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(https://colab.research.google.com/github/AnkurMali/IST597 Spring 2022/blob/main/IST597 Building CNN.ipynb)

# In [13]:

```
import tensorflow as tf
import numpy as np
import matplotlib.pyplot as plt

np.random.seed(5436)
```

### In [14]:

```
(x train, y train), (x test, y test) = tf.keras.datasets.fashion mnist.load data()
x \text{ val} = x \text{ train}[50000:60000]
x train = x train[0:50000]
y_val = y_train[50000:60000]
y train = y train[0:50000]
x train = x train.astype(np.float32).reshape(-1,28,28,1) / 255.0
x \text{ val} = x \text{ val.astype(np.float32).reshape(-1,28,28,1)} / 255.0
x_{test} = x_{test.astype(np.float32).reshape(-1,28,28,1) / 255.0
y train = tf.one hot(y train, depth=10)
y_val = tf.one_hot(y_val, depth=10)
y test = tf.one hot(y test, depth=10)
print(x train.shape)
print(x_test.shape)
print(x val.shape)
train_dataset = tf.data.Dataset.from_tensor_slices((x_train, y_train))
train dataset = train dataset.shuffle(buffer size=1024).batch(128)
train dataset full = train dataset.shuffle(buffer size=1024).batch(len(train_datas
et))
val dataset = tf.data.Dataset.from tensor slices((x val, y val))
val dataset = val dataset.batch(128)
test dataset = tf.data.Dataset.from tensor slices((x test, y test))
test dataset = test dataset.batch(128)
print(len(train dataset))
print(len(test dataset))
```

```
(50000, 28, 28, 1)
(10000, 28, 28, 1)
(10000, 28, 28, 1)
391
79
```

## In [15]:

```
class BatchNormalization(tf.keras.layers.Layer):
    def __init__(self, batch_size, training=False):
        super(BatchNormalization, self).__init__()
        self.convexCoeff = 0.9
        self.numCalls = 0
        self.batch size = batch size
        self.training = training
        self.gamma = self.add weight(name='gamma', shape=[self.batch size,], initi
alizer=tf.initializers.ones, trainable=True)
        self.beta = self.add weight(name='beta', shape=[self.batch size,], initi
alizer=tf.initializers.zeros, trainable=True)
        self.mean = self.add weight(name='mean', shape=[self.batch size,], initi
alizer=tf.initializers.zeros, trainable=False)
        self.var = self.add weight(name='var',
                                                     shape=[self.batch size,], initi
alizer=tf.initializers.zeros, trainable=False)
    def batch norm(self, inputs, training):
        self.numCalls += 1
        axes = list(range(len(inputs.shape) - 1))
        mean = tf.reduce mean(inputs, axes, keepdims=True)
        var = tf.reduce mean(tf.math.squared difference(inputs, tf.stop gradient(
mean)), axes, keepdims=True)
        if training:
            norm = tf.add(tf.multiply(self.gamma, tf.divide(tf.subtract(inputs, me
an), tf.sqrt(var+le-7))), self.beta)
            mean = tf.squeeze(mean, axes)
            var = tf.squeeze(var, axes)
            moving_avg_mean = ((self.convexCoeff/self.numCalls)*mean) + (1-(self.c
onvexCoeff/self.numCalls)*self.mean)
            moving avg var = ((self.convexCoeff/self.numCalls)*var) + (1-(self.convexCoeff/self.numCalls)*var) + (1-(self.convexCoeff/self.numCalls)*var)
onvexCoeff/self.numCalls)*self.var)
            self.mean.assign(moving avg mean)
            self.var.assign(moving avg var)
        else:
            norm = tf.add(tf.multiply(self.gamma, tf.divide(tf.subtract(inputs, me
an), tf.sqrt(var+1e-7))), self.beta)
        return norm
```

