### Principles of Model Checking

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# Chapter 4: Regular Properties

## Principles of Model Checking

Christel Baier and Joost-Pieter Katoen

## Overview

- Automata on finite words
  - Regular safety property's bad prefixes constitute a regular language that can be recognized as a finite automaton (NFA or DFA)
- Model-checking regular safety properties
  - Reduce the safety property check problem to the invariantchecking problem in a product construction of TS with a finite automaton that recognized the bad prefixes of the safety property
- Automata on infinite words
  - Generalize the verification algorithm to a larger class of linear time properties: ω-regular properties
- $\square$  Model-checking  $\omega$ -regular properties
  - ω-regular properties can be represented by Buchi automata that is the key concept to verify ω-regular properties via a reduction to persistence checking

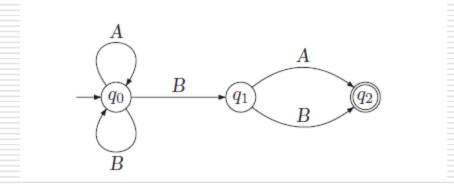
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### Automata on Finite Words

- Definition 4.1. Nondeterministic Finite Automaton (NFA)
- A nondeterministic finite automaton (NFA) A is a tuple A =  $(Q,\Sigma,\,\delta,Q0,\,F)$  where
- Q is a finite set of states,
- $\square$   $\Sigma$  is an alphabet,
- $\square$   $\delta$  : Q ×  $\Sigma \rightarrow 2^Q$  is a transition function,
- $\square$  Q0  $\subseteq$  Q is a set of initial states, and
- $\Box$  F  $\subseteq$  Q is a set of accept (or: final) states.

## An Example of a Finite-State Automaton



- $\square$  Q = { q0, q1, q2 },  $\Sigma$  = {A,B},
- $\square$  Q0 = { q0 }, F = { q2 },
- The transition function  $\delta$  is defined by  $\delta(q0,A) = \{q0\}, \ \delta(q0,B) = \{\ q0,\ q1\ \},$   $\delta(q1,A) = \{q2\}, \ \delta(q1,B) = \{\ q2\ \},$   $\delta(q2,A) = \emptyset, \ \delta(q2,B) = \emptyset$

## Automata on Finite Words

#### Definition 4.3. Runs, Accepted Language of an NFA

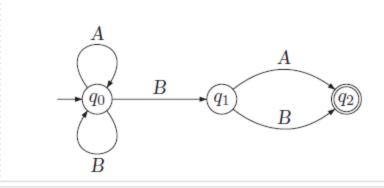
Let  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$  be an NFA and  $w = A_1 \dots A_n \in \Sigma^*$  a finite word. A run for w in  $\mathcal{A}$  is a finite sequence of states  $q_0 q_1 \dots q_n$  such that

- $q_0 \in Q_0$  and
- $q_i \xrightarrow{A_{i+1}} q_{i+1}$  for all  $0 \le i < n$ .

Run  $q_0 q_1 \dots q_n$  is called *accepting* if  $q_n \in F$ . A finite word  $w \in \Sigma^*$  is called *accepted* by  $\mathcal{A}$  if there exists an accepting run for w. The *accepted language* of  $\mathcal{A}$ , denoted  $\mathcal{L}(\mathcal{A})$ , is the set of finite words in  $\Sigma^*$  accepted by  $\mathcal{A}$ , i.e.,

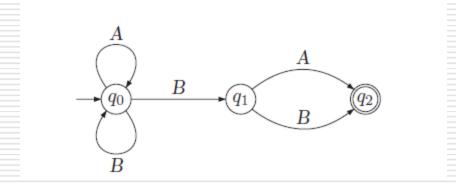
 $\mathcal{L}(\mathcal{A}) = \{ w \in \Sigma^* \mid \text{ there exists an accepting run for } w \text{ in } \mathcal{A} \}.$ 

