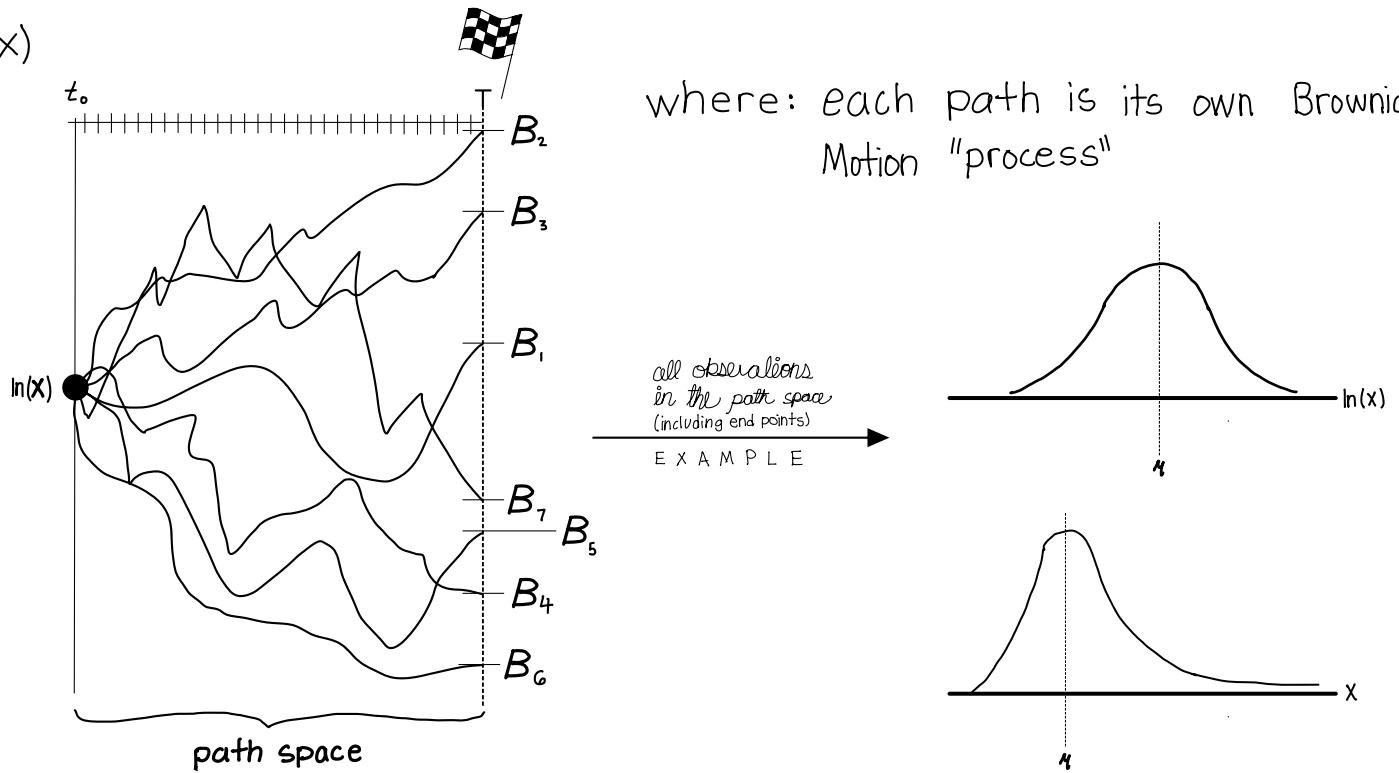


Random processes

a random process is a sequence of random values sampled from a distribution such as the normal distribution indexed by time, describing the evolution in time of a random phenomenon. The outcome is therefore probabilistic.

- a random process can be measured by its **mean**, **autocorrelation** (among the observations), **autocovariance**, **spectral density**, **average power**, **quadratic variation**, & probably several other metrics that you're unaware of.
- most popular random process: **Brownian Motion**, denoted B
- ex)

