Chapter 3 模拟信号的发送和接收

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Analog Signal Transmission and Reception

- 3.1. 调制简介
- 3.2. 振幅调制 (AM)
- 3.3. 角度调制
- 3.4. 无线电广播和电视广播(自学)
- 3.5. 移动无线系统(自学)

3. 1 INTRODUCTION TO MODULATION

◎ 载波调制的基本概念

待发送的消息信号用m(t) (调制信号)表示,它是一个带宽为W的低通功率型信号,其功率用 P_m 表示.

$$P_{m} = \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} |m(t)|^{2} dt$$

载波调制:消息信号记录在

$$c(t) = A_c cos(2\pi f_c t + \Phi_c)$$

的载波信号上。式中: A_c 是载波幅度, f_c 是载波频率, Φ_c 是载波相位。

分类:振幅调制 (AM)、频率调制 (FM)和相位调制 (PM)

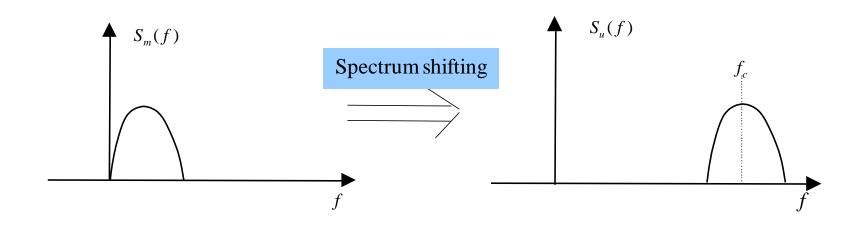


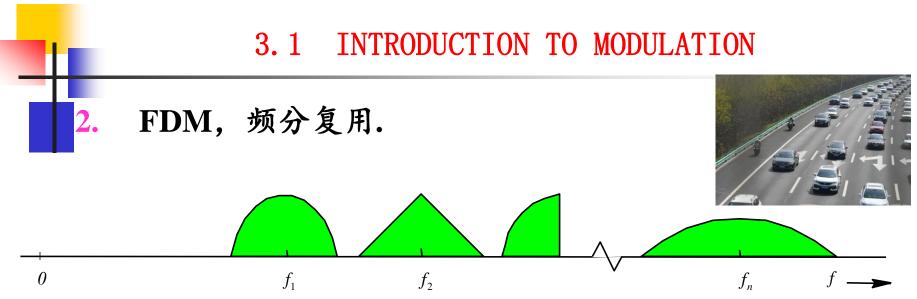
🙂 调制的目标

1. 通过频谱搬移,使信号适应信道。



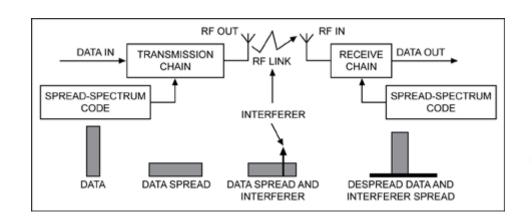
调制将低通信号(基带信号)变成了带通信号。



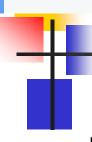


3. 扩展带宽抗噪









上网搜一下,调制还有哪些作用?

3.2 Amplitude Modulation (AM, 幅度调制)

振幅调制中,带宽为W的消息信号m(t)记录在载波 $c(t) = A_c \cos(2\pi f_c t + \phi_c)$ 的振幅上.

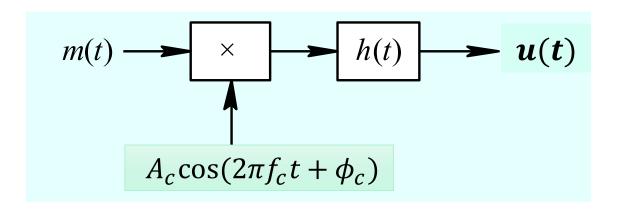


Fig. 3.2.1 Block diagram of AM

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曾实现

$$u(t) = m(t)c(t) = A_c m(t)\cos(2\pi f_c t + \phi_c)$$

· 带宽要求

$$U(f) = F \left[m(t) \right] * F \left[A_c \cos(2\pi f_c t + \phi_c) \right]$$

$$= M(f) * \frac{A_c}{2} \left[e^{j\phi_c} \delta(f - f_c) + e^{-j\phi_c} \delta(f + f_c) \right]$$

$$= \frac{A_c}{2} \left[M(f - f_c) e^{j\phi_c} + M(f + f_c) e^{-j\phi_c} \right]$$

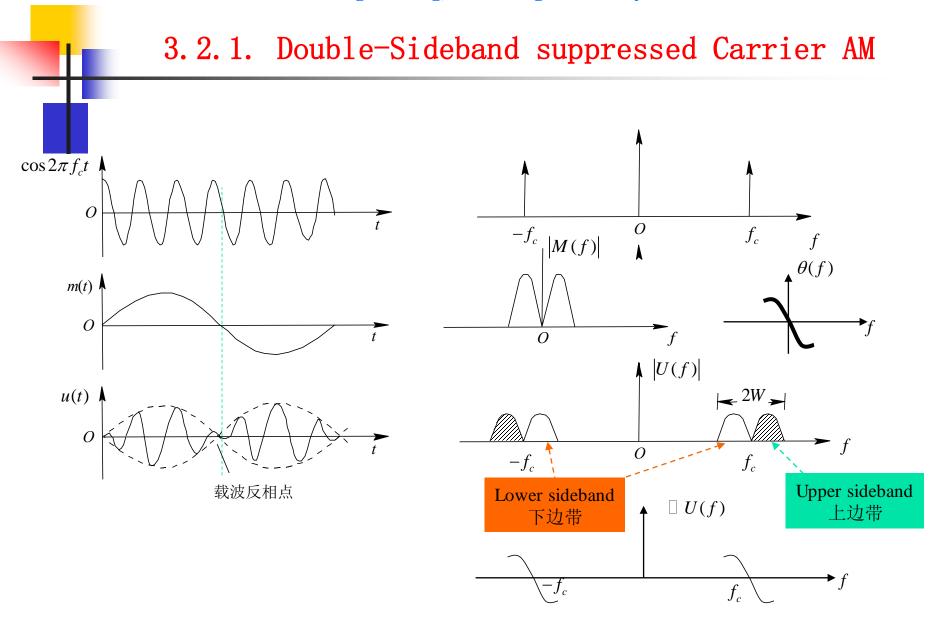
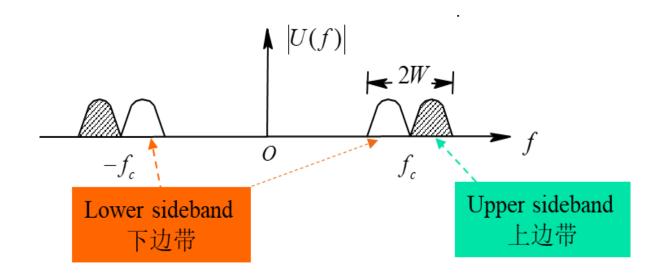


Fig. 3.2.2 DSB-SC AM



Note1. AM信号的带宽为 $2W. \rightarrow$ 从而传输该已调信号 u(t)的信道带宽至少为 $B_c=2W.$

- Note2. 上边带(USB): $f > f_c$;下边带(LSB): $f < f_c$
- Note3. m(t) 不含直流分量 (meaning?). 因此 u(t) 不含载波分量



抑止载波的双边带调幅, DSB-SC AM

Exapmle 3.2.1 假设调制信号 m(t) 是具有如下形式的正弦波,

$$m(t) = a \cos 2 \pi f_m t$$
 $f_m \ll f_c$

试确定DSB-SCAM信号及其上下边带.



