

## # Vector Calculus

We know that  $\int_a^b f(x) dx$  deals the integration along  $x$ -axis, i.e.  $y=0$

Similarly,  $\int_c^d f(y) dy$  deals with integration along  $y$ -axis i.e.  $x=0$ .

In this chapter, ~~we~~<sup>we</sup> extend this notion <sup>(concept)</sup> along curve.

## # Smooth curve

A curve or function is said to be smooth if it is continuous and differentiable at each point.

In particular,  $y = \sin x$ ,  $y = \cos x$  are smooth in the interval  $[-\pi, \pi]$

Eg let  $F = \frac{1}{t} \vec{i} + 2t \vec{j} + \cos t \vec{k}$

Then the value of  $F$  exists for all  $t$  except  $t=0 \in \mathbb{R}$

$\therefore F$  is smooth in  $\mathbb{R} - \{0\}$



Fact:

The curve  $\vec{r} = F_1(x, y, z)\vec{i} + F_2(x, y, z)\vec{j} +$

$F_3(x, y, z)\vec{k}$  always represent space vector.

In particular, the function

$$F = 3xyz\vec{i} + 3xy^2\vec{j} + 3x^2yz\vec{k}$$

represent space curve

### # Smooth Surface

A surface is said to be smooth if it has a unique tangent at each point.

In other words, a surface  $z = f(x, y)$  is called smooth if  $z$ ,  $\frac{\partial z}{\partial x}$ ,  $\frac{\partial z}{\partial y}$  are

exist and continuous at each point.

### # Line integral

Let us consider a vector point function

$$\vec{F} = F_1(x, y, z)\vec{i} + F_2(x, y, z)\vec{j} + F_3(x, y, z)\vec{k}$$

defined on a smooth curve  $C$  which is represented by  $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$

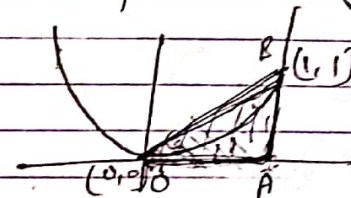
then the line integral of  $F$  along the curve  $C$  is denoted by  $\int_C \vec{F} \cdot d\vec{r}$

Note

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C (F_1\vec{i} + F_2\vec{j} + F_3\vec{k}) \cdot (dx\vec{i} + dy\vec{j} + dz\vec{k}) \\ &= \int_C (F_1 dx + F_2 dy + F_3 dz) \end{aligned}$$

Q) Evaluate the integral

i)  $\int_C xy dx + (x+y) dy$  along the line through  $(0,0)$  to  $(1,1)$   
ii) along the parabola  $y=x^2$  from  $(0,0)$  to  $(1,1)$



iii) along the line OA & then AB (OAB)

Sol<sup>n</sup>

i) Eqn of OB is

$$y-0 = \frac{1-0}{1-0} (x-0)$$

$$\therefore y = x$$

$$\therefore dy = dx$$



$$\begin{aligned}
 & \therefore \int (xy) dx + (x+y) dy \\
 & \stackrel{OB}{=} \int_0^1 x^2 dx + 2x dx \\
 & = \int_0^1 x^2 dx + 2x dx \\
 & = \left[ \frac{x^3}{3} \right]_0^1 + 2 \left[ \frac{x^2}{2} \right]_0^1 \\
 & = \frac{1}{3} + 1 \\
 & = \frac{4}{3}
 \end{aligned}$$

ii)  $y = x^2$   
 $\frac{dy}{dx} = 2x$   
 $dy = 2x dx$

$$\begin{aligned}
 & \stackrel{SO}{=} \int (xy) dx + (x+y) dy \\
 & = \int x^3 dx + (x+x^2) 2x dx \\
 & = \int_0^1 x^3 dx + 2x^2 dx + 2x^3 dx
 \end{aligned}$$

$$\begin{aligned}
 & = \left[ \frac{x^4}{4} \right]_0^1 + 2 \left[ \frac{x^3}{3} \right]_0^1 + 2 \left[ \frac{x^4}{4} \right]_0^1 \\
 & = \frac{1}{4} + \frac{2}{3} + \frac{1}{2} \\
 & = \frac{3 + 8 + 6}{12} \\
 & = \frac{17}{12}
 \end{aligned}$$

iii) Along OA then AB

Eqn of OA is  $y=0$ .

