

# UNIT 4: SPATIAL DATA VISUALIZATION

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# OUTLINE

- ❖ Scalar Fields
  - ❖ Isocontours (Topographic Terrain maps), Scalar Volumes
  - ❖ Direct Volume Rendering (Multidimensional transfer functions)
  - ❖ Maps (dot, pixel)
- ❖ Vector Fields
  - ❖ Defining Marks and Channels

- ❖ Spatial data is any type of data that directly or indirectly *references a specific geographical area or location*.
- ❖ Also known as geospatial data, refers to information about the *physical location and shape of objects or features on Earth*.
- ❖ Represents a physical object in a geographic coordinate system.



# SPATIAL DATA VISUALIZATION

## Geometric Data:

- ❖ Geometric data deals with abstract shapes, positions, and relationships in a Euclidean space.
- ❖ It operates on a plane (x, y, and an optional z coordinate).
- ❖ Examples *include points, lines, and polygons.*
- ❖ Geometric data can be in any projection or coordinate system.

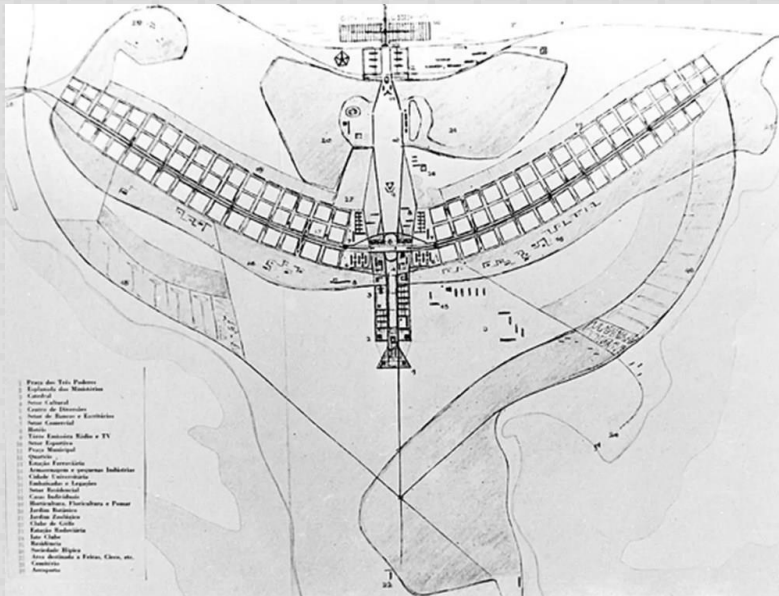
## Geographic Data:

- ❖ Geographic data describes *objects and their positions relative to Earth's surface.*
- ❖ Typically represented using latitude (y) and longitude (x) coordinates (e.g., WGS 84).
- ❖ Examples include GPS locations, country borders, and city names.



# SPATIAL DATA VISUALIZATION

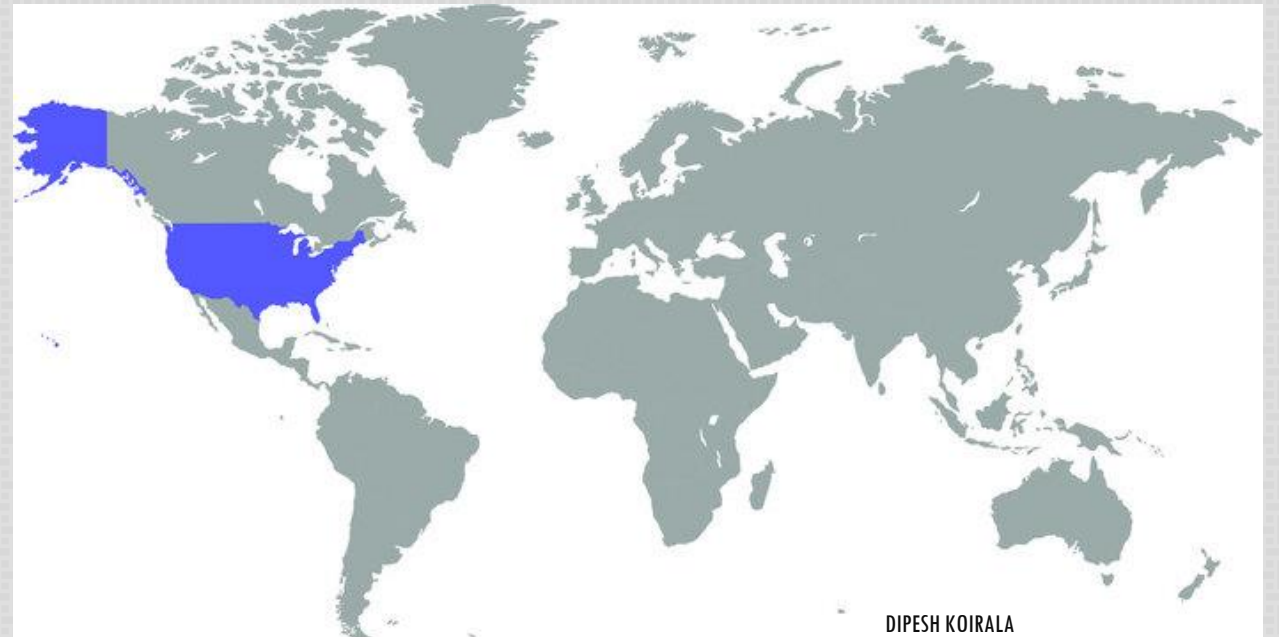
- ❖ Spatial data visualization is the *process of using visual elements such as maps, coordinate systems and geometric shapes* to help understand and analyze geographic data.
- ❖ These visualizations focus on the relationship between data and its physical location to create insight.
- ❖ Is widely used in many fields, including urban planning, public health, environmental science, and business.





# SPATIAL DATA VISUALIZATION

- ❖ Historically, doctors and scientists have used this kind of presentation to map illness, resources, and even simple navigation.
- ❖ The two main spatial data *types are geometry*, where shape information is directly conveyed by spatial elements that do not necessarily have associated attributes, *and spatial fields, where attributes are associated with each cell in the field.*
- ❖ *E.g., choropleth map* for geographic data



