

1 Pre-calculus

Real Numbers & Functions

a^2 - b^2 = (a + b)(a - b)

|x + y| ≤ |x| + |y|

log_a x = ln x / ln a

f : A → B, g ∘ f = g(f(x)), g ∘ f ≠ f ∘ g

A: domain, B: codomain, range: f = {f(x) ∈ B|x ∈ A}
Injective: f(x) = f(y) ⇒ x = y, surjective: ∀z ∈ B, ∃x ∈ A, f(x) = z
If f^-1 exists, then f is bijective

Linear Equations

Slope-intercept: y = mx + b
Point-slope: y - y1 = m(x + x1)
Intercept: x/a + y/b = 1
b: y-intercept, a: x-intercept, (x1, y1) is a point on the line
The gradient of the normal of a line is 1/m

Trigonometric Identities

csc x = 1 / sin x

sec x = 1 / cos x

cot x = 1 / tan x

sin^2 θ + cos^2 θ = 1

tan^2 θ + 1 = sec^2 θ

1 + cot^2 θ = csc^2 θ

sin(A ± B) = sin A cos B ± cos A sin B

cos(A ± B) = cos A cos B ∓ sin A sin B

tan(A ± B) = (tan A ± tan B) / (1 ∓ tan A tan B)

sin 2A = 2 sin A cos A

cos 2A = cos^2 A - sin^2 A = 2 cos^2 A - 1 = 1 - 2 sin^2 A

tan 2A = (2 tan A) / (1 - tan^2 A)

sin P ± sin Q = 2 sin((P ± Q)/2) cos((P ∓ Q)/2)

cos P + cos Q = 2 cos((P + Q)/2) cos((P - Q)/2)

cos P - cos Q = -2 sin((P + Q)/2) sin((P - Q)/2)

Values of Trigonometric Functions

Table with 6 columns: angle, 0, pi/6, pi/4, pi/3, pi/2. Rows: sin, cos, tan.

Range of a Function

First find the maximal domain of f
To find the range of f, let y = f(x), solve for x, deduce the range (exclude values where f(x) is undefined)

2 Limits

Continuity

Table with 5 columns: c, lim_{x→c-} f(x), lim_{x→c+} f(x), lim_{x→c} f(x), f(x)

Continuous if lim_{x→c} f(x) exists (only if left = right limit) AND
Interior point: lim_{x→c} f(x) = f(c)
Left/right end-point: left/right limit equals f(c)
Polynomials, trigonometric/exponential/logarithmic functions and their combinations are continuous

Evaluation of Limits

lim_{x→±∞} (k1x^a / k2x^b) = 0 (a < b), A/B (a = b), ±∞ (a > b)

lim_{x→c} (sin(g(x)) / g(x)) = lim_{x→c} (g(x) / sin(g(x))) = 1

lim_{x→c} (tan(g(x)) / g(x)) = lim_{x→c} (g(x) / tan(g(x))) = 1

In particular, when c = 0 and g(x) = x

Squeeze Theorem

If g(x) ≤ f(x) ≤ h(x) and

lim_{x→c} g(x) = lim_{x→c} h(x) = L ⇒ lim_{x→c} f(x) = L

If lim_{x→c} g(x) = 0,

lim_{x→c} g(x) sin(h(x)) = 0, lim_{x→c} g(x) cos(h(x)) = 0

Intermediate Value Theorem

To show an equation f(x) = c has a root between a and b, f(x) must be continuous and f(a) < c < f(b)

3 Derivatives

Differentiability implies continuity (converse is not true in general)

Table with 2 columns: Function, Derivative. Rows include (f(x))^n, cos(f(x)), sin(f(x)), tan(f(x)), sec(f(x)), csc(f(x)), cot(f(x)), e^{f(x)}, ln(f(x)), sin^{-1}(f(x)), cos^{-1}(f(x)), tan^{-1}(f(x)), cot^{-1}(f(x)), sec^{-1}(f(x)), csc^{-1}(f(x)).

d/dx (uv) = du/dx v + u dv/dx

d/dx (u/v) = (du/dx v - u dv/dx) / v^2

d/dx (f(g(x))) = f'(g(x)) · g'(x)

