Experiment Name: Implementation and Analysis of Linear Search Using recursive function.

Objective: Implement and analyse the recursive implementation of linear search to understand its recursive nature and assess its time and space complexity.

```
#include <stdio.h>
int recursiveLinearSearch(int arr[], int target, int index, int size) {
  if (index == size) {
     return -1;
  }
  if (arr[index] == target) {
     return index;
  }
  return recursiveLinearSearch(arr, target, index + 1, size);
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
  printf("Enter %d elements for the array:\n", arraySize);
```

```
for (int i = 0; i < arraySize; ++i) {
  printf("Element %d: ", i + 1);
  scanf("%d", &myArray[i]);
}
int targetElement;
printf("Enter the target element to search: ");
scanf("%d", &targetElement);
int result = recursiveLinearSearch(myArray, targetElement, 0, arraySize);
if (result != -1) {
  printf("Element %d found at index %d.\n", targetElement, result);
} else {
  printf("Element %d not found in the array.\n", targetElement);
}
return 0;
```

Experiment Name: Implementation and Analysis of Binary Search Using recursive function

Objective: Implement and analyse the recursive implementation of Binary search to understand its recursive nature and assess its time and space complexity.

```
#include <stdio.h>
int recursiveBinarySearch(int arr[], int target, int low, int high) {
  if (low <= high) {
     int mid = low + (high - low) / 2;
     if (arr[mid] == target) {
       return mid;
     }
     if (arr[mid] > target) {
        return recursiveBinarySearch(arr, target, low, mid - 1);
     } else {
       return recursiveBinarySearch(arr, target, mid + 1, high);
     }
  }
  return -1;
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
```

```
scanf("%d", &arraySize);
int myArray[arraySize];
printf("Enter %d sorted elements for the array:\n", arraySize);
for (int i = 0; i < arraySize; ++i) {
  printf("Element %d: ", i + 1);
  scanf("%d", &myArray[i]);
}
int targetElement;
printf("Enter the target element to search: ");
scanf("%d", &targetElement);
int result = recursiveBinarySearch(myArray, targetElement, 0, arraySize - 1);
if (result != -1) {
  printf("Element %d found at index %d.\n", targetElement, result);
} else {
  printf("Element %d not found in the array.\n", targetElement);
}
return 0;
```

Experiment Name: Implementation and Analysis of Insertion Sort .

Objective: To implement the Insertion Sort algorithm and analyze its efficiency in sorting data, evaluating its time complexity and practical performance.

```
#include <stdio.h>
#include <stdlib.h>
void insertionSort(int arr[], int size) {
  int i, key, j;
  for (i = 1; i < size; i++) {
     key = arr[i];
     j = i - 1;
     while (i \ge 0 \&\& arr[i] > key)  {
        arr[j + 1] = arr[j];
       j = j - 1;
     arr[j + 1] = key;
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
```

```
printf("Enter %d elements for the array:\n", arraySize);
for (int i = 0; i < arraySize; i++) {
    printf("Element %d: ", i + 1);
    scanf("%d", &myArray[i]);
}
insertionSort(myArray, arraySize);

printf("Sorted array: ");
for (int i = 0; i < arraySize; i++) {
    printf("%d ", myArray[i]);
}

printf("\n");</pre>
```

Experiment Name: Implementation and Analysis of Bubble Sort.

Objective: Objective: To implement and analyse the Bubble Sort algorithm's efficiency and performance in sorting a given dataset.

```
#include <stdio.h>
#include <stdlib.h>
void bubbleSort(int arr[], int size) {
  for (int i = 0; i < size - 1; i++) {
     for (int j = 0; j < size - i - 1; j++) {
       if (arr[j] > arr[j + 1]) {
          int temp = arr[j];
          arr[j] = arr[j + 1];
          arr[j + 1] = temp;
       }
     }
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
  printf("Enter %d elements for the array:\n", arraySize);
  for (int i = 0; i < arraySize; i++) {
```

```
printf("Element %d: ", i + 1);
scanf("%d", &myArray[i]);
}
bubbleSort(myArray, arraySize);
printf("Sorted array: ");
for (int i = 0; i < arraySize; i++) {
    printf("%d ", myArray[i]);
}
printf("\n");</pre>
```

Experiment Name: Implementation and Analysis of Selection Sort.

