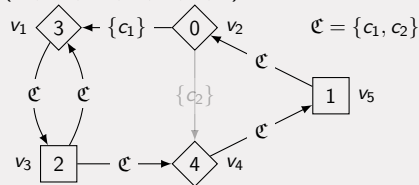
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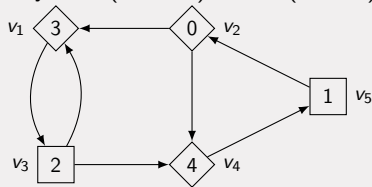


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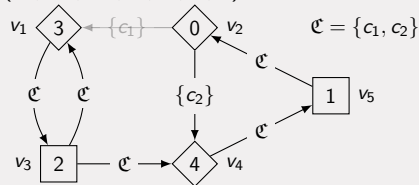
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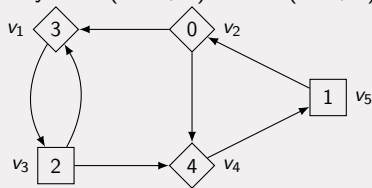


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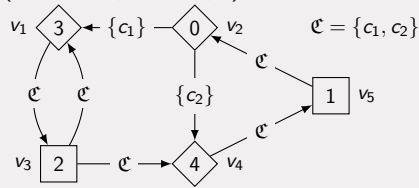
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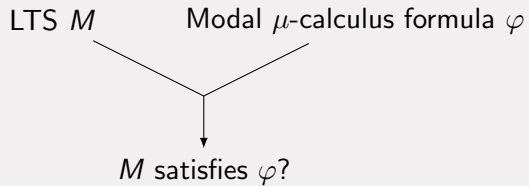
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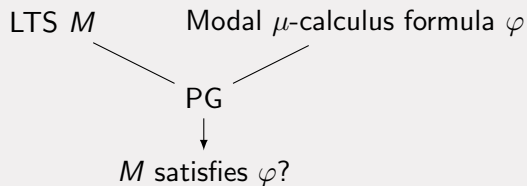
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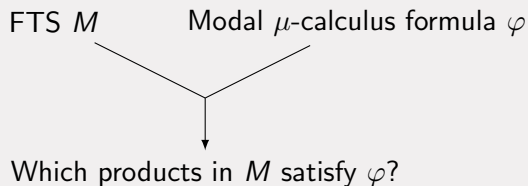
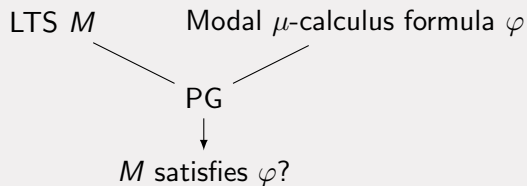
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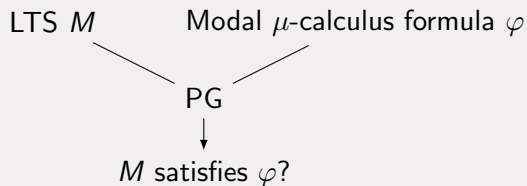
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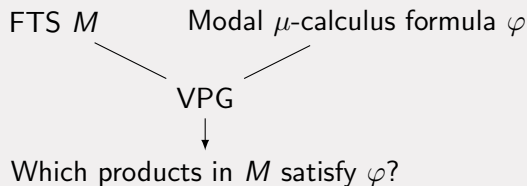
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- ▶ Introduced two collective algorithms
  - ▶ Recursive algorithm
  - ▶ Incremental pre-solve algorithm
- ▶ Evaluate performance of independent approach vs collective approach

# VPG algorithms - Recursive algorithm

- ▶ Existing parity game algorithm
- ▶ Spends most time performing the *attractor* calculation
- ▶ Introduce an efficient attractor calculation for VPGs



