

BrokenCycle  
(self)

Cycles through turning all  
lights blinking orange  
to signify broken lights in  
accordance with NZ road  
rules

Turn all lights off

Wait self.INTERVAL divide 3

Turn all lights off

Turn lights to orange

Wait self.INTERVAL divide 3

Turn all lights off

Wait self.INTERVAL divide 3

Turn all lights off

Turn lights to orange

Wait self.INTERVAL divide 3

Turn all lights off

Wait self.INTERVAL divide 3

Turn all lights off

Turn lights to orange

Wait self.INTERVAL divide 3

Turn lights to red

Return

Example call  
northController.BrokenCycle()

BrokenCycle

IncrementAllWaits

Is used to add 1 to the wait times for every light

Example function call

northController.IncrementRightWait()

IncrementAllWaits

northController.IncrementOtherWait()

eastController.IncrementRightWait()

eastController.IncrementOtherWait()

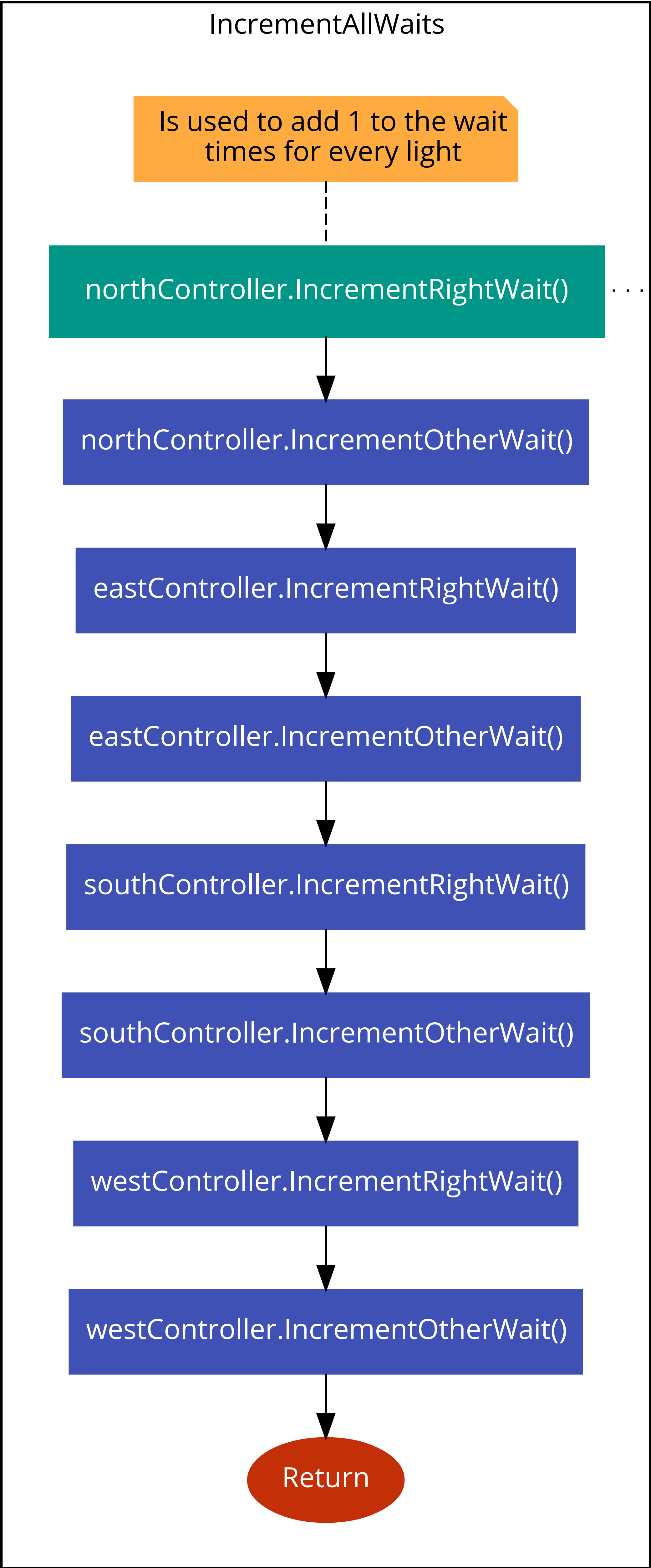
southController.IncrementRightWait()

southController.IncrementOtherWait()

westController.IncrementRightWait()

westController.IncrementOtherWait()