Objective: Objective: To implement and analyse the Selection Sort algorithm's efficiency and performance in sorting a given dataset.

```
#include <stdio.h>
#include <stdlib.h>
void selectionSort(int arr[], int size) {
  for (int i = 0; i < size - 1; i++) {
     int minIndex = i;
     for (int j = i + 1; j < size; j++) {
       if (arr[j] < arr[minIndex]) {</pre>
          minIndex = j;
        }
     }
     int temp = arr[i];
     arr[i] = arr[minIndex];
     arr[minIndex] = temp;
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
```

```
printf("Enter %d elements for the array:\n", arraySize);
for (int i = 0; i < arraySize; i++) {
    printf("Element %d: ", i + 1);
    scanf("%d", &myArray[i]);
}
selectionSort(myArray, arraySize);
printf("Sorted array: ");
for (int i = 0; i < arraySize; i++) {
    printf("%d ", myArray[i]);
}
printf("\n");</pre>
```

Experiment Name: Implementation and Analysis of Merge Sort.

Objective: To implement and analyse the Merge Sort algorithm for efficient sorting of data, assessing its time and space complexity.

```
#include <stdio.h>
#include <stdlib.h>
void merge(int arr[], int left, int middle, int right) {
  int i, j, k;
  int n1 = middle - left + 1;
  int n2 = right - middle;
  int L[n1], R[n2];
  for (i = 0; i < n1; i++)
     L[i] = arr[left + i];
  for (j = 0; j < n2; j++)
     R[j] = arr[middle + 1 + j];
  i = 0;
  j = 0;
  k = left;
  while (i < n1 \&\& j < n2) {
     if (L[i] \le R[j]) {
       arr[k] = L[i];
       i++;
     } else {
       arr[k] = R[j];
       j++;
```

```
k++;
   }
  while (i < n1) {
     arr[k] = L[i];
     i++;
     k++;
   }
  while (j < n2) {
     arr[k] = R[j];
     j++;
     k++;
   }
}
void mergeSort(int arr[], int left, int right) {
  if (left < right) {
     int middle = left + (right - left) / 2;
     mergeSort(arr, left, middle);
     mergeSort(arr, middle + 1, right);
     merge(arr, left, middle, right);
   }
}
int main() {
  int arraySize;
```

```
printf("Enter the size of the array: ");
scanf("%d", &arraySize);
int myArray[arraySize];
printf("Enter %d elements for the array:\n", arraySize);
for (int i = 0; i < arraySize; i++) {
  printf("Element %d: ", i + 1);
  scanf("%d", &myArray[i]);
}
mergeSort(myArray, 0, arraySize - 1);
printf("Sorted array: ");
for (int i = 0; i < arraySize; i++) {
  printf("%d ", myArray[i]);
}
printf("\n");
return 0;
```

Experiment Name: Implementation and Analysis of Quick Sort.

Objective: To implement and analyse the Quick Sort algorithm for efficient sorting of data, assessing its time and space complexity.

```
#include <stdio.h>
#include <stdlib.h>
void swap(int* a, int* b) {
  int temp = *a;
  *a = *b;
  *b = temp;
}
int partition(int arr[], int low, int high) {
  int pivot = arr[high];
  int i = (low - 1);
  for (int j = low; j \le high - 1; j++) {
     if (arr[j] < pivot) {
       i++;
       swap(&arr[i], &arr[j]);
     }
  }
  swap(&arr[i+1], &arr[high]);
  return (i + 1);
}
void quickSort(int arr[], int low, int high) {
  if (low < high) {
```

```
int pi = partition(arr, low, high);
     quickSort(arr, low, pi - 1);
     quickSort(arr, pi + 1, high);
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
  printf("Enter %d elements for the array:\n", arraySize);
  for (int i = 0; i < arraySize; i++) {
     printf("Element %d: ", i + 1);
     scanf("%d", &myArray[i]);
  }
  quickSort(myArray, 0, arraySize - 1);
  printf("Sorted array: ");
  for (int i = 0; i < arraySize; i++) {
     printf("%d ", myArray[i]);
  }
  printf("\n");
  return 0;
}
```

Experiment Name: Implementation and Analysis of Heap Sort.