# Runs and Accepted Words



| Runs        | Words                   |
|-------------|-------------------------|
| q0          | ε                       |
| q0 q0 q0 q0 | ABA, BBA, ABA, BBB, AAA |
| q0 q1 q2    | BA, BB                  |
| q0 q0 q1 q2 | ABB, ABA, BBA, BBB      |

## Runs and Accepted Words



- ☐ Accepting runs: runs that finish in the final state. (e.g., q0q1q2)
- Accepting words: words that can be represented by accepting runs. (e.g., ABA, BBB)
- $\square$  Accepting words belong to the accepted language L(A) that is given by the regular expression (A+B)\*B(A+B).

# Alternative Characterization of the Accepted Language

Lemma 4.5. Alternative Characterization of the Accepted Language
Let A be an NFA. Then:

$$\mathcal{L}(\mathcal{A}) = \{ w \in \Sigma^* \mid \delta^*(q_0, w) \cap F \neq \varnothing \text{ for some } q_0 \in Q_0 \}.$$

An equivalent alternative characterization of the accepted language of an NFA  $\mathcal{A}$  is as follows. Let  $\mathcal{A}$  be an NFA as above. We extend the transition function  $\delta$  to the function  $\delta^*: Q \times \Sigma^* \to 2^Q$  as follows:  $\delta^*(q, \varepsilon) = \{q\}, \ \delta^*(q, A) = \delta(q, A), \ \text{and}$ 

$$\delta^*(q, A_1 A_2 \dots A_n) = \bigcup_{p \in \delta(q, A_1)} \delta^*(p, A_2 \dots A_n).$$

Stated in words,  $\delta^*(q, w)$  is the set of states that are reachable from q for the input word w. In particular,  $\bigcup_{q_0 \in Q_0} \delta^*(q_0, w)$  is the set of all states where a run for w in A can end.

## Properties in NFA

#### Definition 4.6. Equivalence of NFAs

Let  $\mathcal{A}$  and  $\mathcal{A}'$  be NFAs with the same alphabet.  $\mathcal{A}$  and  $\mathcal{A}'$  are called equivalent if  $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}')$ .

#### Theorem 4.7. Language Emptiness is Equivalent to Reachability

Let  $A = (Q, \Sigma, \delta, Q_0, F)$  be an NFA. Then,  $\mathcal{L}(A) \neq \emptyset$  if and only if there exists  $q_0 \in Q_0$  and  $q \in F$  such that  $q \in Reach(q_0)$ .

#### Definition 4.8. Synchronous Product of NFAs

For NFA  $A_i = (Q_i, \Sigma, \delta_i, Q_{0,i}, F_i)$ , with i=1, 2, the product automaton

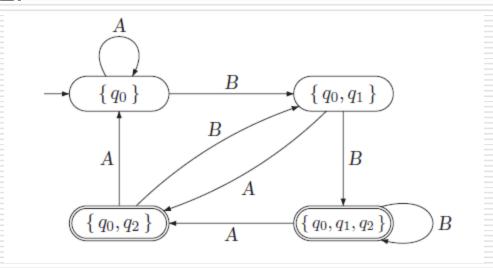
$$\mathcal{A}_1 \otimes \mathcal{A}_2 = (Q_1 \times Q_2, \Sigma, \delta, Q_{0,1} \times Q_{0,2}, F_1 \times F_2)$$

where  $\delta$  is defined by

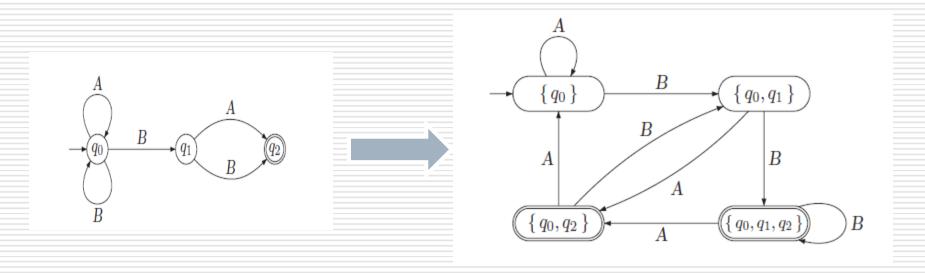
$$\frac{q_1 \xrightarrow{A}_1 q'_1 \land q_2 \xrightarrow{A}_2 q'_2}{(q_1, q_2) \xrightarrow{A} (q'_1, q'_2)}.$$