Eqn of AB is  $x=1$ .

$$\therefore \int_{OAB} xy dx + (x+y) dy$$

$$\begin{aligned}
 & = \int_{OA} xy dx + (x+y) dy + \int_{AB} xy dx + (x+y) dy \\
 & \quad \text{OA } y=0 \therefore dy=0 \quad \text{AB } x=1, dx=0 \\
 & = \int_0^1 x \cdot 0 dx + (x+0) \cdot 0 + \int_0^1 1 \cdot y \cdot 0 + (1+y) dy \\
 & = \int_0^1 0 dx + \int_0^1 dy + y dy \\
 & = 0 + \left[ y \right]_0^1 + \left[ \frac{y^2}{2} \right]_0^1 \\
 & = 0 + 1 + \frac{1}{2} \\
 & = \frac{3}{2}
 \end{aligned}$$

Thi from ①, ②, ③ we see that the integration is done above given function are different. However, initial point & terminal point are same.

Q) Evaluate  $\int_C \vec{F} \cdot d\vec{r}$  where  $\vec{F} = y^2 \vec{i} + x^2 \vec{j}$

and  $C$  is the straight line joining  $(0,0)$  to  $(1,0)$  and from  $(1,0)$  to  $(1,1)$

Soln

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C (y^2 \vec{i} + x^2 \vec{j}) (dx \vec{i} + dy \vec{j}) \\ &= \int_C y^2 dx + x^2 dy \end{aligned}$$

Now

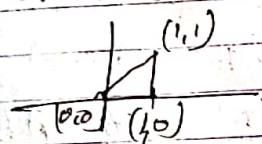
For st. line joining  $(0,0)$  to  $(1,0)$

Equation of st. line

$$y - 0 = \frac{1-0}{1-0} (x - 0)$$

$$y = x$$

$$dy = dx$$



$$\int_C \vec{F} \cdot d\vec{r}$$

$$= \int_C y^2 dx + x^2 dy$$

$$= \int_0^1 x^2 dx + x^2 dx$$

$$= 2 \left[ \frac{x^3}{3} \right]_0^1$$

$$= \frac{2}{3}$$

again

for st. line joining  $(1,0)$  to  $(1,1)$

Equation of st. line

$$y = 0, y = 1$$

$$y - 0 = \frac{1-0}{1-1} (x - 1)$$

$$y = 0$$

$$x = 1$$



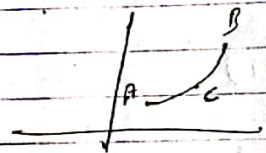
## # Theorem (Line Integration independent of path)

The line integral  $\int_C \vec{F} \cdot d\vec{r}$  is independent of path if  $\vec{F}$  is a continuous function  $\Rightarrow \vec{F} = \nabla \phi$  for some scalar value function  $\phi$ .

Proof

Suppose,  $\vec{F} = \nabla \phi$  for some scalar value function  $\phi$ .  
Our claim;  $\int_C \vec{F} \cdot d\vec{r}$  is independent of path  $C$ .

Let  $C$  be the path joining  $A$  &  $B$ .



$$\text{Now } \int_C \vec{F} \cdot d\vec{r} = \int_C \nabla \phi \cdot d(\vec{i}x + \vec{j}y + \vec{k}z)$$

$$= \int_C \left( \frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k} \right) \cdot \left( \vec{i}dx + \vec{j}dy + \vec{k}dz \right)$$

$$= \int_C \left( \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right)$$

$$\phi = \phi(x, y, z)$$

$$= \int_C d\phi$$

$$= \int_A^B d\phi$$

$$= [\phi]_A^B$$

$$= \phi(B) - \phi(A)$$

This shows that  $\int_C \vec{F} \cdot d\vec{r}$  depends only on initial point  $A$  & final point  $B$ , not the path.