Solution DSB-SC AM 信号在时域的表达式为:

$$u(t) = m(t)c(t) = a\cos 2\pi f_m t \cdot A_c \cos \left(2\pi f_c t + \phi_c\right)$$

$$= \frac{A_c a}{2} \cos \left[2\pi \left(f_c - f_m \right) t + \phi_c \right] + \frac{A_c a}{2} \cos \left[2\pi \left(f_c + f_m \right) t + \phi_c \right]$$

下边带

上边带

$$U(f) = \frac{A_c a}{4} \left[e^{j\phi_c} \delta(f - f_c + f_m) + e^{-j\phi_c} \delta(f + f_c - f_m) \right]$$
$$+ \frac{A_c a}{4} \left[e^{j\phi_c} \delta(f - f_c - f_m) + e^{-j\phi_c} \delta(f + f_c + f_m) \right]$$

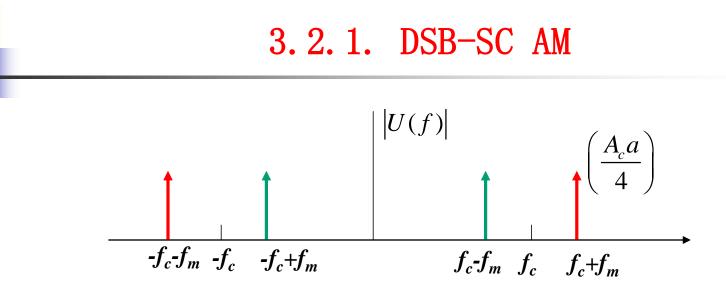
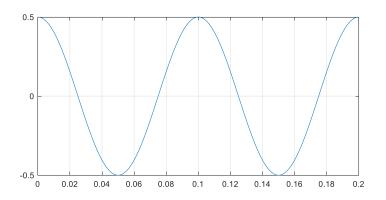


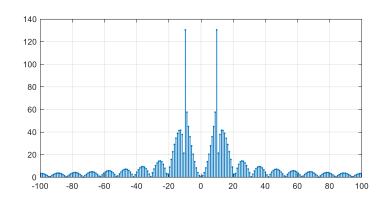
Figure example 3.2.1 Spectrum of the DSB-SC AM signals

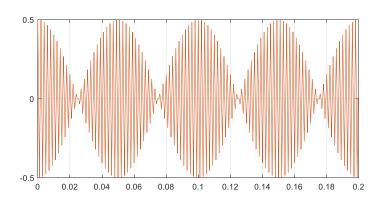
注:绿色为下边带,红色为上边带

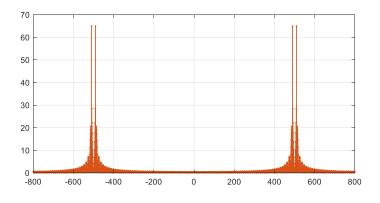
3. 2. 1. DSB-SC AM

Matlab 运行结果









3.2.1. 抑止载波的双边带调幅, DSB-SC AM

■ DSB-SCAM信号的功率谱和功率: 设信号初始 相位为零(?)

$$\begin{split} R_{u}(\tau) &= \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} u(t) u(t-\tau) dt \\ &= \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} A_{c}^{2} m(t) m(t-\tau) \cos(2\pi f_{c} t) \cos(2\pi f_{c} (t-\tau)) dt \\ &= \frac{A_{c}^{2}}{2} \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} m(t) m(t-\tau) \left[\cos(4\pi f_{c} t - 2\pi f_{c} \tau) + \cos(2\pi f_{c} \tau) \right] dt \end{split}$$

3.2.1. 抑止载波的双边带调幅, DSB-SC AM

◎DSB-SC AM信号的功率谱和功率(续):

$$R_{u}(\tau) = \frac{A_{c}^{2}}{2} R_{m}(\tau) \cos(2\pi f_{c}\tau) + \int_{-\infty}^{\infty} m(t) m(t - \tau) \cos(4\pi f_{c}t - 2\pi f_{c}\tau) dt$$

$$= \frac{A_{c}^{2}}{2} R_{m}(\tau) \cos(2\pi f_{c}\tau)$$

$$+ \int_{-\infty}^{\infty} \mathcal{F}[m(t - \tau)] \{\mathcal{F}[m(t) \cos(4\pi f_{c}t - 2\pi f_{c}\tau)]\}^{*} df$$

$$= \frac{A_{c}^{2}}{2} R_{m}(\tau) \cos(2\pi f_{c}\tau)$$

$$+ \int_{-\infty}^{\infty} e^{-j2\pi f\tau} M(f) \left[\frac{M(f - 2f_{c})e^{-j2\pi f\tau}}{2} + \frac{M(f + 2f_{c})e^{j2\pi f\tau}}{2} \right]^{*} df$$

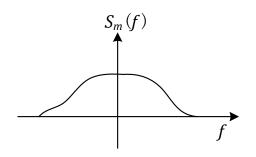
$$= \frac{A_{c}^{2}}{2} R_{m}(\tau) \cos(2\pi f_{c}\tau)$$

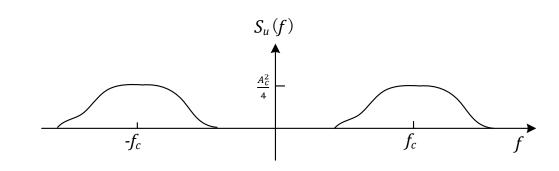
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$$S_u(f) = F[R_u(\tau)] = F\left[\frac{A_c^2}{2}R_m(\tau)\cos 2\pi f_c\tau\right]$$
$$= \frac{A_c^2}{4}[S_m(f - f_c) + S_m(f + f_c)]$$

$$P_u = \frac{A_c^2}{2} R_m(0) = \frac{A_c^2}{2} P_m$$







- Example 3.2.2 确定例3.2.1中已调信号的功率及 每个边带的功率。
 - Solution

$$S_{u}(f) = \frac{A_{c}^{2}a^{2}}{16} [\delta(f - f_{m} - f_{c}) + \delta(f + f_{m} - f_{c}) + \delta(f - f_{m} + f_{c}) + \delta(f + f_{m} + f_{c})]$$

$$P_u = \frac{A_c^2 a^2}{4}$$
, $P_{uu} = P_{ul} = \frac{A_c^2 a^2}{8}$



DSB-SC AM 信号的解调.

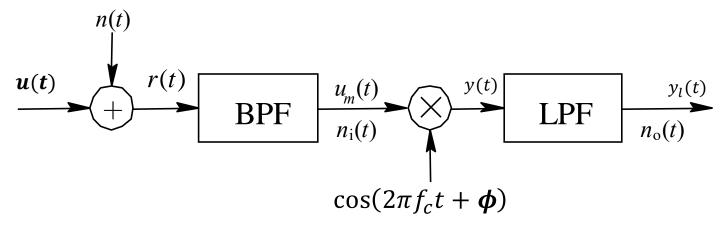


Fig3.2.3. Block diagram of the demodulator

Coherent demodulating or synchronous demodulating

(相干解调或同步解调)

图中,n(t)是均值为零的加性高斯白噪声。

BPF的带宽为 2WHz,允许已调信号u(t)无失真通过。LPF带宽为WHz。



Assuming n(t)=0, 忽略噪声,then

$$r(t) = u_{m}(t) = A_{c}m(t)\cos(2\pi f_{c}t + \boldsymbol{\phi}_{c})$$

$$y(t) = u_m(t)\cos(2\pi f_c t + \boldsymbol{\phi})$$

$$= A_c m(t) \cos(2\pi f_c t + \boldsymbol{\phi}) \cos(2\pi f_c t + \boldsymbol{\phi}_c)$$

$$= \frac{A_c}{2}m(t)\cos(\boldsymbol{\phi}_c - \boldsymbol{\phi}) + \frac{A_c}{2}m(t)\cos(4\pi f_c t + \boldsymbol{\phi} + \boldsymbol{\phi}_c)$$

$$y_l(t) = \frac{A_c}{2} m(t) \cos(\phi_c - \phi)$$
 $\phi_c - \phi = 0$ is desired

 $\phi = \phi_c$ 时,称为相干解调或同步解调。



- 载波获取的两种方法
- 1) Inserting pilot tone(插入导频,图3.24发送端,图3.25 接收端)
- Using phase locked loop(PLL,锁相环) (learning after)

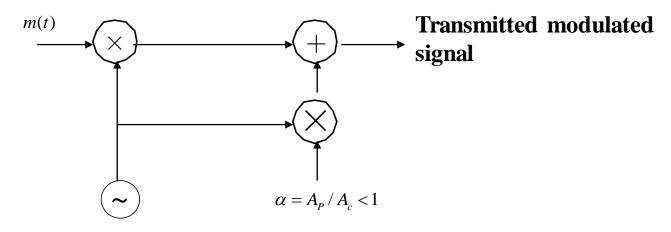


Fig 3.2.4 Addition of a pilot tone to a DSB AM signal

Oscillator



3.2.1. Double-Sideband suppressed Carrier AM

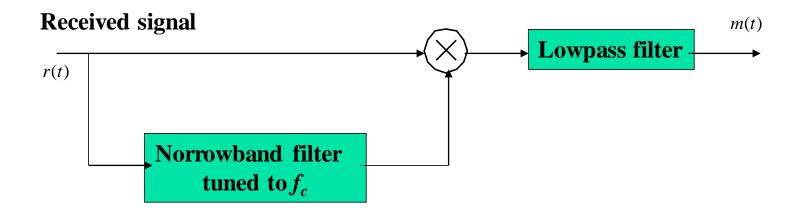
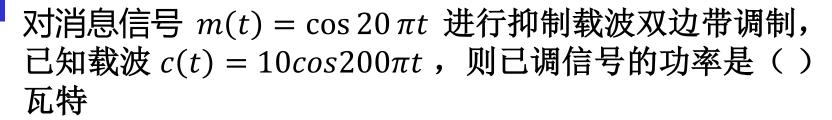


