

Ioannis Tsampras <u>ioannis.tsampras@upnet.gr</u> **Stavros Kanias** <u>up1066584@upnet.gr</u>

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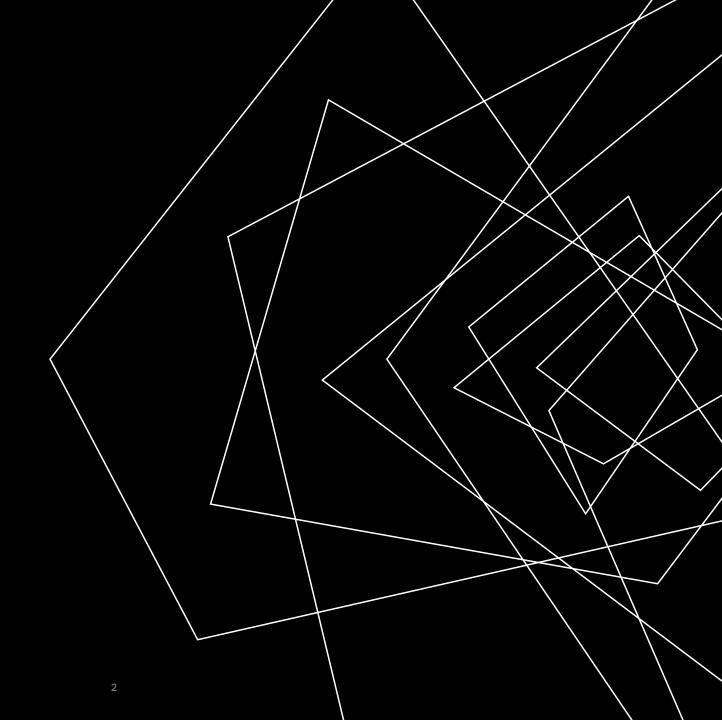
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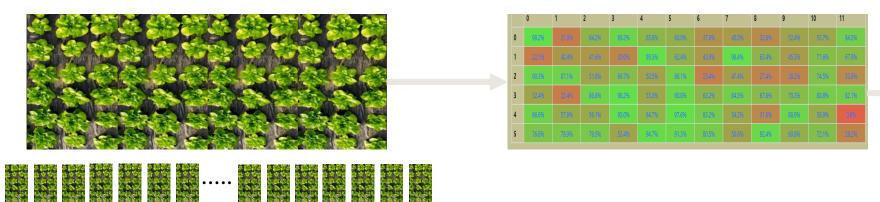
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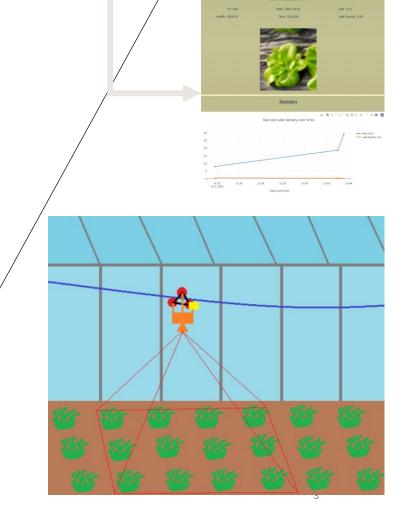
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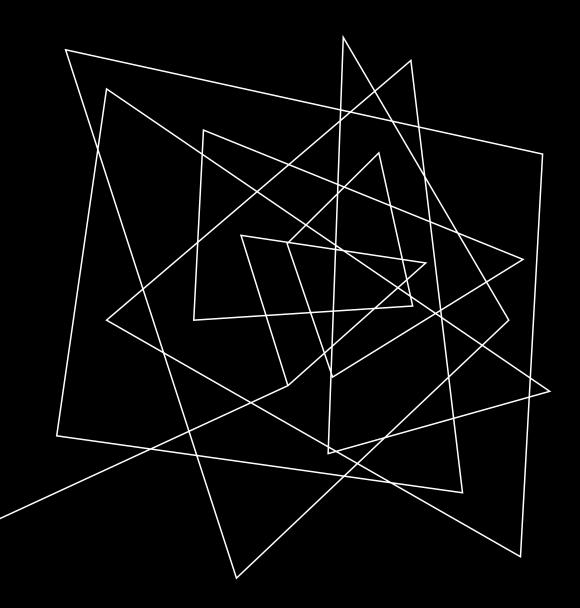




THE PROJECT

- A Device, Cloud and Processing infrastructure for distributed digital twins of herbaceous plant type greenhouses.
- Taking advantage of dwindling power and hardware cost for edge data ingestion we implement an AI solution in top-view image mapping and detection along with a distributed database cloud solution.
- Our cable-lift low cost and easy installation robot moves through the length of a greenhouse, takes top-down images and in real time maps it's position while detecting individual plants, saving multiple snapshots for each and forwarding metrics & sensor data to the cloud.





