

P1D-Lu-Lu

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#Lu Lu - P1D
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#1 For each value of n,n= 2,3,4,5, find the Greedy Path and Greedy \
    Cost for the TSP on n nodes using the weights given previously.
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#n=2
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```
#Greedy path: [0,1,0]
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```
#Greedy Cost: 16
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```
#n=3
```

```
#Greedy path: [0,2,1,0]
```

```
#Greedy Cost: 18
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```
#n=4
```

```
#Greedy path: [0,3,1,2,0]
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```
#Greedy Cost: 14
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```
#n=5
```

```
#Greedy path: [0,4,2,1,3,0]
```

```
#Greedy Cost: 16
```

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#Lu Lu - P1B
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#1. Test given code with an input of 2, 3, 4, and 5
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#The function PathEnumeration will input an integer called numNodes,\
    >1. The function will return the list of all Hamiltonian cycles\
    , on a complete graph, that start at a home node of 0.
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def PathEnumeration(numNodes):
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```
    SP=[[0]]
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```
    LP=[]
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```
    LPpathLengths=0
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while (LPpathLengths < numNodes):

    for i in range(1,len(SP)+1): #cycling through the short \
paths of SP
        for j in range(2, numNodes+1):#Append to SP[i] the \
numbers not in SP[i]
            doAppend=true
            for k in range(1, len(SP[i-1])+1): #see if j is in \
SP[i]

                if j==SP[i-1][k-1]+1:
                    doAppend=false
                    break

            if doAppend:
                LP.append(SP[i-1]+[j-1])

    LPpathLengths=len(LP[0])

    SP=LP
    LP=[]

#    print 'SP =', SP
return SP

PathEnumeration(2)
[[0, 1]]

PathEnumeration(3)
[[0, 1, 2], [0, 2, 1]]

PathEnumeration(4)
[[0, 1, 2, 3], [0, 1, 3, 2], [0, 2, 1, 3], [0, 2, 3, 1], [0, 3, 1, 2], [0, 3, 2, 1]]

PathEnumeration(5)
[[0, 1, 2, 3, 4], [0, 1, 2, 4, 3], [0, 1, 3, 2, 4], [0, 1, 3, 4, 2], [0, 1, 4, 2, 3], [0,
1, 4, 3, 2], [0, 2, 1, 3, 4], [0, 2, 1, 4, 3], [0, 2, 3, 1, 4], [0, 2, 3, 4, 1], [0, 2, 4,
1, 3], [0, 2, 4, 3, 1], [0, 3, 1, 2, 4], [0, 3, 1, 4, 2], [0, 3, 2, 1, 4], [0, 3, 2, 4,
1], [0, 3, 4, 1, 2], [0, 3, 4, 2, 1], [0, 4, 1, 2, 3], [0, 4, 1, 3, 2], [0, 4, 2, 1, 3],
[0, 4, 2, 3, 1], [0, 4, 3, 1, 2], [0, 4, 3, 2, 1]]

#2. Create a variable called "weights. This variable will be a \
list of lists refer to P1A
weights\
= [[0,8,7,2,1],[8,0,3,2,9],[7,3,0,10,8],[2,2,10,0,10],[1,9,8,10,0]]\

#test case for weights
#print weights[0][1]

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#3. Write a function called "goHome". This function will input a \
list of lists (which will actually be the output of \
thePathEnumeration function) and add the home node to each \
sublist. It will then return the new list of lists.
def goHome(list):
    for i in list:
        i.append(0) #add 0 at the end of each list for returning to \
point 0.
    return list

#test case for goHome
#list1=[[0],[0,1],[0,1,2]]
#print goHome(list1)

#4. Write a function called "getCost". This function will input a \
list of any length (such that corresponding weights are available\
).
def getCost(list):
    l=len(list)
    cost=0
    for i in range(0,l-1):
        cost+=weights[list[i]][list[i+1]] #add each weights between \
two points into cost for storing the total cost of the path
    return cost

#test case for getCost
#list=[0,3,2,1,0]
#print getCost(list)

#5. Write a function called "getAllCosts". This function will \
input a list of lists (which will actually be the output of the \
goHome function). It will return a new list of all the costs of \
each sublist.
def getAllCosts(list):
    allCost=[] #create a new list for storing the cost for each \
given path by the order of the list
    for i in list:
        allCost.append(getCost(i)) #for each list of input, using \
getCost to get the cost of the given path and put the results in \
allCost list
    return allCost

#test case for getAllCosts
#list=[[0,1,2,3,0],[0,1,3,2,0],[0,2,1,3,0]]
#print getAllCosts(list)

#Lu Lu - P1C

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#1 Write a function called bfTSP. This function will take an \
integer 2, 3, 4, or 5 as an input. This integer will be \
thenumber of nodes. Note that an input of 2 means you are only \
using nodes 0 and 1. An input of 3 means that you areusing nodes\
0, 1, and 2, etc.
def bfTSP(node):
    list=PathEnumeration(node)    #generate the all the lists
    homeList=goHome(list)         #get the total list of given nodes
    cost=getAllCosts(homeList)    #create list with all the cost in \
it with all the path
    minCost=min(cost)             #find the path with minimum cost
    location=cost.index(minCost)  #find the index of the minimum \
cost
    return homeList[location]     #using the index to find the path

#test case for bfTSP
#bfTSP(4)

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#2 Test your function for each integer 2, 3, 4, and 5.

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#Test for 2 nodes

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print "A solution to TSP with 2 nodes is ", bfTSP(2), "with a cost \
of ", getCost(bfTSP(2)), "."

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A solution to TSP with 2 nodes is [0, 1, 0] with a cost of 16 .

