

## Document 6: Projections in Linear Space

Here are how projections work. We are given  $\vec{x}$  and line  $l$ , where  $l$  may be  $ax + by = c$  or  $\vec{u}$ . such that  $||u|| = 1$ . We want  $\text{proj}_l(\vec{x}) = \vec{x}^{\parallel}$ . We know  $\vec{x} = \vec{x}^{\parallel} + \vec{x}^{\perp}$ . Parallel and perpendicular are the vector components. Lets look at what our want looks like in mathematical terms:

$$T(\vec{x}) = \vec{x}^{\parallel}$$

$$\vec{x}^{\parallel} = k\hat{u}$$

$$\vec{x}^{\perp} = \vec{x} - \vec{x}^{\parallel} = \vec{x} - k\hat{u} \perp L(\hat{u})$$

$$\Rightarrow (\vec{x} - k\hat{u}) \cdot \hat{u} = 0$$

$$\vec{x} \cdot \hat{u} - k(\hat{u} \cdot \hat{u}) = 0$$

$$k||\hat{u}||^2 = \vec{x} \cdot \hat{u}$$

$$\Rightarrow k = \vec{x} \cdot \hat{u}$$

Our solution:  $\vec{x}^{\parallel} = (\vec{x} \cdot \hat{u})\hat{u}$ , so  $\text{proj}_L(\vec{x}) = (\vec{x} \cdot \hat{u})\hat{u}$ . This is how to find the projection for any matrix.

We introduce a new term, span, which lets us create planes between vectors. Consider the following.

$$\text{Let } \vec{x} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}, L = \text{span} \left\{ \begin{bmatrix} 4 \\ 3 \end{bmatrix} \right\} = \text{span}\{\vec{v}\}$$

$$L = c\vec{v}, ||\vec{v}|| = \sqrt{4^2 + 3^2} = 5$$

$$\text{Let } \vec{u} \text{ be a unit vector equal to } \hat{u}, \vec{u} = \frac{\vec{v}}{||\vec{v}||}$$

## MATRIX REPRESENTATIONS AND FORMULAS

Projections:

$$\begin{aligned} \text{proj}_L(\vec{x}) &= (\vec{x} \cdot \vec{u})\vec{u} = \left( \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \times \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \right) \times \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = (x_1 u_1 + x_2 u_2) \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \\ &= \begin{bmatrix} (u_1)^2 x_1 + u_1 u_2 x_2 \\ u_1 u_2 x_1 + (u_2)^2 x_2 \end{bmatrix} = \begin{bmatrix} (u_1)^2 & u_1 u_2 \\ u_1 u_2 & (u_2)^2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \end{aligned}$$

Reflections:

Begin with a line  $L$ , input vector  $\vec{x}$ , we want to get a reflection of the line, called  $\text{ref}_L(\vec{x})$ .

We begin with  $\vec{x} = \vec{x}^{\parallel} + \vec{x}^{\perp}$ . The reflection is  $\text{ref}_L(\vec{x}) = \vec{x}^{\parallel} - \vec{x}^{\perp} = \vec{x}^{\parallel} - (\vec{x} - \vec{x}^{\parallel}) = 2\vec{x}^{\parallel} - \vec{x}$ .

$$\text{So, } \text{ref}_L(\vec{x}) = 2\text{proj}_L(\vec{x}) - \vec{x} = 2 \begin{bmatrix} (u_1)^2 & u_1 u_2 \\ u_1 u_2 & (u_2)^2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Rotations (anticlockwise):

Visually, we have  $\vec{x}$  with a certain rise and run that we want to rotate. Imagine sweeping  $\vec{x}$  anticlockwise 90 degrees. The original  $x$  component would now be the  $y$ , and the original  $y$  component would now be the same magnitude of the new  $x$  component, but opposite direction. We call this new vector, orthogonal to  $\vec{x}$ ,  $\vec{y}$ . If we use more formal names, let's call the  $x$  component of  $\vec{x}$ ,  $x_1$ , and the  $y$  component of  $\vec{x}$ ,  $x_2$ . Thus we have the following.

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \perp \vec{y} = \begin{bmatrix} x_2 \\ -x_1 \end{bmatrix}$$

Both vectors are of equal magnitude. To find the  $\vec{x}$  rotated anticlockwise  $\theta$  degrees, we should scale each vector,  $\vec{x}$  by  $\cos(\theta)$ , and  $\vec{y}$  by  $\sin(\theta)$ . These two then become component vectors of our rotated vector. Thus, we have:

$$R_{\theta}(\vec{x}) = \cos(\theta)\vec{x} + \sin(\theta)\vec{y}$$

$$R_{\theta}(\vec{x}) = \cos(\theta) \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \sin(\theta) \begin{bmatrix} -x_2 \\ x_1 \end{bmatrix}$$

$$R_{\theta}(\vec{x}) = \begin{bmatrix} \cos(\theta)x_1 - \sin(\theta)x_2 \\ \cos(\theta)x_2 + \sin(\theta)x_1 \end{bmatrix} = \begin{bmatrix} \cos(\theta)x_1 - \sin(\theta)x_2 \\ \sin(\theta)x_1 + \cos(\theta)x_2 \end{bmatrix}$$

$$\text{Hence, } R_{\theta}(\vec{x}) = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$