Fig3.2.5. Use of a pilot tone to demodualte a DSB AM signal

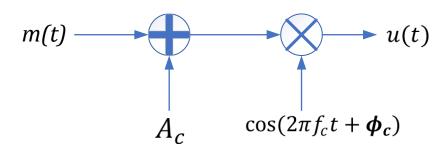
对消息信号 $m(t) = a \cos 20 \pi t$ 进行抑制载波双边带调制,已知载波 $c(t) = A_c \cos 200\pi t$,则已调信号的上边带频率为

- 90Hz
- 110Hz
- **180Hz**
- D 220Hz



- A 25
- **B** 50
- **c** 75
- **D** 100

3.2.2 Conventional Amplitude Modulation(常规调幅)



常规调幅实现框图

$$u(t) = (A_c + m(t))\cos(2\pi f_c t + \boldsymbol{\phi_c}),$$

要求

$$A_c \ge |m(t)|_{\max}$$

定义:

$$\alpha = \frac{|m(t)|_{\text{max}}}{A_c}$$

为调制指数,则 $0 < \alpha \le 1$ 。



3.2.2 Conventional Amplitude Modulation(常规调幅)



归一化 消息信号

$$m_n(t) = \frac{m(t)}{|m(t)|_{\text{max}}}$$

则

$$u(t) = A_c[1 + \alpha m_n(t)]\cos(2\pi f_c t + \boldsymbol{\phi}_c)$$

$$U(f) = \frac{A_c}{2} \left[e^{j\varphi_c} a M_n (f - f_c) + e^{j\varphi_c} \delta(f - f_c) + e^{-j\varphi_c} a M_n (f + f_c) + e^{-j\varphi_c} \delta(f + f_c) \right]$$

3.2.2 Conventional Amplitude Modulation

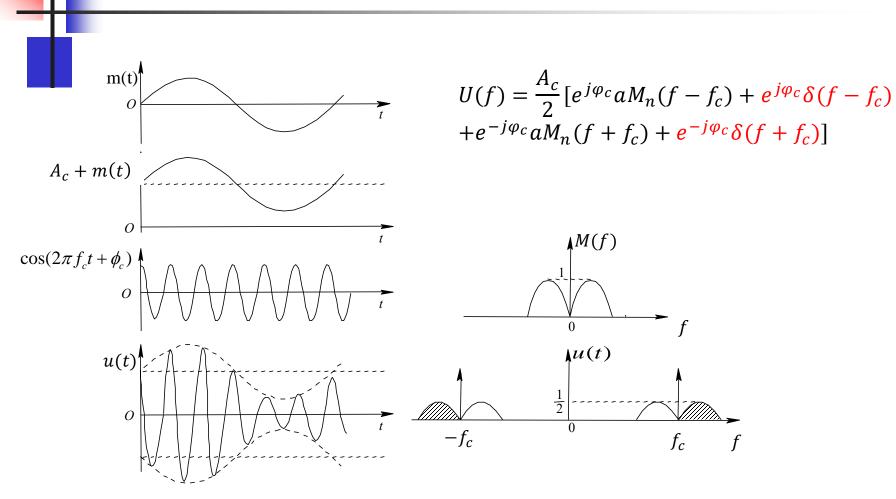


Fig. 3.2.7 Block diagram of AM



- AM 信号的带宽= 2W.
- AM 信号的功率

$$P_u = \frac{A_c^2}{2} + P_m = \frac{A_c^2}{2} + \frac{A_c^2}{2} \alpha^2 P_{m_n}$$

常规AM信号的功率效率远小于DSB-SC AM,但其解调容易.

3.2.2 Conventional Amplitude Modulation

■ DSB AM 信号的解调

Envelope detector(包络检波)

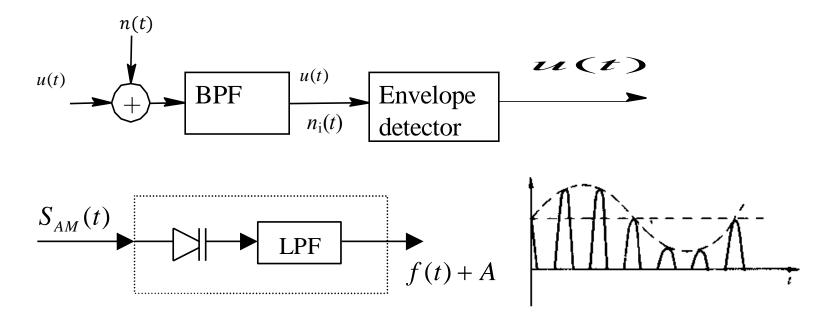


Fig. 3.2.8 Envelope detector

AM

例(problem3.7))已知AM信号如下

$$u(t) = [20 + 2\cos 30\pi t + 10\cos 60\pi t]\cos(2 \times 10^5\pi t)$$

求: (1) 调制指数;

(2) 每个频率分量的功率。

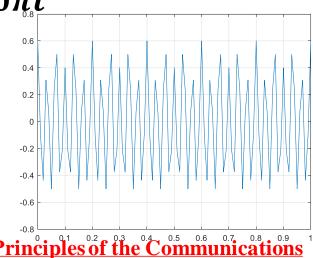
解:

$$u(t) = [20 + 2\cos 30\pi t + 10\cos 60\pi t]\cos(2 \times 10^5\pi t)$$

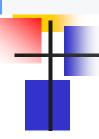
 $= 20[1 + 0.1\cos 30\pi t + 0.5\cos 60\pi t]\cos (2 \times 10^5\pi t)$

故: $\alpha m_n(t) = 0.1\cos 30\pi t + 0.5\cos 60\pi t$

调制指数α=0.6



(2) $u(t) = [20 + 2\cos 30\pi t + 10\cos 60\pi t]\cos(2 \times 10^5\pi t)$ $= 20\cos(2\times10^{5}\pi t) + \cos((2\times10^{5}-30)\pi t) +$ $cos((2 \times 10^5 + 30)\pi t) + 5 cos((2 \times 10^5 - 60)\pi t) +$ $5\cos((2\times10^5+60)\pi t)$ 从而5个频率分量的功率分别为:200、0.5、0.5、 12.5\ 12.5\



请写出AM信号的时域表达式,并基于你写出的表达式画出该信号的功率谱,计算出功率。假设消息信号用m(t)表示,它的功率谱为 $S_m(f)$ 。

正常使用主观题需2.0以上版本雨课堂

解:
$$u(t) = (A_c + m(t))cos2\pi f_c t$$

= $A_c cos2\pi f_c t + m(t)cos2\pi f_c t$

故

$$S_{u}(f) = \frac{A_{c}^{2}}{4} [\delta(f + f_{c}) + \delta(f - f_{c})] + \frac{1}{4} [S_{m}(f + f_{c}) + S_{m}(f - f_{c})]$$

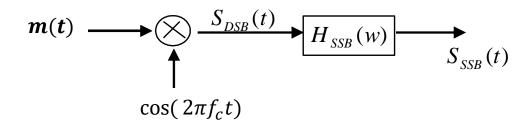
功率为

$$P_u = \frac{A_c^2}{2} + P_m$$



单边带AM 信号的产生.

