# **Trees**

COMP 2210 - Dr. Hendrix



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#### **Trees**

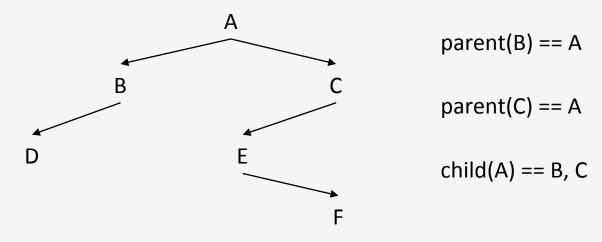
#### A tree is a collection in which the elements are arranged in a hierarchy.

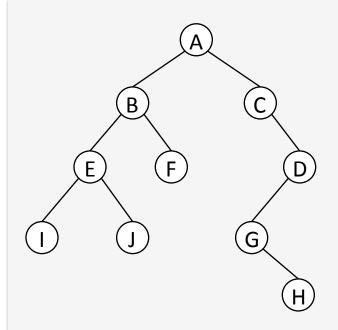
A **list** is a *one dimensional* structure because it defines *linear relationships* between elements: **predecessor**, **successor** 

A 
$$\longrightarrow$$
 B  $\longrightarrow$  C  $\longrightarrow$  D  $\longrightarrow$  E  $\longrightarrow$  F

successor(B) == C predecessor(C) == B

A **tree** is a *two dimensional* structure because it defines *hierarchical relationships* among elements: **parent, child** 





A tree is composed of nodes and branches.

**Node** – places in the tree where the elements are stored



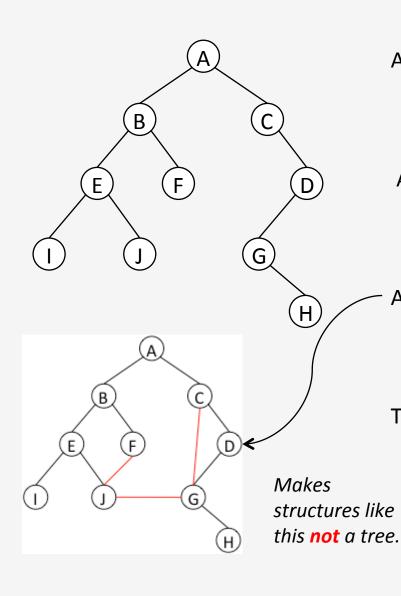
**Branches** – connections between nodes, from parent to child. Also called **edges**.





The terms "nodes" and "branches" are abstract and do not imply a particular implementation.

That is, we could implement a tree with either arrays or (physical) nodes and pointers.



A parent node has one or more children.

A, B, C, E, D, and G are parents.

A leaf node has no children.

I, J, F, and H are leaves.

A **child node** has exactly one parent.

B, C, E, F, D, I, J, G, H are children.

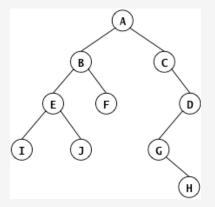
The **root node** has no parent

A is the root.

The **order** of a tree is an integer  $\geq 2$  that represents the upper limit on the number of children that any node can have.

Order = 2

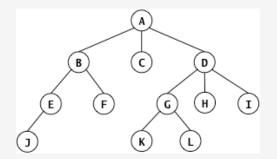
**Binary Tree** 



Each node can have at most 2 children.

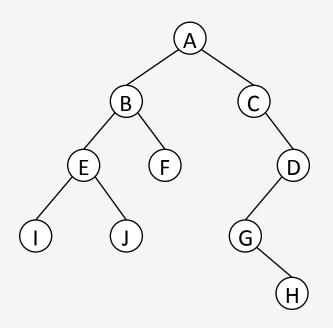
Order = 3

**Ternary Tree** 



Each node can have at most 3 children.

**General tree** = a tree with no specified order.



A path is sometimes defined as a sequence of edges instead of nodes.