Objective: To implement and analyse the Heap Sort algorithm for efficient sorting of data, assessing its time and space complexity.

```
#include <stdio.h>
#include <stdlib.h>
void heapify(int arr[], int size, int i) {
  int largest = i;
  int left = 2 * i + 1;
  int right = 2 * i + 2;
  if (left < size && arr[left] > arr[largest])
    largest = left;
  if (right < size && arr[right] > arr[largest])
    largest = right;
  if (largest != i) {
    int temp = arr[i];
    arr[i] = arr[largest];
     arr[largest] = temp;
    heapify(arr, size, largest);
  }
}
void heapSort(int arr[], int size) {
```

```
for (int i = size / 2 - 1; i >= 0; i--)
    heapify(arr, size, i);
  for (int i = size - 1; i > 0; i--) {
    int temp = arr[0];
    arr[0] = arr[i];
    arr[i] = temp;
    heapify(arr, i, 0);
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
  printf("Enter %d elements for the array:\n", arraySize);
  for (int i = 0; i < arraySize; i++) {
    printf("Element %d: ", i + 1);
    scanf("%d", &myArray[i]);
  }
  heapSort(myArray, arraySize);
  printf("Sorted array: ");
  for (int i = 0; i < arraySize; i++) {
```

```
printf("%d ", myArray[i]);
}
printf("\n");
return 0;
}
```

Experiment Name: Implementation and Analysis of Counting Sort.

Objective: To implement and analyse the Counting Sort algorithm for efficient sorting of data, assessing its time and space complexity.

```
#include <stdio.h>
#include <stdlib.h>
void countingSort(int arr[], int size) {
  int max = arr[0];
  for (int i = 1; i < size; i++) {
    if (arr[i] > max) {
       max = arr[i];
    }
  }
  int* count = (int*)malloc((max + 1) * sizeof(int));
  for (int i = 0; i \le max; i++) {
    count[i] = 0;
  }
  for (int i = 0; i < size; i++) {
    count[arr[i]]++;
  }
  int k = 0;
  for (int i = 0; i \le max; i++) {
    while (count[i] > 0) {
       arr[k++] = i;
```

```
count[i]--;
    }
  }
  free(count);
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
  printf("Enter %d elements for the array:\n", arraySize);
  for (int i = 0; i < arraySize; i++) {
    printf("Element %d: ", i + 1);
    scanf("%d", &myArray[i]);
  }
  countingSort(myArray, arraySize);
  printf("Sorted array: ");
  for (int i = 0; i < arraySize; i++) {
    printf("%d ", myArray[i]);
  }
  printf("\n");
  return 0;
}
```

Experiment Name: Implementation and Analysis of Radix Sort.