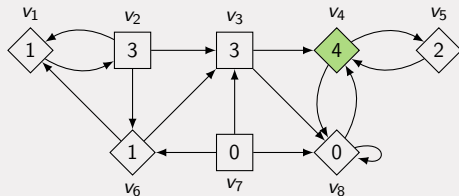
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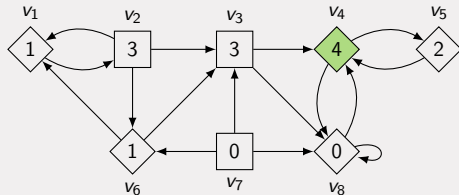
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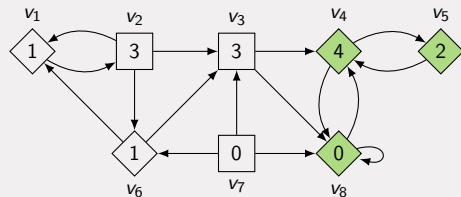


	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$	$v_8$
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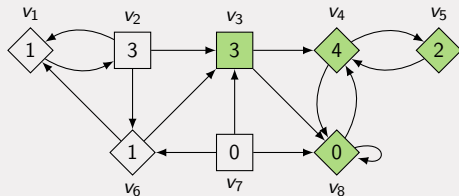


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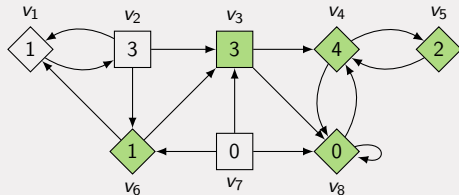


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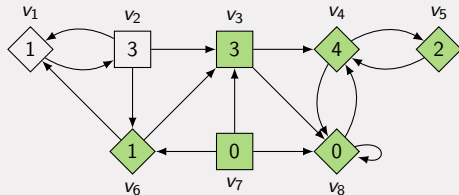


	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$	$v_8$
$A$			✓	✓	✓	✓		✓

# VPG algorithms - Recursive algorithm

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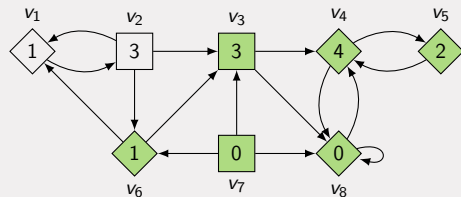


	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$	$v_8$
$A$			✓	✓	✓	✓	✓	✓

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$$A_0 = U, A = \bigcup_{i \geq 0} A_i$$

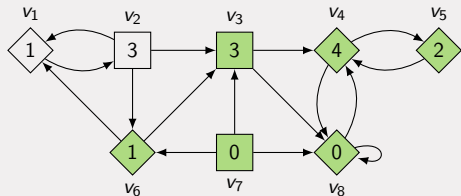
$$A_{i+1} = A_i \cup \{v \in V_\alpha \mid \exists w : (v, w) \in E \wedge w \in A_i\} \\ \cup \{v \notin V_\alpha \mid \forall w : (v, w) \in E \implies w \in A_i\}$$



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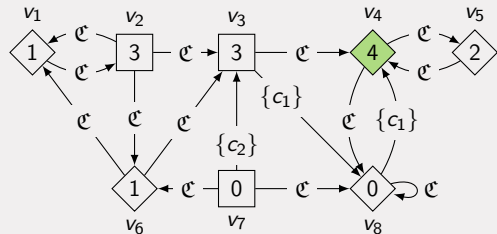
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$A_0$				✓				
$A_1$				✓	✓			✓
$A_2$			✓	✓	✓			✓
$A_3$			✓	✓	✓	✓		✓
$A_4$			✓	✓	✓	✓	✓	✓
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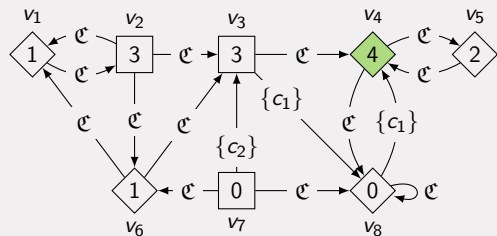
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# VPG algorithms - Recursive algorithm