So, path length is sometimes counted differently.

**Path** – a sequence of nodes from one node to another node, going from parent to child

Path from A to J = A-B-E-J

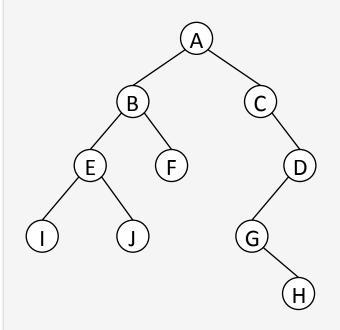
There is no path from J to A.

**Path length** – the number of nodes on the path

Path from A to J has length 4

**Ancestor** – Node X is an ancestor of node Y iff there is a path from X to Y

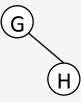
**Descendent**– Node X is an descendent of node Y iff there is a path from Y to X.



descendents of X.

**Example subtrees:** 





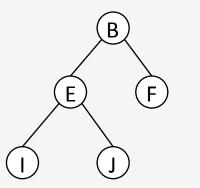
Subtree – A tree within a larger tree, rooted at a

given node X. The subtree consists of X and all

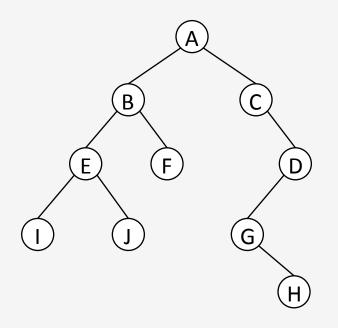


There are as many subtrees are there are nodes in the tree.

The tree itself is a subtree.



#### **Tree terminology – height**



Height depends on how path and path length are defined.



You will be off by one from the text.

Height is a metric that is defined in terms of a given node, but is typically used to describe a tree or subtree.

When height is applied a tree or subtree, it refers to the height of its root.

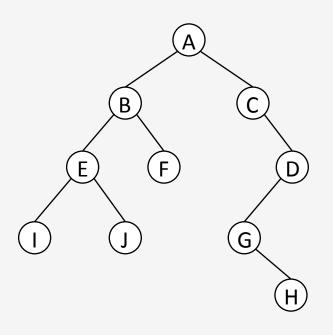
Height measures the distance of a given node from the "bottom" of the tree.

**Height** = length of the longest path from a given node to a descendent leaf

Height of A = 5 ← height of the tree

Height of B = 3 Height of J = 1 Height of H = 1

## Tree terminology – depth



Depth measures the distance of a given node from the "top" of the tree.

Depth is the same concept as "level" in the text.

**Depth** = length of the path from the root of the tree to a given node.



Depth depends on how path and path length are defined.

Depth of A = 1

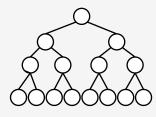
Depth of B = 2 Depth of J = 4 Depth of H = 5



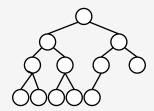
Depth of a leaf on the lowest level is the same as the height of the tree.



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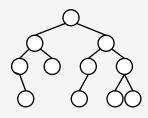


**Full** – A tree is full if all leaves have the same depth and every parent node has the maximum number of children.



**Complete** – A tree is complete if it is full to the next-to-last level, and the leaves on the lowest level are "left justified".

A full or complete tree is the shortest possible tree (minimum height) that could store N nodes.



**Balanced** – A tree is balanced if for each node, its subtrees have similar heights. The term "similar" is intentionally vague since different balancing schemes exist.

A balanced tree will have near-optimal height for storing N nodes.

# **Capacity v. Height**

# **Full Binary Tree** #Nodes (n) Tree Height (h) 3 2 3 15 $h = \lfloor \log_2 n \rfloor + 1 \qquad n = 2^h - 1$

# **Shapes and height**

height Many tree algorithms are dependent to some extent on the tree's height. full complete balanced  $h = \log_2(n+1)$ Height is O(logn)