Objective: To implement and analyse the Radix Sort algorithm for efficient sorting of data, assessing its time and space complexity.

```
#include <stdio.h>
#include <stdlib.h>
int getMax(int arr[], int size) {
  int max = arr[0];
  for (int i = 1; i < size; i++) {
    if (arr[i] > max) {
       max = arr[i];
    }
  }
  return max;
}
void countingSort(int arr[], int size, int place) {
  const int max = 10;
  int output[size];
  int count[max];
  for (int i = 0; i < max; i++) {
    count[i] = 0;
  }
  for (int i = 0; i < size; i++) {
    count[(arr[i] / place) % 10]++;
  }
```

```
for (int i = 1; i < max; i++) {
    count[i] += count[i - 1];
  }
  for (int i = size - 1; i >= 0; i--) {
    output[count[(arr[i] / place) % 10] - 1] = arr[i];
    count[(arr[i] / place) % 10]--;
  }
  for (int i = 0; i < size; i++) {
    arr[i] = output[i];
  }
}
void radixSort(int arr[], int size) {
  int max = getMax(arr, size);
  for (int place = 1; max / place > 0; place *= 10) {
    countingSort(arr, size, place);
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
```

```
printf("Enter %d elements for the array:\n", arraySize);
for (int i = 0; i < arraySize; i++) {
    printf("Element %d: ", i + 1);
    scanf("%d", &myArray[i]);
}

radixSort(myArray, arraySize);
printf("Sorted array: ");
for (int i = 0; i < arraySize; i++) {
    printf("%d ", myArray[i]);
}
printf("\n");</pre>
```

Experiment Name: Implementation and Analysis of Shell Sort.

Objective: To implement and analyse the Shell Sort algorithm for efficient sorting of data, assessing its time and space complexity.

```
#include <stdio.h>
#include <stdlib.h>
void shellSort(int arr[], int size) {
  for (int gap = size / 2; gap > 0; gap \neq 2) {
    for (int i = gap; i < size; i++) {
       int temp = arr[i];
       int j;
       for (j = i; j \ge gap \&\& arr[j - gap] > temp; j -= gap) {
         arr[j] = arr[j - gap];
       }
       arr[j] = temp;
    }
  }
}
int main() {
  int arraySize;
  printf("Enter the size of the array: ");
  scanf("%d", &arraySize);
  int myArray[arraySize];
  printf("Enter %d elements for the array:\n", arraySize);
```

```
for (int i = 0; i < arraySize; i++) {
    printf("Element %d: ", i + 1);
    scanf("%d", &myArray[i]);
}

shellSort(myArray, arraySize);

printf("Sorted array: ");

for (int i = 0; i < arraySize; i++) {
    printf("%d ", myArray[i]);
}

printf("\n");

return 0;
}</pre>
```

Experiment Name: Implementation of Activity Selection Problem

Objective: To select the maximum number of non-overlapping activities from a set of activities, each having a start time and an end time.

```
#include <stdio.h>
void greedy_activity_selector(int start_time[], int finish_time[], int n) {
  int arr[n];
  int count=1;
  int j=0;
  int i;
  arr[0] = 1;
  printf("Selected Activity : \n");
  for (i = 1; i < n; i++) {
    if (start_time[i] >= finish_time[j]) {
       arr[count] = i+1;
       count++;
      j = i;
    }
  }
  for(int i=0;i<count;i++){</pre>
    printf("----");
  }
  printf("\n");
  for(int i=0; i<count; i++){</pre>
    printf(" P%d |", arr[i]);
```

```
printf("\n");

for(int i=0;i<count;i++){
    printf("-----");
}

printf("\n");
}

int main() {
    int start_times[] = {1, 3, 0, 5, 8, 5,11,15};
    int finish_times[] = {2, 4, 6, 7, 9, 9,14,18};
    int n = sizeof(start_times) / sizeof(start_times[0]);
    greedy_activity_selector(start_times, finish_times, n);
    return 0;
}
</pre>
```