#### In [16]:

```
class ImageRecognitionCNN(tf.keras.Model):
    def __init__(self, num_classes, device='cpu:0', checkpoint_directory=None):
           Define the parameterized layers used during forward-pass, the device
            where you would like to run the computation (GPU, TPU, CPU) on and the
checkpoint
            directory.
            Args:
                num_classes: the number of labels in the network.
                device: string, 'cpu:n' or 'gpu:n' (n can vary). Default, 'cpu:0'.
                checkpoint directory: the directory where you would like to save o
r
                                      restore a model.
        1.1.1
        super(ImageRecognitionCNN, self). init ()
        # Initialize layers
        self.conv1 = tf.keras.layers.Conv2D(64, 3, padding='same', activation=None
)
        self.conv2 = tf.keras.layers.Conv2D(64, 3,padding='same', activation=None)
        self.pool1 = tf.keras.layers.MaxPool2D()
        self.conv3 = tf.keras.layers.Conv2D(64, 3, padding='same', activation=None
)
        self.conv4 = tf.keras.layers.Conv2D(64, 3, padding='same', activation=None
)
        # self.pool2 = tf.keras.layers.MaxPool2D()
        # self.conv5 = tf.keras.layers.Conv2D(64, 3, padding='same', activation=No
ne)
        # self.pool2 = tf.keras.layers.MaxPool2D()
        # self.conv6 = tf.keras.layers.Conv2D(64, 3, 2, padding='same', activation
=None)
        # self.conv7 = tf.keras.layers.Conv2D(64, 1, padding='same', activation=No
ne)
        self.conv8 = tf.keras.layers.Conv2D(num classes, 1, padding='same', activa
tion=None)
        self.BN = BatchNormalization(64)
        # Define the device
        self.device = device
        # Define the checkpoint directory
        self.checkpoint directory = checkpoint directory
        self.acc = tf.keras.metrics.Accuracy()
    def predict(self, images, training):
        """ Predicts the probability of each class, based on the input sample.
            Args:
                images: 4D tensor. Either an image or a batch of images.
                training: Boolean. Either the network is predicting in
                          training mode or not.
```

```
x = self.conv1(images)
        x = tf.nn.relu(x)
        x = self.BN.batch_norm(x, training)
        x = self.pool1(x)
        x = self.conv2(x)
        x = tf.nn.relu(x)
        x = self.BN.batch norm(x, training)
        x = self.pool1(x)
        x = self.conv3(x)
        x = tf.nn.relu(x)
        x = self.BN.batch_norm(x, training)
        x = self.pool1(x)
        x = self.conv4(x)
        x = tf.nn.relu(x)
        x = self.BN.batch norm(x, training)
        x = self.pool1(x)
        x = self.conv8(x)
        \#x = tf.nn.relu(x)
        #print(x.shape)
        x = tf.reshape(x, (-1, 1, 10))
        \#x = tf.keras.layers.Flatten(x)
        return x
    def loss fn(self, images, target, training):
        """ Defines the loss function used during
            training.
        preds = self.predict(images, training)
        #print(preds.shape)
        #print(target.shape)
        loss = tf.nn.softmax cross entropy with logits(labels=target, logits=preds
)
        return loss
    def grads fn(self, images, target, training):
           Dynamically computes the gradients of the loss value
            with respect to the parameters of the model, in each
            forward pass.
        with tf.GradientTape() as tape:
            loss = self.loss fn(images, target, training)
        return tape.gradient(loss, self.variables)
    def restore model(self):
        """ Function to restore trained model.
        with tf.device(self.device):
            # Run the model once to initialize variables
            dummy input = tf.constant(tf.zeros((1,48,48,1)))
            dummy_pred = self.predict(dummy_input, training=False)
            # Restore the variables of the model
```

```
saver = tf.Saver(self.variables)
        saver.restore(tf.train.latest checkpoint
                      (self.checkpoint directory))
def save_model(self, global_step=0):
    """ Function to save trained model.
    tf.Saver(self.variables).save(self.checkpoint directory,
                                   global step=global step)
# def compute_accuracy(self, input_data):
      """ Compute the accuracy on the input data.
#
#
#
     with tf.device(self.device):
          #acc = tf.metrics.Accuracy()
          for step ,(images, targets) in enumerate(input data):
#
              # Predict the probability of each class
              #print(targets.shape)
#
#
              logits = self.predict(images, training=False)
#
              # Select the class with the highest probability
#
              #print(logits.shape)
              logits = tf.nn.softmax(logits)
#
#
              logits = tf.reshape(logits, [-1, 10])
              targets = tf.reshape(targets, [-1,10])
#
              preds = tf.argmax(logits, axis=1)
#
              #ml.update state
#
#
              # Compute the accuracy
#
              #print(preds.shape)
              acc(tf.reshape(targets, preds))
      return acc
def compute accuracy 2(self, images, targets, training=False):
    """ Compute the accuracy on the input data.
    with tf.device(self.device):
        # Predict the probability of each class
        logits = self.predict(images, training)
        # Select the class with the highest probability
        logits = tf.nn.softmax(logits)
        logits = tf.reshape(logits, [-1, 10])
