

sensor
(controller, lane)

This controls the removal
of cars from the releant
lane
of traffic

Example function call

northController, northLane

sensor

lights are broken

True

False

More cars in the lane

True

Both lights are green or orange

True

False

Right turning light is green or orange

True

False

Other light is green or orange

True

False

False

No cars go

Remove next car in lane

Remove next car going right in said lane

Remove next car going straight
or left in said lane

Return