```

#Test for 3 nodes

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```

print "A solution to TSP with 3 nodes is ", bfTSP(3), "with a cost \
of ", getCost(bfTSP(3)), "."

```

A solution to TSP with 3 nodes is [0, 1, 2, 0] with a cost of 18 .

```

#Test for 4 nodes

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```

print "A solution to TSP with 4 nodes is ", bfTSP(4), "with a cost \
of ", getCost(bfTSP(4)), "."

```

A solution to TSP with 4 nodes is [0, 2, 1, 3, 0] with a cost of 14 .

```

#Test for 5 nodes

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```

print "A solution to TSP with 5 nodes is ", bfTSP(5), "with a cost \
of ", getCost(bfTSP(5)), "."

```

A solution to TSP with 5 nodes is [0, 3, 1, 2, 4, 0] with a cost of 16 .

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#Lu Lu - PID

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#2. Create a variable called ""gCosts. gCosts will be a list of \
length six. The first two entries will be zero. These \
'wontactually be used for anything. The next four entries will \
be the greedy costs from above.

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gCosts=[0,0,16,18,14,16]

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#3. Make a copy of the PathEnumeration function. Name the new copy \

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“”gbbPathEnumeration. Edit this to perform “”the pruning in the \
Greedy Branch and Bound Algorithm.
def gbbPathEnumeration(numNodes):

    SP=[[0]]
    LP=[]
    LPpathLengths=0

    while (LPpathLengths < numNodes):

        for i in range(1,len(SP)+1): #cycling through the short \
paths of SP
            for j in range(2, numNodes+1):#Append to SP[i] the \
numbers not in SP[i]
                doAppend=true
                for k in range(1, len(SP[i-1])+1): #see if j is in \
SP[i]
                    if j==SP[i-1][k-1]+1 or getCost(SP[i-1])>gCosts[\
numNodes]:
                        doAppend=false
                        break

                if doAppend:
                    LP.append(SP[i-1]+[j-1])

    LPpathLengths=len(LP[0])

    SP=LP
    LP=[]

#    print 'SP =', SP
    return SP

#Test case for gbbPathEnumeration(numNodes)
#gbbPathEnumeration(5)

```

```

#4. Write a function called gbbTSP. Similar to P1C, this function \
will take an integer 2, 3, 4, or 5 as an input. This integer will \
be the number of nodes. Note that an input of 2 means you are \
only using nodes 0 and 1. An input of 3 means that you are using \
nodes 0, 1, and 2, etc.
def gbbTSP(node):
    list=gbbPathEnumeration(node) #generate the branch list
    homeList=goHome(list)         #get the total list of given nodes
    cost=getAllCosts(homeList)     #create list with all the cost in \
it with all the path
    minCost=min(cost)             #find the path with minimum cost

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    location=cost.index(minCost) #find the index of the minimum \
    cost
    return homeList[location]    #using the index to find the path

#Test case for gbbTSP(node)
#gbbTSP(5)

# Test your function for each integer 2, 3, 4, and 5. Put these \
  tests in different cells. Each test should print a sentence which \
  includes the solution.

#Test for 2 nodes
print "A solution to TSP with 2 nodes is ", gbbTSP(2), "with a cost \
  of ", getCost(gbbTSP(2)), "."
A solution to TSP with 2 nodes is [0, 1, 0] with a cost of 16 .

#Test for 3 nodes
print "A solution to TSP with 3 nodes is ", gbbTSP(3), "with a cost \
  of ", getCost(gbbTSP(3)), "."
A solution to TSP with 3 nodes is [0, 1, 2, 0] with a cost of 18 .

#Test for 4 nodes
print "A solution to TSP with 3 nodes is ", gbbTSP(4), "with a cost \
  of ", getCost(gbbTSP(4)), "."
A solution to TSP with 3 nodes is [0, 2, 1, 3, 0] with a cost of 14 .

#Test for 5 nodes
print "A solution to TSP with 3 nodes is ", gbbTSP(5), "with a cost \
  of ", getCost(gbbTSP(5)), "."
A solution to TSP with 3 nodes is [0, 3, 1, 2, 4, 0] with a cost of 16 .

```