Machine Learning Homework 5

1

由題目推得

$$h(x) = sign(wx + b) = sign(-(x - \frac{x_{M+1} + x_M}{2}))$$

 $w = -1$, $b = \frac{x_{M+1} + x_M}{2}$

答案為 [b].

 $\mathbf{2}$

由距離公式 $distance(x,b,w)=\frac{1}{\|w\|}|w^Tx+b|$ 加上條件 $y_n(w^Tx_n+b)\geq 1$ 推得最近的點到 decision boundary 的值為 $\|w\|^{-1}$ 以 $\min_{b,w}\frac{1}{2}w^Tw$ s.t. $y_n(w^Tz_n+b)\geq 1$ 使用 lagrange multiplier 得到 $L(b,w,a)=\frac{1}{2}w^Tw+\sum_{n=1}^N\alpha_n(1-y_n(w^Tz_n+b))$,經過上課一連串推導轉換為

$$\max_{all \ \alpha_n > 0, \sum y_n \alpha_n = 0, w = \sum \alpha_n y_n z_n} - \frac{1}{2} \| \sum_{n=1}^N \alpha_n y_n z_n \|^2 + \sum_{n=1}^N \alpha_n$$

在最佳解時其值與 $\frac{1}{2}||w||^2$ 相同。固

$$\frac{1}{\|w\|} = \left(2\sum_{n=1}^{N} \alpha_n - \|\sum_{n=1}^{N} \alpha_n y_n z_n\|^2\right)^{-1/2}$$

得到 (3)、(6) 符合, 答案為 [c].

3

將四點以 x,y 座標畫出來後可觀察出 decision boundary 與 y 軸平行,且該直線介於 x=0 與 x=1 之間且與兩者的距離比為 4:1,固得到 decision boundary 為 $x-\frac{4}{5}=0$,再代入 x_4 得到 $w_0(1-\frac{4}{5})\geq 1$ 推得 w=(5,0),進一步得到 b=-4。 答案為 [c].

4

Uneven margin SVM 的 lagrange multiplier 如下

$$\max_{all \ \alpha_n \ge 0} \frac{1}{2} w^T w + \sum_{n=1}^N [y_n = +1] \alpha_n (1 - y_n (w^T x_n + b)) + \sum_{n=1}^N [y_n = -1] \alpha_n (\rho^- - y_n (w^T x_n + b))$$

將其對 b 做偏微分得到

$$\frac{\partial L(w, b, \alpha)}{\partial b} = \sum_{n=1}^{N} [y_n = +1] - \alpha_n y_n + \sum_{n=1}^{N} [y_n = -1] - \alpha_n y_n = 0$$

$$\sum_{n=1}^{N} \alpha_n y_n = 0$$

因此上式中的b可以消除,之後再對 w_i 偏微分得到

$$\begin{split} \frac{\partial L(w,b,\alpha)}{\partial w_i} &= w_i - \sum_{n=1}^N \llbracket y_n = +1 \rrbracket - \alpha_n y_n x_{n,i} \\ &+ \sum_{n=1}^N \llbracket y_n = -1 \rrbracket - \alpha_n y_n x_{n,i} = 0 \\ w &= \sum_{n=1}^N \alpha_n y_n x_n \end{split}$$

因此可將原式化進一步轉化為

$$\max_{all \ \alpha_n \ge 0, \sum y_n \alpha_n = 0, w = \sum \alpha_n y_n x_n} -\frac{1}{2} \|\alpha_n y_n x_n\|^2 + \sum_{n=1}^N [y_n = +1] \alpha_n + \sum_{n=1}^N [y_n = -1] \rho^- \alpha_n$$

最後得到

$$\min_{\alpha} \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_{n} \alpha_{m} y_{n} y_{m} x_{n}^{T} x_{m} - \sum_{n=1}^{N} [y_{n} = +1] \alpha_{n} - \sum_{n=1}^{N} [y_{n} = -1] \rho^{-} \alpha_{n}$$

$$subject \ to \ \sum_{n=1}^{N} y_{n} \alpha_{n} = 0; \ \alpha_{n} \geq 0, for \ n = 1, 2, ..., N$$

答案為 [c].

5

我不會寫,但我猜答案是 [a].

