

notes on program

```
int[] A = new int[10001];
```

*waste A[0]

use A[1]... A[10000]

*never use Attribute to get length, keep track with a variable

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*o.k. to pass size as a parameter
BUILD-MAX-HEAP(A)

$$2/4 = 0$$

$$2.0/4.0 = .5$$

notes

COUNTING-SORT(A, B, k)

for $j=1$ to A.length \leftarrow end of "this" for loop

Looking @ how deals w/ an array

A [2 5 3 0 2 3 0 3] $k=5$

C

0	1	2	3	4	5
11		11	111		1

 \Rightarrow [2 0 2 3 0 1]

B

1	2	3	4	5	6	7	8
						3	

A [2 5 3 0 2 3 0 3]

j indexes into A
get 3 from

A

							3
--	--	--	--	--	--	--	---

 \uparrow
 j

C

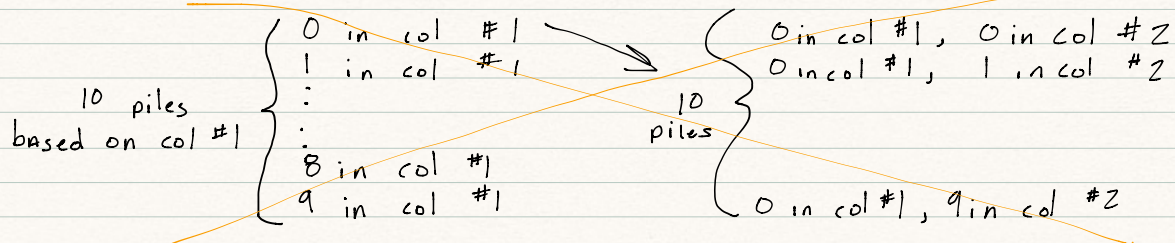
0	1	2	3	4	5
0	2	2	4	7	7

B

1	2	3	4	5	6	7	8
0	0	2	2	3	3	3	5

IBM used EBCDIC

IBM sorter



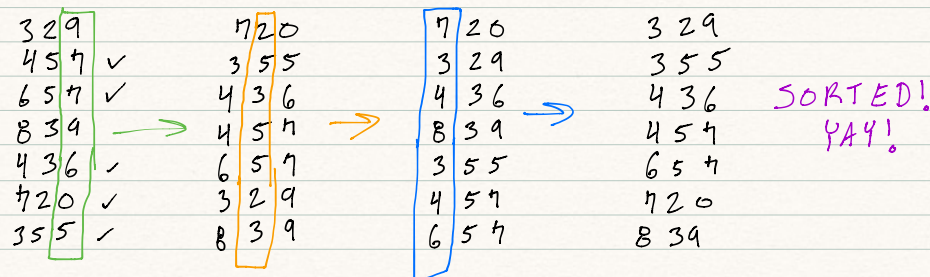
steps

- ① * sort on least significant column first
- ② (take all piles & restack in order of what's in sorted column)
- ③ sort on next least significant pile column
- ④ repeat from step 2 until sorted all columns

Time complexity of above steps is $\Theta(n)$ assuming fixed, finite radix (base) that the #'s are represented in

Assuming you use a STABLE sort for each digit

STABLE SORT - leaves duplicates in the sorted array in the same order they appeared in the input array (only matters when extra info stored w/ each sorting key)



So Stable Sort's time complexity = $\Theta(n)$

Let's say we have integers 0 to k , but don't want to do radix² sort b/c there is sparseness between #'s

So we

Divide input into sub-ranges (call them "buckets")

* Assume input numbers to be sorted are uniformly distributed over range $0 \dots k$ (range $0 \dots 1$ for pseudo-code EX's)

→ any value in the input array is equally likely to fall into any bucket

After bucket sort, Ch. 22