Return



OtherCycle  
(self)

Cycles through turning all  
other lights on then off  
Leaving right lights off

Turn all lights off

Turn right light to red  
Turn other light to green

Wait self.INTERVAL

Turn all lights off

Turn right light to red  
Turn other light to orange

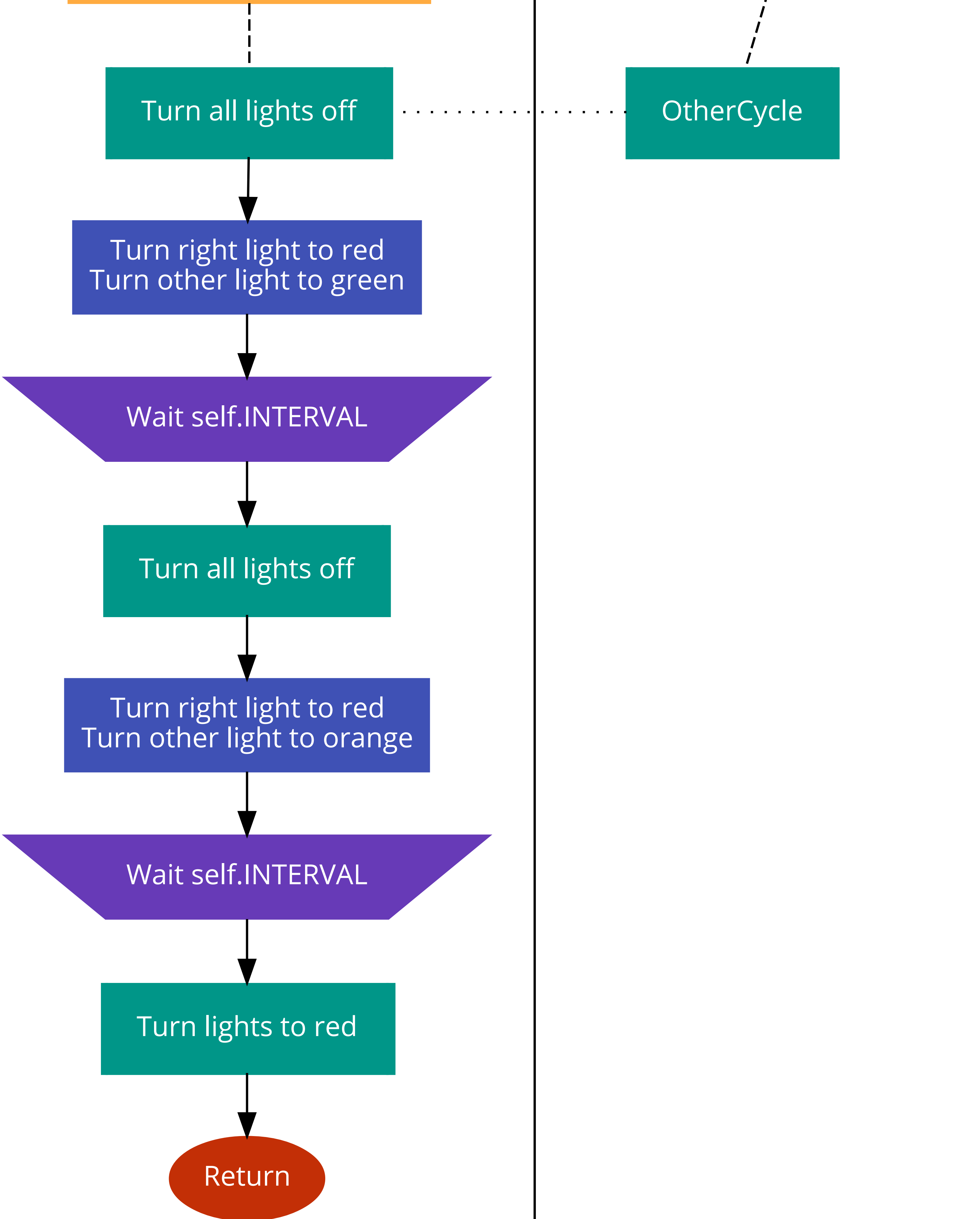
Wait self.INTERVAL

Turn lights to red

Return

Example call  
northController.OtherCycle()

OtherCycle



ResetAllWaits

Is used to reset the wait times for every light

northController.ResetRightWait()