Implicit Differentiation

Differentiate all terms w.r.t. x, chain rule on terms only in y e.g.
d/dx y^3 = 3y^2 dy/dx
For equations of the form f(x, y) = 0,

dy/dx = -(d/dx f(x, y)) / (d/dy f(x, y))

Derivatives of Inverse Functions

For bijective function f,

(f^{-1})'(a) = 1 / f'(f^{-1}(a))

f'(f^{-1}(a)) is the derivative of f evaluated at f^{-1}(a)

Parametric Equations

For curves defined by the equations x = f(t), y = g(t)

dy/dx = dy/dt ÷ dx/dt

d^2y/dx^2 = d/dt (dy/dx) ÷ dx/dt

Concavity, Extremas

$f''(c) > 0 \Rightarrow$ concave upward / local minima, $f''(c) < 0 \Rightarrow$ concave downward / local maxima, $f''(c) = 0 \Rightarrow$ point of inflection
End-points are not considered to be local extremas
Critical point: not an end-point and $f'(c) = 0$ or DNE
Absolute extremum: occurs at end-point or critical point

L'Hôpital's Rule

lim_{x -> c} f(x)/g(x) = lim_{x -> c} f'(x)/g'(x)

4 Integrals

Function	Integral
$\int (ax + b)^n dx$	$\frac{(ax+b)^{n+1}}{(n+1)a} + C, (n \neq -1)$
$\int \frac{1}{ax+b} dx$	$\frac{1}{a} \ln ax + b + C$
$\int e^{ax+b} dx$	$\frac{1}{a} e^{ax+b} + C$
$\int \sin(ax + b) dx$	$-\frac{1}{a} \cos(ax + b) + C$
$\int \cos(ax + b) dx$	$\frac{1}{a} \sin(ax + b) + C$
$\int \tan(ax + b) dx$	$\frac{1}{a} \ln \sec(ax + b) + C$
$\int \sec(ax + b) dx$	$\frac{1}{a} \ln \sec(ax + b) + \tan(ax + b) + C$
$\int \csc(ax + b) dx$	$-\frac{1}{a} \ln \csc(ax + b) + \cot(ax + b) + C$
$\int \cot(ax + b) dx$	$-\frac{1}{a} \ln \csc(ax + b) + C$
$\int \sec^2(ax + b) dx$	$\frac{1}{a} \tan(ax + b) + C$
$\int \csc^2(ax + b) dx$	$-\frac{1}{a} \cot(ax + b) + C$
$\int \sec(ax + b) \tan(ax + b) dx$	$\frac{1}{a} \sec(ax + b) + C$
$\int \csc(ax + b) \cot(ax + b) dx$	$-\frac{1}{a} \csc(ax + b) + C$
$\int \frac{1}{a^2 + (x+b)^2} dx$	$\frac{1}{a} \tan^{-1}(\frac{x+b}{a}) + C$
$\int \frac{1}{\sqrt{a^2 - (x+b)^2}} dx$	$\sin^{-1}(\frac{x+b}{a}) + C$
$\int \frac{-1}{\sqrt{a^2 - (x+b)^2}} dx$	$\cos^{-1}(\frac{x+b}{a}) + C$
$\int \frac{1}{a^2 - (x+b)^2} dx$	$\frac{1}{2a} \ln \frac{x+b+a}{x+b-a} + C$
$\int \frac{1}{(x+b)^2 - a^2} dx$	$\frac{1}{2a} \ln \frac{x+b-a}{x+b+a} + C$
$\int \frac{1}{\sqrt{(x+b)^2 + a^2}} dx$	$\ln (x + b) + \sqrt{(x + b)^2 + a^2} + C$
$\int \frac{1}{\sqrt{(x+b)^2 - a^2}} dx$	$\ln (x + b) + \sqrt{(x + b)^2 - a^2} + C$
$\int \sqrt{a^2 - x^2} dx$	$\frac{\pi}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \sin^{-1} \frac{x}{a} + C$
$\int \sqrt{x^2 - a^2} dx$	$\frac{x}{2} \sqrt{x^2 - a^2} + \frac{a^2}{2} \ln x + \sqrt{x^2 - a^2} + C$

Useful Identities

cos^2 A = 1/2 (1 + cos 2A)
sin^2 A = 1/2 (1 - cos 2A)
sin A cos B = 1/2 (sin(A + B) + sin(A - B))
cos A sin B = 1/2 (sin(A + B) - sin(A - B))
cos A cos B = 1/2 (cos(A + B) + cos(A - B))
sin A sin B = -1/2 (cos(A + B) - cos(A - B))

Partial Fractions

Denominator Factors	Partial Fractions
$ax + b$	$\frac{A}{ax+b}$
$(ax + b)^2$	$\frac{A}{ax+b} + \frac{B}{(ax+b)^2}$
$ax^2 + bx + c, b^2 - 4ac < 0$	$\frac{Ax+B}{ax^2+bx+c}$

Improper fraction -> proper fraction: long division

Integration by Substitution

int f(g(x))g'(x)dx = int f(u)du

Expression	Trigonometric Substitution
$\sqrt{a^2 - (x + b)^2}$	$x + b = a \sin \theta, -\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2}$
$\sqrt{a^2 + (x + b)^2}$	$x + b = a \tan \theta, -\frac{\pi}{2} < \theta < \frac{\pi}{2}$
$\sqrt{(x + b)^2 - a^2}$	$x + b = a \sec \theta, 0 < \theta < \frac{\pi}{2} \text{ or } \pi \leq \theta < \frac{3\pi}{2}$

Manipulate the expression to fit the forms

Integration by Parts

int f'(x)g(x)dx = f(x)g(x) - int f(x)g'(x)dx

Choice of integration:
log, inversion trigo, algebraic functions -> differentiate
exponential functions -> integrate
trigo functions -> either

Fundamental Theorem of Calculus

d/dx int_a^{u(x)} f(t)dt = f(u(x))u'(x)

int_{-a}^a f(x)dx = 0 if f(-x) = -f(x) (odd function)
int_{-a}^a f(x)dx = 2 int_0^a f(x)dx if f(-x) = f(x) (even function)

Improper Integrals

Type 1: integrals with infinite limits of integration

int_a^inf f(x)dx = lim_{b -> inf} int_a^b f(x)dx
int_{-inf}^b f(x)dx = lim_{a -> -inf} int_a^b f(x)dx
int_{-inf}^inf f(x)dx = int_{-inf}^c f(x)dx + int_c^inf f(x)dx

Type 2: integrals of functions that become infinite at a point within the interval of integration

int_a^b f(x)dx = lim_{c -> a+} int_c^b f(x)dx

f(x) is continuous on (a, b] and is discontinuous at a

Area Between Curves

A = int_a^b f(x) - g(x)dx

f(x) is the curve above g(x), if the two curves alternate between being top and bottom, split the regions into their respective integrals and intervals
For curves in terms of y, f(y) is further to the right of the y-axis than g(y),

A = int_c^d f(y) - g(y)dy

Volume of Solid of Revolution

Disk method (revolve about the x-axis):

V = pi int_a^b f(x)^2 dx - pi int_a^b g(x)^2 dx

Use f(y), g(y) and differentiate w.r.t. y for revolution about the y-axis

Cylindrical shell method (use when difficult/impossible to express y = f(x) as x = f(y)):

V = 2pi int_a^b x|f(x) - g(x)|dx

The above is for rotation about the y-axis, for rotation about the x-axis, use y|f(y) - g(y)|dy

Arc Length of a Curve

int_a^b sqrt(1 + f'(x)^2)dx

5 Series

Common Infinite Series

Geometric Series

sum_{n=1}^inf ar^{n-1}, (a != 0)
sum_{i=1}^n ar^{i-1} = (a(1 - r^n))/(1 - r)

Convergent to a/(1-r) when |r| < 1

Harmonic Series

sum_{n=1}^inf 1/n is divergent

Alternating Harmonic Series

sum_{n=1}^inf (-1)^{n+1}/n converges to ln2

p-Series

sum_{n=1}^inf 1/n^p is convergent <=> p > 1

Convergence & divergence

n^th Term Test

If sum_{n=1}^inf a_n is convergent, then lim_{n->inf} a_n = 0

Therefore if lim_{n->inf} a_n does not exist or lim_{n->inf} a_n != 0 then the series is divergent, inconclusive if lim_{n->inf} a_n = 0

Integral Test

Use when integral is simple/known

sum_{n=1}^inf a_n is convergent <=> integral_1^inf f(x)dx is convergent

Comparison Test

Use when able to establish an inequality to compare to a known series

sum_{n=1}^inf a_n, sum_{n=1}^inf b_n, a_n <= b_n for all n

sum_{n=1}^inf b_n is convergent -> sum_{n=1}^inf a_n is convergent

sum_{n=1}^inf a_n is divergent -> sum_{n=1}^inf b_n is divergent

Ratio Test and Root Test

Use root test on series with power n by taking n^th root

sum_{n=1}^inf a_n, lim_{n->inf} |a_{n+1}/a_n| = L OR lim_{n->inf} nth root of |a_n| = L

0 <= L < 1 -> absolutely convergent
L > 1 -> divergent
L = 1 -> inconclusive

Alternating Series

sum_{n=1}^inf (-1)^{n-1} b_n

If b_n is decreasing and lim_{n->inf} b_n = 0 then the series is convergent

Power Series

Power series centered at a

sum_{n=0}^inf c_n (x-a)^n = c_0 + c_1 (x-a) + c_2 (x-a)^2 + ...

Exactly one of the following:

- 1. Converges at x = a only (R = 0)
- 2. Converges for all x (R = inf)
- 3. There exists a positive number R such that the series converges absolutely if |x - a| < R and diverges if |x - a| > R

R is the radius of convergence, end points of the interval of convergence can converge or diverge
To compute R:

lim_{n->inf} |c_{n+1}/c_n| = L OR lim_{n->inf} nth root of |c_n| = L, L in R v L = inf, R = 1/L

Power Series Representation

f'(x) = sum_{n=1}^inf n c_n (x-a)^{n-1} + C, |x-a| < R

integral f(x)dx = sum_{n=0}^inf c_n (x-a)^{n+1}/(n+1) + C, |x-a| < R

To find the power series representation, manipulate the expression into one of the known series to derive the summation

Taylor Series

Coefficients of a power series is given as c_n = f^{(n)}(a)/n!

f(x) = sum_{n=0}^inf f^{(n)}(a)/n! (x-a)^n

Power series representation of f at a, extension of power series

Maclaurin Series

f(x) = sum_{n=0}^inf f^{(n)}(0)/n! x^n

Power series representation of f at 0, special case of Taylor series

6 Vectors & Geometry of Space

Equation of a sphere with center C(x1, y1, z1) and radius r

(x - x1)^2 + (y - y1)^2 + (z - z1)^2 = r^2

Distance formula: |P1 P2| = sqrt((x2 - x1)^2 + (y2 - y1)^2 + (z2 - z1)^2)

Length of a vector: ||v|| = sqrt((v1)^2 + (v2)^2 + (v3)^2)

Unit vector: u = v/||v||

Dot product: a · b = a1b1 + a2b2 + a3b3, a · b = ||a||||b|| cos θ,

a · a = ||a||^2

θ is the angle between a and b

a & b are perpendicular to each other if a · b = 0

Projections

Component of b along a: comp_a b = ||b|| cos θ = (a·b)/||a||

Vector projection of b onto a: proj_a b = comp_a b × (a/||a||) = (a·b/||a||^2) a

Distance from a point to a plane

Shortest distance from point P(x0, y0, z0) to the plane ax + by + cz = d

|ax0 + by0 + cz0 - d| / sqrt(a^2 + b^2 + c^2)

Cross Product

a × b = (a2b3 - a3b2)i + (a3b1 - a1b3)j + (a1b2 - a2b1)k

a × b is perpendicular to both a and b

Area of a parallelogram: ||a × b|| = ||a||||b|| sin θ

Distance from Q to the line through P & R:

||PQ × PR|| / ||PR||

Lines

r0: known point on the line, t: scalar multiple, v: direction vector of the line

Vector equation: r = r0 + tv or <x, y, z> = <x0, y0, z0> + t<a, b, c>

Parametric equation: x = x0 + at, y = y0 + bt, z = z0 + ct

If two lines in 3D space are not parallel and does not intersect, then they are skew

Planes

n: normal vector to the plane, r0: point on the plane Vector equation: n · r = n · r0

Linear equation: ax + by + cz + d = 0, d = -(ax0 + by0 + cz0)

Two planes are parallel if their normal vectors are parallel

If two planes are not parallel, they intersect in a line and the angle between two planes is the acute angle between their normal vectors

7 Functions of Several Variables

Vector-valued Function

r(t) = <f(t), g(t), h(t)> = f(t)i + g(t)j + h(t)k

r'(t) = <f'(t), g'(t), h'(t)>

Derivative Rules

f(t): differentiable scalar function, r(t) & s(t): differentiable vector-valued function

d/dt f(t)r(t) = f'(t)r(t) + f(t)r'(t)

d/dt r(t) · s(t) = r'(t) · s(t) + r(t) · s'(t)

d/dt r(t) × s(t) = r'(t) × s(t) + r(t) × s'(t)

Tangent Vector and Tangent Line to a Curve

r'(t) is the tangent vector of r(t), equation of tangent line can be found using a point on the curve and the corresponding tangent vector

Arc Length of a Space Curve

s = integral_a^b ||r'(t)|| dt

Functions of Two Variables

Elliptic paraboloid symmetric about z-axis

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z}{c}$$

Ellipsoid

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

Partial Derivatives

Clairaut’s Theorem

$f_{xy}(a,b) = f_{yx}(a,b), f_{xyy}(a,b) = f_{yyx}(a,b) = f_{yyx}(a,b)$

Equation of Tangent Planes

$z = f(a,b) + f_x(a,b)(x - a) + f_y(a,b)(y - b)$

Chain Rule

One independent variable: $z = f(x,y), x = g(t), y = h(t)$

$$\frac{dz}{dt} = \frac{\delta f}{\delta x} \frac{dx}{dt} + \frac{\delta f}{\delta y} \frac{dy}{dt}$$

Two independent variables: $z = f(x,y), x = g(s,t), y = h(s,t)$

$$\begin{aligned} \frac{dz}{ds} &= \frac{\delta f}{\delta x} \frac{\delta x}{\delta s} + \frac{\delta f}{\delta y} \frac{\delta y}{\delta s} \\ \frac{dz}{dt} &= \frac{\delta f}{\delta x} \frac{\delta x}{\delta t} + \frac{\delta f}{\delta y} \frac{\delta y}{\delta t} \end{aligned}$$

Implicit Differentiation

Two independent variables: $F(x,y,z) = 0, z = f(x,y)$

$$\frac{\delta z}{\delta x} = -\frac{F_x}{F_z}, \frac{\delta z}{\delta y} = -\frac{F_y}{F_z}$$

Approximation of Increment

Good approximation provided Δx & Δy are small
 $\Delta z \approx dz = f_x(a,b)\Delta x + f_y(a,b)\Delta y$

Directional Derivative

Gradient of $f(x,y)$

$$\nabla f(x,y) = \langle f_x, f_y \rangle = f_x i + f_y j$$

Directional derivative of $f(x,y)$ in the direction of unit vector
 $u = \langle a,b \rangle$

$$D_u f(x,y) = \nabla f(x,y) \cdot u = f_x(x,y)a + f_y(x,y)b$$

Similarly for $f(x,y,z)$

$$D_u f(x,y,z) = \nabla f(x,y,z) \cdot u = f_x(x,y,z)a + f_y(x,y,z)b + f_z(x,y,z)c$$

Tangent Plane to Level Surface

∇f is normal to the level curve/surface f

$$\nabla f(x_0,y_0,z_0) \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$$

Maximum Rate of Increase/Decrease

Maximum value of $D_u f(P)$: $||\nabla f(P)||$, minimum value: $-||\nabla f(P)||$

