

Machine Learning Fall 2020 ——— Homework 3

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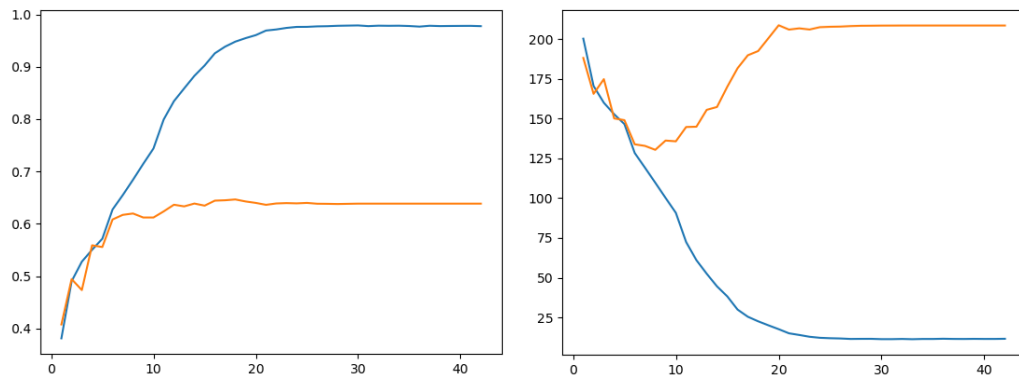
1. (1%) 請說明這次使用的 model 架構，包含各層維度及連接方式。

我的 model 使用了三層 CNN，具體結構如下：

```
self.cnn = nn.Sequential(  
    # Convolution 1 (1 * 48 * 48) -> (64 * 23 * 23)  
    nn.Conv2d(in_channels = 1, out_channels = 64, kernel_size = 3, stride = 1, ),  
    nn.BatchNorm2d(num_features = 64),  
    nn.LeakyReLU(negative_slope = 0.1),  
    nn.MaxPool2d(kernel_size = 2, stride = 2),  
  
    # Convolution 2 (64 * 23 * 23) -> (128 * 9 * 9)  
    nn.Conv2d(in_channels = 64, out_channels = 128, kernel_size = 6, stride = 1, ),  
    nn.BatchNorm2d(num_features = 128),  
    nn.LeakyReLU(negative_slope = 0.1),  
    nn.MaxPool2d(kernel_size = 2, stride = 2),  
  
    # Convolution 3 (128 * 9 * 9) -> (256 * 3 * 3)  
    nn.Conv2d(in_channels = 128, out_channels = 256, kernel_size = 4, stride = 1, ),  
    nn.BatchNorm2d(num_features = 256),  
    nn.LeakyReLU(negative_slope = 0.1),  
    nn.MaxPool2d(kernel_size = 2, stride = 2),  
)  
  
#Fully connection (256 * 3 * 3) -> (1024) -> (128) -> (7)  
self.fc = nn.Sequential(  
    nn.Linear(in_features = 256 * 3 * 3, out_features = 1024),  
    nn.LeakyReLU(negative_slope = 0.1),  
    nn.Dropout(p = 0.5),  
    nn.Linear(in_features = 1024, out_features = 128),  
    nn.LeakyReLU(negative_slope = 0.1),  
    nn.Dropout(p = 0.5),  
    nn.Linear(in_features = 128, out_features = 7)  
)
```