# SPATIAL DATA VISUALIZATION

## Choropleth Maps

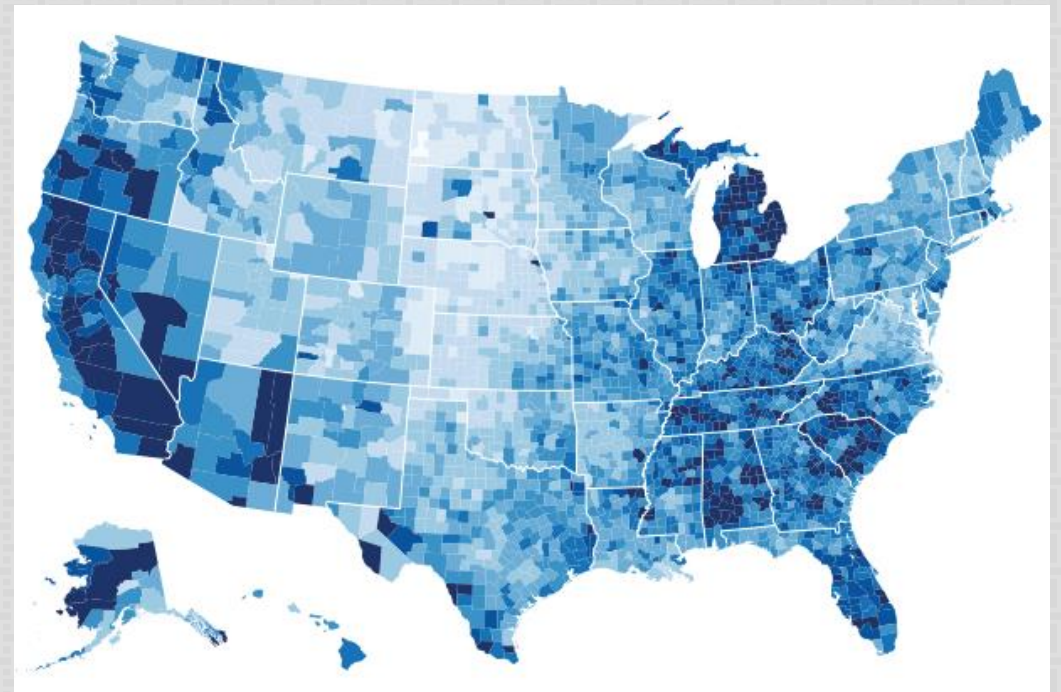
- ❖ To show *how some quantity varies across locations*.
- ❖ Can do so coloring individual regions in a map according to the map according to the data dimension which to be displayed.

### What Data?

- ❖ Geographic geometry data. Table with one quantitative attribute per region

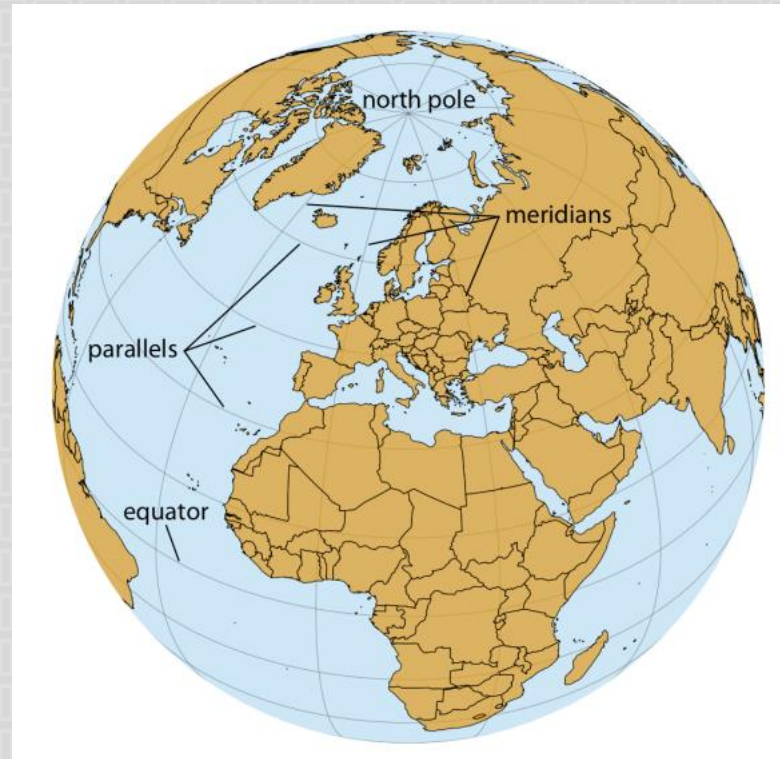
### How to Encode?

- ❖ Use given geometry for area mark boundaries. Color: sequential segmented colormap.



# PROJECTIONS

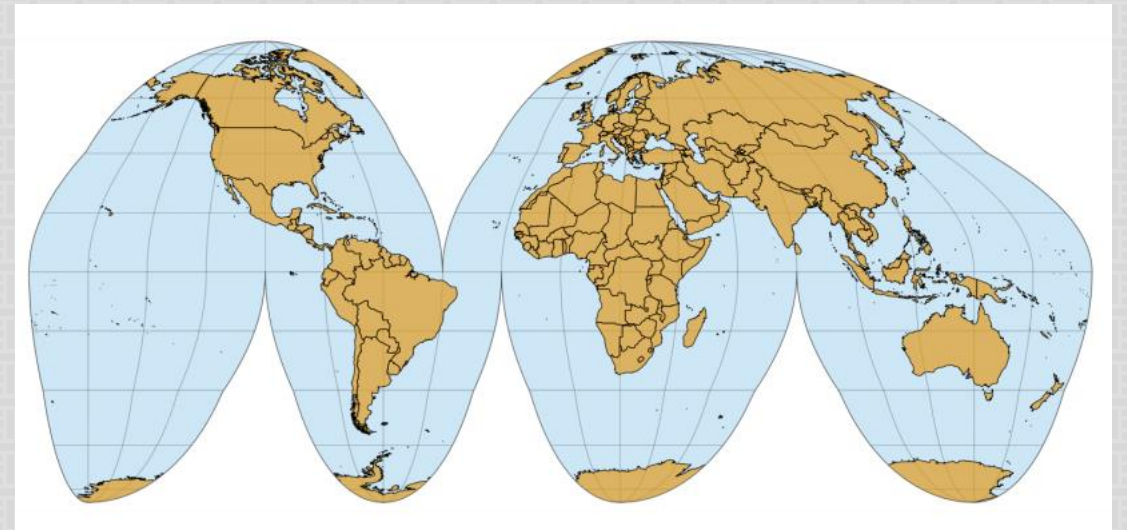
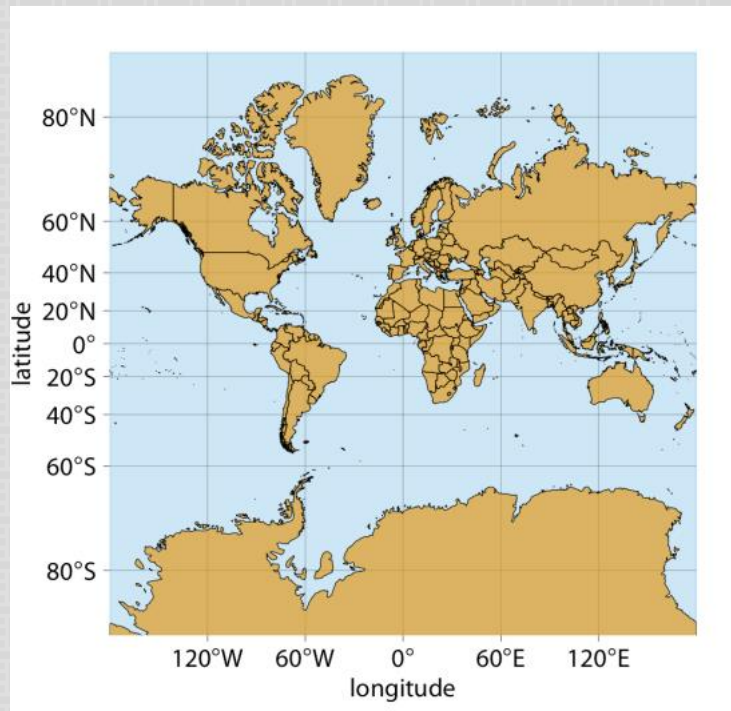
- ❖ The earth *is approximately a sphere* , and more precisely an oblate spheroid that is slightly flattened along its axis of rotation.