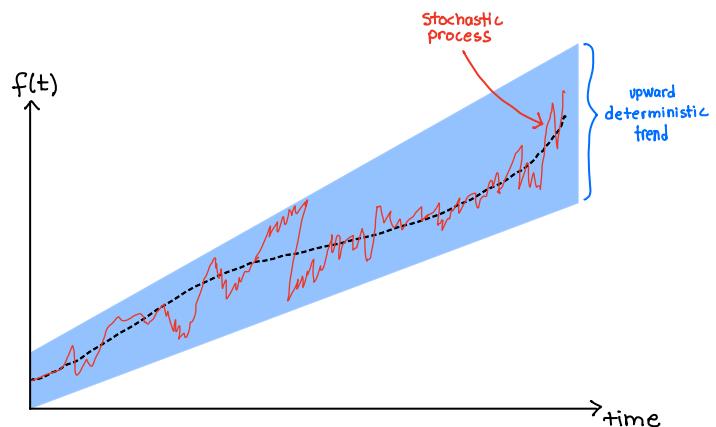
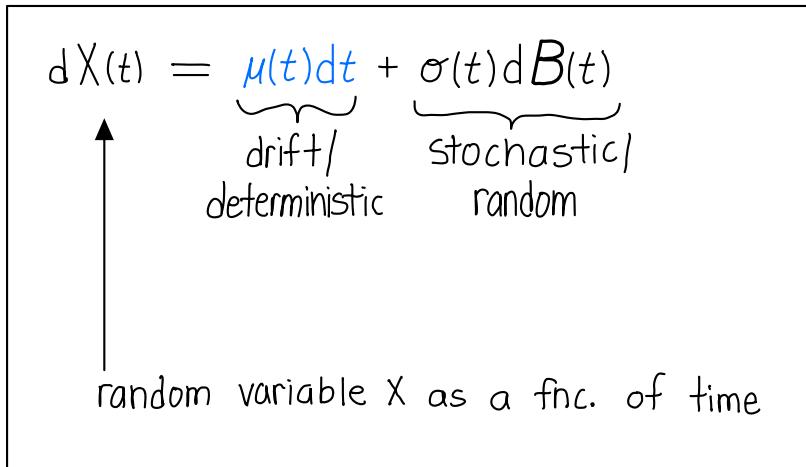


- our stochastic model is only as good as our assumption that $\ln(x)$ is normally distributed over time, for example. **Can use certain numeraires to strengthen this assumption (pg. 41).**
- BM was originally invented to model the erratic movement of microscopic particles in a fluid (scientific application).

Geometric Brownian Motion (GBM)

GBM is simply Brownian Motion with (linear) drift.

\hat{t} Process – pg.31



- $\mu(t) = 0 \Rightarrow$ standard BM = $\sigma(t)dB(t)$
- $\mu(t)dt$ is a constant \Rightarrow BM w/ constant drift *
- $\mu(t)$ is a constant, making $\mu(t)dt$ a linear fnc. of time *

* note that dt is typically held constant anyways, making these two things equivalent
(if dt and $\mu(t)$ are both held constant, then so is $\mu(t)dt$).

DEFINITION: geometric brownian motion

Given $\mu, \sigma > 0$ and $x_0 > 0$. The GBM is the continuous time process, X_t , that solves the SDE

$$dX_t = \mu X_t dt + \sigma X_t dB_t$$

volatility/diffusion coefficient

$X_0 = x_0$

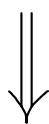
the change in values from one element of any given BM sequence to the next element

held constant

The solution is given by

$$X_t = x_0 \exp \left[\left(\mu - \frac{1}{2}\sigma^2 \right) t + \sigma B_t \right]$$

$$(dt)^2 = 0, \\ (dt)(dB) = 0, \\ (dB)^2 = dt.$$



Multiplication Table

dt	dB	
dt	0	0
dB	0	dt

Probability Spaces, Martingales, and Filtration for Brownian Motion

Ω denotes a probability space containing all possible "events"/sample points on which to define a BM

\mathcal{F} stands for a **natural filtration** through the time index of a BM denoting the amount of information known at time t before the next step; takes on an abstract mathematical structure (an abstract algebraic form) called a " σ -algebra"

$\mathcal{F}(t)$ = amount of information at time t = \tilde{X} 's path up to & including X_t = the BM up to time t

$\mathcal{F}(t)$ is independently and identically distributed (iid) in time

information accumulates over time s.t. $\mathcal{F}(0) \subset \mathcal{F}(1) \subset \mathcal{F}(2) \subset \dots \subset \Omega$

"filtration" refers to filtering out future information from the BM at time t .

3.3.4 Martingale Property for Brownian Motion

Theorem 3.3.4. *Brownian motion is a martingale.*

PROOF: Let $0 \leq s \leq t$ be given. Then

$$\begin{aligned} \mathbb{E}[W(t)|\mathcal{F}(s)] &= \mathbb{E}[(W(t) - W(s)) + W(s)|\mathcal{F}(s)] \\ &\stackrel{\text{↑}}{=} \mathbb{E}[W(t) - W(s)|\mathcal{F}(s)] + \mathbb{E}[W(s)|\mathcal{F}(s)] \\ &= \mathbb{E}[W(t) - W(s)] + W(s) \\ &\stackrel{\text{a random walk}}{=} W(s). \end{aligned}$$

does NOT hold for GBM, in which $\mu \neq 0$

Monte Carlo martingale gambling strategy:

$$C(t) = e^{-r(T-t)} \mathbb{E}_t^{\mathbb{P}^*}[S(T)-K]$$

$$Z = \frac{\text{underlying } X}{\text{numeraire } Y}$$

$$Z_t = \mathbb{E}\left(Z_u \underbrace{\left[\begin{array}{l} \text{all information available up to \&} \\ \text{including } t = \text{all the sim. events up to \& including } t \end{array} \right]}_{\mathcal{F}(t)}\right)$$