1. 滤波法



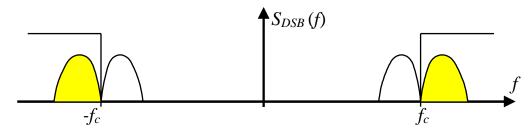
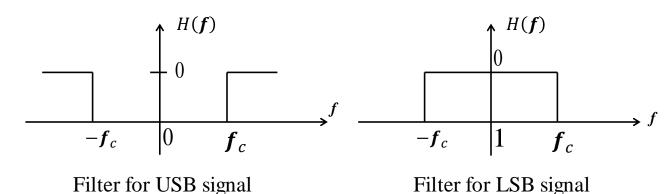


Fig. 3.2.9 Block diagram of SSB-AM

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3. 2. 3 SSB AM



对 USB 信号, $H_U(f)$ 的频率响应为

$$H_U(f) = u(f - f_c) + u(-f - f_c)$$

对 LSB 信号, $H_L(f)$ 的频率响应为

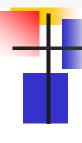
$$H_L(f) = \frac{1}{2} [\text{sgn}(f + f_c) - \text{sgn}(f - f_c)]$$

= $u(f + f_c) - u(f - f_c)$

3.2.3 Single-Sideband AM

以USB信号为例,推导单边带信号的时域表达式

$$\begin{split} M_{USB}(f) &= A_c M(f - f_c) u(f - f_c) + A_c M(f + f_c) u(-f - f_c) \\ &= A_c M(f) u(f) \big|_{f = f - f_c} + A_c M(f) u(-f) \big|_{f = f + f_c} \\ s_{USB}(t) \\ &= A_c m(t) * F^{-1}[u(f)] e^{j2\pi f_c t} + A_c m(t) * F^{-1}[u(-f)] e^{-j2\pi f_c t} \\ &= A_c m(t) * \left[\frac{1}{2} \delta(t) + \frac{j}{2\pi t} \right] e^{j2\pi f_c t} + A_c m(t) \\ * \left[\frac{1}{2} \delta(t) - \frac{j}{2\pi t} \right] e^{-j2\pi f_c t} \\ &= \frac{1}{2} A_c [m(t) + j\widehat{m}(t)] e^{j2\pi f_c t} + \frac{1}{2} A_c [m(t) - j\widehat{m}(t)] e^{-j2\pi f_c t} \\ &= A_c m(t) \cos 2\pi f_c t - A_c \widehat{m}(t) \sin 2\pi f_c t \end{split}$$



请推导下边带信号的表达式。

正常使用主观题需2.0以上版本雨课堂

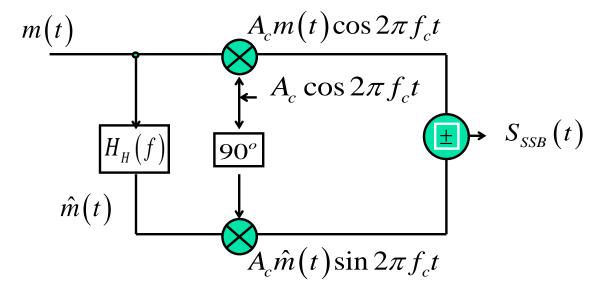


LSB信号的时域表达式为:

$$s_{LSB}(t) = A_c m(t) \cos 2\pi f_c t + A_c \widehat{m}(t) \sin 2\pi f_c t$$

Note: 这里DSBAM 信号为 $2A_cm(t)\cos 2\pi f_ct$

2. 相移法产生 SSB 信号





■ Example 3.2.4. 假设调制信号如下:

$$m(t) = \cos 2\pi f_m t$$
, $f_m \ll f_c$

确定两个可能的SSBAM信号.

Solution The Hilbert transform of m(t) is

$$\hat{m}(t) = \sin 2\pi f_c t$$

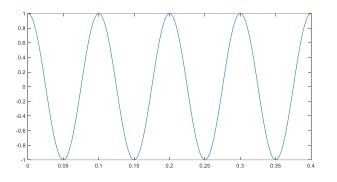
$$u_{SSB}(t) = A_c \cos 2\pi f_m t \cos 2\pi f_c t \mp A_c \sin 2\pi f_m t \sin 2\pi f_c t$$

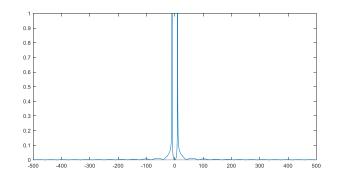
$$= A_c \cos 2\pi (f_c \pm f_m)$$

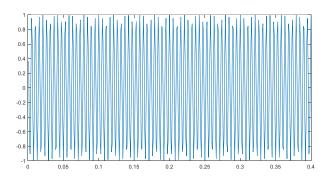
Note: SSB AM 信号的带宽为 W.

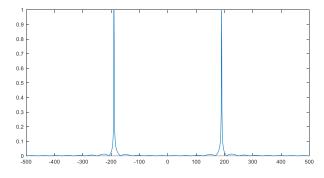


$$f_c = 200Hz, m(t) = cos(20\pi t)$$









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3.2.3 Single-Sideband AM

SSB AM 信号的解调:相干或同步解调.

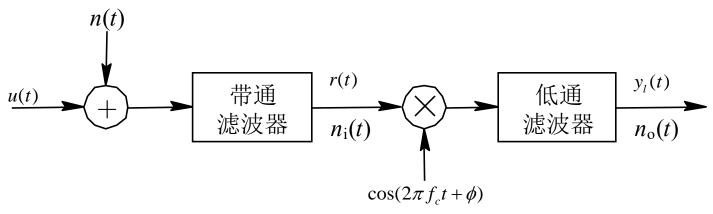
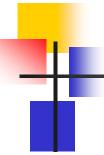
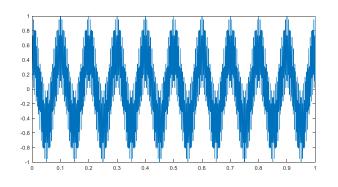


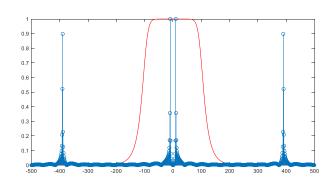
Fig. 3.2.10 Demodulator of SSB-AM

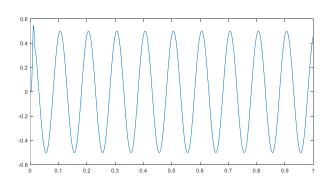


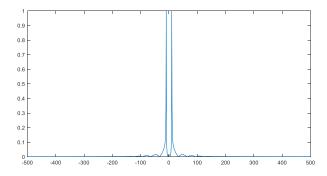


SSB AM









3.2.4 Vestigial-sideband AM (残余边带调幅, VSB AM)

SSB对边带滤波器的频率响应严格。如何克服?

放松对边带滤波器的要求,允许上边带中混入少许下边带的频谱,或者下边带中混入少许上边带频谱。

代价:已调信号带宽和功率都稍微增加。

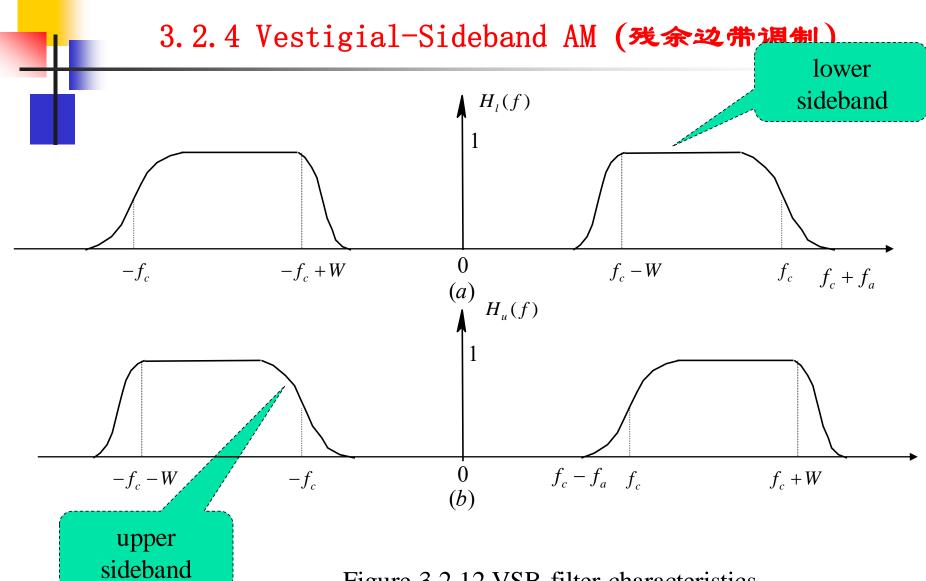


Figure 3.2.12 VSB filter characteristics

The bandwidth of VSB AM signals is a letter large than W.