PRIMARY GOALS

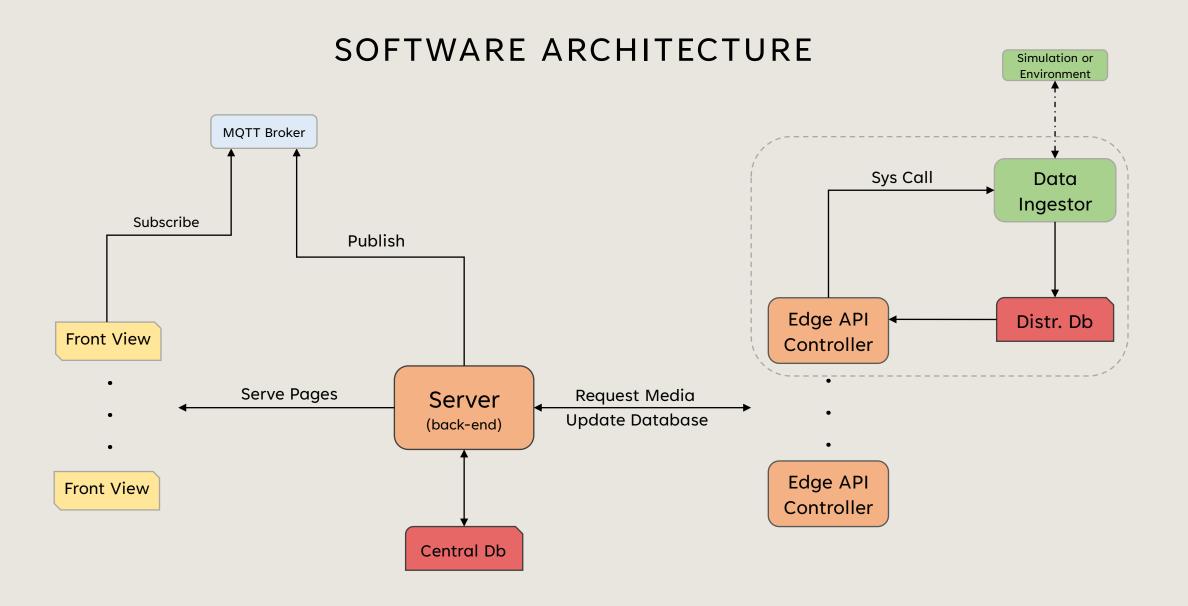
Optimization Axes

- Low cellular data usage
- Inexpensive hardware & installation
- Full digital representation