Experiment Name: Implementation of Knapsack Problem using Greedy Solution

Objective: To determine the most valuable combination of items to include in the knapsack without exceeding its weight capacity.

```
#include <stdio.h>
#include <stdlib.h>
struct Item {
  int value;
  int weight;
};
int compare(const void *a, const void *b) {
  double ratio_a = ((struct Item*)a)->value / (double)((struct Item*)a)->weight;
  double ratio_b = ((struct Item*)b)->value / (double)((struct Item*)b)->weight;
  return (ratio_b > ratio_a) ? 1 : -1;
}
double greedy_knapsack(struct Item items[], int n, int capacity) {
  qsort(items, n, sizeof(struct Item), compare);
  double max_value = 0.0;
  int current_weight = 0;
  printf("Selecting Items :\n");
  for (int i = 0; i < n; i++) {
    if (current_weight + items[i].weight <= capacity) {</pre>
```

```
current_weight += items[i].weight;
      max_value += items[i].value;
      printf("Added item { value: %4d , weight : %4d } to bag\n",items[i].value,items[i].weight);
    } else {
      double remaining_capacity = capacity - current_weight;
      max_value += (remaining_capacity / items[i].weight) * items[i].value;
      break;
    }
  }
  return max_value;
}
int main() {
  struct Item items[] = {{60, 10}, {100, 20}, {120, 30},{50,10},{200,10}};
  int n = sizeof(items) / sizeof(items[0]);
  int capacity = 50;
  double max_value = greedy_knapsack(items, n, capacity);
  printf("Maximum value: %.2lf\n", max_value);
  return 0;
}
```

Experiment Name: Implement and Analysis of the 0/1 Knapsack problem using Dynamic Programming method

Objective: To maximize the total value of the selected items while ensuring that the total weight does not exceed the capacity of the knapsack.

```
#include <stdio.h>
struct Item
{
  int value;
  int weight;
};
int max(int a, int b)
{
  return (a > b) ? a : b;
}
int knapsackDP(int capacity, const struct Item items[], int n)
{
  int dp[n + 1][capacity + 1];
  int isSelected[n + 1][capacity + 1];
  for (int i = 0; i \le n; i++)
  {
    for (int w = 0; w <= capacity; w++)
    {
       if (i == 0 | | w == 0)
       {
```

```
dp[i][w] = 0;
       isSelected[i][w] = 0;
    }
     else if (items[i - 1].weight <= w)
    {
       int include = items[i - 1].value + dp[i - 1][w - items[i - 1].weight];
       int exclude = dp[i - 1][w];
       if (include > exclude)
       {
         dp[i][w] = include;
         isSelected[i][w] = 1;
       }
       else
       {
         dp[i][w] = exclude;
         isSelected[i][w] = 0;
       }
     }
     else
    {
       dp[i][w] = dp[i - 1][w];
       isSelected[i][w] = 0;
    }
  }
printf("Selected items: \n");
int i = n, w = capacity;
```

```
while (i > 0 \&\& w > 0)
  {
    if (isSelected[i][w])
    {
       printf("Item { value: %d , weight: %d} \n", items[i - 1].value, items[i - 1].weight);
       w -= items[i - 1].weight;
    }
    i--;
  }
  printf("\n");
  return dp[n][capacity];
}
int main()
{
  struct Item items[] = {{60, 10}, {100, 20}, {120, 30}, {50, 10}, {200, 10}};
  int n = sizeof(items) / sizeof(items[0]);
  int capacity = 50;
  int max_value = knapsackDP(capacity, items, n);
  printf("Maximum value: %d\n", max_value);
  return 0;
}
```

Experiment Name: Implementation and Analysis of LCS

Objective: To find the longest subsequence that two sequences have in common

```
Program:
```

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
int lcsLength(const char *X, const char *Y) {
  int m = strlen(X);
  int n = strlen(Y);
  int dp[m + 1][n + 1];
  for (int i = 0; i \le m; i++) {
    for (int j = 0; j \le n; j++) {
       if (i == 0 | | j == 0)
         dp[i][j] = 0;
       else if (X[i - 1] == Y[j - 1])
         dp[i][j] = dp[i - 1][j - 1] + 1;
       else
         dp[i][j] = (dp[i-1][j] > dp[i][j-1]) ? dp[i-1][j] : dp[i][j-1];
    }
  }
  return dp[m][n];
}
void printLCS(const char *X, const char *Y, int m, int n) {
  int dp[m + 1][n + 1];
```

