Assignment - 2

Title - CRC (Kyclic Redundancy Kheck)

Problem Statement - White a forogram for error detection and correction for 718 bils ASCII rodes using CRC. Demonstrate the frackets rafetured using Wireshark Packet Analyzer Tool for freer to freer mode.

Software and Hardware Requirements - C++ comfiles, wireshark Packet Analyzer Tool, FDE, Processes.

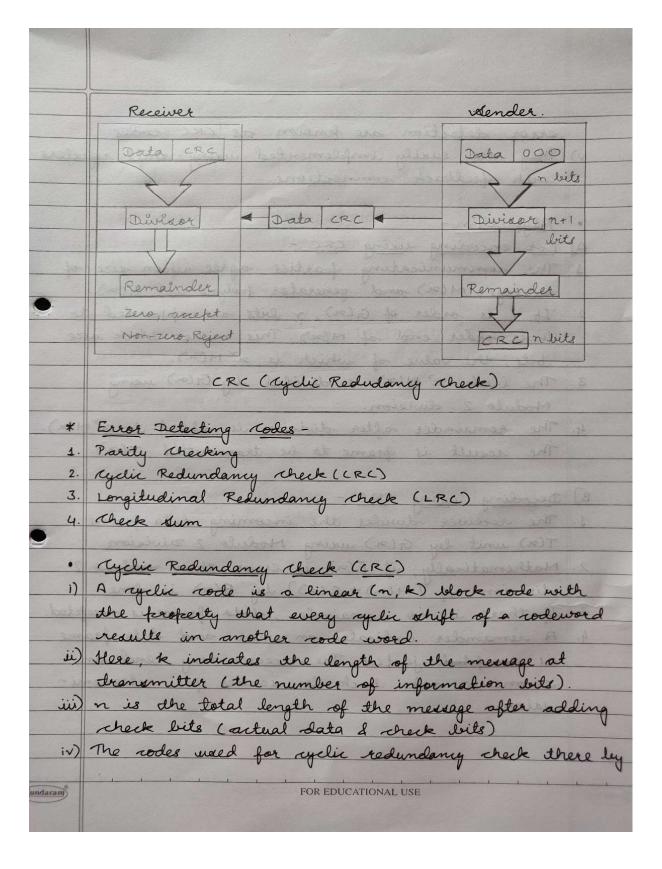
In digital systems, the analog dignals will change into digital sequence (in form of bits). This sequence of bits is called as "Data ofteam". The change in feation of single bit also leads to catastrophic (major) error in data output.

- · Error
 - i) The data can be corrupted during transmission (from source to receiver).
 - ii) It may be affected by external noise or some other februarial imprespections.
 - iii) In this case, the infeut data is not same as the received outfut data.
 - in) This mismatched data is called 'Error'.

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*	Types of Error			
1]	Single Bit Errors -			
i)	The change in one bit in whole dala requence,			
	is called single Bit Error.			
(ii:	occurence of single bit error is very rare in serial			
900	communication ayatem.			
(ننند	This type of error occurs only in frarallel comes			
Listane	communication system, as data is transferred bit			
	wide in single line, there is chance that single			
4417	line to be noisy.			
	Maryland Parket Anglyon Jose 797 Penerusa			
2]	Multifele Bit Data Errors -			
i)	If there is change in two or more bits of data sequence of transmitter to receiver, it is called			
acr.	sequence of transmitter to receiver, it is called			
SAMOUN	Munifel Bu Ceror			
(نن	This type of error owns in both verial type			
3374	This type of error occurs in both serial type and fearallel type data communication networks.			
	Austria ctab in resea Conjuno			
3]	Bural Errors -			
i)	The change of set of bits in data sequence is			
(45)	called 'Burat Error'			
(نند	The burst error is calculated in from first bit			
	change to last bit change.			
	other Johnston in profession of			
*	Error Detecting rodes			
i)	In digital communication system errors are			
	transferred from one communication eyatem to			
	another, along with the data.			
ii)	If these errors are not detected I corrected, data			
- 10	will lee lost.			
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	- Andrewsky				
	error detection are known as CRC rodes.				
(V)	They are easily implemented using shift registers				
	with feedback comnections.				
	Algorithm -				
A	For encoding using CRC -				
3.	1. The communicating parties agree upon size of				
	mexage, M(2) and generator prolynomial G(2).				
2.	If r is order of G(2), r lits are appended to				
	lower order end of M(2e). This makes block size				
7	bits, the value of which is at M(2).				
٥.	The block of M(x) is divided by G(x) using				
	Modulo 2 division.				
4.	The remainder after division is added to 2 M(2).				
	The result is frame to be transmitted, T(2).				
67	2 Andre Redundance Aborto 1 CR. C.				
1	Decoding using CRC-				
1	The receiver divides the incoming data frame				
0	T(x) unit lay G(x) maing Modulo 2 Division.				
2.	Nathematically, if E(a) is error, then modulo 2				
7	division of [M(a) + E(a)] by G(a) is done.				
	If there is no remainder, data frame is accepted.				
4.	A remainder indicates an error, and data frame				
	is accepted rejected. The receiver may send an				
	erroneous ack, back to sender for retransmi-				
No. 1	saion.				
	talks street & areh lowers) and shows				
V S	and does used for the regulation of the				
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*	Texting-					
70,	Bender Site	Receiver Site	Result			
1.	Data: 1010101	Received: 101010100	No error received			
	Divisor: 101	Remainder: 00	in message.			
	CRC: 00 Transmitted: 101010100					
•						
2.	Data: 10011 Diviser: 1101	Received: 10011001 Remainder: 001	Error detected!			
	CRC: 011	Kemainaer: 001	data.			
	Transmitted: 100 11 011		PODCEA.			
•	· Conclusion - Error Detection & Correction riding CRC was studied & implemented successfully.					
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