## Deterministic Finite Automaton (DFA)

Let  $A=(Q,\Sigma,\delta,Q0,F)$  be an NFA. A is called deterministic if |Q0|<=1 and  $|\delta(q,A)|<=1$  for all states  $q\in Q$  and all symbols  $A\in \Sigma$ . We will use the abbreviation DFA for a deterministic finite automaton. DFA A is called total if |Q0|=1 and  $|\delta(q,A)|=1$  for all  $q\in Q$  and all  $A\in \Sigma$ .



## **Powerset Construction**



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## Regular Safety Properties

Every trace that violates a safety property has a bad prefix that causes a refutation.

The set of bad prefixes constitutes a language of finite words over the alphabet  $\Sigma = 2^{AP}$ .

The input symbols  $A \in \Sigma$  of the NFA are now sets of atomic propositions AP.

E.g., 
$$AP = \{a, b\}$$
, then  $\Sigma = \{\{\}, \{a\}, \{b\}, \{a, b\}\}$ 

## Regular Safety Property

#### Definition 4.11. Regular Safety Property

Safety property  $P_{safe}$  over AP is called regular if its set of bad prefixes constitutes a regular language over  $2^{AP}$ .

Every invariant is a regular safety property. If  $\Phi$  is the state condition (propositional formula) of the invariant that should be satisfied by all reachable states, then the language of bad prefixes consists of the words  $A_0 A_1 \dots A_n$  such that  $A_i \not\models \Phi$  for some  $0 \leqslant i \leqslant n$ . Such languages are regular, since they can be characterized by the (casually written) regular notation

$$\Phi^*(\neg \Phi)$$
 true\*.

Here,  $\Phi$  stands for the set of all  $A \subseteq AP$  with  $A \models \Phi$ ,  $\neg \Phi$  for the set of all  $A \subseteq AP$  with  $A \not\models \Phi$ , while true means the set of all subsets A of AP. For instance, if  $AP = \{a, b\}$  and  $\Phi = a \lor \neg b$ , then

- $\Phi$  stands for the regular expression  $\{\} + \{a\} + \{a,b\},\$
- ¬Φ stands for the regular expression consisting of the symbol { b },
- true stands for the regular expression  $\{\} + \{a\} + \{b\} + \{a,b\}$ .

## Regular Safety Property

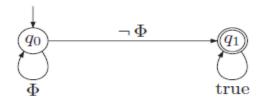
$$\Phi^*(\neg \Phi) \text{ true}^*. \qquad \Phi = a \vee \neg b$$

- $\Phi$  stands for the regular expression  $\{\} + \{a\} + \{a,b\},\$
- $\neg \Phi$  stands for the regular expression consisting of the symbol  $\{b\}$ ,
- $\bullet \,$  true stands for the regular expression  $\{\} + \{\, a\, \} + \{\, b\, \} + \{\, a, b\, \}.$

The bad prefixes of the invariant over condition  $a \vee \neg b$  are given by the regular expression:

$$\mathsf{E} = \underbrace{(\{\} + \{a\} + \{a,b\})^*}_{\Phi^*} \underbrace{\{b\}}_{\neg \Phi} \underbrace{(\{\} + \{a\} + \{b\} + \{a,b\})^*}_{\text{true}^*}.$$

Thus,  $\mathcal{L}(\mathsf{E})$  consists of all words  $A_1 \dots A_n$  such that  $A_i = \{b\}$  for some  $1 \leq i \leq n$ . Note that, for  $A \subseteq AP = \{a,b\}$ , we have  $A \not\models a \vee \neg b$  if and only if  $A = \{b\}$ . Hence,  $\mathcal{L}(\mathsf{E})$  agrees with the set of bad prefixes for the invariant induced by the condition  $\Phi$ .