```
for (int i = 0; i \le m; i++) {
  for (int j = 0; j \le n; j++) {
     if (i == 0 | | j == 0)
        dp[i][j] = 0;
     else if (X[i - 1] == Y[j - 1])
       dp[i][j] = dp[i - 1][j - 1] + 1;
     else
       dp[i][j] = (dp[i-1][j] > dp[i][j-1]) ? dp[i-1][j] : dp[i][j-1];
  }
}
int index = dp[m][n];
char lcs[index + 1];
lcs[index] = '\0';
int i = m, j = n;
while (i > 0 \&\& j > 0) {
  if (X[i-1] == Y[j-1]) {
     lcs[index - 1] = X[i - 1];
     i--;
     j--;
     index--;
  } else if (dp[i - 1][j] > dp[i][j - 1]) {
     i--;
  } else {
     j--;
  }
}
```

```
int main() {
  const char *X = "ABCBDAB";
  const char *Y = "BDCAB";
  int m = strlen(X);
  int n = strlen(Y);
  int length = lcsLength(X, Y);
  printf("Length of LCS: %d\n", length);
  printLCS(X, Y, m, n);
```

return 0;

Experiment Name: Implementation of Kruskal's algorithm to find MST

Objective: To find the subset of edges that forms a tree and includes every vertex, with the total weight of the edges minimized.

Program: #include <stdio.h> #include <stdlib.h> #define V 10 #define E 20 struct Edge { int src, dest, weight; **}**; struct Subset { int parent, rank; **}**; int compareEdges(const void *a, const void *b) { return ((struct Edge *)a)->weight - ((struct Edge *)b)->weight; } int find(struct Subset subsets[], int i) { if (subsets[i].parent != i)

subsets[i].parent = find(subsets, subsets[i].parent);

```
return subsets[i].parent;
}
void Union(struct Subset subsets[], int x, int y) {
  int xroot = find(subsets, x);
  int yroot = find(subsets, y);
  if (subsets[xroot].rank < subsets[yroot].rank)</pre>
    subsets[xroot].parent = yroot;
  else if (subsets[xroot].rank > subsets[yroot].rank)
    subsets[yroot].parent = xroot;
  else {
    subsets[yroot].parent = xroot;
    subsets[xroot].rank++;
  }
}
void kruskalMST(struct Edge edges[], int n, int e) {
  struct Edge result[n];
  int i = 0, j = 0;
  qsort(edges, e, sizeof(edges[0]), compareEdges);
  struct Subset *subsets = (struct Subset *)malloc(n * sizeof(struct Subset));
```

```
for (int v = 0; v < n; v++) {
    subsets[v].parent = v;
    subsets[v].rank = 0;
  }
  while (i < n - 1 \&\& j < e) {
    struct Edge next_edge = edges[j++];
    int x = find(subsets, next_edge.src);
    int y = find(subsets, next_edge.dest);
    if (x != y) {
       result[i++] = next_edge;
       Union(subsets, x, y);
    }
  }
  printf("Edge Weight\n");
  for (int i = 0; i < n - 1; i++)
    printf("%d - %d %d\n", result[i].src, result[i].dest, result[i].weight);
  free(subsets);
int main() {
  int n, e;
```

```
printf("Enter the number of vertices in the graph: ");
scanf("%d", &n);

printf("Enter the number of edges in the graph: ");
scanf("%d", &e);

struct Edge edges[E];

printf("Enter the edges (source destination weight) of the graph:\n");
for (int i = 0; i < e; i++)
    scanf("%d %d %d", &edges[i].src, &edges[i].dest, &edges[i].weight);

kruskalMST(edges, n, e);

return 0;</pre>
```

Experiment Name: Implementation of Prim's algorithm to find MST

Objective: To finds a minimum spanning tree (MST) for a connected, undirected graph.