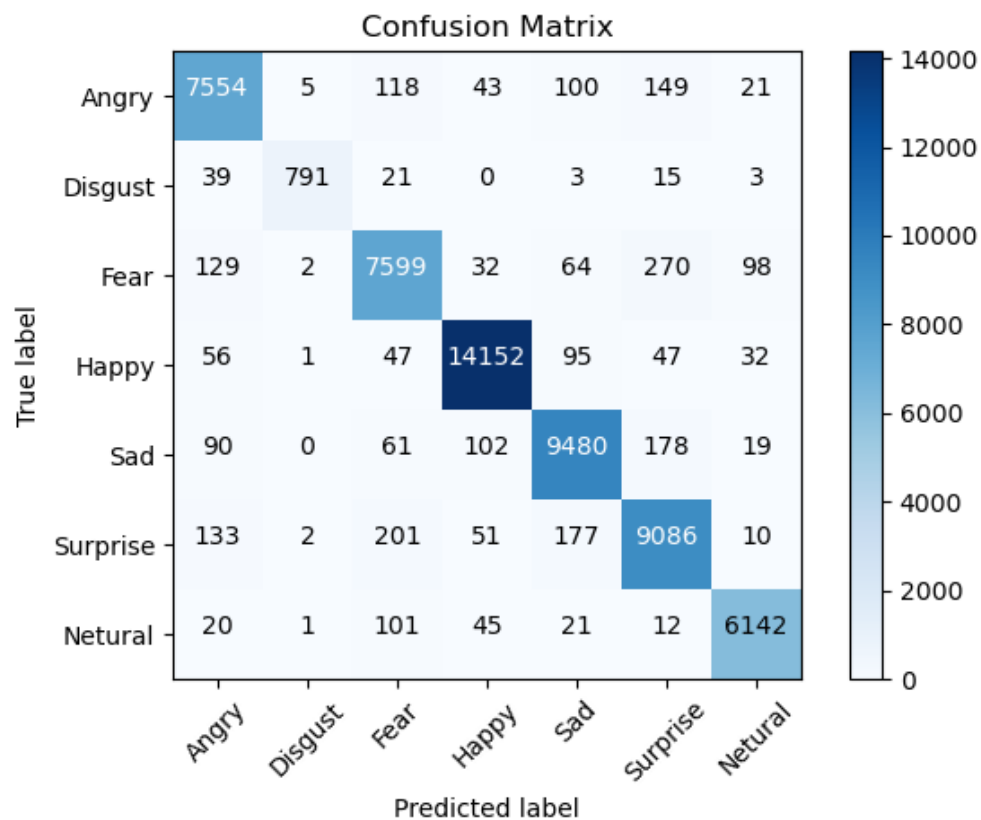
2. (1%) 請附上 model 的 training/validation history (loss and accuracy)。

我先將所有資料做左右翻轉得到兩倍資料後，再對全部資料的 90% 拿來做 training，10% 做 validation，在 batch size 為 128 時做 40 次 epoch 所得到結果如下。其中左圖為 training/validation 的 accuracy history，右圖為 training/validation 的 loss history。(藍線為 training，橘線為 validation)



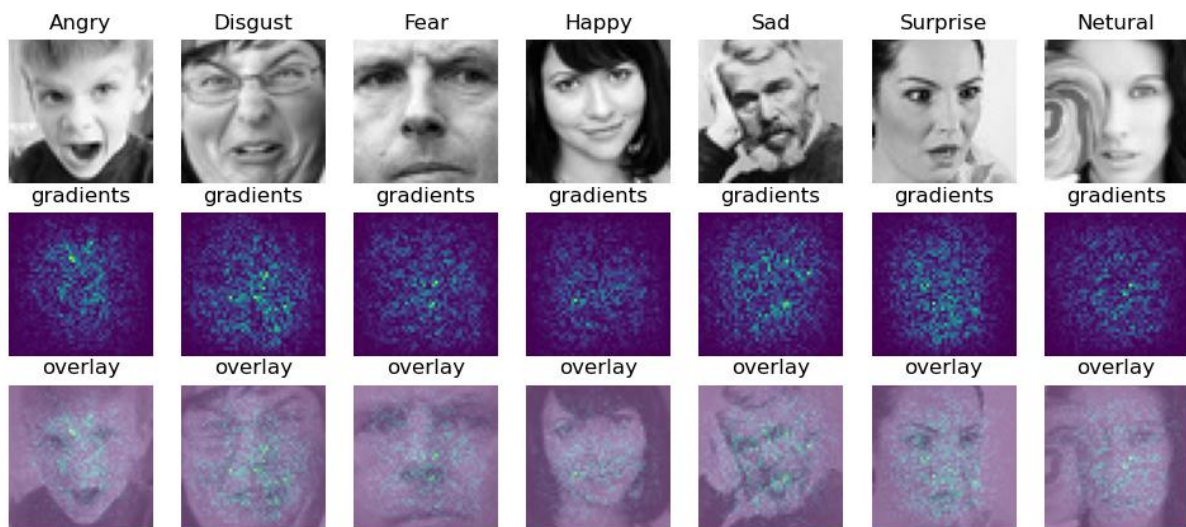
3. (1%) 畫出 confusion matrix 分析哪些類別的圖片容易使 model 搞混，並簡單說明。