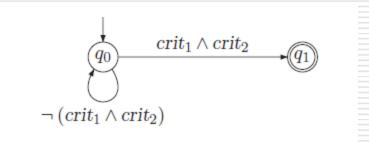
# Example: Regular Safety Property for Mutual Exclusion Algorithms

Consider a mutual exclusion algorithm such as the semaphore-based one or Peterson's algorithm. The bad prefixes of the safety property P\_mutex ("there is always at most one process in its critical section") constitute the language of all finite words A0 A1 . . . An such that

$$\{ \text{ crit1, crit2} \} \subseteq \text{Ai}$$

for some index i with  $0 \le i \le n$ .

A regular expression representing all bad prefixes is (~(crit1^crit2))\*(crit1^crit2).

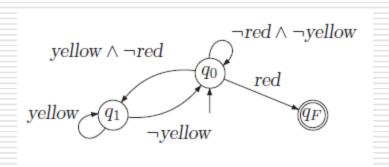


# Example: Regular Safety Property for the Traffic Light

Consider a traffic light with three possible colors: red, yellow and green. The property "a red phase must be preceded immediately by a yellow phase" is specified by the set of infinite words  $\sigma = A0\ A1\ldots$  with  $Ai \subseteq \{red, yellow\}$  such that for all i >= 0 we have that

red  $\in$  Ai implies i > 0 and yellow  $\in$  Ai-1.

A NFA recognizing all bad prefixes of the property is shown as below:



## A Nonregular Safety Property

Not all safety properties are regular. As an example of a nonregular safety property, consider:

"The number of inserted coins is always at least the number of dispensed drinks."

Let the set of propositions be { pay, drink }. Minimal bad prefixes for this safety property constitute the language

$$\{ pay^n drink^{n+1} \mid n \geqslant 0 \}$$

which is not a regular, but a context-free language.

## Verifying Regular Safety Properties

Let  $P_{\mathit{safe}}$  be a regular safety property over the atomic propositions AP and A an NFA recognizing the bad prefixes of  $P_{\mathit{safe}}$ .

Lemma 3.25. Satisfaction Relation for Safety Properties

For transition system TS without terminal states and safety property  $P_{safe}$ :

$$TS \models P_{safe}$$
 if and only if  $Traces_{fin}(TS) \cap BadPref(P_{safe}) = \varnothing$ .

Therefore, we need to check whether  $Traces_{fin}(TS) \cap \mathcal{L}(A) = \emptyset$ 

To check whether the NFAs A1 and A2 do intersect, it suffices to consider their product automaton, so

$$\mathcal{L}(\mathcal{A}_1) \cap \mathcal{L}(\mathcal{A}_2) = \emptyset$$
 if and only if  $\mathcal{L}(\mathcal{A}_1 \otimes \mathcal{A}_2) = \emptyset$ .

## Verifying Regular Safety Properties

#### Definition 4.16. Product of Transition System and NFA

Let  $TS = (S, Act, \rightarrow, I, AP, L)$  be a transition system without terminal states and  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$  an NFA with the alphabet  $\Sigma = 2^{AP}$  and  $Q_0 \cap F = \emptyset$ . The product transition system  $TS \otimes \mathcal{A}$  is defined as follows:

$$TS \otimes \mathcal{A} = (S', Act, \rightarrow', I', AP', L')$$

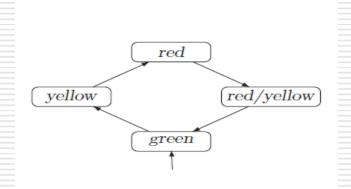
where

- $S' = S \times Q$ ,
- $\bullet \to '$  is the smallest relation defined by the rule

$$\frac{s \xrightarrow{\alpha} t \land q \xrightarrow{L(t)} p}{\langle s, q \rangle \xrightarrow{\alpha}' \langle t, p \rangle},$$