```
#include <stdio.h>
#include <stdbool.h>
#include <limits.h>
#define V 10
int minKey(int key[], bool mstSet[], int n) {
  int min = INT_MAX, min_index;
  for (int v = 0; v < n; v++) {
    if (mstSet[v] == false && key[v] < min) {
       min = key[v];
       min_index = v;
    }
  }
  return min_index;
}
void printMST(int parent[], int graph[V][V], int n) {
  printf("Edge Weight\n");
  for (int i = 1; i < n; i++)
    printf("%d - %d %d\n", parent[i], i, graph[i][parent[i]]);
}
```

```
void primMST(int graph[V][V], int n) {
  int parent[V];
  int key[V];
  bool mstSet[V];
  for (int i = 0; i < n; i++) {
    key[i] = INT_MAX;
    mstSet[i] = false;
  }
  key[0] = 0;
  for (int count = 0; count < n - 1; count++) {
    int u = minKey(key, mstSet, n);
    mstSet[u] = true;
    for (int v = 0; v < n; v++) {
       if (graph[u][v] \&\& mstSet[v] == false \&\& graph[u][v] < key[v]) {
         parent[v] = u;
         key[v] = graph[u][v];
      }
    }
```

```
}
  printMST(parent, graph, n);
}
int main() {
  int n;
  printf("Enter the number of vertices in the graph: ");
  scanf("%d", &n);
  int graph[V][V];
  printf("Enter the adjacency matrix for the graph:\n");
  for (int i = 0; i < n; i++)
    for (int j = 0; j < n; j++)
       scanf("%d", &graph[i][j]);
  primMST(graph, n);
  return 0;
}
```

Experiment Name: Implementation of Warshal's Algorithm for All Pair Shortest Path.

Objective: To find the shortest paths between all pairs of vertices in a given directed weighted graph.

```
Program:
```

```
#include <stdio.h>
#define V 4
#define INF 99999
void printSolution(int dist[][V]);
void floydWarshall(int dist[][V])
{
         int i, j, k;
         for (k = 0; k < V; k++) {
                  for (i = 0; i < V; i++) {
                           for (j = 0; j < V; j++) {
                                    if (dist[i][k] + dist[k][j] < dist[i][j])
                                              dist[i][j] = dist[i][k] + dist[k][j];
                           }
                  }
         }
```

```
printSolution(dist);
}
void printSolution(int dist[][V])
{
         printf(
                  "The following matrix shows the shortest distances"
                  " between every pair of vertices \n");
         for (int i = 0; i < V; i++) {
                  for (int j = 0; j < V; j++) {
                           if (dist[i][j] == INF)
                                   printf("%7s", "INF");
                           else
                                    printf("%7d", dist[i][j]);
                  }
                  printf("\n");
        }
}
int main()
{
         int graph[V][V] = \{ \{ 0, 5, INF, 10 \}, \}
                                                     { INF, 0, 3, INF },
                                                      { INF, INF, 0, 1 },
                                                      { INF, INF, INF, 0 } };
```

```
floydWarshall(graph);
return 0;
}
```

Experiment Name: Implementation of Dijkstra Algorithm for Single Source Shortest Path.

Objective: To find the shortest paths from a given source vertex to all other vertices in a weighted graph.

```
#include <stdio.h>
#include <stdbool.h>
#include <limits.h>
#define V 10
int minDistance(int dist[], bool sptSet[], int n) {
  int min = INT_MAX, min_index;
  for (int v = 0; v < n; v++) {
    if (!sptSet[v] && dist[v] <= min) {
       min = dist[v];
       min_index = v;
    }
  }
  return min_index;
}
void printSolution(int dist[], int n, int src) {
  printf("Vertex Distance from Source\n");
  for (int i = 0; i < n; i++)
    printf("%d \t\ %d\n", i, dist[i]);
}
void dijkstra(int graph[V][V], int src, int n) {
```