6

題目要求的 $\Phi(x)$ 可看成是從 d 個維度中組合出 Q 個可重複的 x_i 的重複組合問題,故其維度為 $H_Q^d=C_{d-1}^{Q+d-1}=C_Q^{Q+d-1}$ 。 答案為 [a].

7

由距離公式推得

$$\|\Phi(x) - \Phi(x')\|^2 = \|\Phi(x)\Phi(x) - 2\Phi(x)\Phi(x') + \Phi(x')\Phi(x')\|$$
$$= K_2(x,x) - 2K_2(x,x') + K_2(x',x')$$

由於 x,x' 為單位向量,故 $K_2(x,x)=K_2(x',x')=(1+1)^2=4$,而 $K_2(x,x')$ 的最小值為 $x^Tx'=-1$ 時 $K_2(x,x')=(1-1)^2=0$,故 $\max\|\Phi(x)-\Phi(x')\|^2=4-0+4=8$ 。 答案為 [d].

8

由下列公式

$$w_{t+1} = w_t + y_{n(t)} \Phi(x_{n(t)})$$
$$w_t = \sum_{n=1}^{N} \alpha_t[n] \Phi(x_n)$$

可看出當 $(\Phi(x_{n(t)}), y_{n(t)})$ 分類錯誤時,對應到的 $\alpha_t[n(t)]\Phi(x_{n(t)})$ 會 更新為 $\alpha_t[n(t)]\Phi(x_{n(t)}) + y_{n(t)}\Phi(x_{n(t)}) = (\alpha_t[n(t)] + y_{n(t)})\Phi(x_{n(t)})$,故 $\alpha_{t+1}[n(t)] = \alpha_t[n(t)] + y_{n(t)}$ 。 答案為 [c]. 加上 lagrange multiplier 後得到下式

$$\max_{\alpha_n \ge 0, \beta_n \ge 0} \frac{1}{2} w^T w + \sum_{n=1}^N u_n \xi_n + \sum_{n=1}^N \alpha_n (1 - \xi_n - y_n (w^T \Phi(x_n) + b)) + \sum_{n=1}^N \beta_n (-\xi_n)$$

將其對 ξ_n 做偏微分得到

$$\frac{\partial L(w, b, \xi, \alpha, \beta))}{\partial \xi_n} = \mu_n - \alpha_n - \beta_n = 0$$

在不失其最佳性的情況下得到 $\beta_n=u_n-\alpha_n, 0\leq \alpha_n\leq u_n$,故可將 上式簡化為

$$\max_{0 \le \alpha_n \le u_n, \beta_n = u_n - \alpha_n} \frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n (1 - y_n (w^T \Phi(x_n) + b)) + \sum_{n=1}^N (u_n - \alpha_n - \beta_n) \xi_n$$
$$= \frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n (1 - y_n (w^T \Phi(x_n) + b))$$

之後如同一般的SVM一樣,對 b 做偏微後得到 $\sum_{n=1}^N \alpha_n y_n = 0$; 對 w_i 做偏微後得到 $w = \sum_{n=1}^N \alpha_n y_n \Phi(x_n)$,最後推得

$$\min_{\alpha} \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_n \alpha_m y_n y_m \Phi(x_n)^T \Phi(x_m) - \sum_{n=1}^{N} \alpha_n$$
subject to
$$\sum_{n=1}^{N} y_n \alpha_n = 0; \quad 0 \le \alpha_n \le u_n, \text{ for } n = 1, 2, ..., N$$

答案為 [a].

10

透過積分計算得到

$$\int_{0}^{1} (E_{smooth} - E_{hinge})^{2} d\rho = \int_{0}^{1} (\frac{1}{2} (1 - \rho^{2})^{2} d\rho = \int_{0}^{1} \frac{1}{4} (\rho^{4} - 2\rho^{2} + 1) d\rho$$
$$= \frac{1}{4} (\frac{1}{5} \rho^{5} - \frac{2}{3} \rho^{3} + \rho) \Big|_{0}^{1} = \frac{2}{15}$$

答案為 [e].

```
import numpy as np
import math
  import tqdm
return np.sum(y != predict) / y.shape[0]
 def OneLabelTransform(data, target):
      temp = data.copy()
      for i in range(len(temp)):
    if temp[i] == target:
        temp[i] = 1
    else:
                temp[i] = -1
      return np.array(temp).astype(np.int)
def MySVM(x_train, y_train, x_test, y_test, par, ReturnNode=False):
    prob = svm_problem(y_train, x_train)
    param = svm_parameter(par)
    model = svm_train(prob, param)
    p_label, p_acc, p_val = svm_predict(y_test, x_test, model, '-q')
     if ReturnNode:
    return E_01(y_test, p_label), model.nSV[0] + model.nSV[1]
else:
    return E_01(y_test, p_label)
      y_train, x_train = svm_read_problem('satimage.scale')
y_test, x_test = svm_read_problem('satimage.scale.t')
      p11, p12, p13, p14, p15, p16 = True, True, True, True, True, True
            y_train_5 = OneLabelTransform(y_train, 5)
           prob = svm_problem(y_train_5, x_train)
param = svm_parameter('-s 0 -t 0 -c 10 -q')
model = svm_train(prob, param)
p_label, p_acc, p_val = svm_predict(y_train_5, x_train, model, '-q')
            w = np.zeros(len(x_train) + 1)
            for i in range(model.l):
                  for node in model.SV[i]:
    if node.index == -1:
                        w[node.index] += model.sv_coef[0][i] * node.value
            print('Problem 11:', '|w| =', math.sqrt(np.dot(w, w)))
```

```
p12 or p13:
label, Ein, NodeNumber = [], [], []
          for i in range(2, 7):
    y_train_i = OneLabelTransform(y_train, i)
    par = '-s 0 -t 1 -d 3 -c 10 -g 1 -r 1 -q'
    ein, nn = MySVM(x_train, y_train_i, x_train, y_train_i, par, ReturnNode=True)
                 label.append(i)
Ein.append(ein)
NodeNumber.append(nn)
         if p12:
   ans = np.argmax(Ein)
   print('Problem 12:', 'OVA class =', label[ans], 'with Ein', Ein[ans])
                 ans = np.argmax(NodeNumber)
print('Problem 13:', 'Node number =', NodeNumber[ans])
          y_train_1 = OneLabelTransform(y_train, 1)
y_test_1 = OneLabelTransform(y_test, 1)
C, Eout = [0.01, 0.1, 1, 10, 100], []
         for c in C:
    par = '-s 0 -t 2 -g 10 -c ' + str(c) + ' -q'
    eout = MySVM(x_train, y_train_1, x_test, y_test_1, par)
    Eout.append(eout)
          ans = np.argmin(Eout)
print('Problem 14:', 'C =', C[ans], 'with Eout', Eout[ans])
         y_train_1 = OneLabelTransform(y_train, 1)
         y_test_1 = OneLabelTransform(y_test, 1)
G, Eout = [0.1, 1, 10, 100, 1000], []
          for g in 6:
   par = '-s 0 -t 2 -c 0.1 -g ' + str(g) + ' -q'
   eout = MySVM(x_train, y_train_1, x_test, y_test_1, par)
                 Eout.append(eout)
          ans = np.argmin(Eout)
print('Problem 15:', 'Gamma =', G[ans], 'with Eout', Eout[ans])
          T = 1000
          y_train_1 = OneLabelTransform(y_train, 1)
G = [0.1, 1, 10, 100, 1000]
score = np.zeros(len(G))
                i in tqdm.trange(T):
rd_val = np.random.choice(len(x_train), 200)
rd_tra = np.delete(np.array(np.arange(len(x_train))), rd_val)
x_val, y_val = np.array(x_train)[rd_val], np.array(y_train_1)[rd_val]
x_tra, y_tra = np.array(x_train)[rd_tra], np.array(y_train_1)[rd_tra]
                for g in G:
    par = '-s 0 -t 2 -c 0.1 -g ' + str(g) + ' -q'
    ev = MySVM(x_tra, y_tra, x_val, y_val, par)
    Eval.append(ev)
                 best = np.argmin(Eval)
score[best] += 1
                if(i > 0 and i % 100 == 0):
    print(score)
         ans = np.argmax(score)
print('Problem 16:', 'Gamma =', G[ans], 'for selected', score[ans], 'times')
__name__ == '__main__':
main()
```

答案依序為[a], [c], [e], [d], [b], [a].