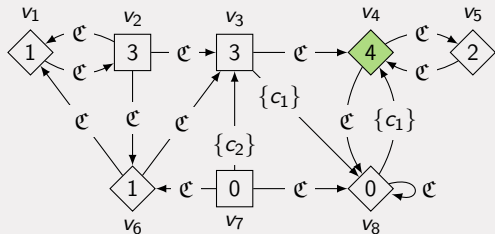
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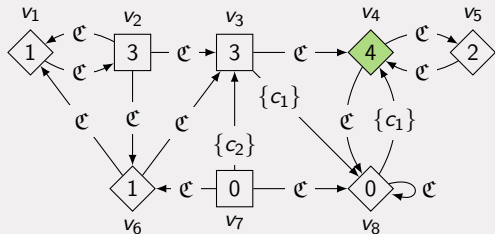
	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$	$v_8$
$A_0$				$\mathcal{C}$				

$$A_{i+1}(v) = A_i(v) \cup \begin{cases} \bigcup_{(v,w) \in E} (\theta(v,w) \cap A_i(w)) & \text{if } v \in V_\alpha^* \\ \bigcap_{(v,w) \in E} ((\mathcal{C} \setminus \theta(v,w)) \cup A_i(w)) & \text{if } v \notin V_\alpha^* \end{cases}$$

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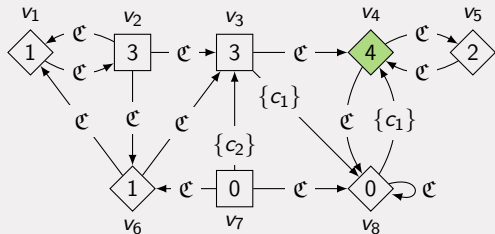
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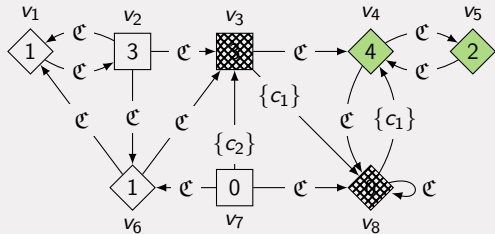
If  $v \notin V_\alpha$ : Find for every outgoing edge through which configurations player  $1 - \alpha$  cannot escape  $A_i$ , add the intersection to  $A_i(v)$

$$A_{i+1}(v) = A_i(v) \cup \begin{cases} \bigcup_{(v,w) \in E} (\theta(v,w) \cap A_i(w)) & \text{if } v \in V_\alpha^* \\ \bigcap_{(v,w) \in E} ((\mathcal{C} \setminus \theta(v,w)) \cup A_i(w)) & \text{if } v \notin V_\alpha \end{cases}$$

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$A_1$			$\{c_2\}$	$\mathfrak{C}$	$\mathfrak{C}$			$\{c_1\}$

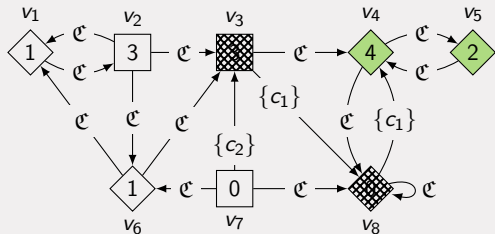
$$\begin{aligned} A_1(v_5) &= A_0(v_5) \cup (\theta(v_5, v_4) \cap A_0(v_4)) \\ &= \emptyset \cup (\mathfrak{C} \cap \mathfrak{C}) = \mathfrak{C} \end{aligned}$$

