

i.mobilathon 5.0

Driving innovation to create **smarter,**
scalable solutions

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Problem Statement : AI-Enhanced Driver Wellness Monitoring

Brief about the Idea:

Our solution is a **privacy-first, multi-modal AI co-pilot** designed to enhance driver safety by continuously monitoring **fatigue, stress, and distraction** in real time.

The system fuses three complementary data streams:

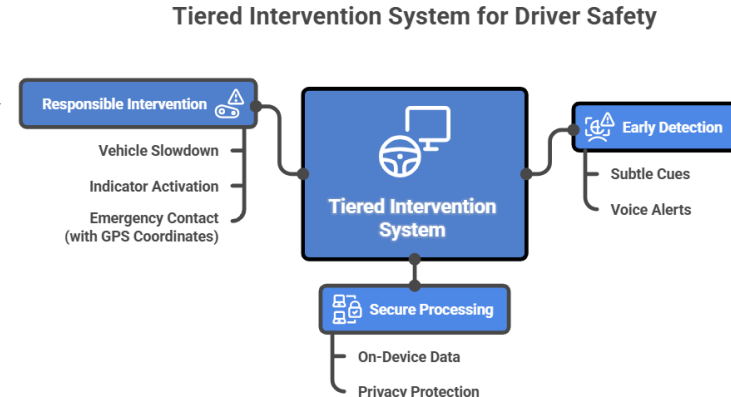
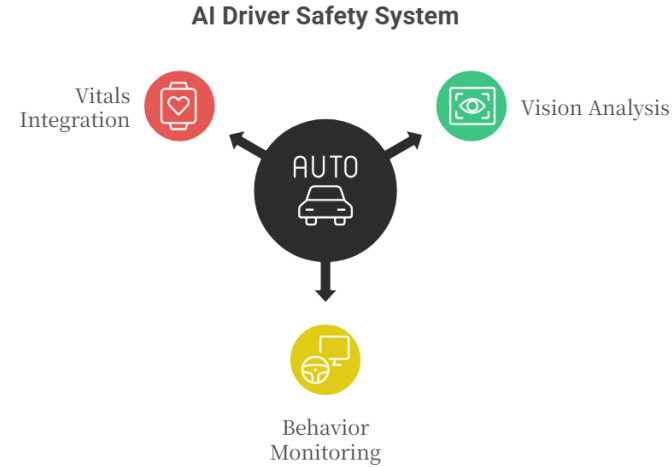
- **Vision (Camera):** Tracks facial landmarks such as **eye closure (PERCLOS)**, **gaze direction**, and **yawning** to detect drowsiness.
- **Behavior (Vehicle):** Monitors **steering wheel activity** (via potentiometer sensor) to identify erratic or inactive driving patterns.
- **Vitals (Wearable):** Integrates with a PC-based vitals simulator to test and validate the system's emergency logic against medical events, proving the multi-modal fusion works as designed.

All processing is done **locally on the edge device (Raspberry Pi 4)** – ensuring **privacy-first analysis** without cloud dependency.

When risk is detected, the **Tiered Intervention System** automatically activates:

- Subtle audio or visual cues to regain driver attention.
- Voice-based alerts prompting rest or focus.
- Intelligent assistance (e.g., **vehicle slowdown, indicator activation, and emergency contact notifications with GPS**).

This multi-modal, on-device approach ensures **early detection, secure processing**, and **responsible intervention**, significantly reducing fatigue-related road accidents.