下圖為原先資料加上左右翻轉的資料合計 57418 筆資料產生的 confusion matrix。



可以觀察出 Fear 跟 Surprise 彼此最容易使 model 搞混。推測原因為人類對這兩種情緒的反應較為相似(ex. 睜大眼睛、嘴巴)，導致 CNN 產生的結果也較為接近。

4. (1%) 畫出 CNN model 的 saliency map，並簡單討論其現象。



可以看出 gradient 再眼睛、鼻子及嘴巴等處數值較大，代表 model 主要是利用人的五官來辨識照片中人物的情緒。

5. (1%) 畫出最後一層的 filters 最容易被哪些 feature activate。

以下為我的 model 中最後一層的 256 筆 4×4 的 filters。



6. (3%) Refer to math problem

1.

設變化後大小變為 $(B^*, W^*, H^*, input_channels^*)$ 。

$$B^* = B$$

$$W^* = \frac{W + 2 * p_1 - k_1}{s_1} + 1$$

$$H^* = \frac{W + 2 * p_2 - k_2}{s_2} + 1$$

$$input_channels^* = output_channels$$

2.

由題目得到

$$\mu_B = \frac{1}{m} \sum_{i=1}^m x_i$$

$$\sigma_B^2 = \frac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2$$

$$\hat{x}_i = (x_i - \mu_B) \left(\sigma_B^2 + \epsilon \right)^{\frac{1}{2}}$$

$$y_i = \gamma \hat{x}_i + \beta$$

可推得

$$\frac{\partial l}{\partial \hat{x}_i} :$$

$$\frac{\partial l}{\partial \hat{x}_i} = \frac{\partial l}{\partial y_i} \frac{\partial y_i}{\partial \hat{x}_i} = \frac{\partial l}{\partial y_i} \gamma$$

$$\frac{\partial l}{\partial \sigma_B^2} :$$

$$\frac{\partial l}{\partial \sigma_B^2} = \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \frac{\partial \hat{x}_i}{\partial \sigma_B^2} = - \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \frac{1}{2} (x_i - \mu_B) \left(\sigma_B^2 + \epsilon \right)^{\frac{3}{2}}$$

$$\frac{\partial l}{\partial \mu_B} :$$

$$\begin{aligned}
\frac{\partial l}{\partial \mu_B} &= \sum_{i=1}^m \left(\frac{\partial l}{\partial \hat{x}_i} \frac{\partial \hat{x}_i}{\partial \mu_B} \right) + \frac{\partial l}{\partial \sigma_B^2} \frac{\partial \sigma_B^2}{\partial \mu_B} \\
&= - \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} + \frac{\partial l}{\partial \sigma_B^2} \frac{-2}{m} \sum_{i=1}^m (x_i - \mu_B) \\
&= - \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} + \frac{\partial l}{\partial \sigma_B^2} \frac{-2}{m} \left(\sum_{i=1}^m x_i - m\mu_B \right) \\
&= - \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} + \frac{\partial l}{\partial \sigma_B^2} \frac{-2}{m} \left(\sum_{i=1}^m x_i - \sum_{i=1}^m x_i \right) \\
&= - \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} + 0 = - \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}}
\end{aligned}$$