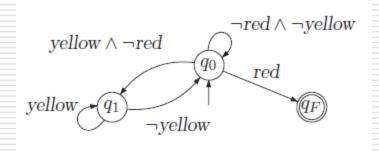
- $I' = \{ \langle s_0, q \rangle \mid s_0 \in I \land \exists q_0 \in Q_0. \ q_0 \xrightarrow{L(s_0)} q \},$
- AP' = Q, and
- $L': S \times Q \to 2^Q$  is given by  $L'(\langle s, q \rangle) = \{q\}.$

## Example: a product automaton



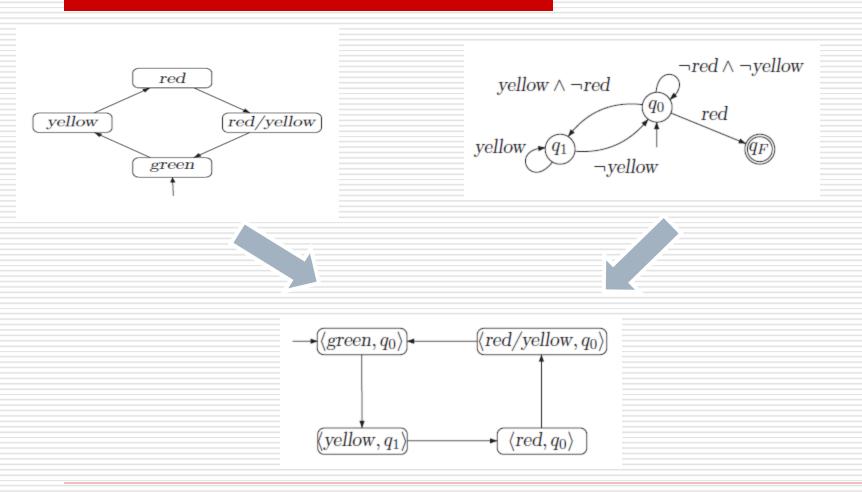
Consider a German traffic light, AP = { red, yellow } indicating the corresponding light phases.

The labeling is defined as follows:  $L(red) = \{ red \}, L(yellow) = \{ yellow \}, L(green) = \emptyset = L(red+yellow).$ 



The language of the minimal bad prefixes of the safety property "each red light phase is preceded by a yellow light phase" is accepted by the DFA A indicated here.

## Example: a product automaton



## Verifying Regular Safety Properties

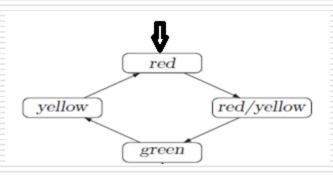
The following theorem shows that the verification of a regular safety property can be reduced to checking an invariant in the product.

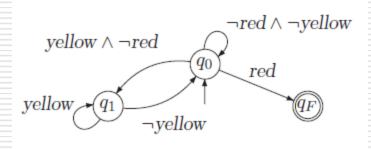
Let TS and A be as before. Let  $P_{inv(A)}$  be the invariant over  $AP' = 2^Q$  which is defined by the propositional formula

$$\bigwedge_{q \in F} \neg q.$$

In the sequel, we often write  $\neg F$  as shorthand for  $\bigwedge_{q \in F} \neg q$ . Stated in words,  $\neg F$  holds in all nonaccept states.

## Example: a product automaton











## Verifying Regular Safety Properties

#### Algorithm 5 Model-checking algorithm for regular safety properties

Input: finite transition system TS and regular safety property  $P_{safe}$ Output: true if  $TS \models P_{safe}$ . Otherwise false plus a counterexample for  $P_{safe}$ .