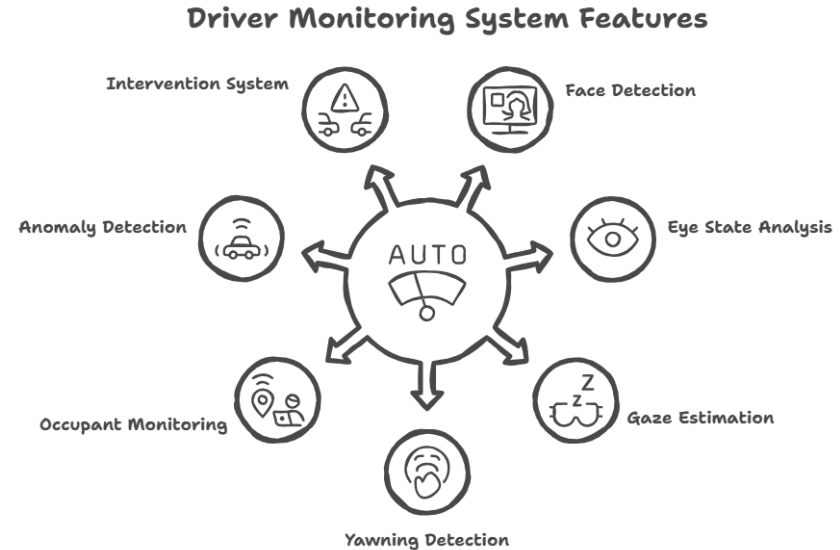


Opportunity should be able to explain the following:

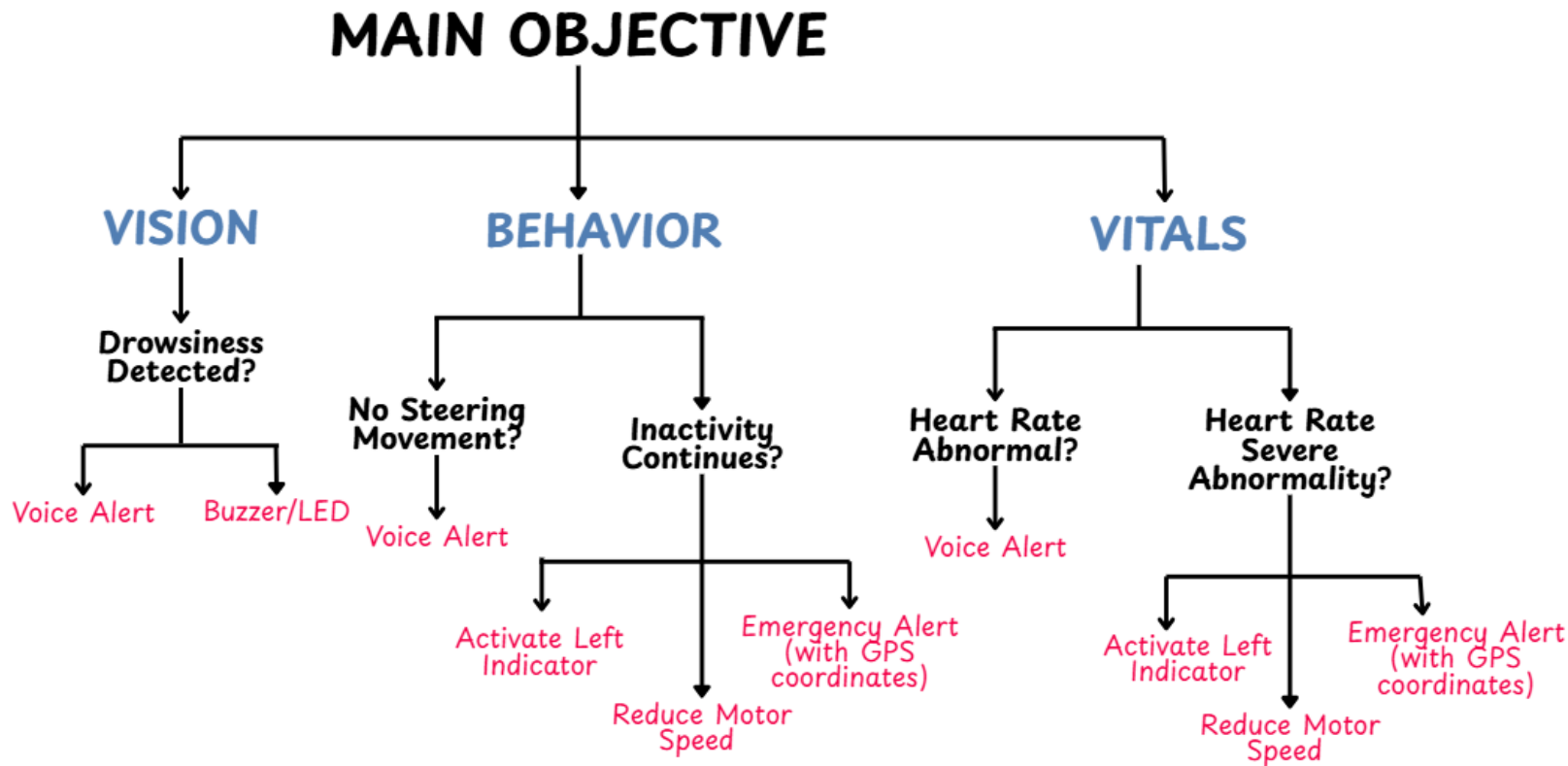
- **Privacy-first, multi-modal AI co-pilot** that fuses data from vision, steering behavior, and vitals to monitor driver wellness in real time.
- Detects **fatigue, distraction, and stress** early, enabling proactive accident prevention.
- Ensures **consistent performance** across all conditions — day, night, or when the driver's face is partially covered.
- Executes **on-device edge processing** on Raspberry Pi, guaranteeing **data privacy, low latency, and offline functionality**.
- Integrates **a tiered intervention system** with escalating responses — from subtle alerts to **automatic vehicle control and GPS-based emergency notifications**.
- Uses **lightweight AI models** (MediaPipe, TensorFlow Lite) optimized for low-power, embedded systems.
- Designed for **low-cost scalability**, making it feasible for **commercial fleets, personal vehicles, and public transport**.
- Provides a **holistic safety net** that combines intelligent detection, real-time decision-making, and human-centered intervention.
- Provides a **redundant, multi-modal safety net** by fusing diverse data streams. It triggers emergencies from behavioral (no steering) or physiological (vitals failure) anomalies—catching what vision-only systems miss.