# PROJECTIONS

- ❖ The challenge in map making is that we need to take the spherical surface of the earth and flatten it out so we can display it on a map. (*This process is called projection.*)
- ❖ Introduces distortions, because a curved surface cannot be projected exactly onto a flat surface.



# SPATIAL SCALAR FIELDS

- ❖ A scalar field *associates a scalar value to every point in a space.*
- ❖ Widely used in physics, engineering and other fields to describe quantities.

Some examples of scalar fields include:

1. **Temperature:** A scalar field that describes the temperature at each point in space.
2. **Pressure:** A scalar field that describes the pressure at each point in space.
3. **Density:** A scalar field that describes the density of a fluid at each point in space.

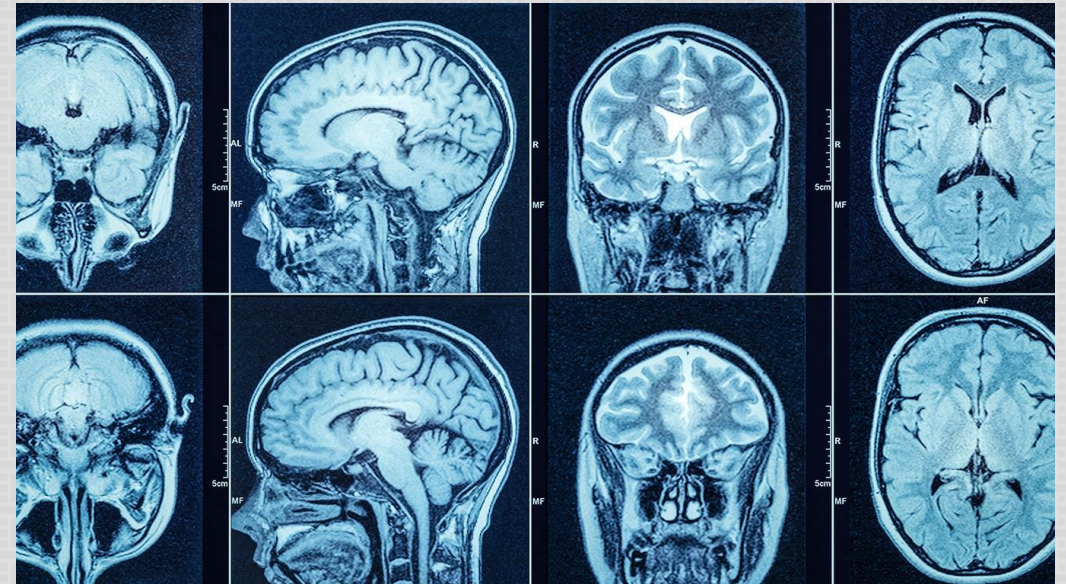
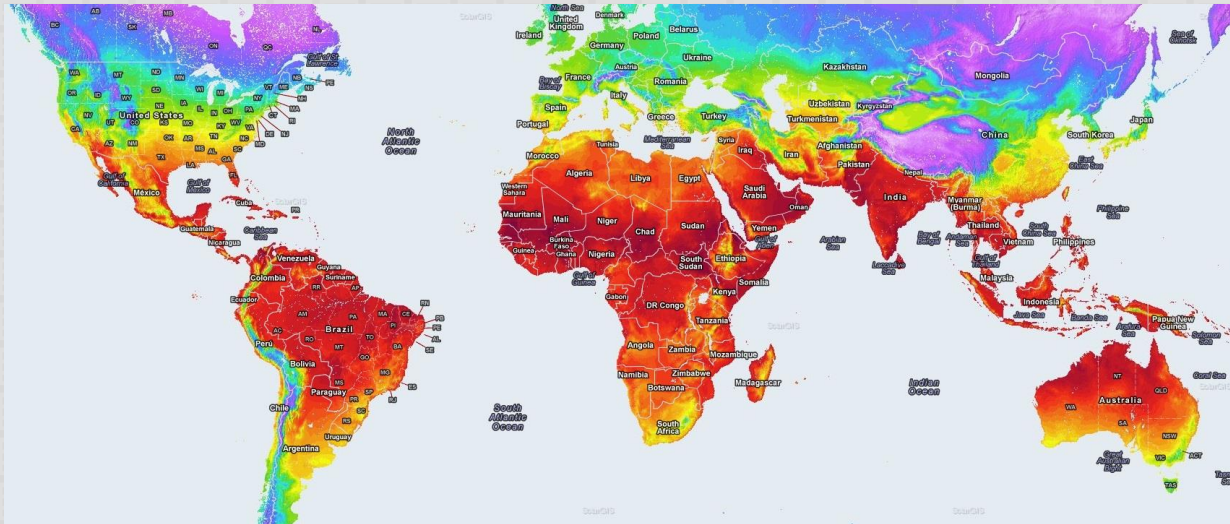
In summer, temperatures at the North Pole can reach over 20°C

WEATHER IN DEGREES CELSIUS

|                | Jan   | Feb   | Mar   | Apr  | May  | Jun | Jul  | Aug  | Sep  | Oct  | Nov   | Dec   |
|----------------|-------|-------|-------|------|------|-----|------|------|------|------|-------|-------|
| Avg. Temp (°C) | -24.2 | -20.3 | -12.4 | -1   | 8.8  | 15  | 15.9 | 13.4 | 6.9  | -4.1 | -15.3 | -23.3 |
| Max. Temp (°C) | -19.5 | -14.3 | -5    | 4.9  | 14.7 | 21  | 21.5 | 18.9 | 12.1 | 0.2  | -11.1 | -19.1 |
| Min. Temp (°C) | -28.8 | -26.2 | -19.8 | -6.9 | 2    | 9.1 | 10.4 | 8    | 1.8  | -8.3 | -19.5 | -27.4 |

# SPATIAL SCALAR FIELDS

- ❖ A scalar spatial field has a single value associated *with each spatially defined cell*.
- ❖ Scalar fields are often collected through *medical imaging*, where the measured value is radio-opacity in the case of computed tomography (CT) scans and proton density in the case of magnetic resonance imaging (MRI) scans.