        targets = tf.reshape(targets, [-1,10])
        preds = tf.argmax(logits, axis=1)
        goal = tf.argmax(targets, axis=1)
        self.acc.update state(goal, preds)
        # Compute the accuracy
        result = self.acc.result().numpy()
    return result
def fit fc(self, training data, eval data, optimizer, num epochs=500,
        early stopping rounds=10, verbose=10, train from scratch=False):
    """ Function to train the model, using the selected optimizer and
        for the desired number of epochs. You can either train from scratch
```

```
or load the latest model trained. Early stopping is used in order to
            mitigate the risk of overfitting the network.
            Args:
                training_data: the data you would like to train the model on.
                                Must be in the tf.data.Dataset format.
                eval data: the data you would like to evaluate the model on.
                            Must be in the tf.data.Dataset format.
                optimizer: the optimizer used during training.
                num_epochs: the maximum number of iterations you would like to
                            train the model.
                early stopping rounds: stop training if the loss on the eval
                                       dataset does not decrease after n epochs.
                verbose: int. Specify how often to print the loss value of the net
work.
                train from scratch: boolean. Whether to initialize variables of th
e
                                    the last trained model or initialize them
                                    randomly.
        0.00
        if train from scratch==False:
            self.restore model()
        # Initialize best loss. This variable will store the lowest loss on the
        # eval dataset.
        best loss = 999
        # Initialize classes to update the mean loss of train and eval
        train loss = tf.keras.metrics.Mean('train loss')
        eval loss = tf.keras.metrics.Mean('eval loss')
        acc train = tf.keras.metrics.Mean('train acc')
        acc val = tf.keras.metrics.Mean('val acc')
        # Initialize dictionary to store the loss history
        self.history = {}
        self.history['train loss'] = []
        self.history['eval loss'] = []
        self.history['train acc'] = []
        self.history['val acc'] = []
        # Begin training
        with tf.device(self.device):
            for i in range(num epochs):
                # Training with gradient descent
                #training data x = training data.shuffle(buffer size=1024).batch(1)
28)
                for step, (images, target) in enumerate(training data):
                    grads = self.grads_fn(images, target, True)
                    optimizer.apply_gradients(zip(grads, self.variables))
                # Compute the loss on the training data after one epoch
                for step, (images, target) in enumerate(training_data):
                    loss = self.loss fn(images, target, False)
                    accuracy = self.compute accuracy 2(images, target)
                    acc train(accuracy)
```

```
train loss(loss)
                self.history['train loss'].append(train loss.result().numpy())
                self.history['train acc'].append(acc train.result().numpy())
                # Reset metrics
                train_loss.reset_states()
                acc train.reset states()
                # Compute the loss on the eval data after one epoch
                for step, (images, target) in enumerate(eval data):
                    loss = self.loss fn(images, target, False)
                    accuracy = self.compute accuracy_2(images, target)
                    acc val(accuracy)
                    eval loss(loss)
                self.history['eval_loss'].append(eval_loss.result().numpy())
                self.history['val acc'].append(acc val.result().numpy())
                # Reset metrics
                eval loss.reset states()
                acc val.reset states()
                # Print train and eval losses
                if (i==0) | ((i+1)%verbose==0):
                    print('Train loss at epoch %d: ' %(i+1), self.history['train l
oss'][-1])
                    print('Train Acc at epoch %d: ' %(i+1), self.history['train ac
c'][-1])
                    print('Eval loss at epoch %d: ' %(i+1), self.history['eval los
s'][-1])
                    print('Eval Acc at epoch %d: ' %(i+1), self.history['val acc']
[-1])
                # Check for early stopping
                if self.history['eval loss'][-1]<best loss:</pre>
                    best loss = self.history['eval loss'][-1]
                    count = early stopping rounds
                else:
                    count -= 1
                if count==0:
                    break
```

### In [17]:

## In [18]:

Train loss at epoch 1: 0.39473918 Train Acc at epoch 1: 0.8569706 Eval loss at epoch 1: 0.42880878 Eval Acc at epoch 1: 0.85936445 Train loss at epoch 2: 0.3098746 Train Acc at epoch 2: 0.8664856 Eval loss at epoch 2: 0.36494917 Eval Acc at epoch 2: 0.8729166 Train loss at epoch 4: 0.23083213 Train Acc at epoch 4: 0.88663375 Eval loss at epoch 4: 0.31804806 Eval Acc at epoch 4: 0.890514 Train loss at epoch 6: 0.19120531 Train Acc at epoch 6: 0.89926225 Eval loss at epoch 6: 0.3109435 Eval Acc at epoch 6: 0.90184706

## In [ ]: