Source:

1 | Definitions

1.1 | Linear Map

A linear map is a function/map from one vector space to another such that it satisfies the properties of additivity and homogeneity. Notationally, a linear map $T \in \mathcal{L}(V,W)$ satisfies $T(a)+T(b)=T(a+b): a,b \in V$ and $\lambda Ta=T(\lambda a): \lambda \in \mathbb{F}, a \in V$

1.2 | Null Space

The null space of a linear map is the space of vectors that are sent to 0 by T, aka $\{v: v \in V \land Tv = 0\}$

1.3 | Column Space

The column space of a linear map is the subspace of the codomain that is an output to the map, aka $\{w: Tv=w, v\in V, w\in W\}$

1.4 | Homogeneous system of equations

A system of equations where all the right hand sides are 0.

1.5 | Injective

When each element in the column space of a map is mapped to by exactly one element in the domain, aka when $Tu = Tv \implies u = v$.

1.6 | Surjective

When every element in the codomain is mapped to, aka the column space is the codomain, aka $W = \{Tv : v \in V\}$.

2 | Fundamental theorem of linear maps

In a map $T \in \mathcal{L}(U,V)$ where U is finite dimensional, dim $U = \dim \operatorname{range} T + \dim \operatorname{null} T$. Intuitively, the dimension of the input space is the dimension of everything that gets sent to zero plus everything that doesn't get sent to zero.

3 | Why is the range also called the "column space"?

When a linear map is thought of as a matrix, (which Jana promises is always possible), everything that can be mapped to is a linear combination of the columns. Why columns instead of rows? The convention we use is to multiply operation matrices on the left, and the way matrix multiplication works means that when a $n \times 1$ matrix is multiplied each element ends up as the coefficient for a column in a linear combination. Thus, all possible $n \times 1$ matrices when taken as input to the operation matrix will create the span of the columns.

Exr0n · 2020-2021 Page 1

4 | Prove that for (presumably a linear map) $T \in \mathcal{L}(V, W)$ the null space is a subspace of V.

4.1 | Contains Zero

Let v = T0.

$$T0 = T(0+0) = T0 + T0 = v + v \implies v = 0$$

thus linear maps send zero to zero. Thus zero is in the null space.

4.2 | Additivity

For vectors $a,b\in \operatorname{null} T$ if Ta=0 and Tb=0, then

$$Ta + Tb = 0 + 0 = 0$$
 and $Ta + Tb = T(a + b) = 0$

thus a + b is in the null space and the null space is closed under addition.

4.3 | Homogeneity

If $a\in \operatorname{null} T$ (aka Ta=0) and $\lambda\in\mathbb{F}$, then

$$\lambda Ta = \lambda 0 = 0$$
 and $\lambda Ta = T(\lambda a)$

thus λa is in the null space and the null space is closed under scalar multiplication.

Thus the null space is a vector space and a subspace of V.

5 | Prove that $T \in \mathcal{L}(V, W)$ is injective iff null(T) = 0

5.1 | In the forwards direction

T being injective means $Tu = Tv \implies u = v$, so only one vector $v \in V$ satisfies Tv = 0. Because linear maps take zero to zero (result 4.1 in the previous proof), that vector v must be zero. Thus, null T = 0.

5.2 | In the reverse direction

Intuitively: if any information is lost, then some of it must be lost to zero because zero is an element in every vector space and information should be lost "linearly" meaning "evenly".

Given that null T=0, suppose we have $u,v\in V$ s.t. Tu=Tv. Then

$$0 = Tu - Tv = T(u - v)$$

$$\therefore u - v \in \text{null } T$$

$$\therefore u - v = 0$$

$$\therefore u = v$$

Thus $Tu = Tv \implies u = v$ aka T is injective.

Exr0n · 2020-2021 Page 2

6 | Prove that for any $T\in \mathcal{L}(V,W)$, there is a subspace U of V such that $U\bigoplus \operatorname{null} T=V$

A the sum of two subspaces being a direct sub is equivalent to their intersection = 0. Let

$$U=\{v:v\in V, Tv\neq 0\}\cup 0$$

Exr0n · 2020-2021 Page 3