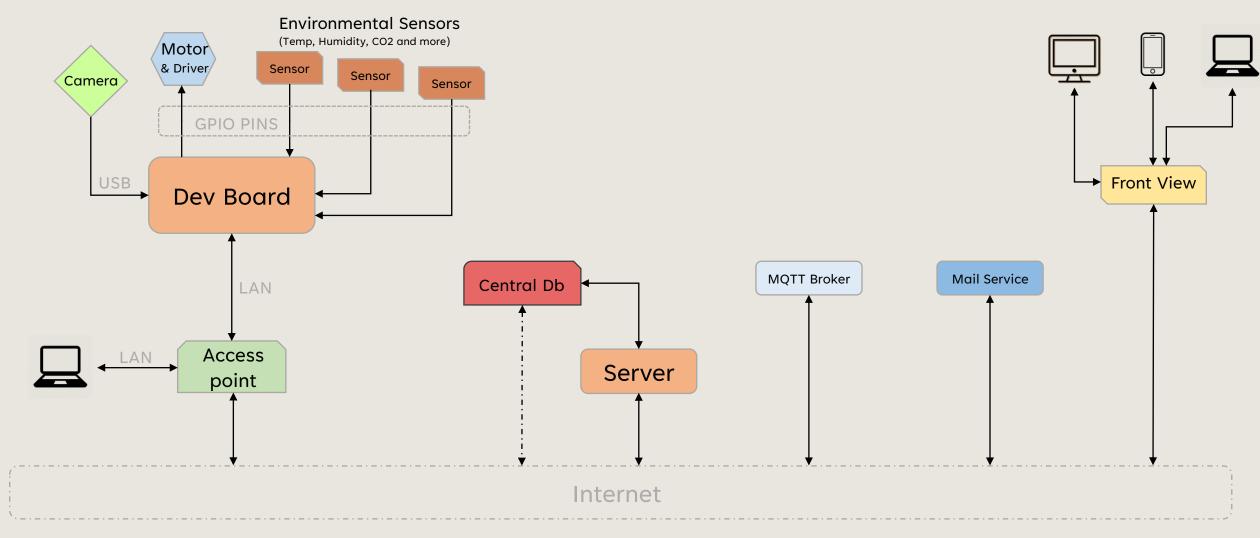
ARCHITECTURAL CHOICES

System Design

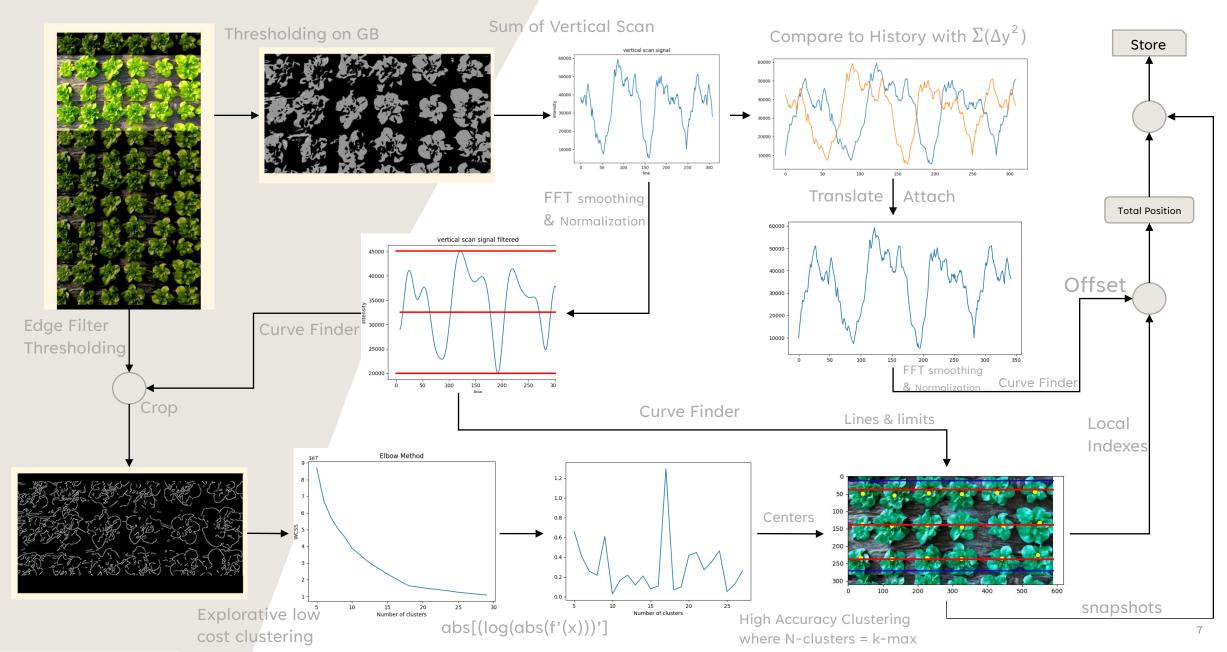
- Mapping and detection on edge (cost, data usage)
- Metrics extraction on site, updating central Db only for metrics (data usage)
- On demand access to media through distributed Db, central Db cache (data usage)
- MQTT front view refresher
- LAN option for data extraction (data usage)



DEVICE FLOW DIAGRAM



OUR MODEL

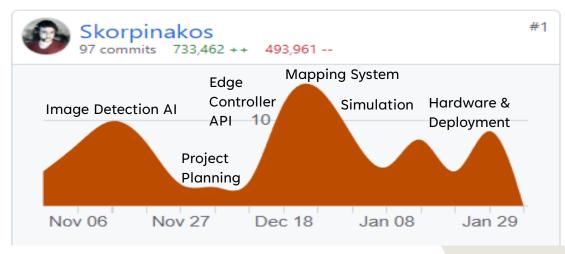


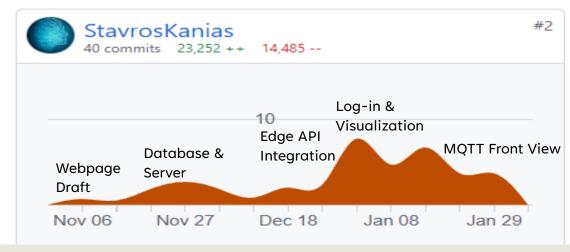
LIVE DEMO



Contributions to main, excluding merge commits and bot accounts

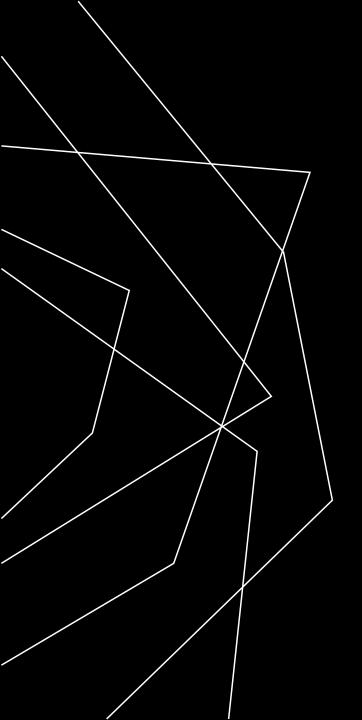






TIMELINE

20XX



THANK YOU

Ioannis Tsampras & Stavros Kanias

www.github.com/Skorpinakos/IoT-2022