

Supplementary Materials

A Unified and Fast Explainable Model for Predictive Analytics

1 Proofs of Lemmas

Lemma 1. FXAM's normal equations satisfy stationarity conditions of \mathcal{L} .

Proof. According to equation (20) in [29], we equivalently need to prove that normal equations should satisfy the bellowing criteria (here M^- denote generalized inverse satisfying $MM^-M = M$):

$$\mathcal{L} = \left\| y - \sum_{j=1}^p f_j - f_z - f_T - f_s \right\|^2 + \sum_{j=1}^p f_j^T (M_j^- - I) f_j + f_z^T (M_z^- - I) f_z + f_T^T (M_T^- - I) f_T + f_s^T (M_s^- - I) f_s$$

Recall that $M_j = (I + \lambda K_j)^{-1}$ implies M_j is invertible, so $M_j^- = I + \lambda K_j \Rightarrow f_j^T (M_j^- - I) f_j = \lambda f_j^T K_j f_j$. Same deduction for M_T .

Re-write $M_z = ZAZ^T$ where $A = (Z^T Z + \lambda_z I)^{-1}$ which is a $Q \times Q$ symmetric and invertible matrix. and because $M_z M_z^- M_z = M_z$, expanding it we get $ZAXA^T Z^T = ZAZ^T$ where $X = Z^T S_z^- Z$. Then we get to know $X = A^{-1} + H$, where H is some matrix satisfying $ZAH A^T Z^T = 0$. Recall that $f_z = Z\beta$, thus $f_z^T (M_z^- - I) f_z = \beta^T X \beta - \beta^T Z^T Z \beta = \beta^T (A^{-1} + H - Z^T Z) \beta = \beta^T (\lambda_z I + H) \beta = \lambda_z \beta^T \beta$. The last equality holds because $\beta = AZ^T \tilde{y}$ according to normal equations, thus $\beta^T H \beta = \tilde{y}^T ZAH A^T Z^T \tilde{y} = 0$.

Because permutation matrix P is orthogonal matrix, thus $M_s^- = P^T \begin{bmatrix} I + \lambda_s K'_{S_0} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & I + \lambda_s K'_{S_{d-1}} \end{bmatrix} P = I + \lambda_s P^T \begin{bmatrix} K'_{S_0} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & K'_{S_{d-1}} \end{bmatrix} P$, and considering K'_{S_φ} is a $|\mathcal{T}_\varphi| \times |\mathcal{T}_\varphi|$ matrix only applies to phase- φ data points, thus it is easy to see $f_s^T (M_s^- - I) f_s = \lambda_s \sum_{\varphi=0}^{d-1} f_{S_\varphi}^T K'_{S_\varphi} f_{S_\varphi}$. ■

Theorem 1. Solutions of FXAM's normal equations exists and are global optimal.

Proof. According to theorem 2 of [29], the normal equations exists and are global optimal if each smoothing matrix M_j, M_z, M_T , or M_s is symmetric and shrinking (i.e., with eigenvalues in $[0,1]$). Thus we check M_j, M_z, M_T , and M_s one by one:

M_j, M_T are indeed symmetric and shrinking according to standard analysis of cubic spline smoothing matrix.

Re-write $M_z = ZAZ^T$ where $A = (Z^T Z + \lambda_z I)^{-1}$. It is easy to see that A is a symmetric matrix thus $M_z^T = (Z^T)^T A^T Z^T = ZAZ^T = M_z$.