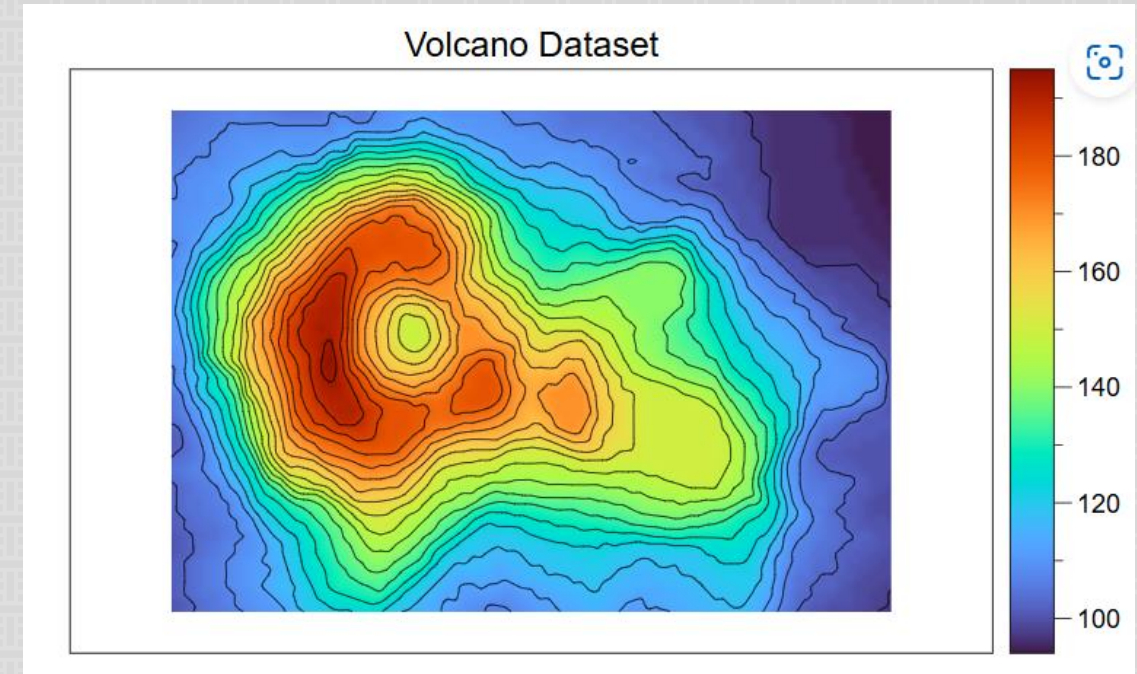
# SPATIAL SCALAR FIELD

- ❖ For scalar fields with one attribute at each field each, the two main visual encoding idiom families are:
  - i. Isocountours
  - ii. Direct Volume Rendering



# ISOCONTOURS

- ❖ A set of isolines, namely, lines that represent the *contours of a particular level of the scalar value*, can be derived from a scalar spatial field.
- ❖ Contours are imaginary lines joining places having the *same or equal elevation*.
- ❖ These lines provide valuable information about the shape, slope of the terrain or any other variable being represented on the map.

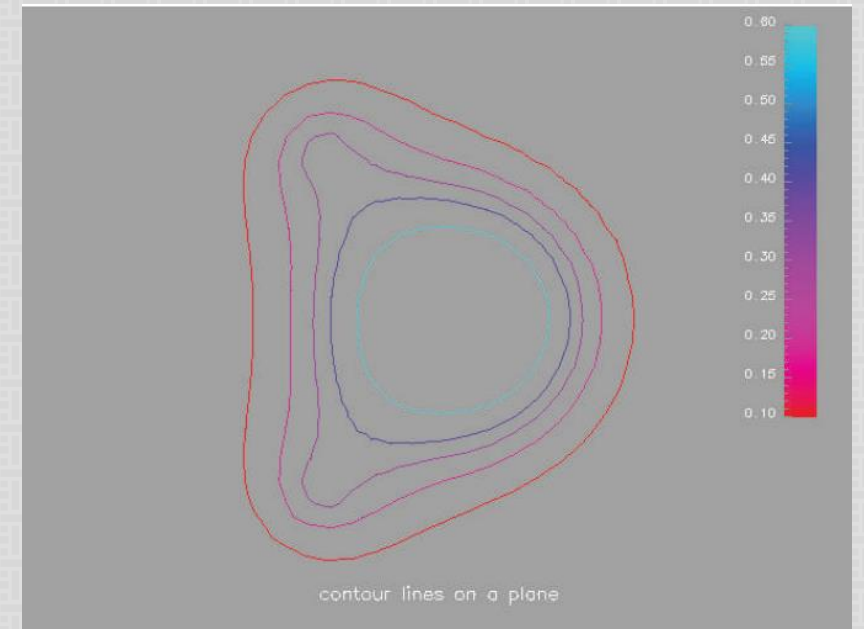




# ISOCONTOURS

## Isocontours (Characteristics)

- ❖ A contour or isovalue map conveys boundary information extracted from an image *depicting a continuous phenomenon*, such as elevation or temperature.
- ❖ The term isovalue means “single value,” and thus a contour on such a map indicates the *boundary between points above this value and points below the value*.
- ❖ Each isovalue may generate multiple closed contours. Multiple isovalues may be plotted simultaneously, using color, line thickness, line style, or labels to differentiate values.