northController.ResetOtherWait()

eastController.ResetRightWait()

eastController.ResetRightWait()

southController.ResetRightWait()

southController.ResetOtherWait()

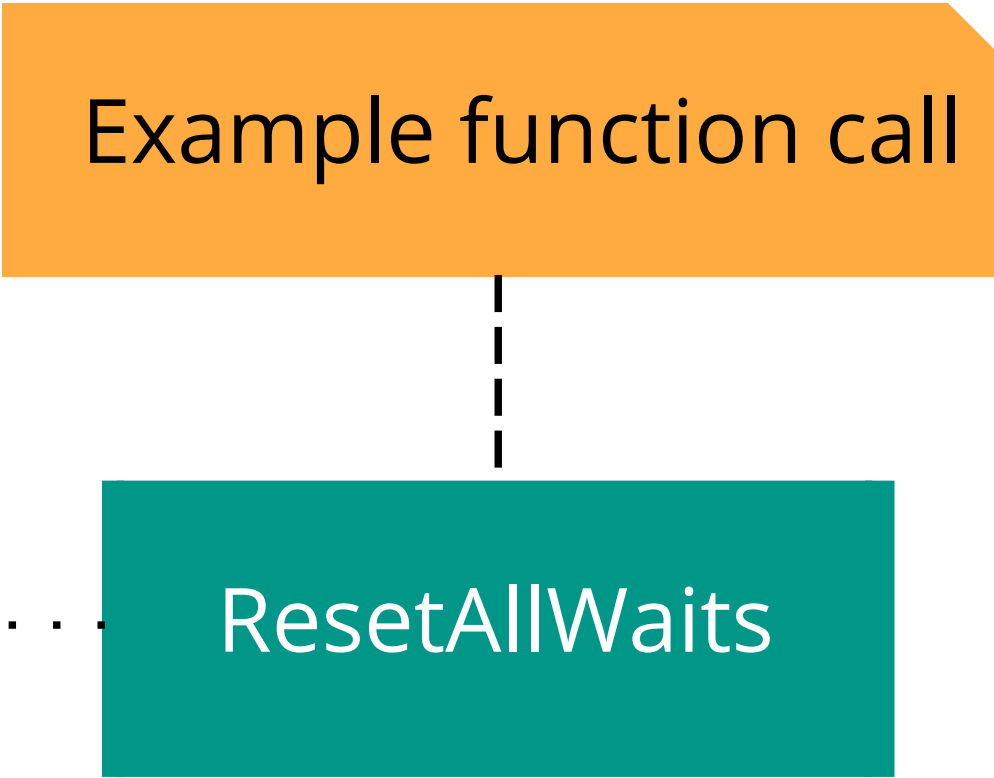
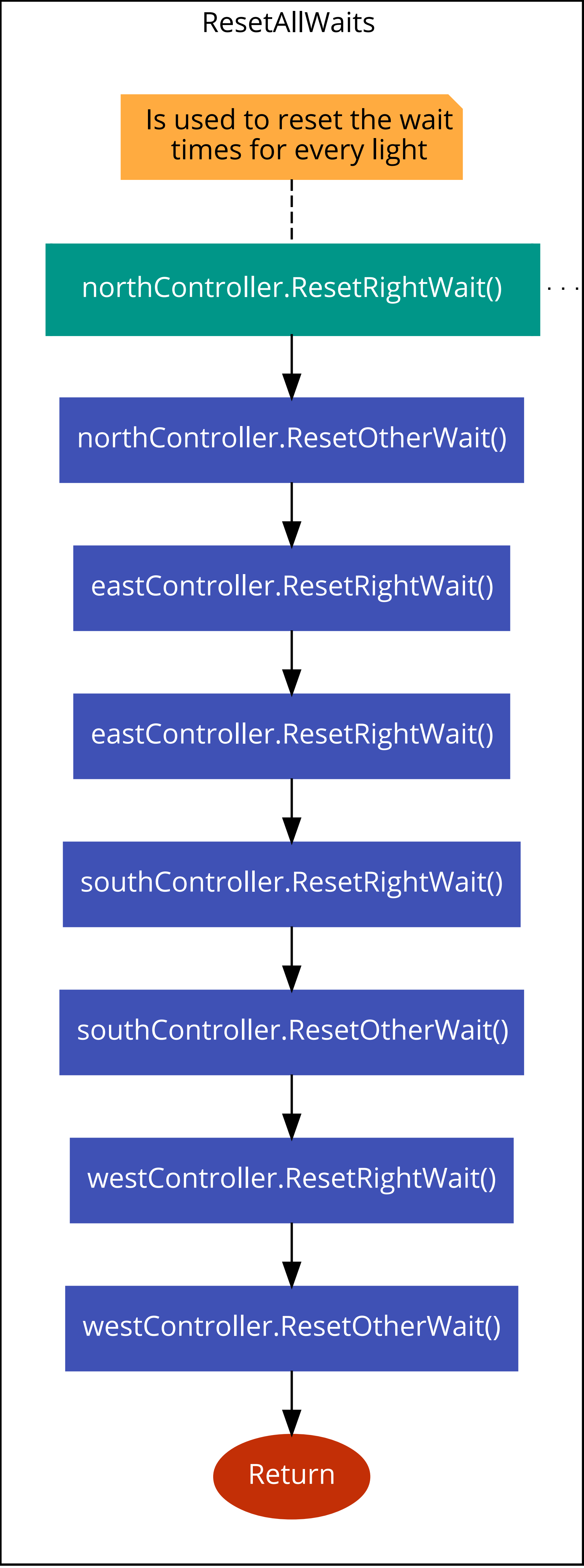
westController.ResetRightWait()

