

Source:

1 | **Axler3.6 sum** $(S + T)$

If $S, T \in \mathcal{L}(V, W)$ then the *sum* $S + T$ is defined by

$$(S + T)(v) = Sv + Tv$$

$(S + T)$ is a linear map.

2 | **Axler3.6 scalar product** λT

If $T \in \mathcal{L}(V, W)$ and $\lambda \in \mathbb{F}$ then the *product* $(\lambda T)v = \lambda Tv$. λT is a linear map.

3 | **Axler3.8 Product of Linear Maps**

It's basically the composition of linear maps. Let U, V, W be vector spaces over \mathbb{F} and T, S be linear maps s.t. $T \in \mathcal{L}(U, V)$ and $S \in \mathcal{L}(V, W)$. Then the *product*

$$ST \in \mathcal{L}(U, W) : (ST)(u) = S(Tu)$$

#aka $ST = S \circ T$

3.1 | **careful**

3.1.1 | **Evaluate backwards**

Like the composition of functions, remember to evaluate these guys backwards. $(ST)(u) = S(Tu)$ meaning you evaluate Tu first, then S of that.

3.1.2 | **T maps into the domain of S**

Otherwise it's not defined.

4 | **Results**

4.1 | **Axler3.7** $\mathcal{L}(V, W)$ **is a vector space over** \mathbb{F}

4.2 | **Axler3.9 Algebraic properties**

4.2.1 | **associativity**

$$(T_1 T_2) T_3 = T_1 (T_2 T_3)$$

when it makes sense to multiply them.

1. TODO #question what about $(T_1 + T_2) + T_3 \stackrel{?}{=} T_1 + (T_2 + T_3)$?
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