Let NFA  $\mathcal{A}$  (with accept states F) be such that  $\mathcal{L}(\mathcal{A}) = \text{bad prefixes of } P_{safe}$ 

```
Construct the product transition system TS \otimes \mathcal{A}
Check the invariant P_{inv(\mathcal{A})} with proposition \neg F = \bigwedge_{q \in F} \neg q on TS \otimes \mathcal{A}.

if TS \otimes \mathcal{A} \models P_{inv(\mathcal{A})} then return true else

Determine an initial path fragment \langle s_0, q_1 \rangle \dots \langle s_n, q_{n+1} \rangle of TS \otimes \mathcal{A} with q_{n+1} \in F return (false, s_0 s_1 \dots s_n)
fi
```

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## ω-Regular Languages and Properties

Infinite words over the alphabet  $\Sigma$  are infinite sequences A0 A1 A2 . . . of symbols Ai  $\in \Sigma$ .

 $\Sigma^{\omega}$  denotes the set of all infinite words over  $\Sigma$ .

Any subset of  $\Sigma^{\omega}$  is called a language of infinite words, called an  $\omega$ -language.

For instance, the infinite repetition of the finite word AB yields the infinite word ABABABABAB. . . (ad infinitum) and is denoted by  $(AB)^{\omega}$ .

For the special case of the empty word, we have  $\varepsilon^{\omega} = \varepsilon$ . For an infinite word, infinite repetition has no effect, that is,  $\sigma^{\omega} = \sigma$  if  $\sigma \in \Sigma^{\omega}$ .

## ω-Regular Expression

Definition 4.23.  $\omega$ -Regular Expression

An  $\omega$ -regular expression G over the alphabet  $\Sigma$  has the form

$$\mathsf{G} = \mathsf{E}_1.\mathsf{F}_1^\omega + \ldots + \mathsf{E}_n.\mathsf{F}_n^\omega$$

where  $n \ge 1$  and  $E_1, \ldots, E_n, F_1, \ldots, F_n$  are regular expressions over  $\Sigma$  such that  $\varepsilon \notin \mathcal{L}(F_i)$ , for all  $1 \le i \le n$ .

The semantics of the  $\omega$ -regular expression G is a language of infinite words, defined by

$$\mathcal{L}_{\omega}(\mathsf{G}) = \mathcal{L}(\mathsf{E}_1).\mathcal{L}(\mathsf{F}_1)^{\omega} \cup \ldots \cup \mathcal{L}(\mathsf{E}_n).\mathcal{L}(\mathsf{F}_n)^{\omega}$$

where  $\mathcal{L}(\mathsf{E}) \subseteq \Sigma^*$  denotes the language (of finite words) induced by the regular expression  $\mathsf{E}$  (see page 914).

Examples for  $\omega$ -regular expressions over the alphabet  $\Sigma = \{A, B, C\}$  are

$$(A+B)^*A(AAB+C)^{\omega}$$
 or  $A(B+C)^*A^{\omega}+B(A+C)^{\omega}$ .

## ω-Regular Language

#### Definition 4.24. $\omega$ -Regular Language

A language  $\mathcal{L} \subseteq \Sigma^{\omega}$  is called  $\omega$ -regular if  $\mathcal{L} = \mathcal{L}_{\omega}(\mathsf{G})$  for some  $\omega$ -regular expression  $\mathsf{G}$  over  $\Sigma$ .

For instance, the language consisting of all infinite words over  $\{A,B\}$  that contain infinitely many A's is  $\omega$ -regular since it is given by the  $\omega$ -regular expression  $(B^*A)^{\omega}$ . The language consisting of all infinite words over  $\{A,B\}$  that contain only finitely many A's is  $\omega$ -regular too. A corresponding  $\omega$ -regular expression is  $(A+B)^*B^{\omega}$ . The empty set is  $\omega$ -regular since it is obtained, e.g., by the  $\omega$ -regular expression  $\varnothing^{\omega}$ . More generally, if  $\mathcal{L} \subseteq \Sigma^*$  is regular and  $\mathcal{L}'$  is  $\omega$ -regular, then  $\mathcal{L}^{\omega}$  and  $\mathcal{L}.\mathcal{L}'$  are  $\omega$ -regular.