Denote singular value decomposition of Z is $Z = UDV^T$, where U and V are orthogonal matrices, D is a $Q \times Q$ diagonal matrix, with diagonal entries $d_{11} \geq \cdots \geq d_{QQ} \geq 0$. Thus we have

$M_Z y = Z(Z^T Z + \lambda I)^{-1} Z^T y = UDV^T (VD^2 V^T + \lambda I)^{-1} VDU^T y = UDV^T (VD^2 V^T + \lambda VIV^T)^{-1} VDU^T y = UDV^T V(D^2 + \lambda I)^{-1} V^{-1} VDU^T y = UD(D^2 + \lambda I)^{-1} DU^T y = \sum_{j=1}^Q u_j \frac{d_j^2}{d_j^2 + \lambda} u_j^T y$, thus the eigenvalues $\frac{d_j^2}{d_j^2 + \lambda}$ are in $[0, 1]$ considering $\lambda > 0$.

Re-write $M_S = P^T \Theta P$. Since each K'_{S_ϕ} is a symmetric matrix, thus $(I + \lambda_S K'_{S_\phi})^{-1}$ is symmetric and Θ is symmetric, thus M_S is symmetric. Due to the shrinking property of $(I + \lambda_S K'_{S_\phi})^{-1}$, and considering Θ is a block-diagonal matrix with $(I + \lambda_S K'_{S_\phi})^{-1}$ as its blocks, thus Θ is also shrinking: $\|\Theta y\|^2 \leq \|y\|^2 \forall y$. So $\|M_S y\|^2 = y^T M_S^T M_S y = y^T P^T \Theta^T \Theta P y = \|\Theta P y\|^2 \leq \|P y\|^2 = \|y\|^2$, thus M_S is shrinking. ■

Theorem 2. TSI algorithm converges to a solution of FXAM's normal equations.

Proof. Denote the index set $I := \{1, 2, \dots, p, Z, T, S\}$. We only need to prove that TSI converges to a solution of FXAM's homogenous equations (i.e., FXAM's normal equations with $y = 0$), because a general solution is a solution of homogenous equations plus an arbitrary solution of FXAM's normal equations. Denote the loss function of homogenous equations as $\mathcal{L}_0(f) := \|\sum_{j \in I} f_j\|^2 + \sum_{j \in I} f_j^T (M_j^- - I) f_j$.

We define a linear map T_j to describe the updating of j th component in TSI when $y = 0$:

$$T_j: \begin{bmatrix} f_1 \\ \vdots \\ f_p \\ f_z \\ f_T \\ f_S \end{bmatrix} \equiv f \rightarrow \begin{bmatrix} f_1 \\ \vdots \\ -M_j \sum_{i \in I, i \neq j} f_i \\ f_z \\ f_T \\ f_S \end{bmatrix}, \forall j \in I$$

A full cycle of backfitting over numerical features is then described by $K = T_p T_{p-1} \dots T_1$. Denote the m full cycles as K^m . It is obvious that K^m converges to a limit K^∞ (we can view this as a standard task of backfitting over pure numerical features) therefore with property $KK^\infty = K^\infty$. Note that K^∞ describes the procedure of stage 1, thus the full cycle of entire TSI is $\mathcal{K} = T_S T_T T_Z K^\infty$. Since each component of \mathcal{K} is minimizer of $\mathcal{L}_0(f)$ and since \mathcal{L}_0 is a quadratic form, hence $\mathcal{L}_0(\mathcal{K}f) \leq \mathcal{L}_0(f)$. When $\mathcal{L}_0(\mathcal{K}f) = \mathcal{L}_0(f)$, no strict descent is possible on any component, thus $T_S f = f, T_T f = f, T_Z f = f, K^\infty f = f$. Considering $KK^\infty = K^\infty$, thus $KK^\infty f = K^\infty f \Leftrightarrow Kf = f$ when descent vanishes. Since each component T_j of K only updates separate f_j , thus $Kf = f \Leftrightarrow T_j f = f \forall j \in \{1, \dots, p\}$. So descent vanishes on any f equivalent to $T_j f = f \forall j \in I$. Meanwhile, such f satisfies homogenous equations, which indicates $\mathcal{L}_0(f) = 0$ according to theorem 5 in [29]. In summary, we have a linear mapping \mathcal{K} satisfying $\mathcal{L}_0(\mathcal{K}f) < \mathcal{L}_0(f)$ when $\mathcal{L}_0(f) > 0$ and $\mathcal{K}f = f$ when $\mathcal{L}_0(f) = 0$. According to theorem 8 of [29], \mathcal{K}^m converges to \mathcal{K}^∞ . ■

Lemma 2. $LOSS = \sum_{i=1}^n (f(x_i) - y_i)^2 \leq n((2LBh)^2 + 2\sigma^2)$ where B is the bounded support of kernel K_h .