List of features offered by the solution:

- 1. Face Detection:** Detects and aligns faces using Medium pipe and OpenCV.
- 2. Eye State / Blink Analysis:** Computes PERCLOS and uses a CNN to classify eye state.
- 3. Gaze & Head Pose Estimation:** Tracks head orientation to detect prolonged downward gaze.
- 4. Yawning Detection:** Uses a sequence-aware model to distinguish yawns from talking.
- 5. Occupant Monitoring:** Detects phone use and hands-off-wheel behavior.
- 6. Driving Anomaly Detection:** Monitors steering wheel data via steering column sensor (prototyped with 10k potentiometer) to detect erratic movements and lane weaving, acting as a non-visual confirmation of fatigue or stress.
- 7. Tiered Intervention System:** Four-level alert system that escalates from subtle chimes to proactive voice guidance (e.g., "Please Take a break & Calm Down") using TTS and Maps APIs.

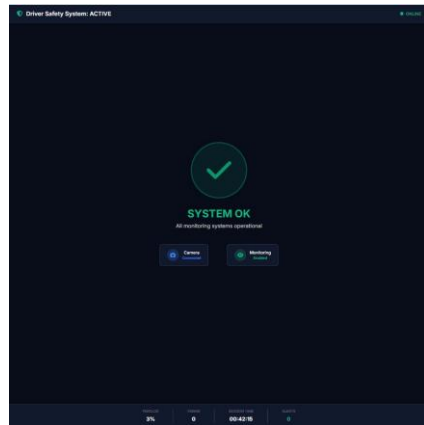


Process flow diagram or Use-case diagram:

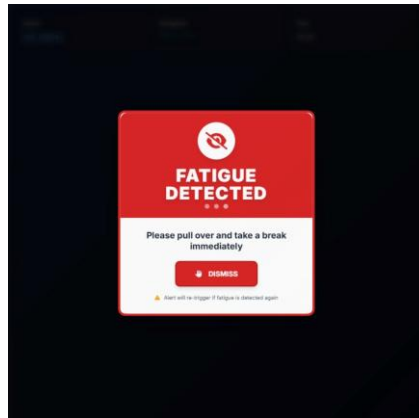


Wireframes/Mock diagrams of the proposed solution:

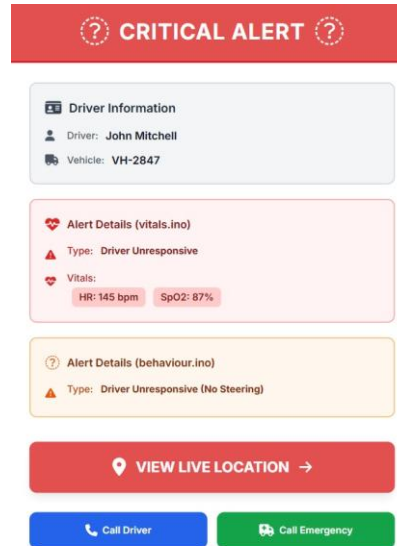
1. The Main Dashboard (Calm State)



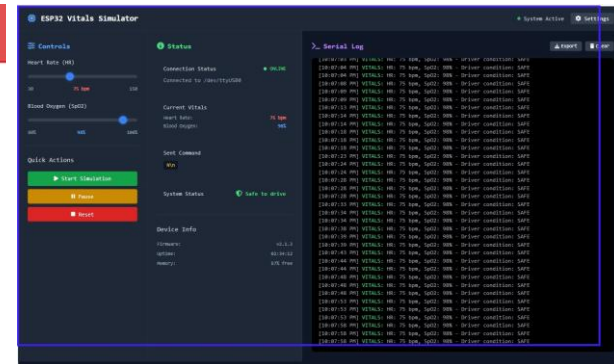
2. Fatigue Alert (Microsleep)



3. The Emergency Alert (Incoming)



4. The Developer/Tester Control Panel



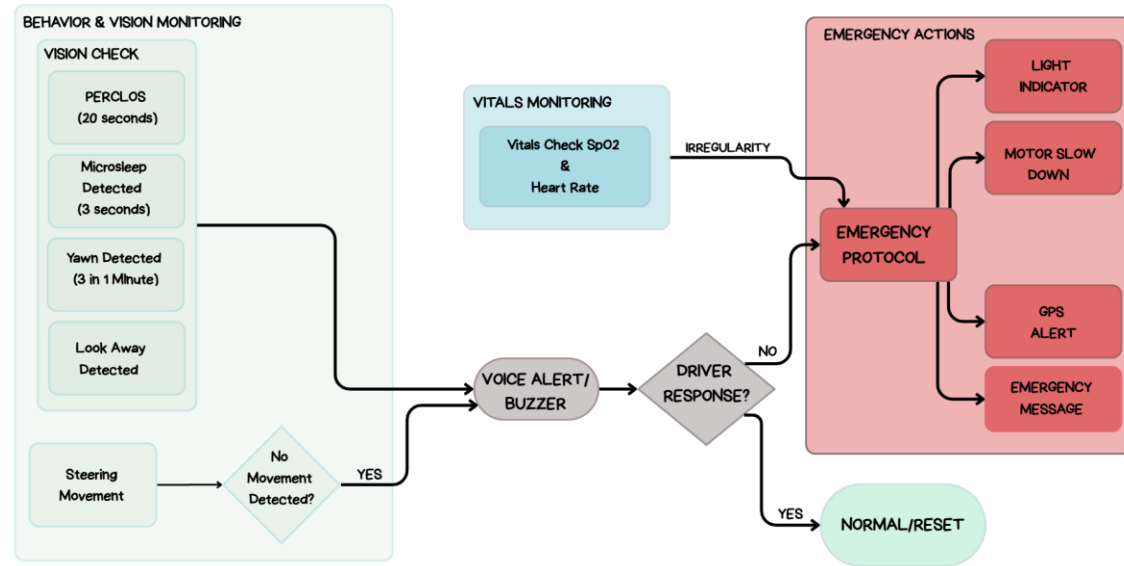
Architecture diagram of the proposed solution:

1. Data Collection: The system continuously collects parallel streams of data from the cabin camera, the vehicle's steering wheel, and a wearable (smartwatch).

2. Edge Compute Processing: All data is processed locally on the edge device. This includes video preprocessing, running AI perception models, and fusing all sensor data.

3. Decision Engine: The fusion engine weighs the inputs and makes a real-time decision on the driver's state (Alert, Drowsy, or Stressed).