## ω-Regular Properties

#### Definition 4.25. $\omega$ -Regular Properties

LT property P over AP is called  $\omega$ -regular if P is an  $\omega$ -regular language over the alphabet  $2^{AP}$ .

For instance, for  $AP = \{a, b\}$ , the invariant  $P_{inv}$  induced by the proposition  $\Phi = a \vee \neg b$  is an  $\omega$ -regular property since

$$P_{inv} = \left\{ A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} \mid \forall i \ge 0. (a \in A_i \text{ or } b \notin A_i) \right\}$$
$$= \left\{ A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} \mid \forall i \ge 0. (A_i \in \{\{\}, \{a\}, \{a, b\}\}) \right\}$$

is given by the  $\omega$ -regular expression  $\mathsf{E}=(\{\}+\{a\}+\{a,b\})^\omega$  over the alphabet  $\Sigma=2^{AP}=\{\{\},\{a\},\{b\},\{a,b\}\}$ .

## **Example: Mutual Exclusion**

An example of an  $\omega$ -regular property is the property given by the informal statement "process P visits its critical section infinitely often" which, for AP = { wait, crit }, can be formalized by the  $\omega$ -regular expression:

$$((\underbrace{\{\} + \{ \operatorname{wait} \}}_{\operatorname{negative literal} \ \neg \operatorname{crit}})^*.(\underbrace{\{ \operatorname{crit} \} + \{ \operatorname{wait}, \operatorname{crit} \}}_{\operatorname{positive literal} \ \operatorname{crit}}))^\omega.$$

Starvation freedom in the sense of "whenever process P is waiting then it will enter its critical section eventually later" is an  $\omega$ -regular property as it can be described by

```
((\neg wait)^*.wait.\mathrm{true}^*.crit)^\omega \ + \ ((\neg wait)^*.wait.\mathrm{true}^*.crit)^*.(\neg wait)^\omega
```

## Nondeterministic Buchi Automata

Definition 4.27. Nondeterministic Büchi Automaton (NBA)

A nondeterministic Büchi automaton (NBA)  $\mathcal{A}$  is a tuple  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$  where

- Q is a finite set of states,
- $\Sigma$  is an alphabet,
- $\delta: Q \times \Sigma \to 2^Q$  is a transition function,
- $Q_0 \subseteq Q$  is a set of initial states, and
- F ⊆ Q is a set of accept (or: final) states, called the acceptance set.

A run for  $\sigma = A_0 A_1 A_2 \dots \in \Sigma^{\omega}$  denotes an infinite sequence  $q_0 q_1 q_2 \dots$  of states in  $\mathcal{A}$  such that  $q_0 \in Q_0$  and  $q_i \xrightarrow{A_i} q_{i+1}$  for  $i \geqslant 0$ . Run  $q_0 q_1 q_2 \dots$  is accepting if  $q_i \in F$  for infinitely many indices  $i \in \mathbb{N}$ . The accepted language of  $\mathcal{A}$  is

 $\mathcal{L}_{\omega}(\mathcal{A}) = \{ \sigma \in \Sigma^{\omega} \mid \text{there exists an accepting run for } \sigma \text{ in } \mathcal{A} \}.$ 

### NFA v.s. NBA

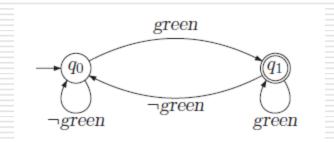
Syntax differences between NFA and NBA: None

Semantics differences between NFA and NBA: the accepted language of an NFA A is a language of **finite words**, whereas the accepted language of NBA A is an  $\omega$ -language.