$$\frac{\partial l}{\partial x_i} :$$

$$\begin{aligned}
\frac{\partial l}{\partial x_i} &= \frac{\partial l}{\partial \hat{x}_i} \frac{\partial \hat{x}_i}{\partial x_i} + \frac{\partial l}{\partial \mu_B} \frac{\partial \mu_B}{\partial x_i} + \frac{\partial l}{\partial \sigma_B^2} \frac{\partial \sigma_B^2}{\partial x_i} \\
&= \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} + \frac{\partial l}{\partial \mu_B} \frac{1}{m} + \frac{\partial l}{\partial \sigma_B^2} \frac{2}{m} (x_i - \mu_B) \\
&= \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} - \frac{1}{m} \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} \\
&\quad - \frac{1}{m} (x_i - \mu_B) \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} (x_j - \mu_B) (\sigma_B^2 + \epsilon)^{-\frac{3}{2}} \\
&= \frac{\partial l}{\partial \hat{x}_i} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} - \frac{1}{m} \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} - \hat{x}_i \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \frac{\hat{x}_j}{m} (\sigma_B^2 + \epsilon)^{-\frac{1}{2}} \\
&= \frac{(\sigma_B^2 + \epsilon)^{-\frac{1}{2}}}{m} \left(m \frac{\partial l}{\partial \hat{x}_i} - \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} - \hat{x}_i \sum_{j=1}^m \frac{\partial l}{\partial \hat{x}_j} \hat{x}_j \right)
\end{aligned}$$

$$\frac{\partial l}{\partial \gamma} :$$

$$\frac{\partial l}{\partial \gamma} = \sum_{i=1}^m \frac{\partial l}{\partial y_i} \frac{\partial y_i}{\partial \gamma} = \sum_{i=1}^m \frac{\partial l}{\partial y_i} \hat{x}_i$$

$$\frac{\partial l}{\partial \beta} :$$

$$\frac{\partial l}{\partial \beta} = \sum_{i=1}^m \frac{\partial l}{\partial y_i} \frac{\partial y_i}{\partial \beta} = \sum_{i=1}^m \frac{\partial l}{\partial y_i}$$

3.

已知

$$\text{softmax}(z_t) = \frac{e^{z_t}}{\sum_i e^{z_i}}$$

$$\text{cross_entropy} = L_t(y, \hat{y}) = - \sum_i y_i \log \hat{y}_i$$

$$\text{cross_entropy} = L_t(y_t, \hat{y}_t) = -y_t \log \hat{y}_t$$

$$\hat{y}_t = \text{softmax}(z_t)$$

在 $y_t = 1$ 時 $\text{cross_entropy} = L_t(y_t, \hat{y}_t) = -y_t \log \hat{y}_t$ ，故

$$\begin{aligned} \frac{\partial L_t}{\partial z_t} &= - \frac{\partial}{\partial z_t} y_t \log \frac{e^{z_t}}{\sum_i e^{z_i}} \\ &= - \frac{\partial}{\partial z_t} y_t \left(\log e^{z_t} - \log \sum_i e^{z_i} \right) \\ &= -y_t \left(1 - \frac{e^{z_t}}{\sum_i e^{z_i}} \right) \\ &= -y_t (1 - \hat{y}_t) = \hat{y}_t y_t - y_t = \hat{y}_t - y_t \end{aligned}$$

在 $y_t = 0$ 時 $\text{cross_entropy} = L_t(y_t, \hat{y}_t) = -(1 - y_t) \log(1 - \hat{y}_t)$ ，故

$$\begin{aligned} \frac{\partial L_t}{\partial z_t} &= - \frac{\partial}{\partial z_t} (1 - y_t) \log \left(1 - \frac{e^{z_t}}{\sum_i e^{z_i}} \right) \\ &= - \frac{\partial}{\partial z_t} (1 - y_t) \left(\log \sum_{i, i \neq t} e^{z_i} - \log \sum_i e^{z_i} \right) \\ &= -(1 - y_t) \left(0 - \frac{e^{z_t}}{\sum_i e^{z_i}} \right) \\ &= (1 - y_t) \hat{y}_t = \hat{y}_t - y_t \hat{y}_t = \hat{y}_t - y_t \end{aligned}$$