```
int dist[V];
 bool sptSet[V];
for (int i = 0; i < n; i++) {
               dist[i] = INT_MAX;
               sptSet[i] = false;
}
 dist[src] = 0;
for (int count = 0; count < n - 1; count++) {
               int u = minDistance(dist, sptSet, n);
               sptSet[u] = true;
               for (int v = 0; v < n; v++) {
                             if (!sptSet[v] \&\& \ graph[u][v] \&\& \ dist[u] != INT\_MAX \&\& \ dist[u] + graph[u][v] < dist[v]) \{ left (!sptSet[v] \&\& \ graph[u][v] < left
                                            dist[v] = dist[u] + graph[u][v];
                            }
              }
}
 printSolution(dist, n, src);
```

```
int main() {
  int n;
  printf("Enter the number of vertices in the graph: ");
  scanf("%d", &n);
  int graph[V][V];
  printf("Enter the adjacency matrix for the graph:\n");
  for (int i = 0; i < n; i++) {
    for (int j = 0; j < n; j++) {
       scanf("%d", &graph[i][j]);
    }
  }
  int src;
  printf("Enter the source vertex: ");
  scanf("%d", &src);
  dijkstra(graph, src, n);
  return 0;
```

Experiment Name: Implementation of N Queen Problem using Backtracking

Objective: To place N chess queens on an $N\times N$ chessboard in such a way that no two queens threaten each other.

```
#include <stdio.h>
#include <stdbool.h>
#include <stdlib.h>
void printSolution(int **board, int N) {
  for (int i = 0; i < N; i++) {
    for (int j = 0; j < N; j++)
       printf("%c ", board[i][j] ? 'Q' : '.');
    printf("\n");
  }
  printf("\n");
}
bool isSafe(int **board, int row, int col, int N) {
  int i, j;
  for (i = 0; i < col; i++)
    if (board[row][i])
       return false;
  for (i = row, j = col; i >= 0 && j >= 0; i--, j--)
    if (board[i][j])
       return false;
```

```
for (i = row, j = col; i < N && j >= 0; i++, j--)
    if (board[i][j])
       return false;
  return true;
}
bool solveNQueensUtil(int **board, int col, int N) {
  if (col >= N) {
    printSolution(board, N);
    return true;
  }
  bool res = false;
  for (int i = 0; i < N; i++) {
    if (isSafe(board, i, col, N)) {
       board[i][col] = 1;
       res = solveNQueensUtil(board, col + 1, N) | | res;
       board[i][col] = 0;
    }
  }
  return res;
}
void solveNQueens(int N) {
```

```
int **board = (int **)malloc(N * sizeof(int *));
  for (int i = 0; i < N; i++) {
     board[i] = (int *)malloc(N * sizeof(int));
     for (int j = 0; j < N; j++)
       board[i][j] = 0;
  }
  if (!solveNQueensUtil(board, 0, N)) {
     printf("Solution does not exist");
  }
  for (int i = 0; i < N; i++) {
     free(board[i]);
  }
  free(board);
}
int main() {
  int N;
  printf("Enter the value of N for N-Queens: ");
  scanf("%d", &N);
  solveNQueens(N);
  return 0;
```

Experiment Name: Implementation of Sum of Subset problem using Backtracking

Objective: To find a subset of a given set of positive integers such that the sum of the elements in the subset is equal to a given target sum.

```
#include <stdio.h>
#include <stdbool.h>
bool isSubsetSum(int set[], int n, int sum) {
  if (sum == 0)
    return true;
  if (n == 0)
    return false;
  if (set[n - 1] > sum)
    return isSubsetSum(set, n - 1, sum);
  return isSubsetSum(set, n - 1, sum) || isSubsetSum(set, n - 1, sum - set[n - 1]);
}
int main() {
  int n, sum;
  printf("Enter the number of elements in the set: ");
  scanf("%d", &n);
  int set[n];
  printf("Enter the elements of the set:\n");
  for (int i = 0; i < n; i++) {
```

```
scanf("%d", &set[i]);
}

printf("Enter the target sum: ");
scanf("%d", &sum);

if (isSubsetSum(set, n, sum)) {
    printf("Found a subset with the given sum\n");
} else {
    printf("No subset with the given sum\n");
}

return 0;
}
```