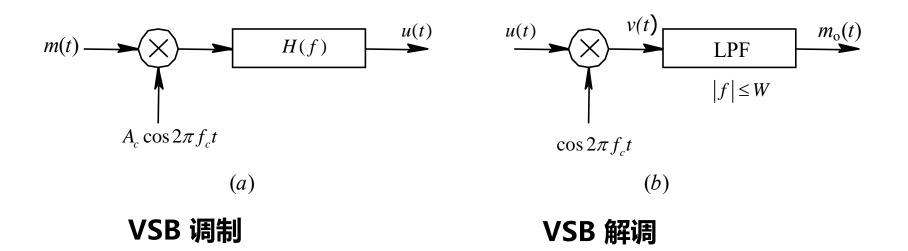


Fig. 3.2.11 VSB-AM

3. 2. 4 Vestigial-sideband AM

对H(f)的要求

$$u(t) = [A_c m(t) \cos 2\pi f_c t] * h(t)$$

$$U(f) = \frac{A_c}{2} [M(f + f_c) + M(f - f_c)]H(f)$$

$$v(t) = u(t) \cos 2\pi f_c t$$

$$V(f) = \frac{1}{2} [U(f + f_c) + U(f - f_c)]$$

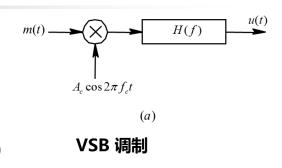
$$= \frac{A_c}{4} [M(f + 2f_c) + M(f)]H(f + f_c)$$

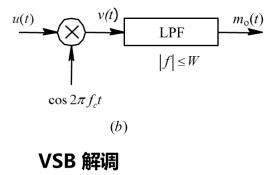
$$+\frac{A_c}{4}[M(f)+M(f-2f_c)]H(f-f_c)$$

低通滤波后,得到的 $m_o(t)$,必须满足

$$m_o(t) = am(t)$$

其中a是常数.







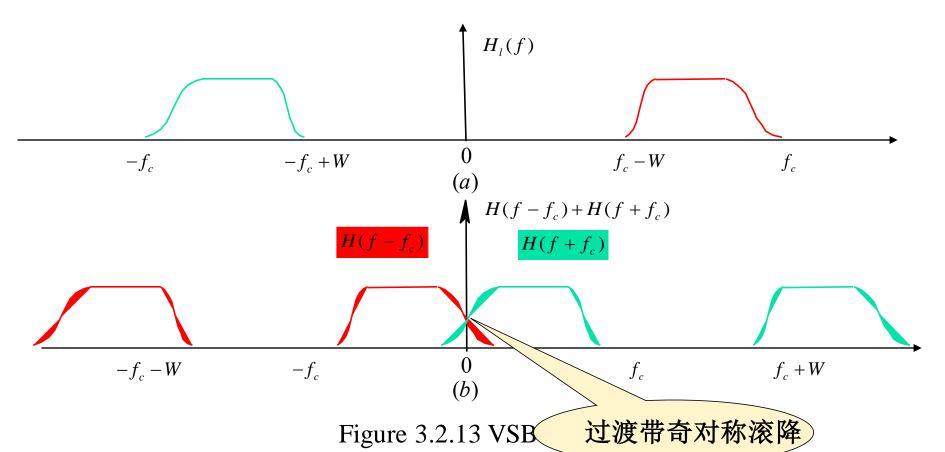
3.2.4 Vestigial-Sideband AM

Thus,

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$$M_o(f) = \frac{A_c}{4}M(f)[H(f+f_c)+H(f-f_c)]$$

$$[H(f+f_c)+H(f-f_c)] = \cos \tan t \qquad |f| \le W$$



Principles of the Communications

- 3.2.5 AM 信号调制与解调器的实现 (自学, 或者高频电路课程学习)
- **Modulators**
- **Power-Law Modulation (conventional AM)**
- 2. Switching Modulation(conventional AM)
- **Balanced Modulation (DSB-SC AM)**
- 4. Ring Modulator (DSB-SC AM)

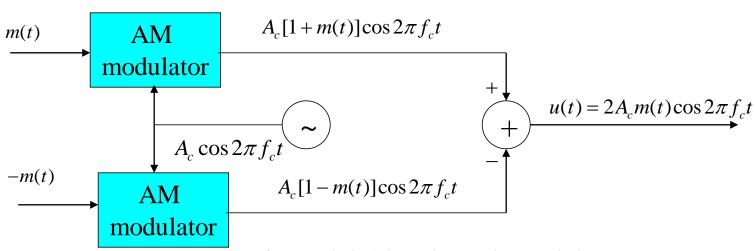
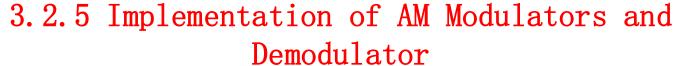


Figure 3.2.14 Balanced Modulator



- Demodulator
- 1. Envelope Detector
- Demodulation of DSB-SC AM signals (pp93, Fig3.21)
- 3. Demodulation of SSB Signals(pp93, Fig3.22)
- 4. Demodulation of VSB signals



Multiplexing (复用). 将许多独立的消息信号合并成一个组合信号,以便在一条公共信道上传输的过程称为多路复用.

TDM (时分复用). Time-division multiplexing FDM(频分复用). Frequency-division multiplexing.

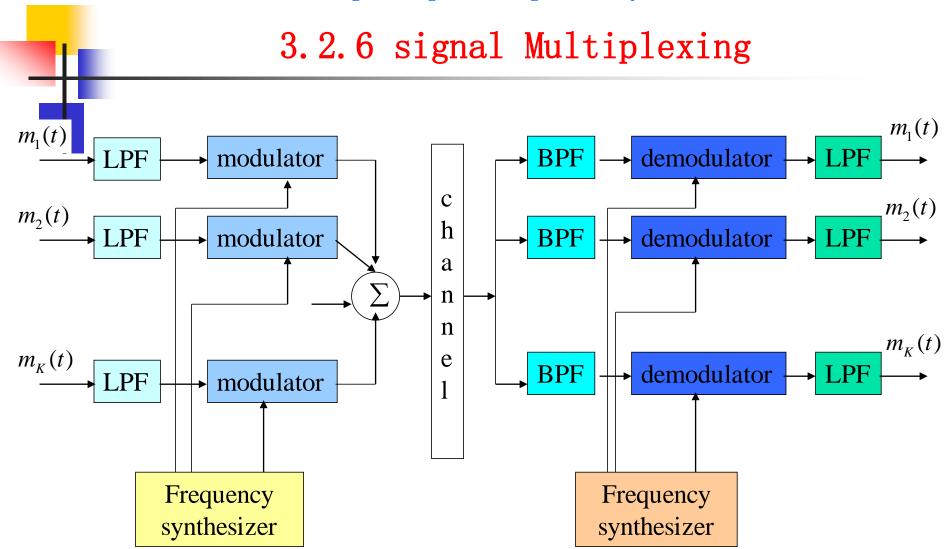
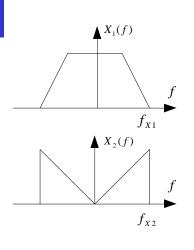
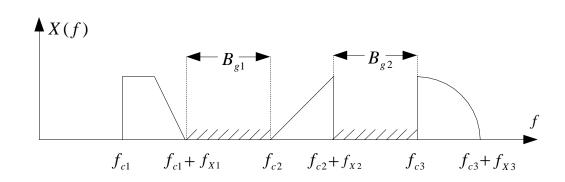
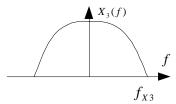


Figure 3.2.15 FDM









B is the guard band

Fig. 3.2.16 Spectrum of FDM signal

FDM 信号的带宽: $W_{FDM}=nW+(n-1)B$

我们希望用SSB和FDM来传输12路语音信号,已知每一路语音信号的频带范围为(0,3.4k) Hz。 现要求每路信号之间的保护间隔为0.6kHz,问合成的FDM信号带宽是[填空1] Hz?

正常使用填空题需3.0以上版本雨课堂

3.2.6 signal Multiplexing

思考:这种实现FDM的方式适合大规模频分复用吗?还有 没有其他的实现方法?

