

AVL Trees

COMP 2210 – Dr. Hendrix

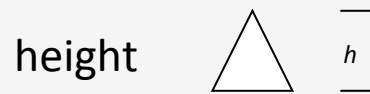


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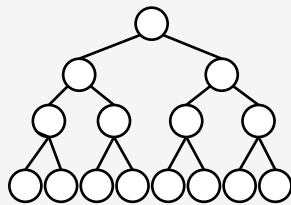
Shapes and height



Many tree algorithms are dependent to some extent on the tree's height.

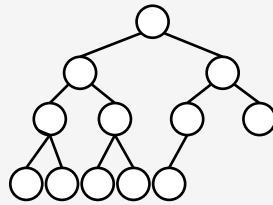
best-case BST

full

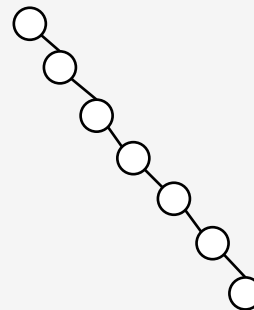


$$h(t) = \text{floor}(\log_2 N) + 1$$

complete

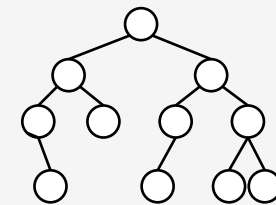


worst-case BST



$$h(t) = N$$

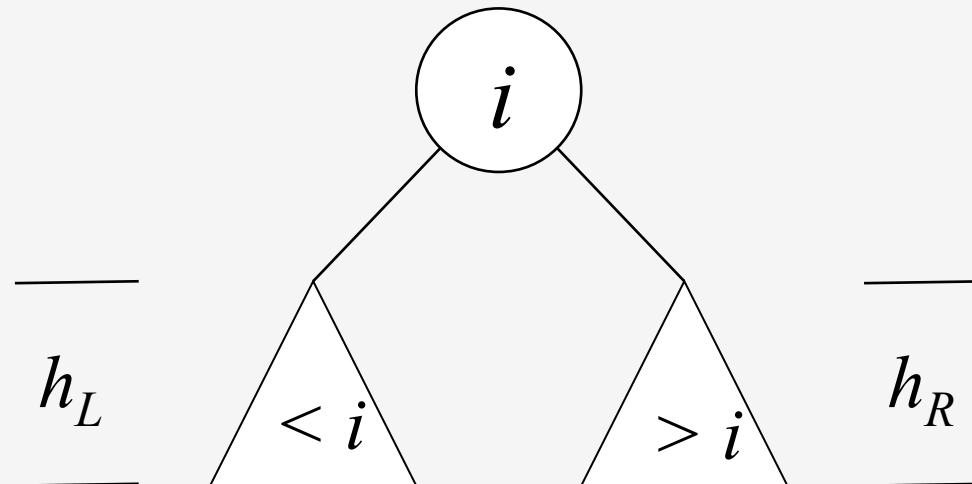
balanced BST



$$h(t) = O(\log N)$$

AVL Trees

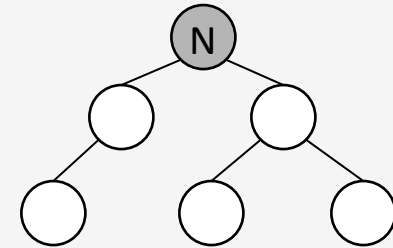
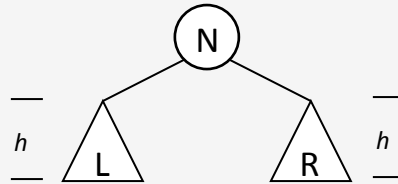
An AVL tree is a **binary search tree**
in which the heights of the left and right subtree
of *every* node differ by at most 1.



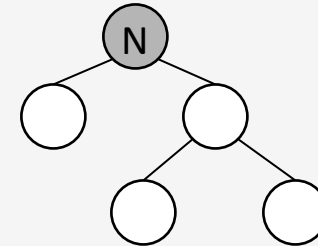
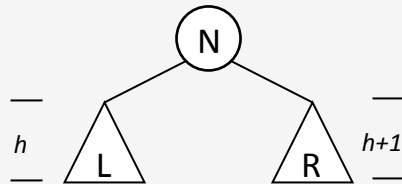
$$|h_R - h_L| \leq 1$$

Structural possibilities

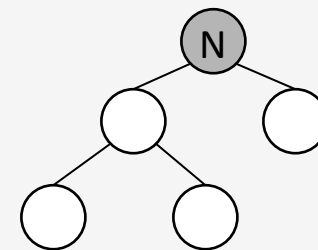
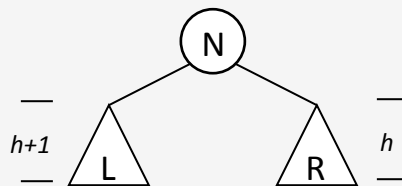
Equal heights



Right is 1 level taller



Left is 1 level taller



Balance factors

Every node in an AVL tree has a **balance factor**.

$$bf_N = h_R - h_L$$



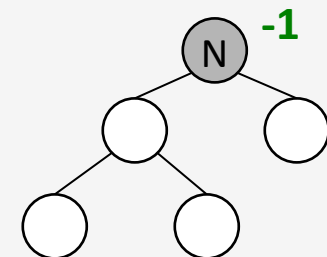
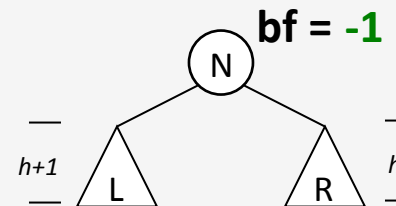
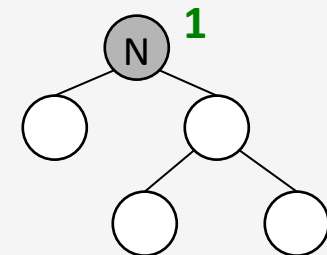
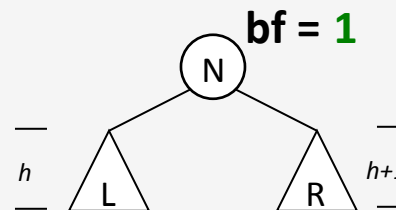
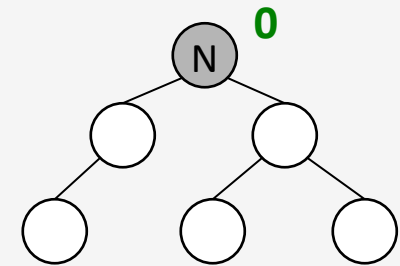
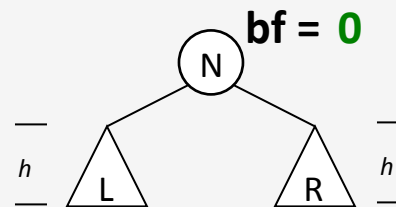
Remember to subtract heights, not balance factors.



The text counts path lengths differently from me.



Balance factors are sometimes computed as $h_L - h_R$.



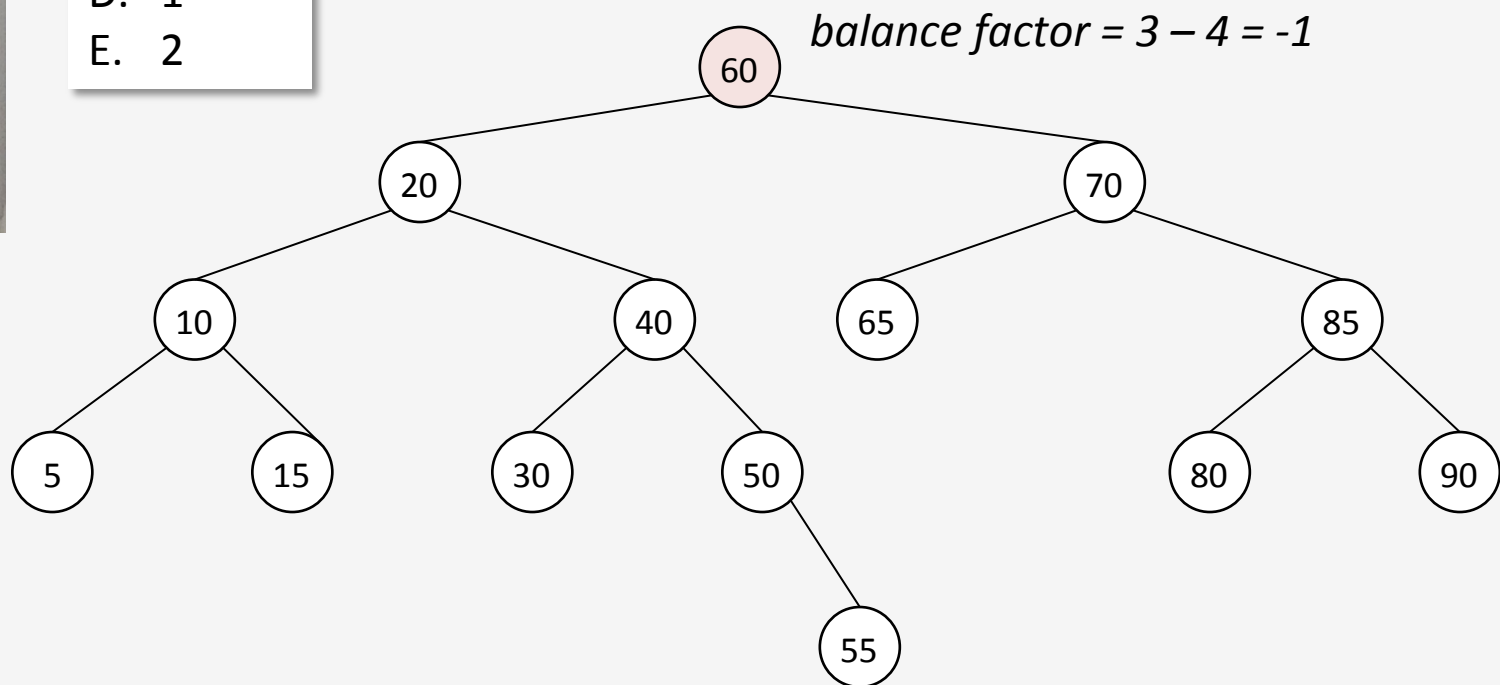
[illegible]

Participation question



Q. In the AVL tree below, what is the balance factor of the shaded node?

- A. -2
- B. -1
- C. 0
- D. 1
- E. 2

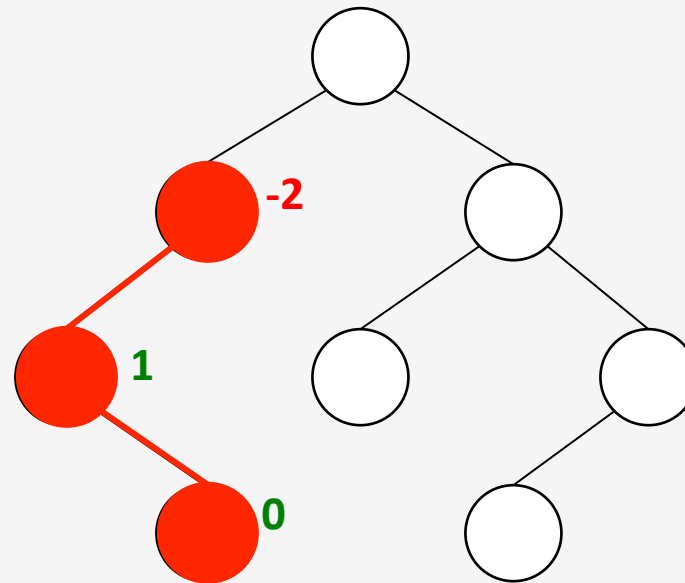


Rebalancing

A bf of ± 2 means that the subtree rooted at that node is out of balance.

Balance will be restored by subtree rotations.

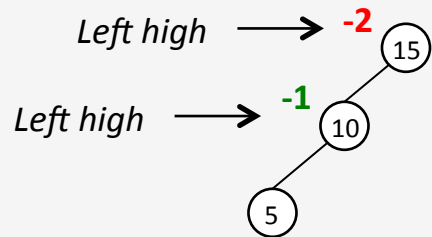
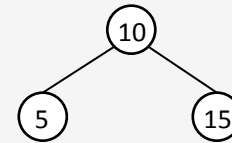
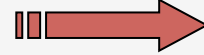
All rotations will occur in the context of a 3-node neighborhood.



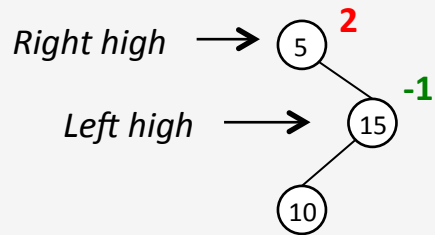
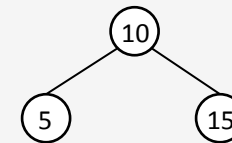
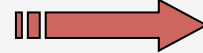
Rebalancing operations



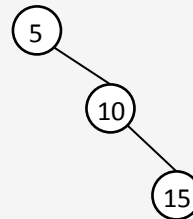
Left rotation



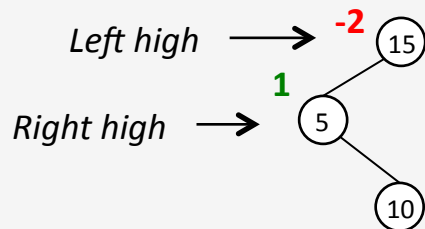
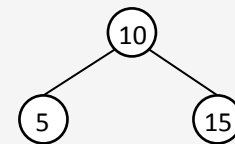
Right rotation



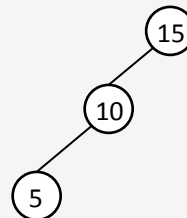
Right rotation



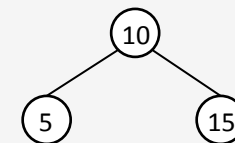
Left rotation



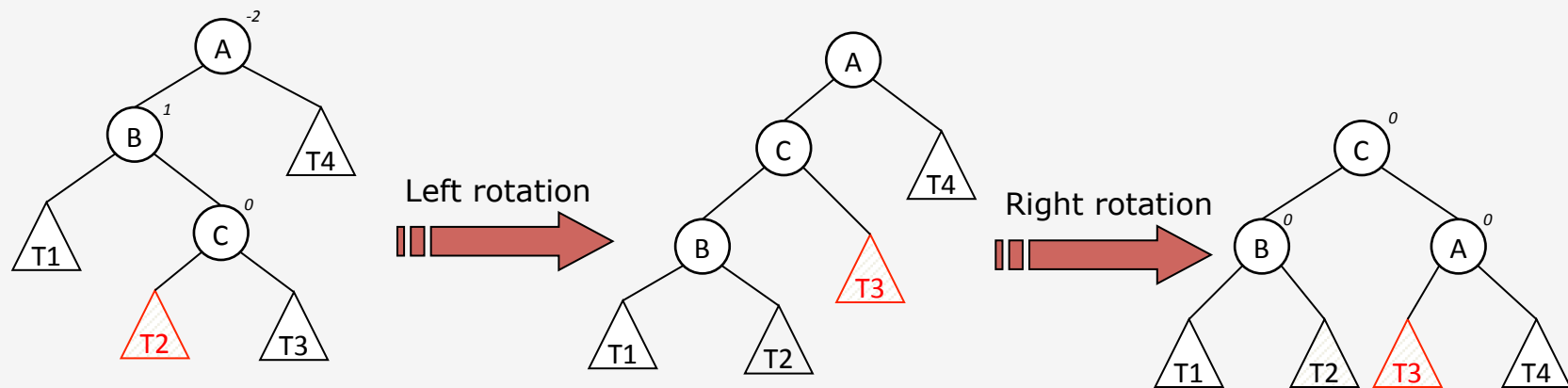
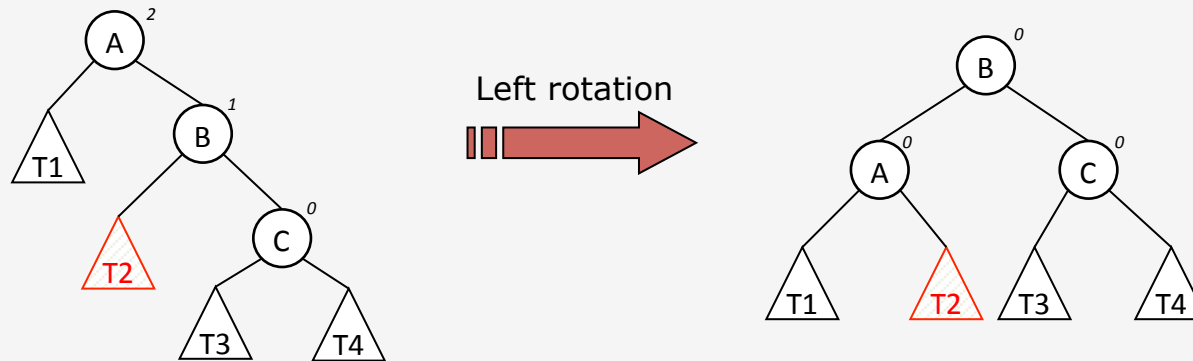
Left rotation



Right rotation



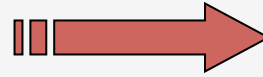
Subtree displacement



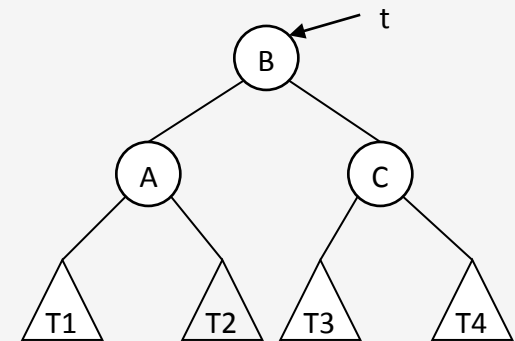
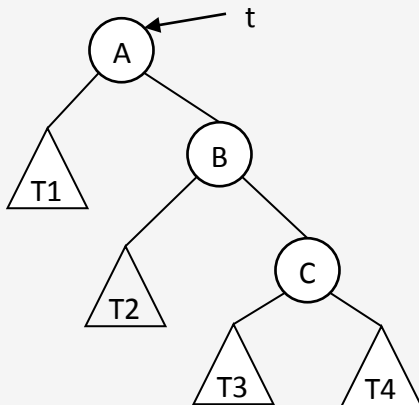
Coding rotations

t = rotateLeft(t);

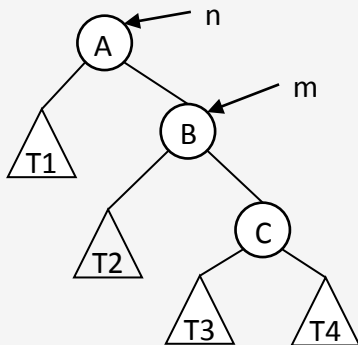
Left rotation around t



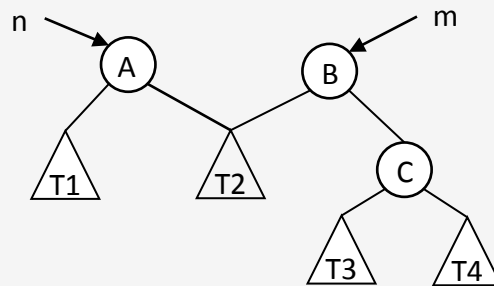
```
public BTN rotateLeft(BTN n)
{
    BTN m = n.right;
    n.right = m.left;
    m.left = n;
    return m;
}
```



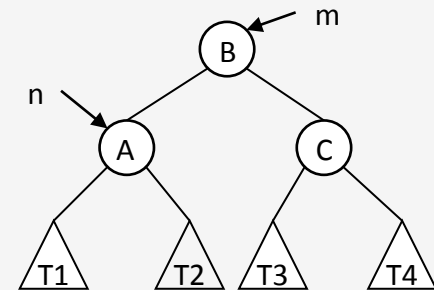
BTN m = n.right;



n.right = m.left;



m.left = n;



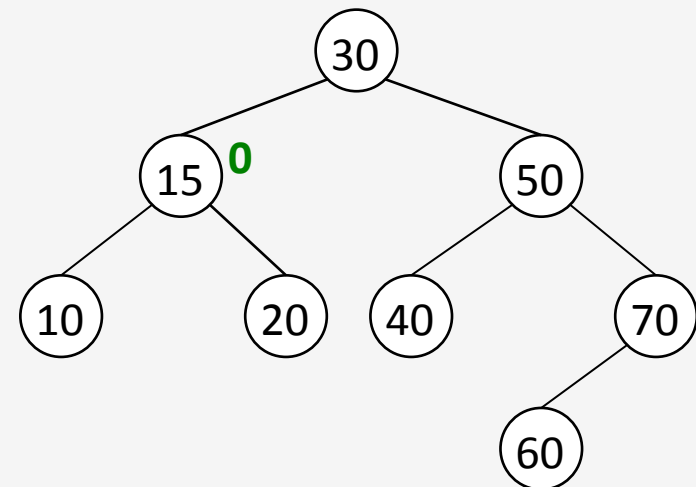
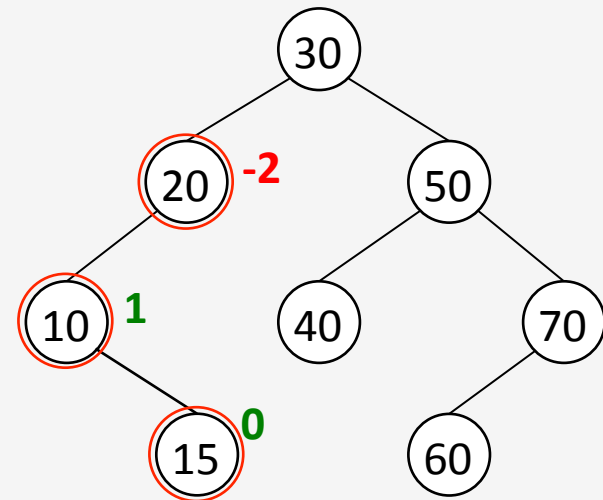
Inserting a new element

Use the standard BST insertion algorithm to insert the new node. (Ex: 15)

Beginning with the node just inserted, walk the reverse path back toward the root, recalculating balance factors.

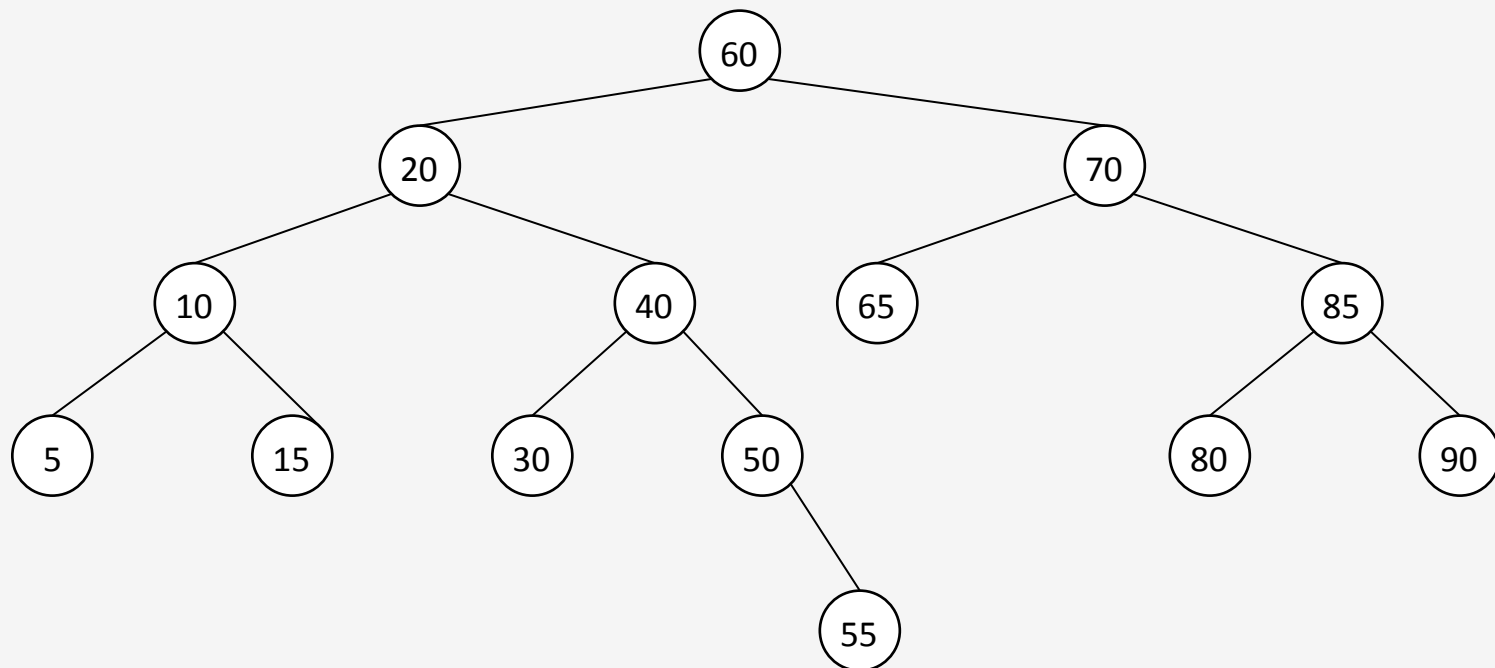
Stop at the first (lowest) node that has a balance factor of ± 2 . This node roots the 3-node neighborhood that will be rotated.

At most one rebalancing operation will be required per insertion.



Building an AVL tree

Insert: 10, 85, 15, 70, 20, 60, 30, 50, 65, 80, 90, 40, 5, 55



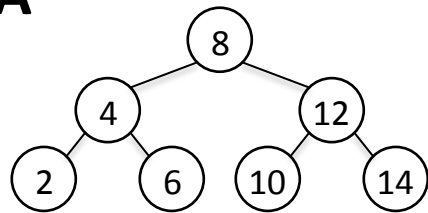
Participation question



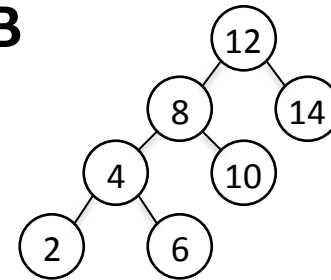
Q. Which AVL tree would result from inserting the following values in the order they are written?

14, 12, 10, 8, 6, 4, 2

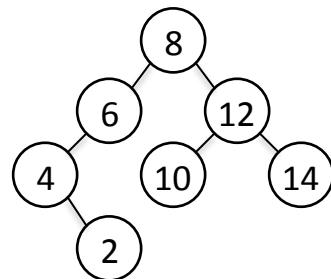
A



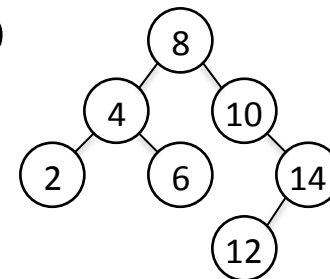
B



C



D



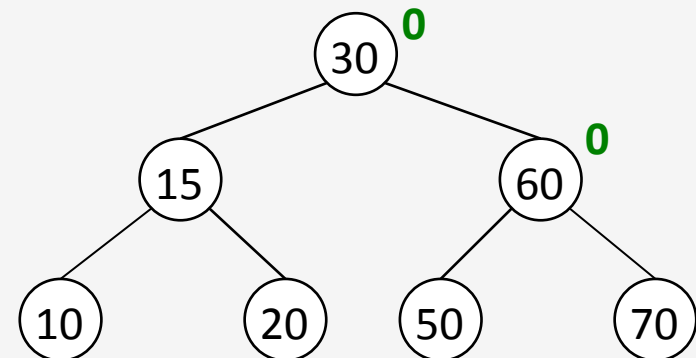
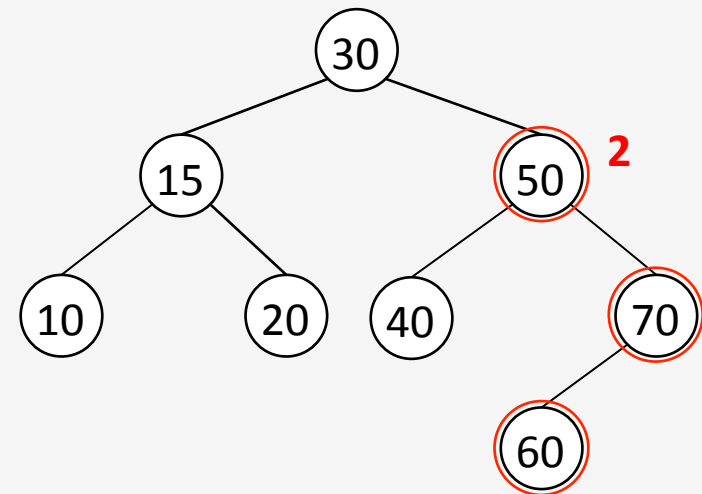
Deleting an element

Use the standard BST deletion algorithm to delete the element. Ex: 40

Beginning at the *point of deletion*, walk the reverse path back toward the root, recalculating balance factors.

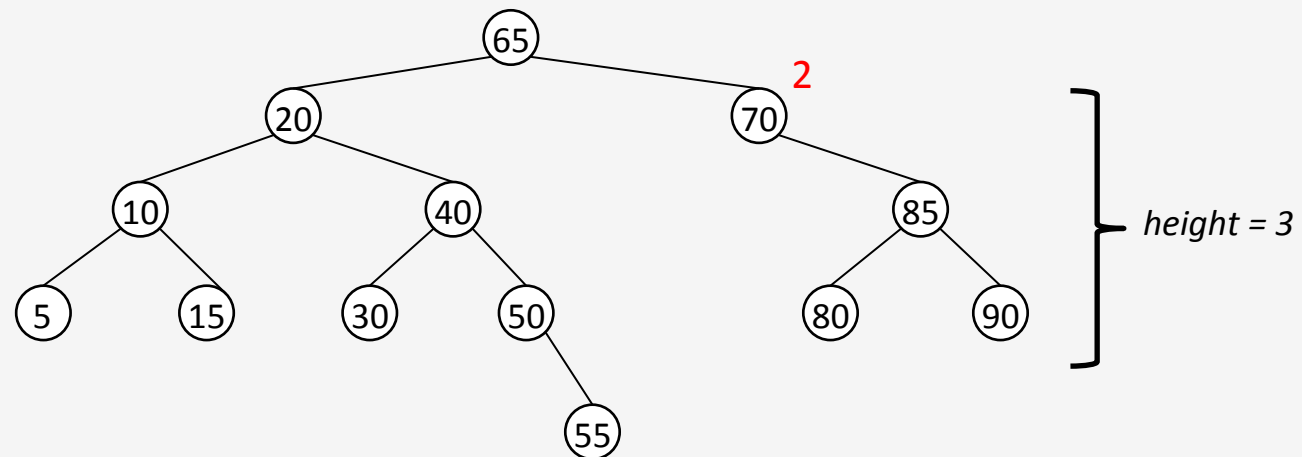
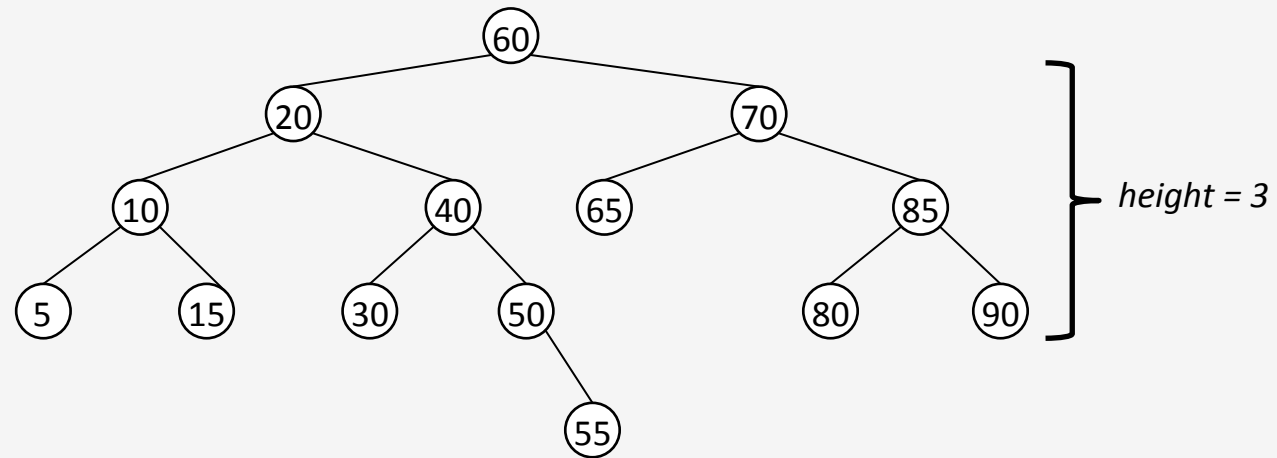
Stop at the first (lowest) node that has a balance factor of ± 2 . This node roots the 3-node neighborhood that will be rotated.

Multiple rebalancing operations may be required per deletion, so the reverse walk must go to the root each time.

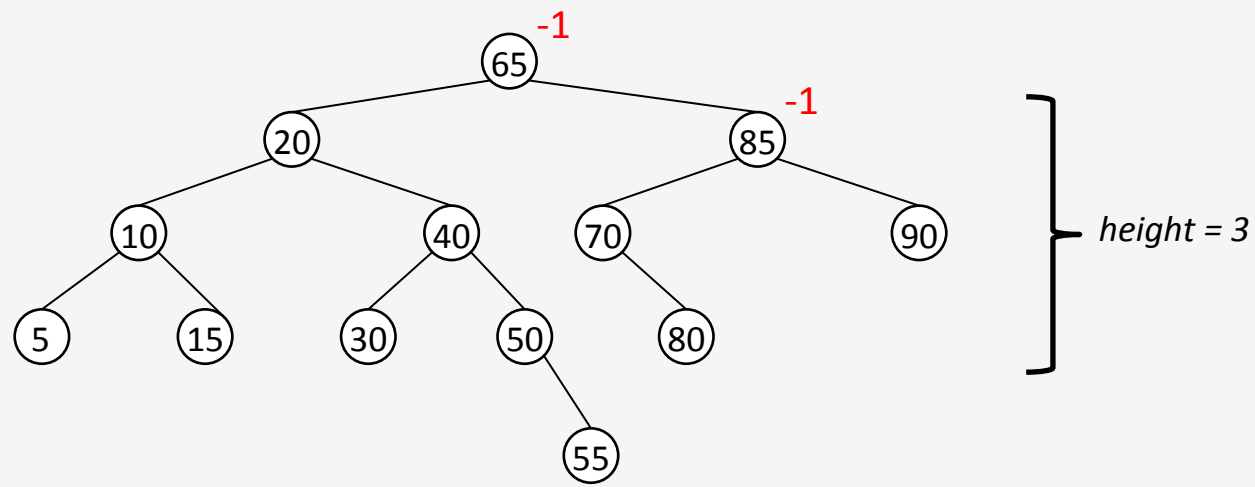
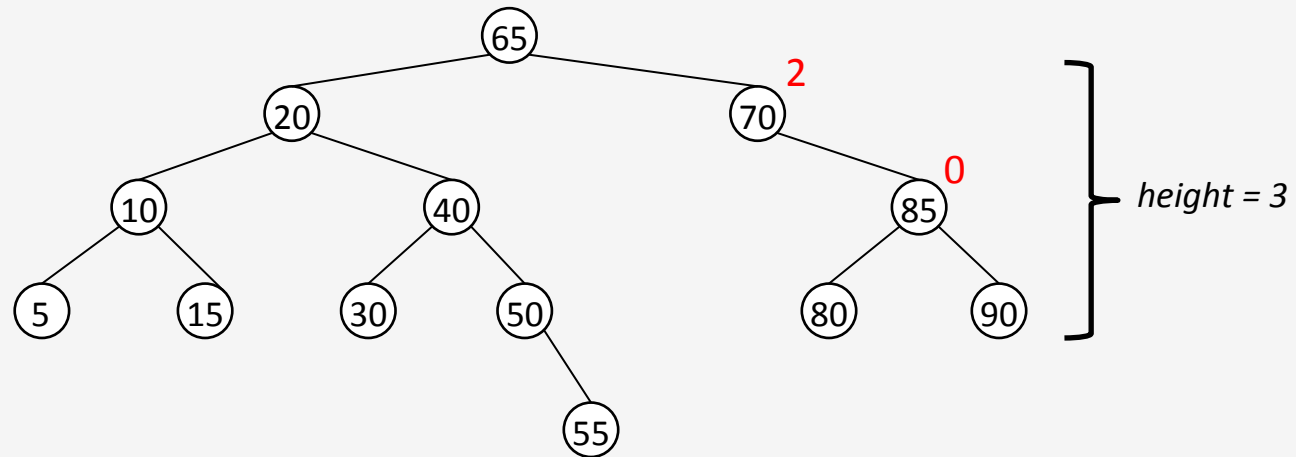


Example deletion

Delete 60:
(use successor)

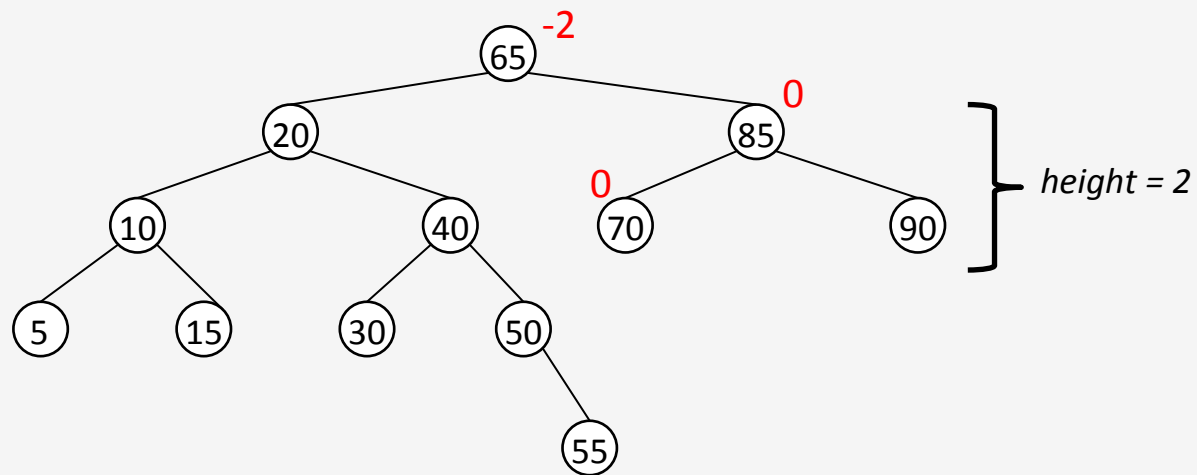
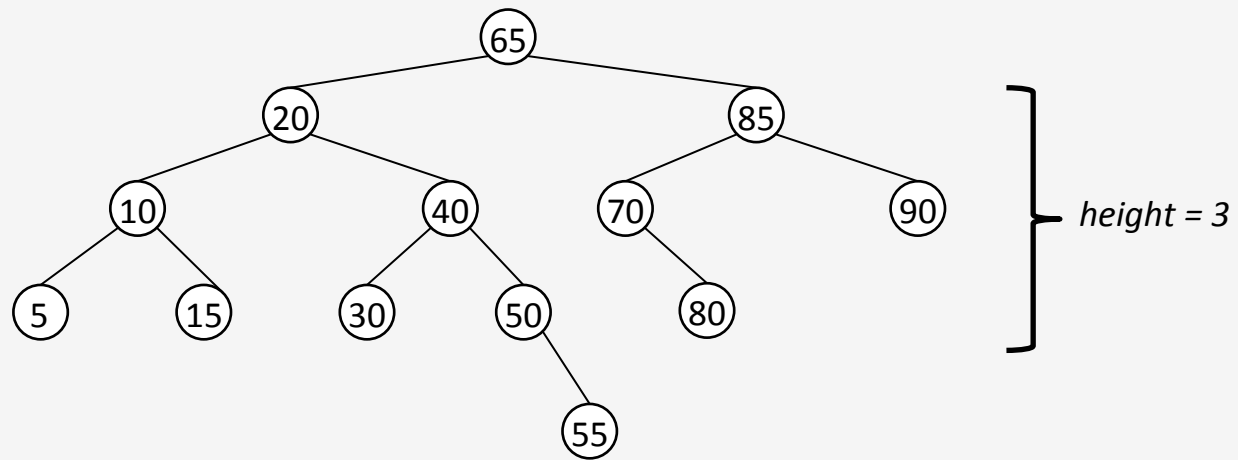


Example deletion

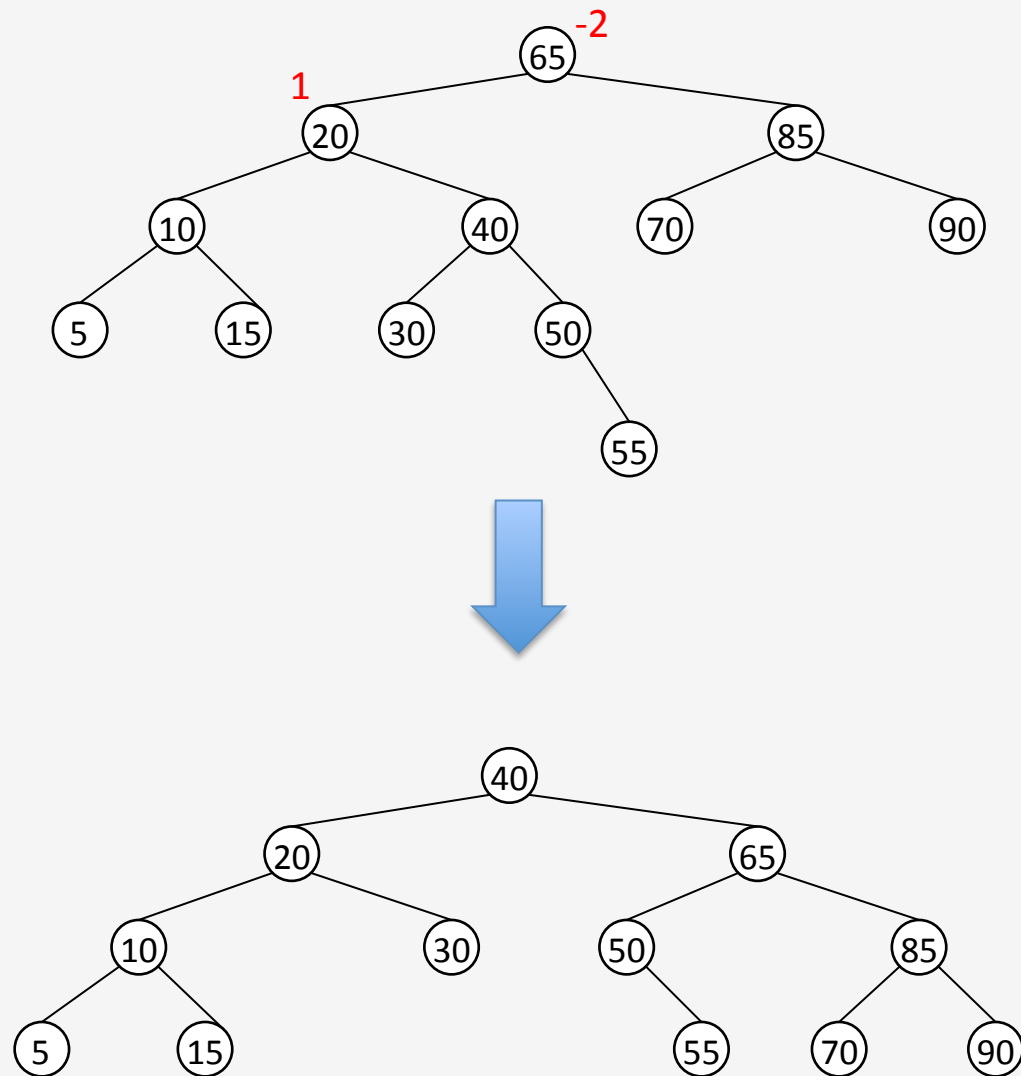


Example deletion

Delete 80:

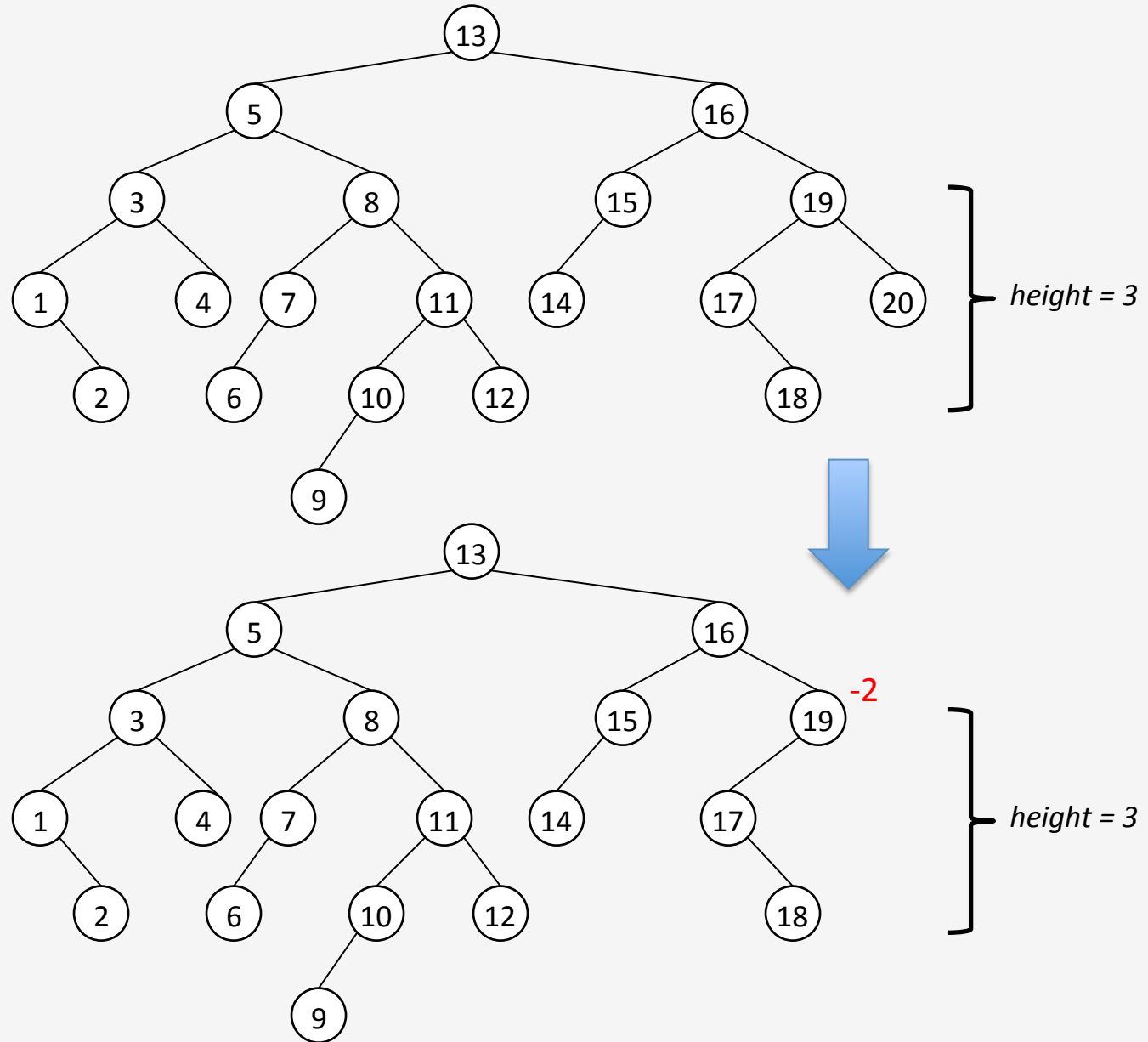


Example deletion

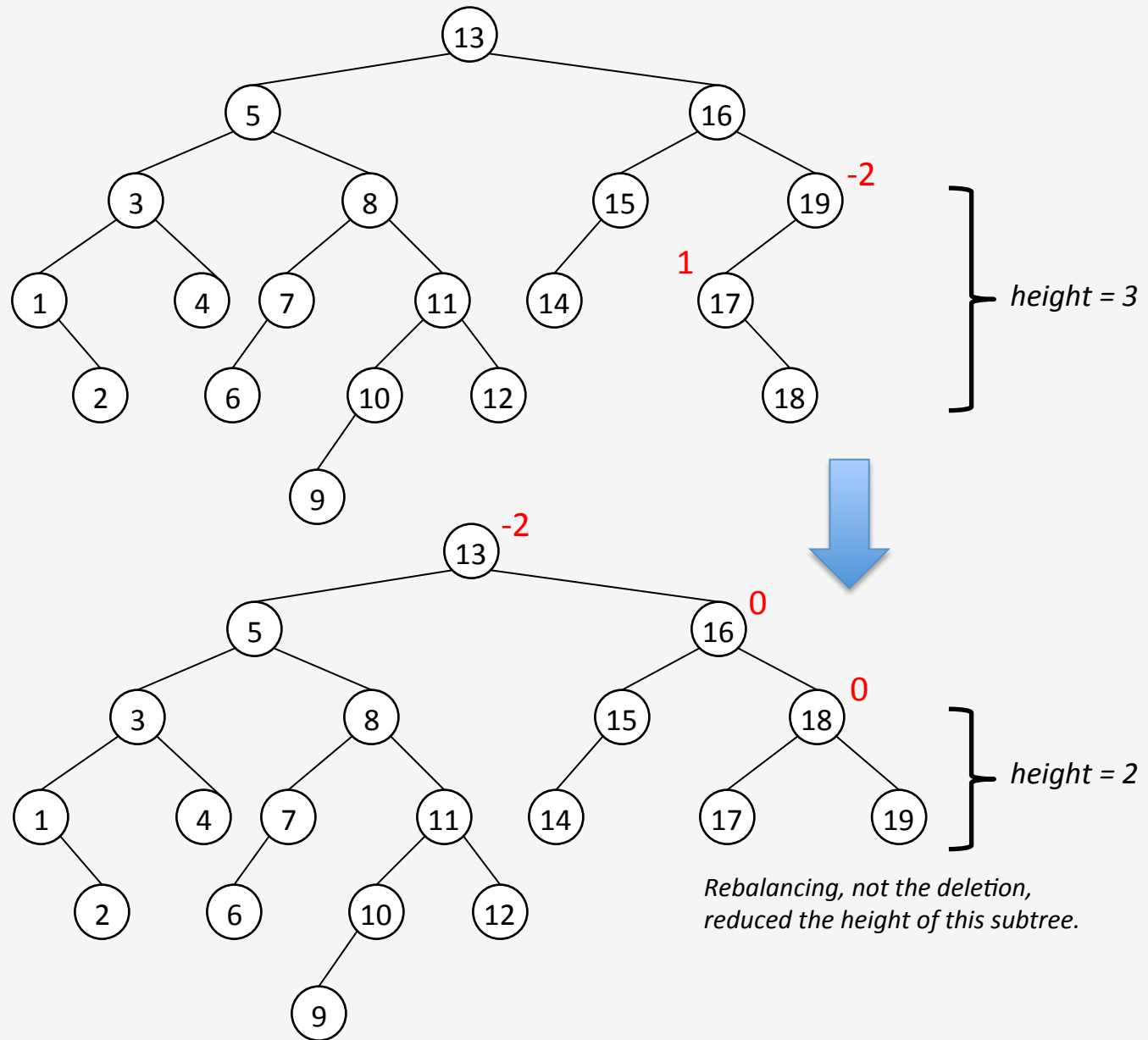


Example deletion

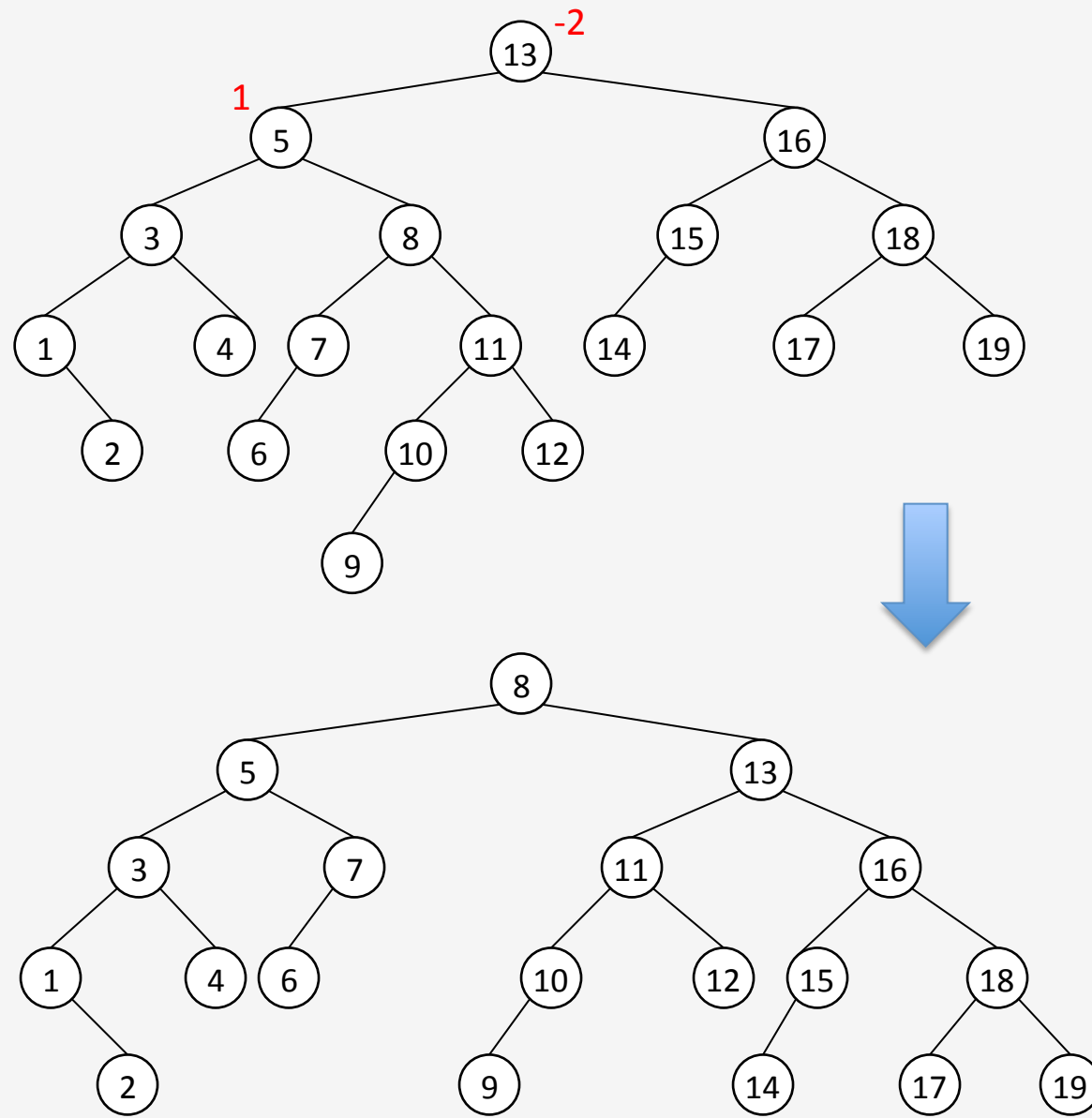
Delete 20:



Example deletion



Example deletion



Remind me: what's the point of all this?

Performance analysis of lists ...

Performance analysis

method	Indexed List		Non-indexed List		Self-ordered List	
	Array	Nodes	Array	Nodes	Array	Nodes
remove(element)	$O(N)$	$O(N)$	$O(N)$	$O(N)$	$O(N)$	$O(N)$
addAfter(element, target)	*	*	$O(N)$	$O(N)$	*	*
add(element)	$O(1)$	$O(1)$	*	*	$O(N)$	$O(N)$
add(index, element)	$O(N)$	$O(N)$	*	*	*	*
get(index)	$O(1)$	$O(N)$	*	*	*	*
indexOf(element)	$O(N)$	$O(N)$	*	*	*	*

Tell me why ... ☐ Tell me how... ☐

If we could use binary search on a node-based structure, then add() and remove() would be $O(\log N)$ – a huge improvement!

Stay tuned ... this is exactly where we're headed.

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Balanced binary search trees are like a structural implementation of the binary search algorithm.

So, now we can use binary search on a structure built with linked nodes.

AVL trees offer guaranteed $O(\log N)$ performance on all three major collection operations: add, remove, and search.

	Self-Ordered Lists		
	Array	Linked List	AVL Tree
add(element)	$O(N)$	$O(N)$	$O(\log N)$
remove(element)	$O(N)$	$O(N)$	$O(\log N)$
search(element)	$O(\log N)$	$O(N)$	$O(\log N)$