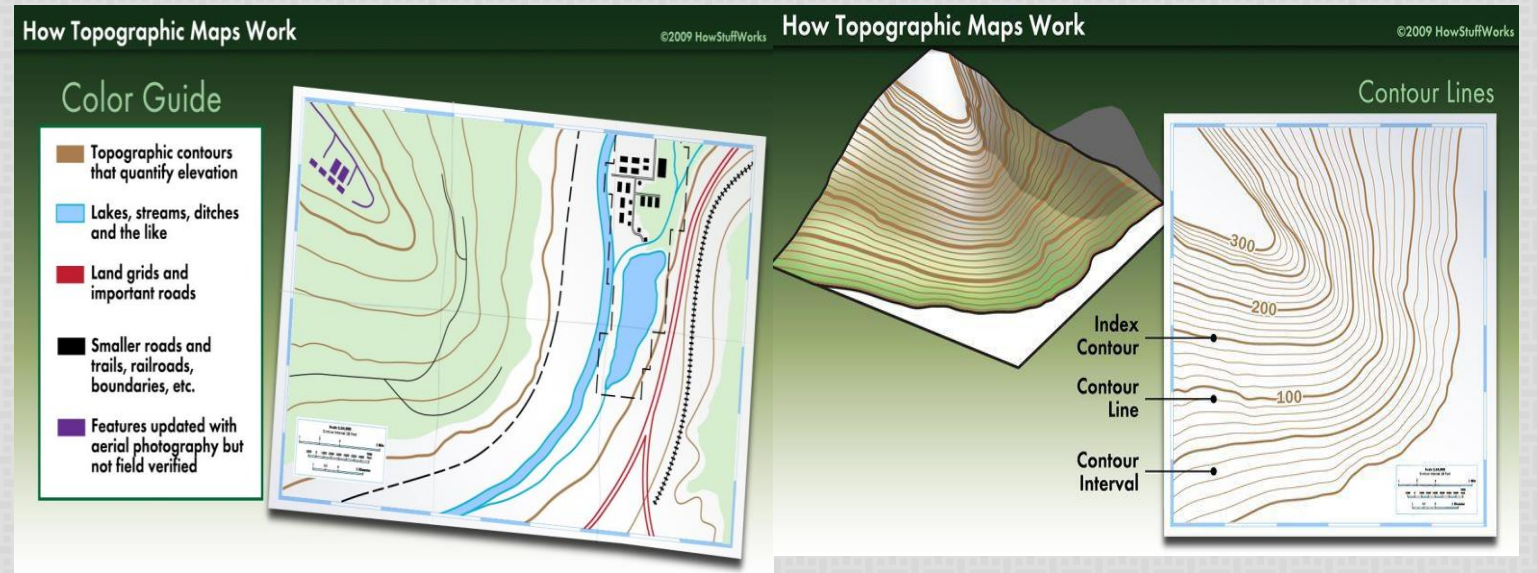
# ISOCONTOURS

## Characteristics

- ❖ **Elevation Representation:** Each contour line represents a constant elevation above a reference point, usually mean sea level on a topographic map. For e.g., if the contour interval is set to 10 meters, every contour line will represent a point that is 10 meters higher or lower than the adjacent lines.
- ❖ **Gradient and Slope:** Close contour lines indicate a steep slope, while widely spaced lines suggest a gentle slope. The steepest slope on a topographic map is where the contour lines are closest together or when two contour lines merge into one, forming a cliff or a vertical slope.
- ❖ Contour lines *never intersect or branch out*. They can form closed loops to indicate hills, depressions, or mountains.
- ❖ Close contour lines indicate a steep slope, while widely spaced lines suggest a gentle slope. The steepest slope on a topographic map is where the contour lines are closest together or when two contour lines merge into one, forming a cliff or a vertical slope

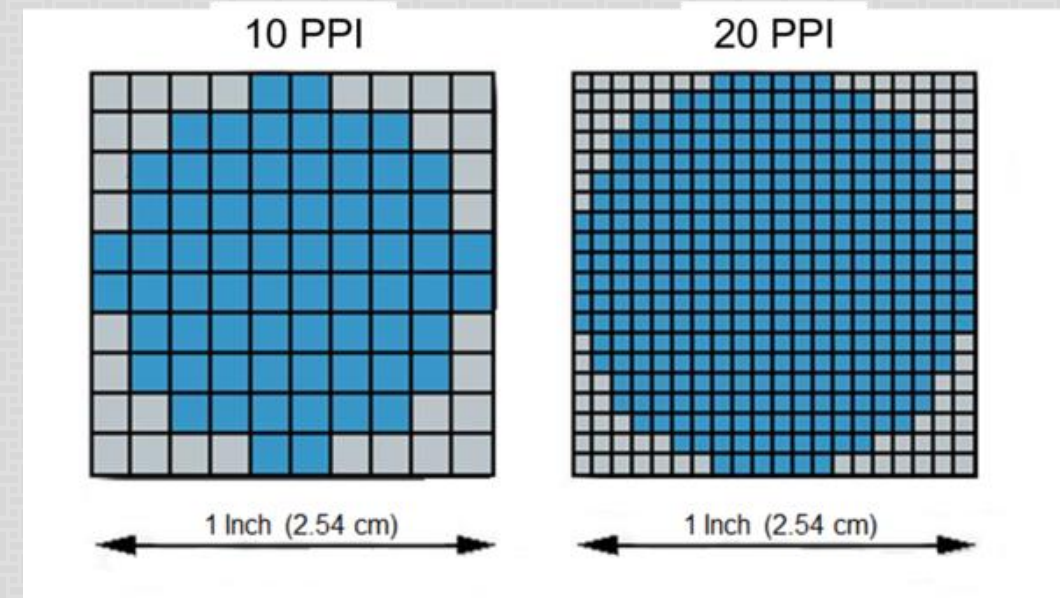
# SPATIAL DATA VISUALIZATION

## ❖ Topographic Terrain Maps



# SCALAR VOLUMES

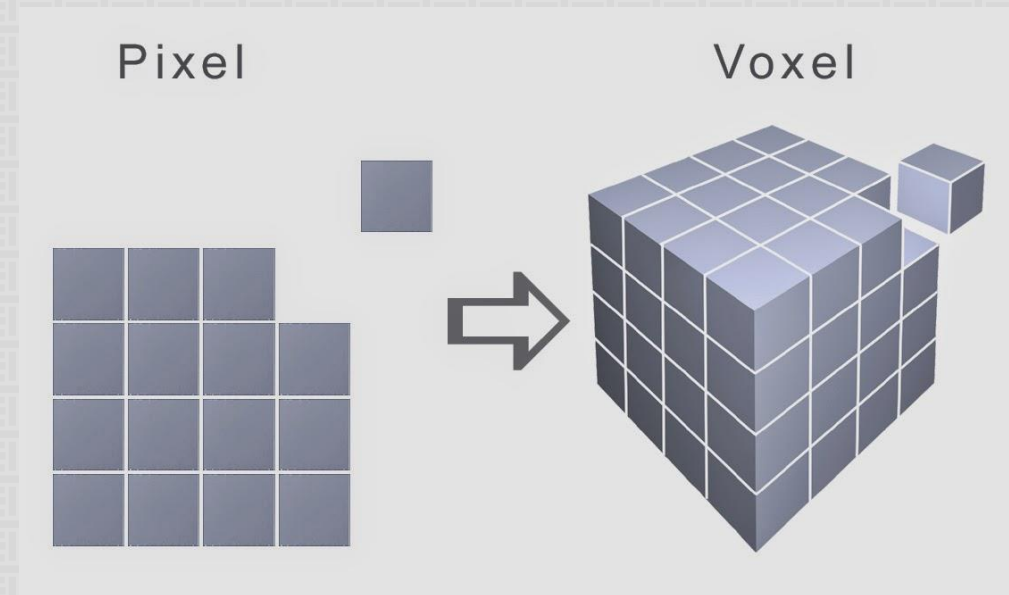
- ❖ As pixels are to two-dimensional visualization, **voxels**, or *volume elements*, are to three-dimensional visualization.
- ❖ In a scalar volume, the scalar values are typically represented on a regular grid, forming a three-dimensional array.
- ❖ Each grid point, also known as a **voxel**, contains a scalar value.