The intuitive meaning of the acceptance criterion named after Buchi is that the accept set of A has to be visited infinitely often. Thus, the accepted language  $L\omega(A)$  consists of all infinite words that have a run in which some accept state is visited infinitely often.

## Example: Infinitely Often Green

Let AP = { green, red } or any other set containing the proposition green. The language of words  $\sigma = A0 \ A1 \dots \in 2^{AP}$  satisfying the LT property "infinitely often green" is accepted by the NBA A depicted below.



Accepting runs:  $(q0q1)^{W}$  ,  $(q0q1)^{n}q1^{w}$  ...

Non accepting runs:  $q1^W$  ,  $q0^W$  ...

## **NBA** Properties

#### Theorem 4.32. NBAs and $\omega$ -Regular Languages

The class of languages accepted by NBAs agrees with the class of  $\omega$ -regular languages.

#### Lemma 4.33. Union Operator on NBA

For NBA  $A_1$  and  $A_2$  (both over the alphabet  $\Sigma$ ) there exists an NBA A such that:

$$\mathcal{L}_{\omega}(\mathcal{A}) = \mathcal{L}_{\omega}(\mathcal{A}_1) \cup \mathcal{L}_{\omega}(\mathcal{A}_2)$$
 and  $|\mathcal{A}| = \mathcal{O}(|\mathcal{A}_1| + |\mathcal{A}_2|).$ 

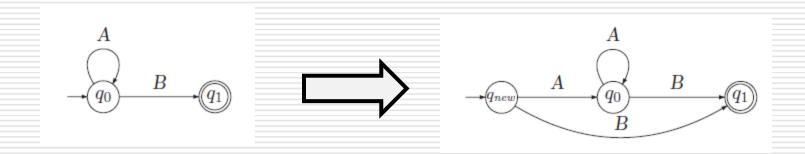
#### Lemma 4.34. $\omega$ -Operator for NFA

For each NFA  $\mathcal{A}$  with  $\varepsilon \notin \mathcal{L}(\mathcal{A})$  there exists an NBA  $\mathcal{A}'$  such that

$$\mathcal{L}_{\omega}(\mathcal{A}') = \mathcal{L}(\mathcal{A})^{\omega}$$
 and  $|\mathcal{A}'| = \mathcal{O}(|\mathcal{A}|)$ .

## Constructing a NBA from a NFA

Add a new initial (nonaccept) state  $q_{new}$  to Q with the transitions  $q_{new} \xrightarrow{A} q$  if and only if  $q_0 \xrightarrow{A} q$  for some initial state  $q_0 \in Q_0$ . All other transitions, as well as the accept states, remain unchanged.



## Constructing a NBA from a NFA

In the sequel, we assume that  $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$  is an NFA such that the states in  $Q_0$  do not have any incoming transitions and  $Q_0 \cap F = \varnothing$ . We now construct an NBA  $\mathcal{A}' = (Q, \Sigma, \delta', Q'_0, F')$  with  $\mathcal{L}_{\omega}(\mathcal{A}') = \mathcal{L}(\mathcal{A})^{\omega}$ . The basic idea of the construction of  $\mathcal{A}'$  is to add for any transition in  $\mathcal{A}$  that leads to an accept state new transitions leading to the initial states of  $\mathcal{A}$ . Formally, the transition relation  $\delta'$  in the NBA  $\mathcal{A}'$  is given by

$$\delta'(q, A) = \begin{cases} \delta(q, A) & \text{if } \delta(q, A) \cap F = \emptyset \\ \delta(q, A) \cup Q_0 & \text{otherwise.} \end{cases}$$

The initial states in the NBA  $\mathcal{A}'$  agree with the initial states in  $\mathcal{A}$ , i.e.,  $Q'_0 = Q_0$ . These are also the accept states in  $\mathcal{A}'$ , i.e.,  $F' = Q_0$ .