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$A_0$				$\mathcal{C}$				
$A_1$			$\{c_2\}$	$\mathcal{C}$	$\mathcal{C}$			$\{c_1\}$

$$\begin{aligned}
 A_1(v_8) &= A_0(v_8) \cup (\theta(v_8, v_8) \cap A_0(v_8)) \\
 &\quad \cup (\theta(v_8, v_4) \cap A_0(v_4)) \\
 &= \emptyset \cup (\mathcal{C} \cap \emptyset) \cup (\{c_1\} \cap \mathcal{C}) = \{c_1\}
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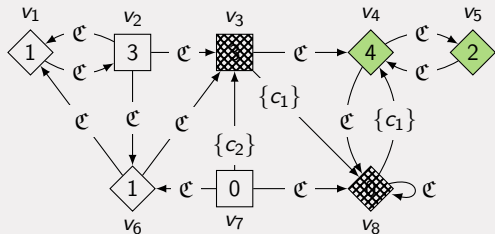
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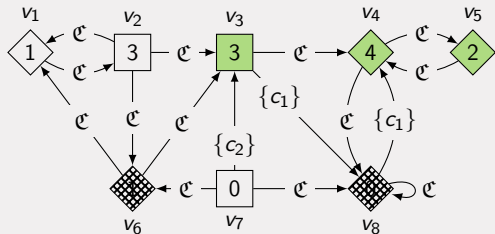
$$\begin{aligned}
 A_1(v_3) &= A_0(v_3) \cup ( \\
 &\quad ((\mathcal{C} \setminus \theta(v_3, v_4)) \cup A_0(v_4)) \cap \\
 &\quad ((\mathcal{C} \setminus \theta(v_3, v_8)) \cup A_0(v_8))) \\
 &= \emptyset \cup ((\emptyset \cup \mathcal{C}) \cap (\{c_2\} \cup \emptyset)) = \{c_2\}
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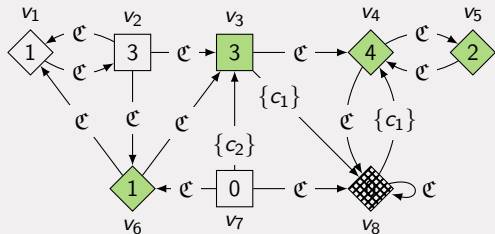
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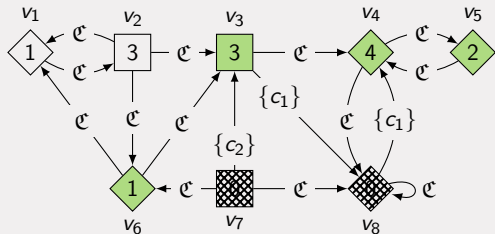
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- ▶ Modified attractor calculation relies on set operations between sets of configurations
- ▶ Can we perform these operations efficiently?

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Boolean formula:

$$F(x_2, x_1, x_0) = (\neg x_2 \wedge x_1 \wedge \neg x_0) \vee (x_2 \wedge (x_1 \vee \neg x_0))$$

$x_2 x_1 x_0$	$F(x_2, x_1, x_0)$
000	0
001	0
010	1
011	0
100	1
101	0
110	1
111	1

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- ▶ Boolean operators  $\vee, \wedge$  coincide with set operators  $\cup, \cap$

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- ▶ Simple formulas  $\implies$  small BDDs  $\implies$  quick set operators
- ▶ FTSs use features
- ▶ FTSs use boolean formulas to enable/disable parts of the system
- ▶ VPGs are constructed such that every edge either:
  - ▶ admits all configurations, or
  - ▶ is guarded by a set that coincides with a formula from the FTS

# VPG algorithms - Recursive algorithm - Time complexities

$n$ : # vertices,  $e$ : # edges,  $d$ : # distinct priorities,  $c$  # configurations

Set operations	
Explicit sets	
Symbolic sets	
Algorithms	
Original recursive algorithm	
Independent approach	
Collective algorithm (explicit)	
Collective algorithm (symbolic)	

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Algorithms	
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Collective algorithm (explicit)	$O(n * c^2 * e * n^d)$
Collective algorithm (symbolic)	$O(n * c^3 * e * n^d)$

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- ▶ 128 valid feature assignments
- ▶ 600 states and 1400 transitions
- ▶ 9 requirements
- ▶ 9 VPGs ranging from 3000 to 9200 vertices and 2 to 4 distinct priorities