习题3.42是其中一种。

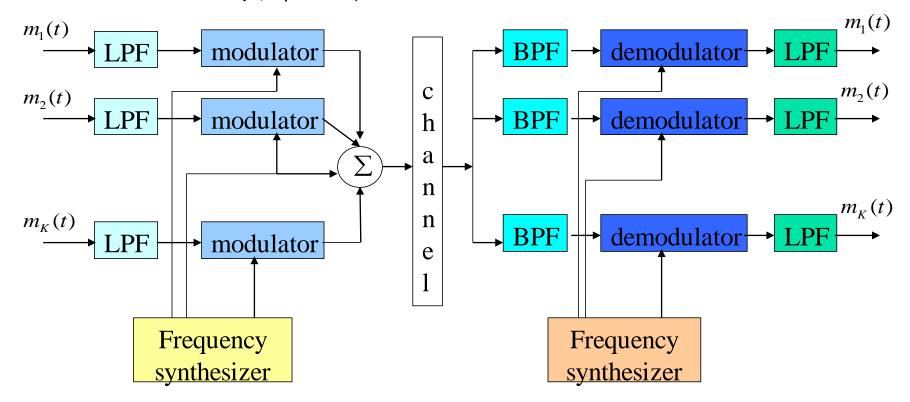


Figure 3.2.15 FDM

3.2.6 signal Multiplexing

■ 载波正交多路复用.

利用两个正交载波 $A_c cos2\pi f_c t$ 和 $A_c sin2\pi f_c t$, 在同一个载频上传送两路消息信号.

$$u(t) = A_c m_1(t) \cos 2\pi f_c t + A_c m_2(t) \sin 2\pi f_c t$$

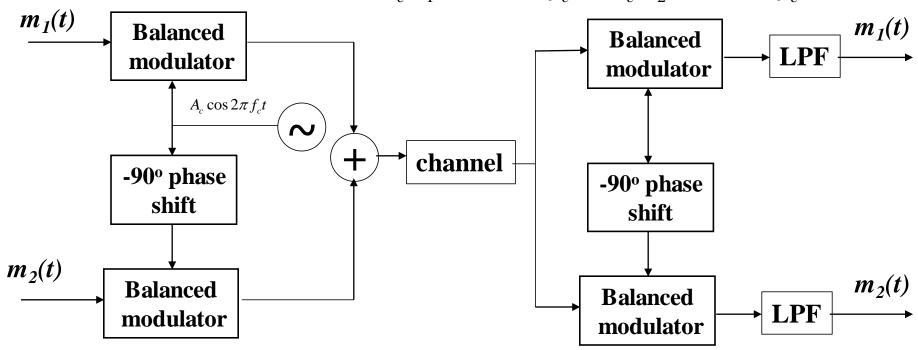


Figure 3.2.17 Quadrature-Carrier Multiplexing

Summarizing

- Introduction to modulation
- Amplitude modulation (DSB-SC AM, Conventional AM, SSB AM, VSB AM)
- 问题1:AM 调制一般称为线性调制,它们是线性变换吗?

答:不是。

问题2:请按信号带宽从大到小的顺序排列AM信号。

答: DSB-SC AM = Conventional AM> VSB AM > SSB AM.



目的:用带宽来换取较高的抗噪声性能。

■ 3.3.1 FM信号和PM信号的表示形式 角度已调信号通常表示如下

$$u(t)=A_{c}cos(\theta(t)).$$

其中 $\theta(t)$ 是信号的相位,其瞬时频率 $f_i(t)$ 由下式给出

$$f_i(t) = \frac{1}{2\pi} \frac{d}{dt} \theta(t)$$

已调信号u(t)是带通信号,它可以表示为

$$u(t)=A_c cos(2\pi f_c t + \Phi(t))$$

故

$$f_i(t) = f_c + \frac{1}{2\pi} \frac{d}{dt} \boldsymbol{\phi}(t)$$

3.3.1 FM信号和PM信号的表示形式

若m(t)是消息信号,在相位调制(PM)系统中

$$\Phi(t)=k_pm(t);$$

在频率调制 (FM) 系统中, 瞬时频率偏移

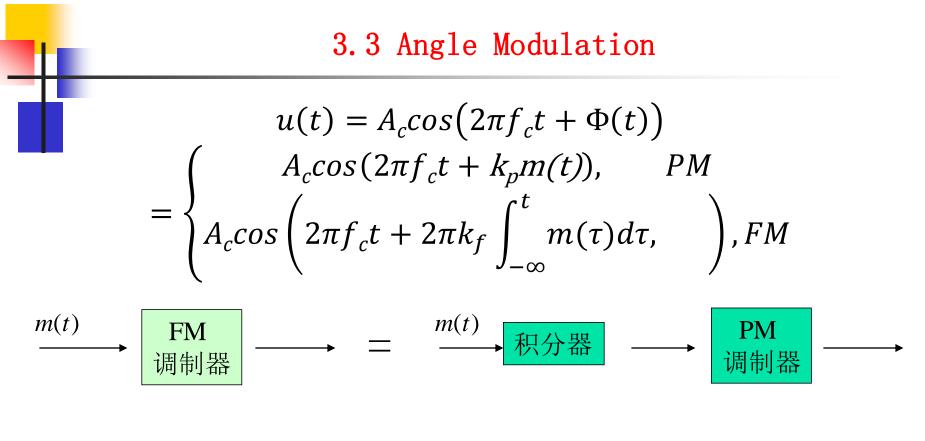
$$\Delta f = f_i(t) - f_c = k_f m(t) = \frac{1}{2\pi} \frac{d}{dt} \boldsymbol{\phi}(t)$$

So

$$\boldsymbol{\phi}(t) = \begin{cases} k_p m(t), & PM \\ 2\pi k_f \int_{-\infty}^t m(\tau) d\tau, & FM \end{cases}$$

Kp和 Kf分别是相位偏移常数和频率偏移常数

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$$\frac{m(t)}{}$$
 \longrightarrow $\frac{PM}{}$ \longrightarrow $=$ $\frac{m(t)}{}$ 微分器 \longrightarrow $\frac{FM}{}$ 调制器 \longrightarrow

Figure 3.3.1 FM和PM调制器的比较



1. 定义PM系统的最大相位偏移为

$$\Delta \boldsymbol{\phi}_{\text{max}} = k_p \max[|m(t)|]$$

2. 定义FM系统的最大频率偏移为

$$\Delta f_{\max} = k_f \max[|m(t)|]$$

3. 定义信号 m(t) 的调制指数为

$$\beta_p = k_p \max[|m(t)|] = \Delta \phi_{\max}$$
$$\beta_f = \frac{k_f \max[|m(t)|]}{W} = \frac{\Delta f_{\max}}{W}$$

W----信号 m(t)的带宽.



3.3.1 FM信号和PM信号的表示形式

例3.3.1 消息信号:

$$m(t) = a\cos(2\pi f_m t)$$

试确定其PM和FM已调信号的形式。

解:

在PM调制中: $\Phi(t)=k_p m(t)=k_p a cos(2\pi f_m t)$

所以PM已调信号

3.3.1 FM信号和PM信号的表示形式

在FM调制中:

$$\phi(t) = 2\pi k_f \int_{-\infty}^{t} m(\tau) d\tau$$

$$= 2\pi k_f \int_{-\infty}^{t} a\cos(2\pi f_m \tau) d\tau$$

$$= \frac{ak_f}{f_m} \sin(2\pi f_m t)$$

所以FM已调信号为:

$$u(t) = A_c cos(2\pi f_c t + \beta_f sin(2\pi f_m t))$$

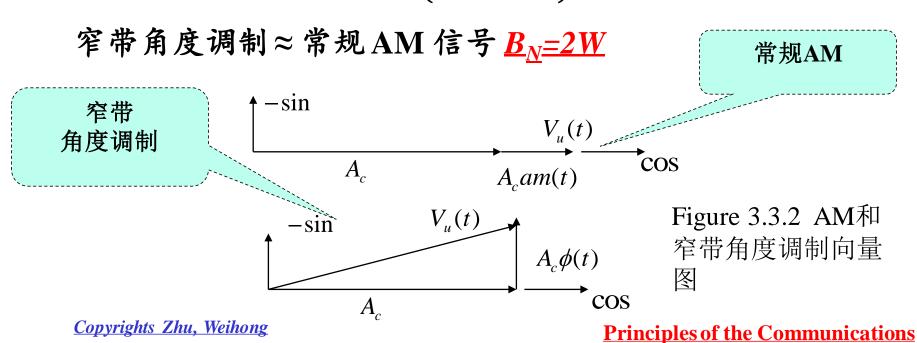
其中

$$\beta_f = ak_f / f_m$$



窄带角度调制.