## # Irrotational Vector

A vector function  $\vec{F}$  is called irrotational if  $\nabla \times \vec{F} = \vec{0}$ .

Ex: The vector  $\vec{F} = (x^2 - yz)\vec{i} + (y^2 - zx)\vec{j} + (z^2 - xy)\vec{k}$

irrotational?

Soln

$$\nabla \times \vec{F} = \left( \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \times \left( (x^2 - yz)\vec{i} + (y^2 - zx)\vec{j} + (z^2 - xy)\vec{k} \right)$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (x^2 - yz) & (y^2 - zx) & (z^2 - xy) \end{vmatrix}$$



$$\begin{aligned}
 &= \vec{i} \left[ \frac{\partial}{\partial y} (z^2 - xy) - \frac{\partial}{\partial z} (y^2 - 2xz) \right] \\
 &\quad - \vec{j} \left[ \frac{\partial}{\partial x} (z^2 - xy) - \frac{\partial}{\partial z} (x^2 - yz) \right] \\
 &\quad + \vec{k} \left[ \frac{\partial}{\partial x} (y^2 - 2xz) - \frac{\partial}{\partial y} (x^2 - yz) \right] \\
 &= \vec{i} [(0-2) - (0-2)] - \vec{j} [(0-y) - (0-y)] \\
 &\quad + \vec{k} [(0-2) - (0-2)] \\
 &= \vec{0}
 \end{aligned}$$

Q In the above example  
 $\vec{F} = (x^2 - yz)\vec{i} + (y^2 - 2xz)\vec{j} + (z^2 - xy)\vec{k}$   
 show that  $\int_C \vec{F} \cdot d\vec{r}$  is independent of path.  
 soln

We show that  $\vec{F} = \nabla \phi$  for some scalar valued function  $\phi$ .

now,  $\vec{F} = \nabla \phi$

$$\begin{aligned}
 \text{or, } (x^2 - yz)\vec{i} + (y^2 - 2xz)\vec{j} + (z^2 - xy)\vec{k} &= \vec{i} \frac{\partial \phi}{\partial x} + \vec{j} \frac{\partial \phi}{\partial y} + \vec{k} \frac{\partial \phi}{\partial z}
 \end{aligned}$$

on equating the corresponding component.

$$\frac{\partial \phi}{\partial x} = x^2 - yz, \quad \frac{\partial \phi}{\partial y} = y^2 - 2xz, \quad \frac{\partial \phi}{\partial z} = z^2 - xy$$

now

$$\phi = \frac{x^3}{3} - xyz + \frac{y^3}{3} - 2yzx + \frac{z^3}{3} - 2xyz + c$$

$\therefore$  required function

$$\phi = \frac{x^3}{3} + \frac{y^3}{3} + \frac{z^3}{3} - 3xyz + c$$

Formula

If  $x = x(t)$ ,  $y = y(t)$ ,  $z = z(t)$  then,

$$\int_C \vec{F} \cdot d\vec{r} = \int_C (F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k}) \cdot (\vec{i} dx + \vec{j} dy + \vec{k} dz)$$

$$= \int_C (F_1 dx + F_2 dy + F_3 dz)$$

$$= \int_a^b \left( F_1 \frac{dx}{dt} + F_2 \frac{dy}{dt} + F_3 \frac{dz}{dt} \right) dt$$



Q) Evaluate  $\int \vec{F} \cdot d\vec{r}$

where,  $\vec{F} = yz\vec{i} + 2x\vec{j} + 2y\vec{k}$   
 $\vec{r} = a \cos t \vec{i} + b \sin t \vec{j} + e^t \vec{k}$   
 from  $t=0$  to  $t = \pi/2$