4. Trigger Intervention: If a high-risk state is confirmed (e.g., high PERCLOS + steering anomaly), the system triggers the appropriate-level alert from the Tiered Intervention System.



Technologies to be used in the solution:

• Hardware (Edge Compute):

- Raspberry Pi 4
- Raspberry Pi Camera Module v2
- 10k rotatory potentiometer
- DC Motor
- Motor Driver Module
- Neo-6M GPS Module
- ESP32
- Micro SD card
- Buzzer
- LED Indicator

• Software & AI Models:

- Python
- OpenCV
- Mediapipe
- Arduino IDE
- Tkinter
- Pyserial

• APIs & Cloud Services:

- Twilio APIs

• Development Tools:

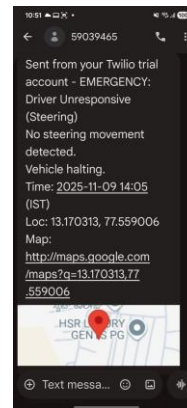
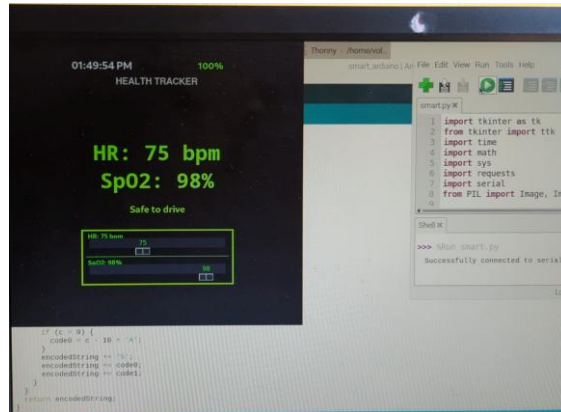
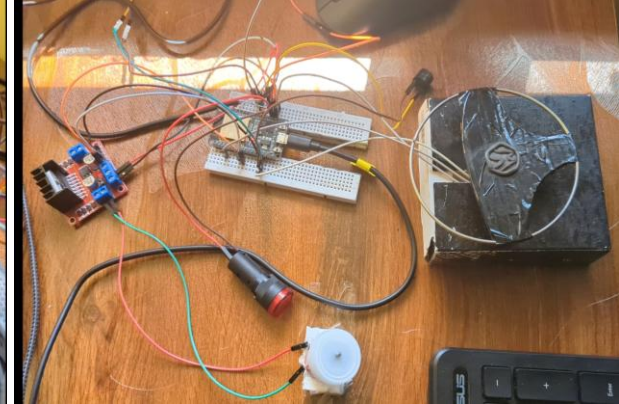
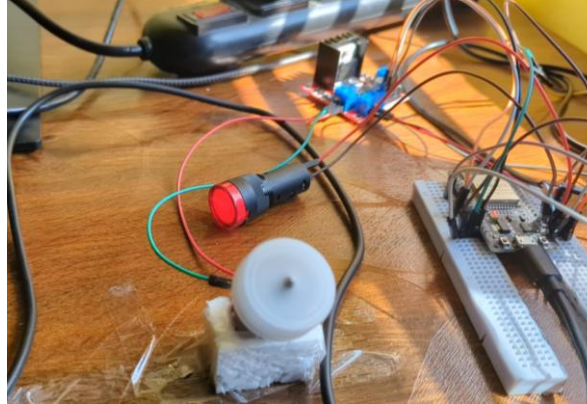
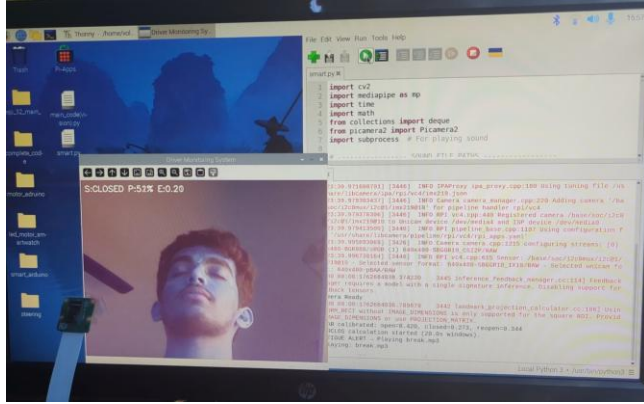
- GitHub: For version control.