如果角度调制系统中,偏移常数 k_p 和 k_f 以及消息信号m(t)满足条件:对所有的t,都有 $\Phi(t)$ 远小于I,则 $u(t) = A_c \cos \phi(t) \cos 2\pi f_c t - A_c \sin \phi(t) \sin 2\pi f_c t$ $\approx A_c \cos 2\pi f_c t - A_c \phi(t) \sin 2\pi f_c t$ $u_{AM}(t) = Ac(1+m(t))cos 2\pi f_c t$





正弦信号的角度调制.

$$m(t) = a\cos 2\pi f_m t$$

In PM, we have

$$\phi(t) = k_p m(t) = k_p a \cos 2\pi f_m t = \beta_p \cos 2\pi f_m t$$

In FM, we have

$$\boldsymbol{\phi}(t) = 2\pi k_f \int_{-\infty}^{t} m(\tau)d\tau = \frac{k_f a}{f_m} \sin 2\pi f_c t = \beta_f \sin 2\pi f_m t$$

So we have

$$u(t) = \begin{cases} A_c \cos(2\pi f_c t + \beta_p \cos(2\pi f_m t)), & \rho_M \\ A_c \cos(2\pi f_c t + \beta_f \sin(2\pi f_m t)), & F_M \end{cases}$$

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3.3.2 角度调制信号的频谱特性

以FM 信号为例(PM signal is same as FM), 有

$$u(t) = A_c \cos(2\pi f_c t + \beta \sin 2\pi f_m t) = \text{Re} \left[A_c e^{j2\pi f_c t} e^{j\beta \sin 2\pi f_m t} \right]$$

e^{jβ sin 2π f_mt} 是周期函数,可以展成傅立叶级数的形式,其傅立叶级数的系数为

$$c_{n} = f_{m} \int_{0}^{\frac{1}{f_{m}}} e^{j\beta \sin 2\pi f_{m}t} e^{-jn2\pi f_{m}t} dt \underline{\qquad u = 2\pi f_{m}t} \underline{\qquad \frac{1}{2\pi}} \int_{0}^{2\pi} e^{j(\beta \sin u - nu)} du = J_{n}(\beta)$$

SO
$$e^{jeta\sin2\pi f_mt}=\sum_{n=-\infty}^{\infty}J_n(eta)e^{j2\pi nf_mt}$$

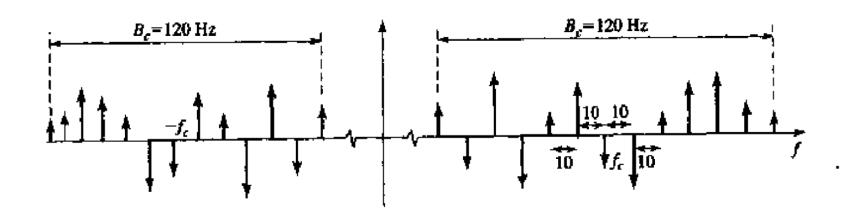
$$u(t) = \operatorname{Re}\left(A_c \sum_{n=-\infty}^{\infty} J_n(\beta) e^{j2\pi n f_m t} e^{j2\pi f_c t}\right) = \sum_{n=-\infty}^{\infty} A_c J_n(\beta) \cos(2\pi (f_c + n f_m) t)$$



 $J_n(\beta)$ 是第一类n 阶贝塞尔(Bessel)函数

$$J_{n}(\beta) = \sum_{k=0}^{\infty} \frac{(-1)^{k} \left(\frac{\beta}{2}\right)^{n+2k}}{k!(k+n)!} \approx \frac{\beta^{n}}{2^{n}n!}, \quad J_{-n}(\beta) = \begin{cases} J_{n}(\beta), & n & even \\ -J_{n}(\beta), & n & odd \end{cases}$$

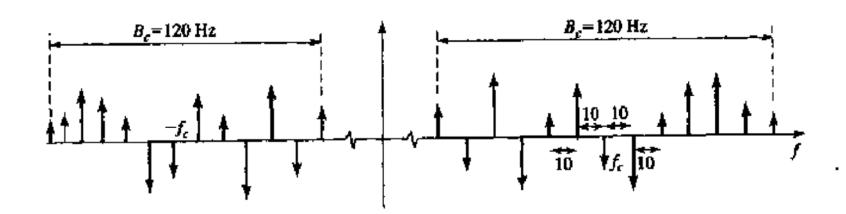
下图为 $k_f = 50$, $f_m = 10Hz$ 时的调频信号频谱。可见单频信号经过FM之后,产生了一些列频率分量。



3.3.2 角度调制信号的频谱特性

一般情况下,已调角信号的有效带宽应包含至少 98%的信号功率,因此单频已调角信号的带宽由下 式给出

$$B_c = 2(\beta + 1)f_m = \begin{cases} 2(k_p a + 1)f_m = 2(k_p a + 1)f_m \\ 2(\frac{k_f a}{f_m} + 1)f_m = 2(k_f a + f_m) \end{cases} PM$$

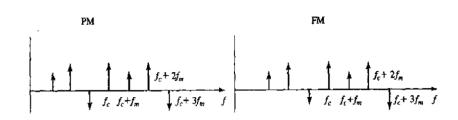


3.3.2 角度调制信号的频谱特性

· 将带宽内的谐波数量用M_c来表示,则

$$M_c = 2\lfloor \beta \rfloor + 3 = \begin{cases} 2\lfloor k_p a \rfloor + 3 & PM \\ 2 \left\lfloor \frac{k_f a}{f_m} \right\rfloor + 3, & FM \end{cases}$$

- 1. 带宽与谐波数量紧密相关。 相邻谐波间隔 f_m 。
- 2. a增加,带宽增加。
- 3. FM 信号的带宽对消息信 号的频率的敏感度较低
- 4. $FM, f_m \uparrow, M_c \downarrow$, 谐波之间的间隔 \uparrow , B_c 略微增加.
- 5. $PM, f_m \uparrow, M_c$ 不变,谐波之间的间隔 \uparrow , B_c 线性增大.



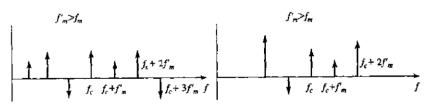


图 3.30 在 FM 和 PM 中增加消息带宽的影响



- 非正弦信号的角度调制
- Carson's rule (卡森公式)

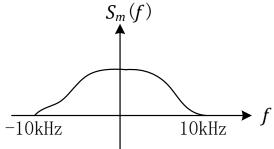
$$B_c = 2(\beta + 1)W$$

W是消息信号m(t)的带宽,且定义

$$\beta = \begin{cases} k_p \max[|m(t)|], & PM \\ \frac{k_f \max[|m(t)|]}{W}, & FM \end{cases}$$

角度调制信号的带宽远大于其它各种振幅调制信号的带宽。

- 信号m(t)的功率谱 $S_m(f)$ 如下图所示,信号从A点发送到B点。已知信号已经归一化,即 $-1 \le m(t) \le 1$ 。
- 1、如果采用USSB调制,已调信号带宽是多少?
- 2、如果采用 $\alpha = 0.8$ 的AM,已调信号带宽是多少?
- 3、如果采用 $k_f = 60kHz$ 的FM,已调信号带宽是多少?



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- 1、USSB信号带宽为10kHz;
- 2、 $\alpha = 0.8$ 的AM信号带宽为20kHz;
- 3、 $k_f = 60kHz$ 的FM信号

$$eta_{\text{FM}} = k_f \frac{max|m(t)|}{W} = 60k \frac{1}{10k} = 6$$
 $B_c = 2(\beta_{\text{FM}} + 1)W = 140\text{kHz}$

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3.3.3 角度调制器和解调器的实现 (自学或在高频电路课程中学习)

调制器

直接法:压控振荡器-变容二极管或电抗管.

间接法: 窄带调制→宽带调制.