Local Extrema

If $f(x,y)$ has a local maximum or minimum at (a,b) , then

$f_x(a,b) = f_y(a,b) = 0$

(a,b) is a critical point if the above is true or one of the partial derivatives does not exist

Second Derivative Test

$$D(a,b) = f_{xx}(a,b)f_{yy}(a,b) - (f_{xy}(a,b))^2$$

f_{yy} can be substituted as f_{xx} below

- Local maximum: $D > 0$ and $f_{xx}(a,b) > 0$
- Local minimum: $D > 0$ and $f_{xx}(a,b) < 0$
- Saddle point: $D < 0$
- No conclusion: $D = 0$

8 Double Integrals

Iterated Integral

$$V = \int \int_R f(x,y) dA = \int_a^b \int_c^d f(x,y) dy dx = \int_c^d \int_a^b f(x,y) dx dy$$

If $f(x,y)$ can be factored into $g(x)h(y)$

$$\int \int_R g(x)h(y) dA = (\int_a^b g(x) dx)(\int_c^d h(y) dy)$$

Double Integral Over a General Region

Type I domain, region between two functions of x

$$\int_a^b \int_{g_1(x)}^{g_2(x)} f(x,y) dy dx, y = g_1(x), y = g_2(x)$$

Type II domain, region between two functions of y

$$\int_c^d \int_{h_1(y)}^{h_2(y)} f(x,y) dx dy, x = h_1(y), x = h_2(y)$$

Double Integrals in Polar Coordinates

$r^2 = x^2 + y^2, x = r \cos \theta, y = r \sin \theta$

$$\int \int_R f(x,y) dA = \int_{\alpha}^{\beta} \int_a^b f(r \cos \theta, r \sin \theta) r dr d\theta$$

$0 \leq a \leq r \leq b, \alpha \leq \theta \leq \beta$, sketch R to determine limits, use polar coordinates when region is circular

Surface Area

$$\int \int_D \sqrt{(f_x)^2 + (f_y)^2 + 1} dA$$

9 Ordinary Differential Equations

Separable ODE

$$\frac{dy}{dx} = f(x)g(y)$$

Separate the variables

$$\frac{1}{g(y)} dy = f(x) dx$$

Integrate both sides

$$\int \frac{1}{g(y)} dy = \int f(x) dx + C$$

Reduction to Separable Form

Radical

$$y' = g(\frac{y}{x})$$

Let $v = \frac{y}{x}$, then $y = vx$ and $y' = v + xv'$, and the equation becomes $v + xv' = g(v)$ which is separable

Linear

$$y' = f(ax + by + c)$$

Set $u = ax + by + c$

Linear First Order ODE

$$\frac{dy}{dx} + P(x)y = Q(x)$$

Integrating factor: $I(x) = e^{\int P(x) dx}$

Multiply both sides by $I(x)$ and integrate both sides, solve for y

$$y \cdot I(x) = \int Q(x) \cdot I(x) dx$$

Bernoulli Equation

$$y' + p(x)y = q(x)y^n$$

Let $u = y^{1-n}$, then $u' = (1-n)y^{1-n}y'$, so

$$u' + (1-n)p(x)u = (1-n)q(x)$$

Which is a linear first order ODE

Improved Malthus Model of Population

$$N = \frac{N_{\infty}}{1 + (\frac{N_{\infty}}{N} - 1)e^{-Bt}}$$

$D = sN, N_{\infty} = \frac{B}{s}$ (carrying capacity), $N = \frac{B}{2s}$ (point of inflection)

Common ODE

Half-life of x

Let $x(t)$ be the amount of x at time t , $\frac{dx}{dt} = -k_x x(t) \rightarrow x(t) = x_0 e^{-k_x t} \rightarrow k_x = \frac{\ln 2}{\text{half-life of } x}$

Newton’s Law of Cooling

$$\frac{dT}{dt} = -k(T - T_{\text{amb}})$$

Newton’s Second Law

$$\text{force} - \text{resistance} = m \frac{dV}{dt}$$

Mixture

$$\frac{dQ}{dt} = \text{input} - \text{output}$$