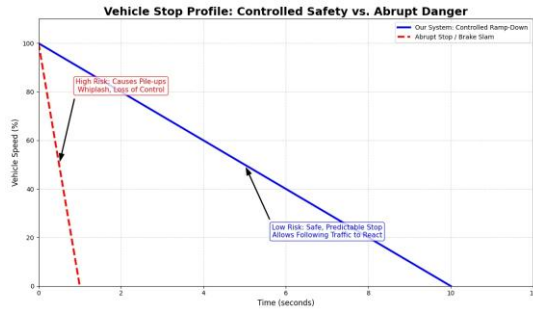
Estimated implementation cost :

Cost Component	Estimated Cost (INR)	Key Points
Hardware	₹8,000 – ₹10,000	<ul style="list-style-type: none">▪ Covers essential hardware for development and testing.▪ Includes a devices like a Raspberry Pi for edge computing, a quality camera etc.
Cloud Services & APIs	₹0 – ₹1,000	<ul style="list-style-type: none">▪ This cost is allocated specifically for Twilio API usage (e.g., for sending SMS alerts).▪ The budget suits Twilio's pay-as-you-go model, with free tiers covering initial testing.
Miscellaneous	₹0 – ₹2,000	<ul style="list-style-type: none">▪ A small buffer for unforeseen expenses or minor subscriptions.
Total Estimated MVP Cost	₹8,000 – ₹13,000	<ul style="list-style-type: none">▪ This represents a realistic, lean budget to get a functional and impressive prototype.

Snapshots of the Prototype:



Prototype Performance report/Benchmarking



Feature	Drowsiness detection in real-time via convolutional neural networks and transfer learning, Salem & Waleed, 2024	A systematic review on detection and prediction of driver drowsiness, Md. Ebrahim Shaikh, 2023	Our proposed solution
Eye state detection (open/closed)	✓	✓	✓
Blink detection (PERCLOS/MAR)	✓	✓	✓
Yawn detection	✓	✓	✓
Head pose / gaze estimation	✓	✓	✓
Steering / vehicle data fusion	X	X	✓
Physiological signals (heart rate, SpO2)	Rare / X	X	✓
Multi-class drowsiness states (beyond binary)	✓	✓	✓
Real-time on-device processing	Limited / Partial	Limited	✓
Tiered intervention alerts	X	X	✓
Privacy-focused on-device inference	Limited	Limited	✓
Alert escalation (audio, SMS)	Basic alerting	Basic alerting	✓
Landmark detection	✓	✓	✓

Future Development

Future Enhancements:

- **Direct Phone Integration:** Wireless connection enables **automatic emergency contact** with GPS location
- **Emergency Notifications:** Alerts sent to nearby **emergency services** and **designated contacts**
- **Production-Ready Sensor Fusion:** Combines **vision data with physiological signals**(heart rate variability, skin conductance) and behavior (Steering movement).
- **Advanced AI:** Machine learning models **for reducing false alarms and contextual awareness**
- **Connected Safety Ecosystem: Vehicle-to-Everything (V2X) communication** to warn nearby vehicles of driver state.
- **CAN Bus Integration:** Graduate from the potentiometer prototype to **direct CAN Bus integration** via the OBD-II port. This will allow us to read production-grade steering angle, vehicle speed, and ADAS status.

Benefits:

- Improved real-world robustness with **infrared cameras**
- **Personalized calibration** for driver variability
- Integration with **Advanced Driver Assistance Systems (ADAS)**
- Fleet management support with **data logging** and **analytics**

GitHub & Demo video URL:

Prototype Video URL:

<https://vimeo.com/1135088291?share=copy&fl=sv&fe=ci>

Idea Pitch URL:

<https://github.com/Sjsh007/imobilothon5.0-virtus-synergie/blob/main/Prototype%20round%202/Idea%20Pitch.pdf>

GitHub URL:

<https://github.com/Sjsh007/imobilothon5.0-virtus-synergie>



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