westController.ResetOtherWait()

Return

Example function call

ResetAllWaits



RightCycle  
(self)

Cycles through turning all  
right lights on then off

Turn all lights off

Turn right light to green  
Turn other light to red

Wait self.INTERVAL

Turn all lights off

Turn right light to orange  
Turn other light to red

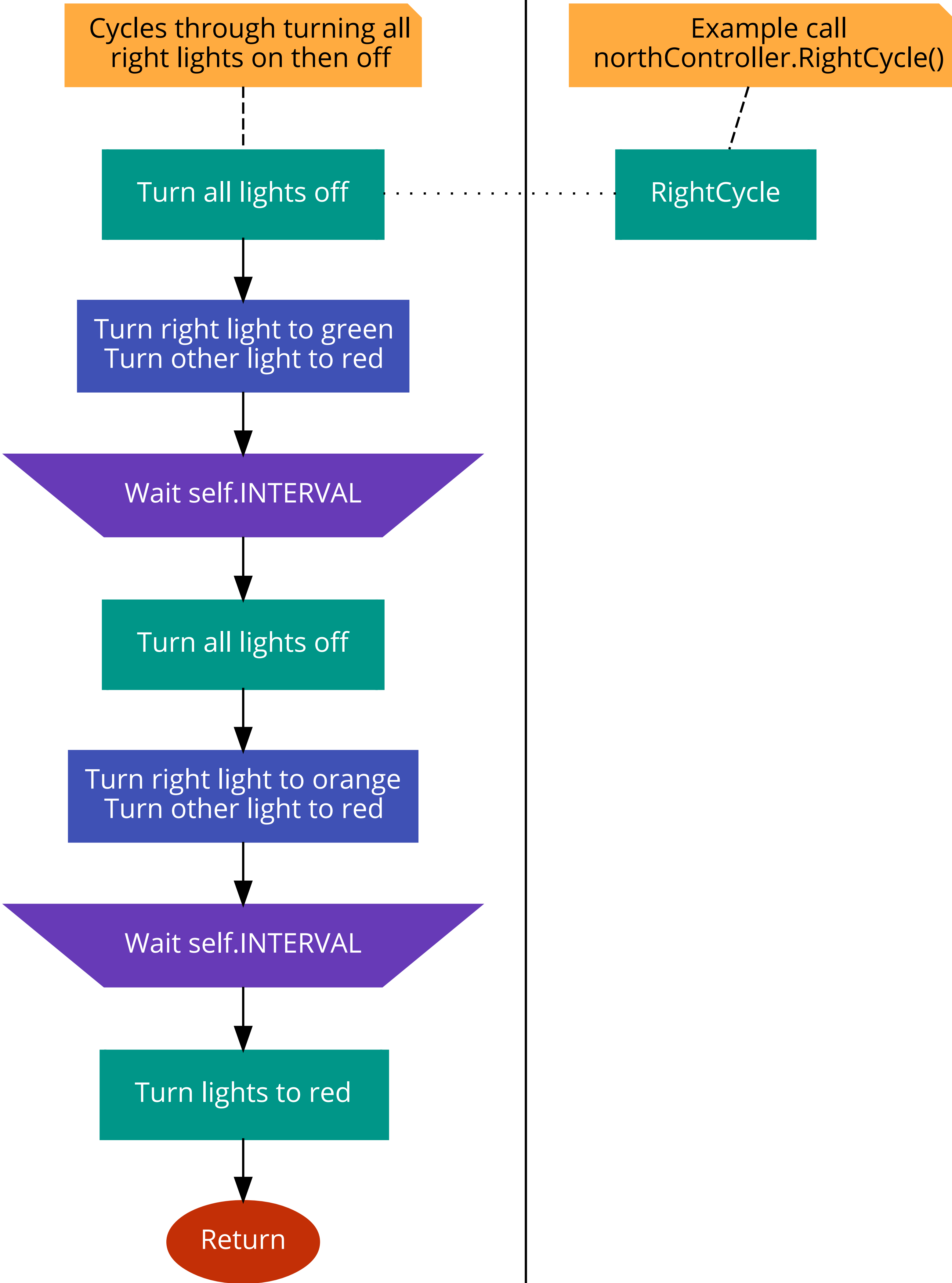
Wait self.INTERVAL

Turn lights to red

Return

Example call  
northController.RightCycle()

RightCycle



RunDual  
(controllerOne, controllerTwo)

We use threading to turn on  
two seperate light  
controllers at once

set a thread worker to controllerOne.Cycle

set a thread worker to controllerTwo.Cycle

start both thread workers

Call join() to wait for them to finish

Reset the wait time for controllerOne

Reset the wait time for controllerTwo

Return

**northController, southController**

An example function call

RunDual

sensor  
(controller, lane)

This controls the removal  
of cars from the releant  
lane  
of traffic

Example function call

sensor

northController, northLane

lights are broken

True

False

More cars in the lane

True

Both lights are green or orange

True

False

Right turning light is green or orange

True

False

Other light is green or orange

True

False

False

No cars go

Remove next car in lane

Remove next car going right in said lane

Remove next car going straight  
or left in said lane

Return