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- ▶ Keep a mine shaft free from water
- ▶ 10 features that change the sensor/actor setup
- ▶ 128 valid feature assignments
- ▶ 600 states and 1400 transitions
- ▶ 9 requirements
- ▶ 9 VPGs ranging from 3000 to 9200 vertices and 2 to 4 distinct priorities

## Elevator SPL

- ▶ Elevator travelling between five floor
- ▶ 5 features, including overload detection and parking

# Experimental results - SPL games

## Minepump SPL

- ▶ Keep a mine shaft free from water
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## Elevator SPL

- ▶ Elevator travelling between five floor
- ▶ 5 features, including overload detection and parking
- ▶ 64 valid feature assignments
- ▶ 34k states and 200k
- ▶ 7 requirements
- ▶ 7 VPGs ranging from 440k and 1.85m vertices and 2 to 3 distinct priorities

# Experimental results - SPL games

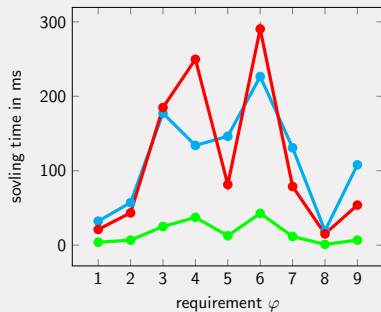


Figure: Running times, in ms, on the minepump games.

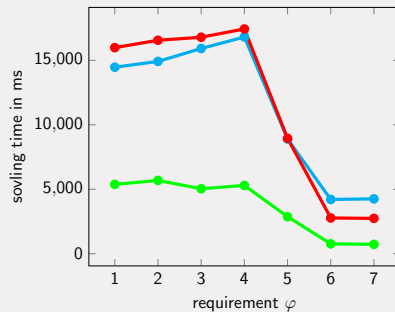


Figure: Running times, in ms, on the elevator games.

- Independent recursive algorithm
- Collective recursive algorithm with a symbolic representation of configurations
- Collective recursive algorithm with an explicit representation of configurations



# Discussion

Collective recursive algorithm:

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- ▶ For certain random games the symbolic performance drops rapidly, explicit performance is steady

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Collective recursive algorithm:

- ▶ Symbolic variant increases performance 3-18 times (SPL games)
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Incremental pre-solve algorithm:

- ▶ Same time complexity as independent approach ( $O(c * e * n^d)$ )
- ▶ Slightly increases performance of SPL games and random games
- ▶ Not consistent or very significant

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- ▶ Parity games: Terminate when special vertex  $v_0$  is solved
- ▶ VPGs: Terminate when special vertex  $v_0$  is solved for all configurations

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- ▶ Is the relative local performance greater than the relative global performance?

## Results:

- ▶ Recursive algorithms: no significant increase in relative performance
- ▶ Incremental pre-solve algorithm: increases relative performance for random games

# Conclusions

- ▶ VPGs can be used to verify SPLs
- ▶ Collective approaches outperform independent approaches
- ▶ Locally solving VPGs can increase performance (more so than locally solving parity games does)





## Extra - Incremental pre-solve

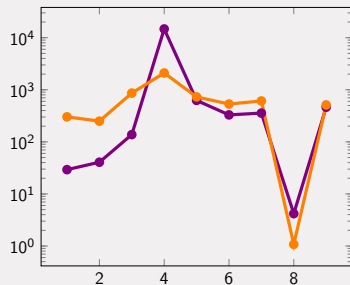


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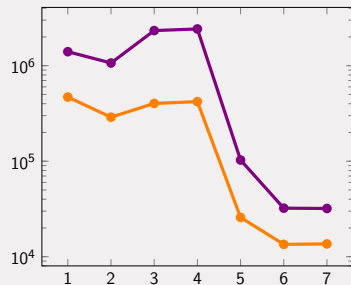


Figure: Running times, in ms, on the elevator games.