Pixel

# SCALAR VOLUMES

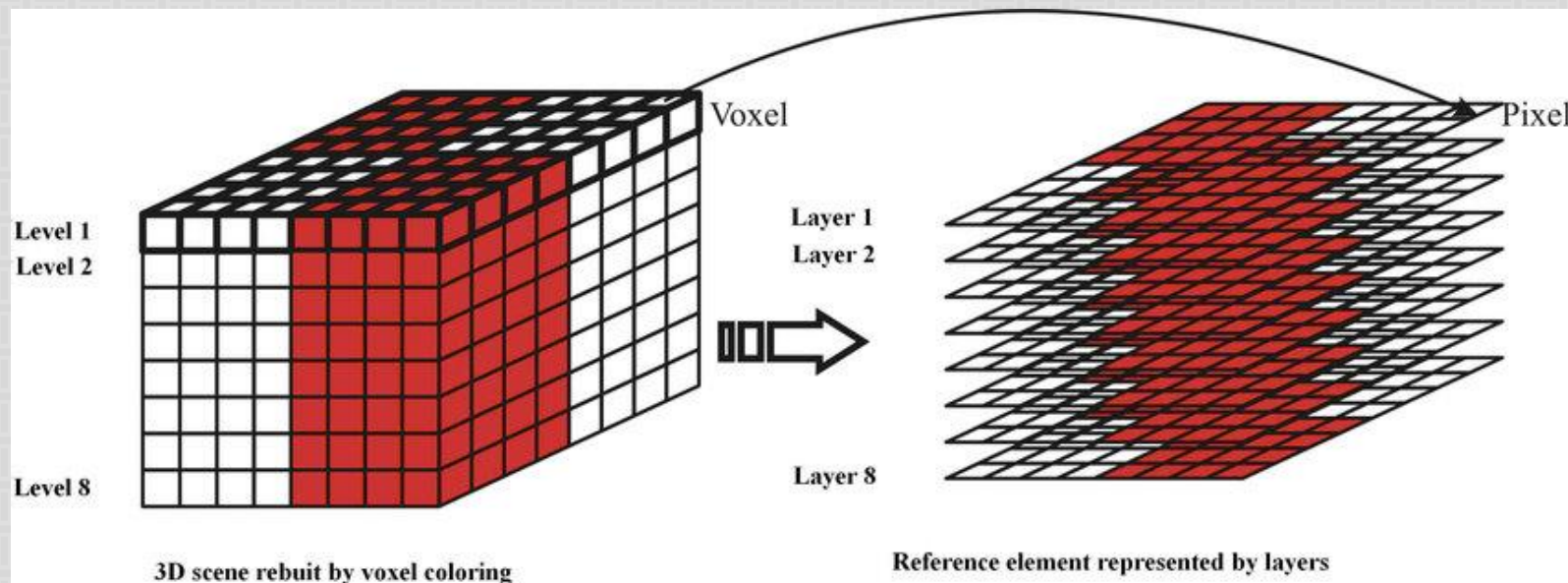
- ❖ Volume data is generally a sampling of a continuous phenomenon, and can be either acquired via sensors (e.g., *tomographic data sets*) or generated via simulations (e.g., computational fluid dynamics).
- ❖ The goal is to convey to the viewer the structure, patterns, and anomalies within the data.
- ❖ Suppose we have a scalar volume representing temperature distribution in a cubic region. *The volume has dimensions of 50 x 50 x 50 voxels.* Each voxel contains a temperature value ranging from 0 to 50 degrees Celsius.





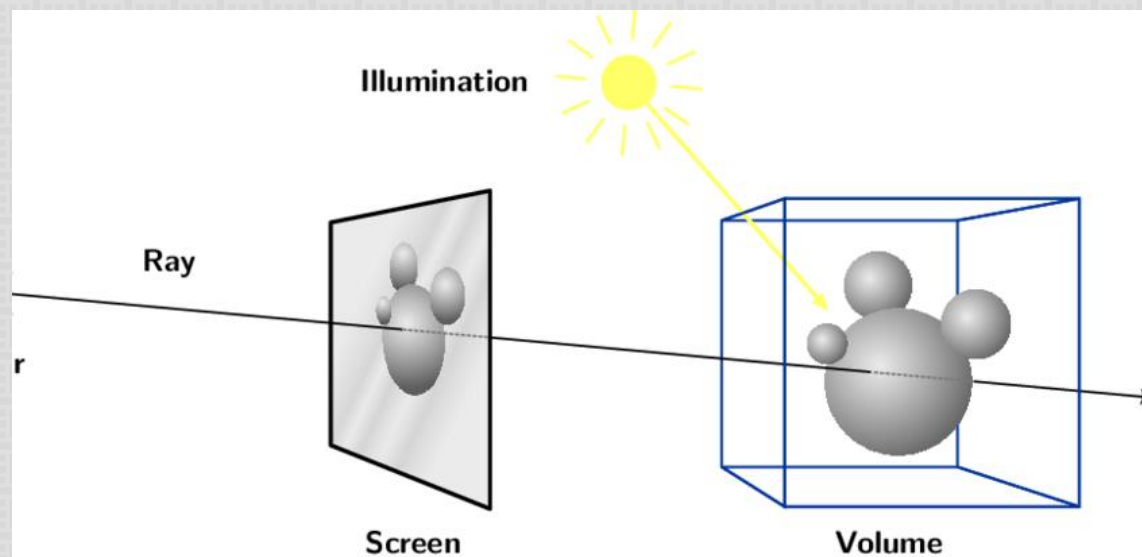
# DIRECT VOLUME RENDERING

- ❖ Direct volume rendering (DVR) is a visualization technique used *to generate images of volumetric data, such as medical CT or MRI scans, scientific simulations, or 3D models.*
- ❖ It allows for the direct exploration and analysis of data without the need for intermediate geometric representations like surfaces or contours.



# DIRECT VOLUME RENDERING

- ❖ To generate a 2D image from the volumetric data, DVR employs a process *called ray casting*.
- ❖ Either cast rays into the volume and compute a pixel value based on the data encountered by the ray, or project each voxel onto the projection plane.
- ❖ The basic idea *is to cast rays from the viewpoint of the camera* into the volume and accumulate the properties of the intersected voxels along the ray path.
- ❖ A crucial visual encoding design choice with direct volume rendering is *picking the transfer function that maps changes in the scalar value to opacity and color*.



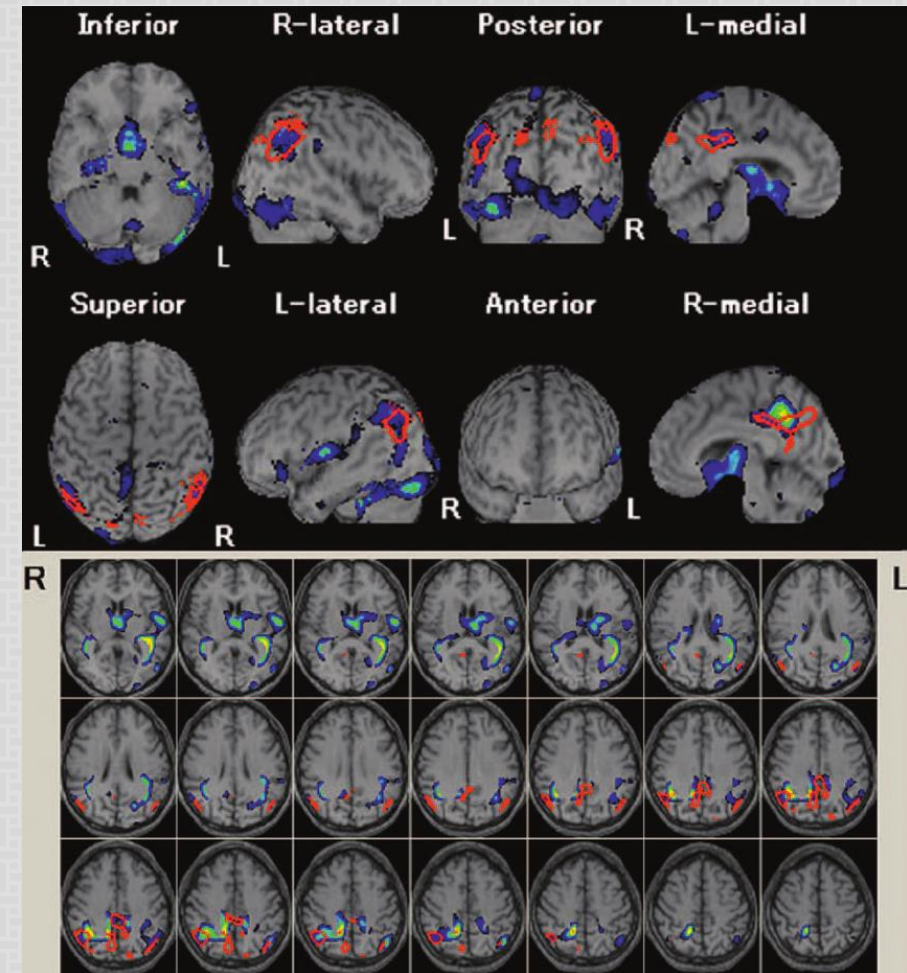
# DIRECT VOLUME RENDERING

Here are five key points that explain direct volume rendering:

**i. Volumetric Data Representation:** Direct volume rendering operates on volumetric datasets

**ii. Ray Casting:** For each pixel on the image plane, *a ray is cast into the volume*, and its interaction with the data is calculated to determine the final pixel color.

**iii. Transfer Function:** A transfer function maps the scalar values of the voxels *to optical properties, such as color and opacity*. For example, in medical imaging, a transfer function can be designed to assign different colors to different tissue types or highlight specific structures of interest.



# DIRECT VOLUME RENDERING

Here are five key points that explain direct volume rendering:

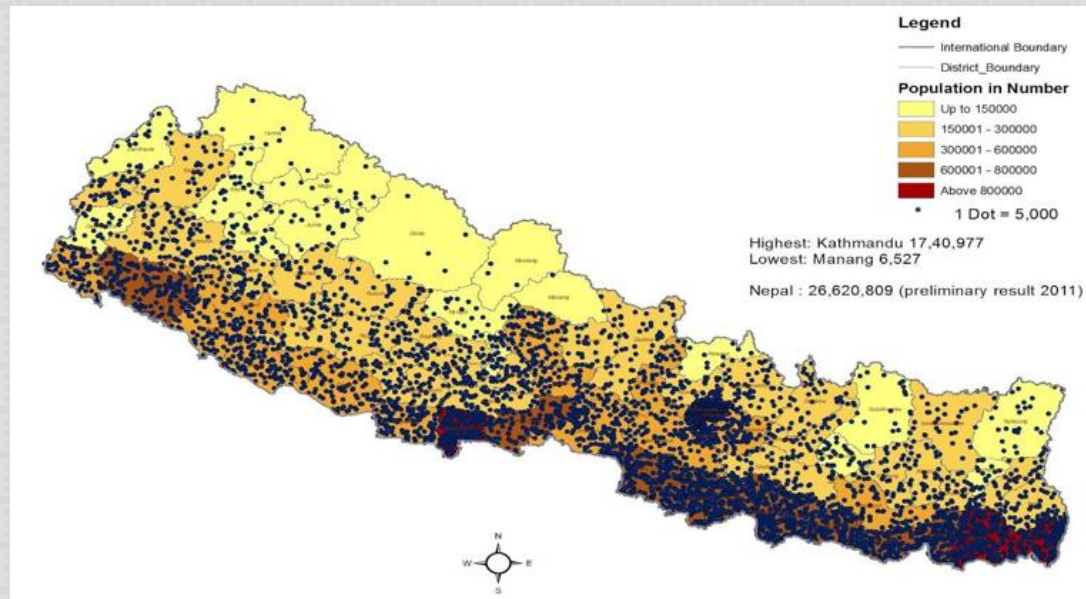
**iv. Compositing Techniques:** Direct volume rendering employs various compositing techniques to combine the contributions from multiple voxels along a ray. The most commonly used compositing method is the alpha blending technique, where the colors and opacities of voxels are blended based on their positions along the ray.

**v. Lighting and Shading:** To enhance the visual quality and perception of depth, *direct volume rendering often incorporates lighting and shading techniques*. These techniques simulate the interaction between light sources and the volumetric data, allowing for the depiction of highlights, shadows, and gradients.

# MAPS (DOT, PIXEL)

## Dot Maps

- ❖ Uses dots to represent data.
- ❖ The density of the dots represents the *density of the data in that area*.
- ❖ Dot maps are used to represent the distribution of data points geographically. Each dot on the map signifies a certain quantity of data (e.g., population, events).

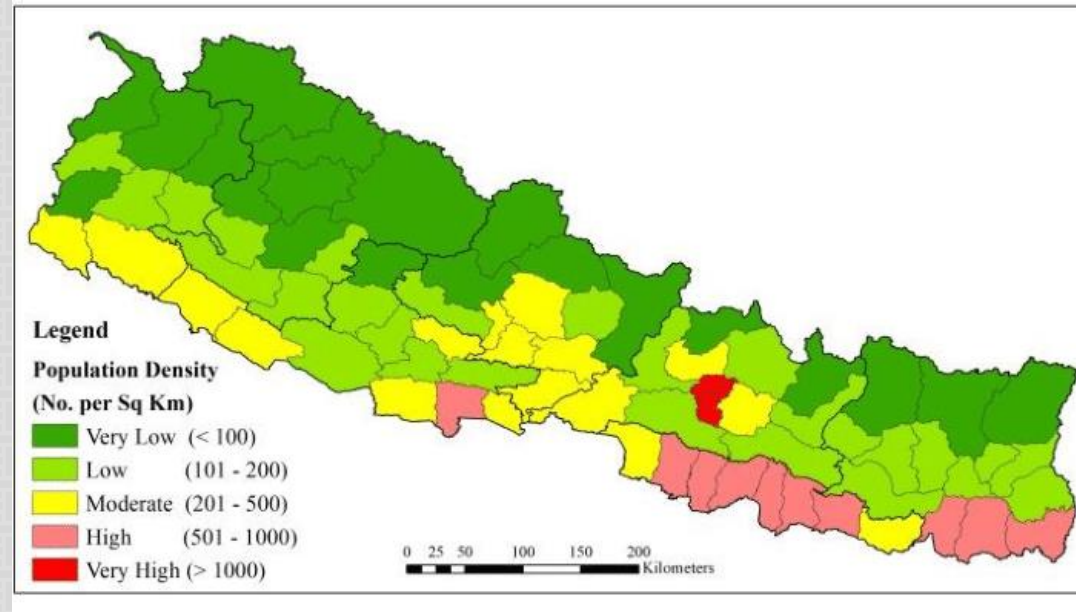




# MAPS (DOT, PIXEL)

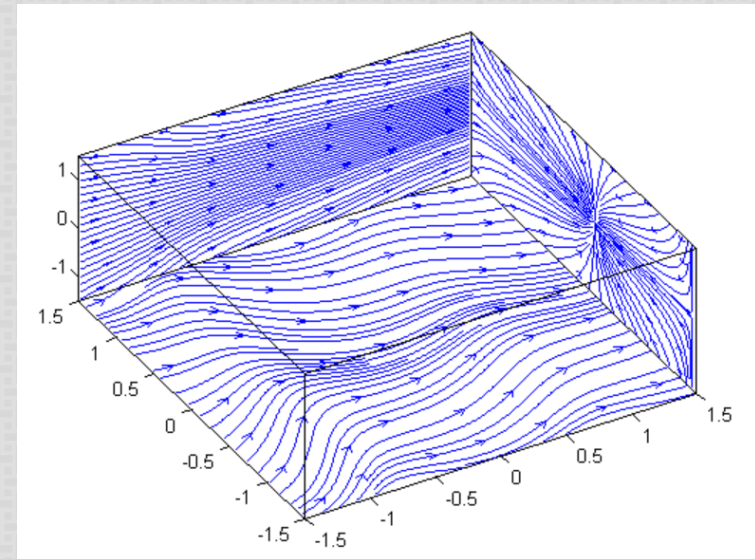
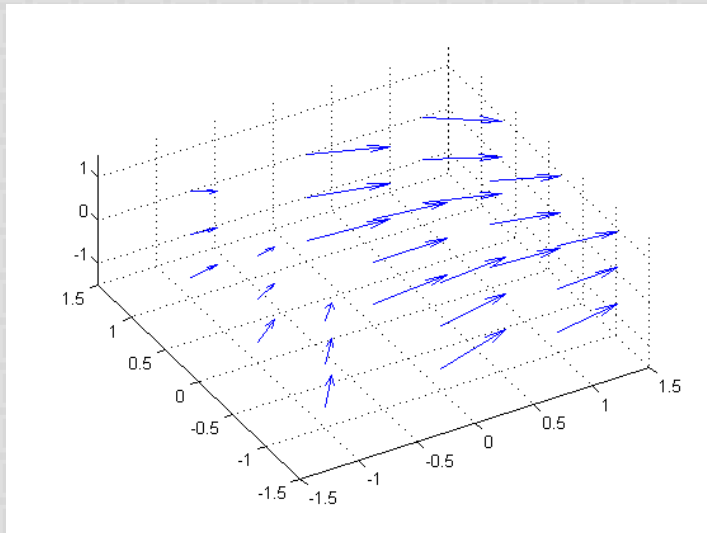
## Pixel Maps

- ❖ A pixel map (or bitmap) is typically a rasterized image, where pixels represent color information.
- ❖ When used in a mapping context, each pixel could *represent a small unit of space on a map.*



# VECTOR FIELDS

- ❖ A vector field assigns a **vector (magnitude and direction)** to every point in space.
- ❖ Each vector represents a specific attribute, **such as velocity or force**, at a particular location.
- ❖ Vector fields are commonly used in scientific simulations, fluid dynamics, weather forecasting, and many other fields where understanding the behavior of vector quantities is essential.



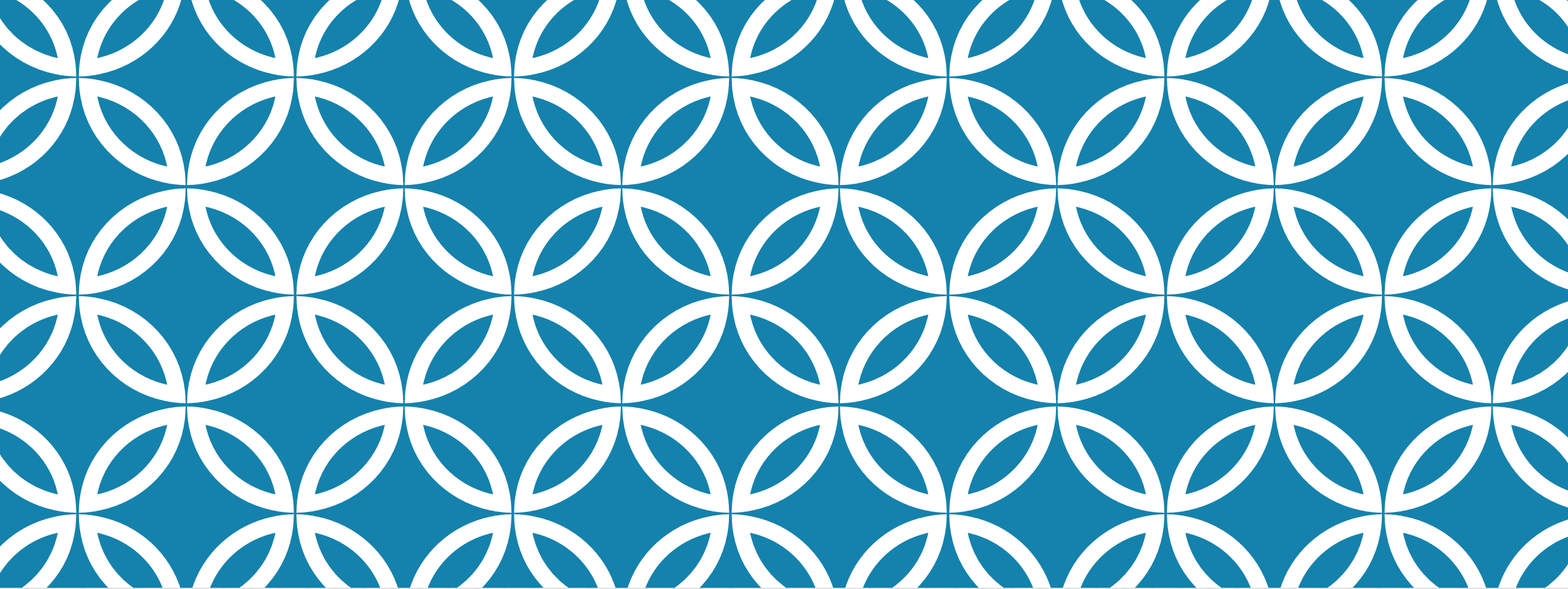
# VECTOR FIELDS

## Techniques:

- ❖ Velocity Plot (Quiver Plot)
- ❖ Velocity Plot (Cone Plot)
- ❖ Streamlines
- ❖ Streamslice
- ❖ Stream Tube and Stream Ribbon

## **Source:**

[https://web.mit.edu/8.13/matlab/MatlabTraining\\_IAP\\_2012/AGV/DemoFiles/ScriptFiles/html/Part8\\_VectorFields.html](https://web.mit.edu/8.13/matlab/MatlabTraining_IAP_2012/AGV/DemoFiles/ScriptFiles/html/Part8_VectorFields.html)



# THANK YOU

Dipesh Koirala