Proof. $\sum_{i=1}^n (f(x_i) - y_i)^2 = \sum_{i=1}^n \left(\frac{\sum_{j=1}^n (y_j - y_i) K_h(x_i - x_j)}{\sum_{j=1}^n K_h(x_i - x_j)} \right)^2 \leq \sum_{i=1}^n \frac{\sum_{j=1}^n (y_j - y_i)^2 K_h(x_i - x_j)}{\sum_{j=1}^n K_h(x_i - x_j)}$ (Jensen's inequality). Considering item $(y_j - y_i)^2 K_h(x_i - x_j)$: Since K_h is bounded with B , $(y_j - y_i)^2 K_h(x_i - x_j)$ only accounts for x_i such that $x_i \in B(x_j)$. Denote the indexes of all the data points within $B(x_j)$ are $\{q_1, \dots, q_k\}$, denote $u \in \{1 \sim k\}, v \in \{1 \sim k\}$ such that $y_{q_u} \leq y_{q_i} \forall i \neq u; y_{q_v} \geq y_{q_i} \forall i \neq v$, then $y_{q_u} \leq f(x) = \frac{\sum_{j=1}^n y_j K_h(x - x_j)}{\sum_{j=1}^n K_h(x - x_j)} = \frac{\sum_{j=1}^k y_{q_j} K_h(x - x_{q_j})}{\sum_{j=1}^k K_h(x - x_{q_j})} \leq y_{q_v}$, hence $(y_j - y_i)^2 K_h(x_i - x_j) \leq (y_{q_v} - y_{q_u})^2 K_h(x_i - x_j)$. Considering y_{q_v} is a sample drawn from $Y_{q_v} = F(x_{q_v}) + \epsilon_{q_v}$, and y_{q_u} is a sample drawn from $Y_{q_u} = F(x_{q_u}) + \epsilon_{q_u}$, we get to know that $E(Y_{q_v} - Y_{q_u})^2 = E(F(x_{q_v}) - F(x_{q_u}) + \epsilon_{q_v} - \epsilon_{q_u})^2 = E(F(x_{q_v}) - F(x_{q_u}))^2 + E(\epsilon_{q_v} - \epsilon_{q_u})^2 \leq (2LBh)^2 + 2\sigma^2$. Then approximately, we write $(y_{q_v} - y_{q_u})^2 \lesssim (2LBh)^2 + 2\sigma^2$ which leads to $LOSS = \sum_{i=1}^n (f(x_i) - y_i)^2 \leq n((2LBh)^2 + 2\sigma^2)$. ■

Lemma 3. $E\|f_n - f_s\|^2 \leq 4c \left(\frac{(\sigma^2 + \sup|F|^2)L}{s} \right)^{\frac{2}{3}}$

Proof. $E\|f_n - f_s\|^2 = \int (f_n(x) - f_s(x))^2 \mu(dx) = \int (f_n(x) - F(x) + F(x) - f_s(x))^2 \mu(dx) \leq \int (f_n(x) - F(x) + F(x) - f_s(x))^2 \mu(dx) + \int (f_n(x) - F(x) - F(x) + f_s(x))^2 \mu(dx) = 2(E\|f_n - F\|^2 + E\|f_s - F\|^2) \leq 4E\|f_s - F\|^2 = 4c \left(\frac{(\sigma^2 + \sup|F|^2)L}{s} \right)^{\frac{2}{3}}$. ■