Soln

Here,  $F_1 = yz$ ,  $F_2 = 2x$ ,  $F_3 = 2y$

$x = a \cos t$ ,  $y = b \sin t$ ,  $z = e^t$

now  $\frac{dx}{dt} = -a \sin t$ ,  $\frac{dy}{dt} = b \cos t$ ,  $\frac{dz}{dt} = e^t$

now

$\int \vec{F} \cdot d\vec{r}$

$= \int_0^{\pi/2} [(b \sin t \cdot e^t (-a \sin t) + (e^t \cdot a \cos t) b \cos t + (a \cos t \cdot b \sin t) e^t] dt$

$= \int_0^{\pi/2} [-ab e^t \sin^2 t + ab e^t \cos^2 t + 2ab e^t \sin t \cos t] dt$

$= ab \int_0^{\pi/2} [e^t \cos^2 t + \frac{1}{2} e^t \sin 2t] dt$

= 0

Q) Evaluate:  $\int \vec{F} \times d\vec{r}$

where,  $\vec{F} = xy\vec{i} - 2\vec{j} + x^2\vec{k}$

$C$  is the curve

$x = t^2$ ,  $y = 2t$ ,  $z = t^3$   
 from  $t=0$  to  $t=1$

Soln

$\vec{r} = t^2\vec{i} + 2t\vec{j} + t^3\vec{k}$

$d\vec{r} = (2t\vec{i} + 2\vec{j} + 3t^2\vec{k}) dt$

now

$\vec{F} \times d\vec{r} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ xy & -2 & x^2 \\ 2t & 2 & 3t^2 \end{vmatrix}$

$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2t^3 & -2 & t^4 \\ 2t \cdot dt & 2 \cdot dt & 3t^2 \cdot dt \end{vmatrix}$

$= \vec{i} (-3t^5 \cdot dt - 2t^4 \cdot dt) - \vec{j} (6t^5 \cdot dt - 2t^5 \cdot dt) + \vec{k} (4t^3 \cdot dt + 2t^4 \cdot dt)$

$= \vec{i} (-3t^5 - 2t^4) dt - \vec{j} (4t^5 \cdot dt) + \vec{k} (4t^3 + 2t^4) dt$



$$= \int_C \vec{F} \cdot d\vec{r}$$

$$= \int_0^1 \left( \left( -\frac{3t^6}{6} - \frac{2t^5}{5} \right) \vec{i} + \left( \frac{4t^6}{6} \right) \vec{j} + \left( \frac{4t^4}{4} - \frac{2t^5}{5} \right) \vec{k} \right) dt$$

$$= \left( -\frac{3t^6}{6} - \frac{2t^5}{5} \right) \vec{i} + \left( \frac{4t^6}{6} \right) \vec{j} + \left( \frac{4t^4}{4} - \frac{2t^5}{5} \right) \vec{k}$$

$$= \frac{-9}{10} \vec{i} - \frac{2}{3} \vec{j} + \frac{7}{5} \vec{k}$$

Ex Evaluate

$\int_C \phi d\vec{r}$  where

$\phi = 2xyz^2$  &  $C$  is the curve

$x = t^2, y = 2t, z = t$   
from  $t=0$  to  $t=1$

ans:  $\frac{8}{11} \vec{i} + \frac{4}{5} \vec{j} + \vec{k}$

## # Divergence & Curve

Let  $\vec{V} = F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k}$   
where,

$F_1, F_2, F_3$  are the function of  $x, y, z$ .

Here,  $\vec{F}$  is called vector function of scalar variable  $x, y, z$ .

Then, the divergence of  $\vec{F}$  is denoted by  $\nabla \cdot \vec{F}$  and is defined by

$$\nabla \cdot \vec{F} = \left( \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \cdot (F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k})$$

$$= \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

$$= \sum \frac{\partial F_i}{\partial x_i} \quad i=1,2,3, \quad x \text{ varies } x, y, z$$

which is scalar point function.

Here,  $\nabla$  (nabla) is called vector differential operator.

## # Curl of vector function

same

Then the curl of  $\vec{F}$  is denoted by  $\nabla \times \vec{F}$  and is defined by