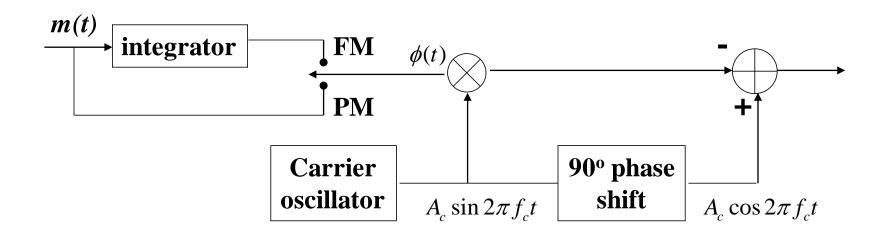


Figure 3.3.3 窄带调制信号的产生

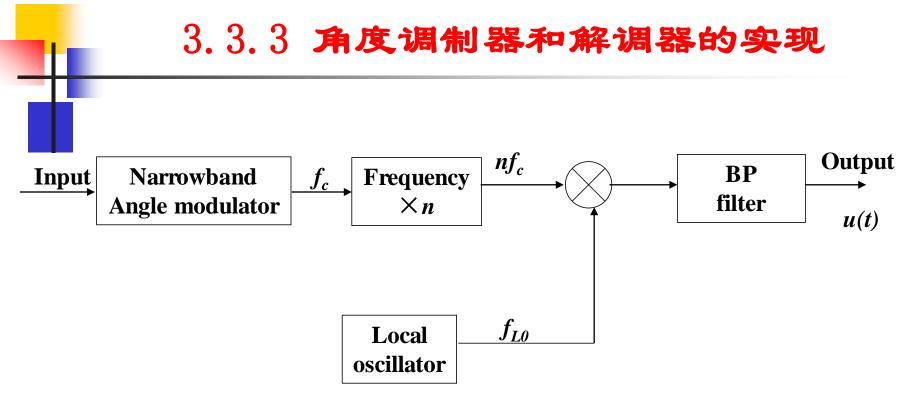


Figure 3.3.4 角度调制信号的间接法产生

$$u(t) = A_c \cos\left(2\pi (nf_c - f_{L0})t + n\phi(t)\right)$$

3.3.3 角度调制器和解调器的实现

解调器

1. Discriminator(鉴频器):

Differentiator(微分器)
or balance discriminator (鉴频器)

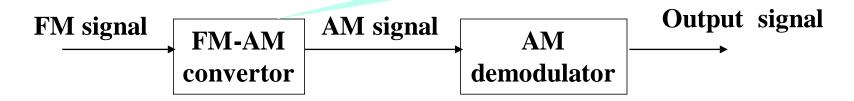


Figure 3.3.5 FM解调器

2. FM demodulator with feedback (FMFB, 调频负反馈)

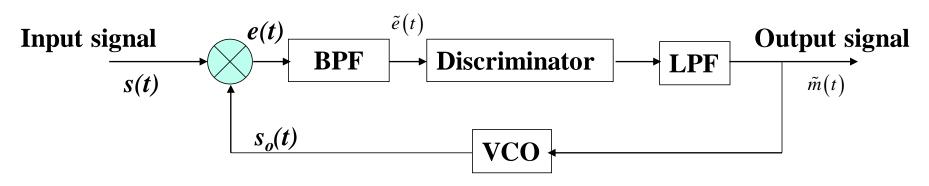
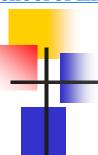


Figure 3.3.6 FMFB 解调器方框图



3.3 Angle Modulation

输入信号为

$$s(t) = A_c \cos\left(2\pi f_c t + \varphi(t)\right) = A_c \cos\left(2\pi f_c t + 2\pi k_f \int_{-\infty}^t m(\tau) d\tau\right)$$

VCO 的输出信号为

$$s_o(t) = A_o \cos\left(2\pi f_o t + \varphi_o(t)\right) = A_o \cos\left(2\pi f_o t + 2\pi k_v \int_{-\infty}^t \tilde{m}(\tau) d\tau\right)$$

则

$$\begin{split} &e(t) = A_c A_o \cos\left(2\pi f_c t + \varphi(t)\right) \cos\left(2\pi f_o t + \varphi_o(t)\right) \\ &= \frac{1}{2} A_c A_o \cos\left(2\pi (f_c - f_o)t + \varphi(t) - \varphi_o(t)\right) \\ &+ \frac{1}{2} A_c A_o \cos\left(2\pi (f_c + f_o)t + \varphi(t) + \varphi_o(t)\right) \end{split}$$

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3.3 Angle Modulation

假设 BPF 的中心频率为 f_c - f_o ,则

$$\tilde{e}(t) = \frac{1}{2} A_c A \cos(2\pi (f_c - f_o)t + \varphi(t) - \varphi_o(t))$$

鉴频器测的输出为瞬时频率偏移,故输出信号为误差信号相位偏移的微分,所以

$$\tilde{m}(t) = \frac{1}{2\pi} \frac{d\left[\varphi(t) - \varphi_o(t)\right]}{dt}$$

$$= \frac{1}{2\pi} \frac{d\left[\left(\int_{-\infty}^{t} 2\pi k_f m(\tau) - 2\pi k_v \tilde{m}(\tau)\right) d\tau\right]}{dt}$$

$$= k_f m(t) - k_v \tilde{m}(t)$$

$$\tilde{m}(t) = \frac{k_f}{1 + k_s} m(t)$$



■ 同时还有

$$\tilde{e}(t) = \frac{1}{2} A_c A \cos \left[2\pi (f_c - f_o)t + \left(\frac{1}{1 + k_v} \right) 2\pi k_f \int_{-\infty}^t m(\tau) d\tau \right]$$

是一个调制指数为 [1/(1+k_v)]的调频信号.

由于 $k_{\nu}>>1$,上述信号是一个窄带调频信号.

3. PLL-FM demodulator (工作原理自学,见pp89-90)

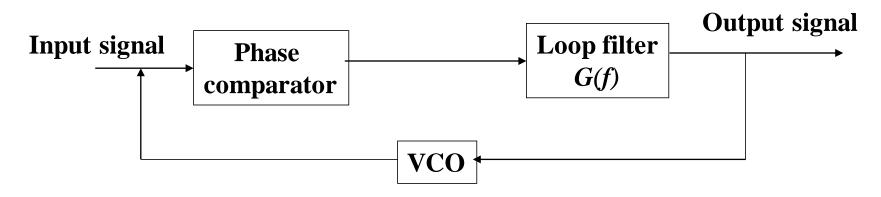
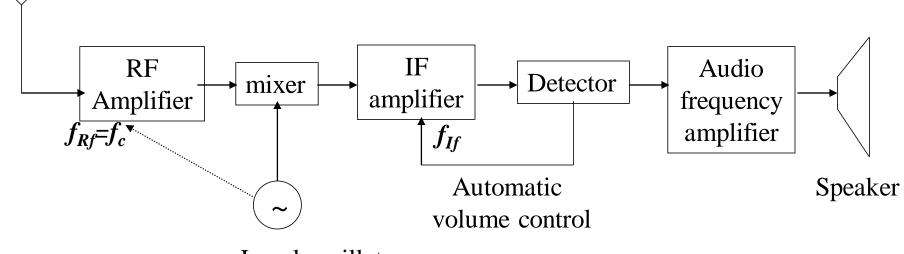


Figure 3.3.7 Block diagram of PLL-FM demodulator

3.4 无线电广播和电视广播 (自学或高频电路课程中学习)

■ 3.4.1 Superheterodyne AM receiver (超外差接收机)



Local oscillator f_{Lo}

Figure 3.4.1 超外差 AM 接收机

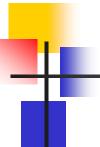
$$f_{LO} = f_{Rf} + f_{If} = f_c + f_{If}$$



 f_{RF} =535~1605kHz, f_{IF} =455kHz where is chosen to be below the lowest transmitted signal (<535kHz) but high enough to avoid radio frequency interference from image signals, whose frequency is f_{image} = f_{LO} + f_{If}

The function of the mixer (混频器) is as following:

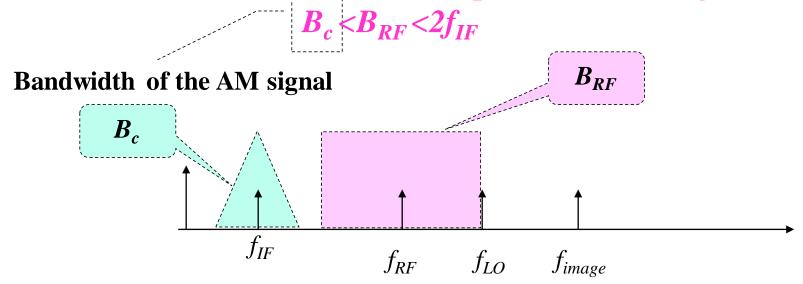
$$u_o(t) = u_i(t)\cos 2\pi f_{LO}t = m(t)\cos 2\pi f_c t \cos 2\pi f_{LO}t$$
$$= \frac{1}{2}m(t)[\cos 2\pi f_{IF}t + \cos 2\pi (2f_c + f_{IF})t]$$



3.4 Radio and Television Broadcasting

$$u_o(t) = u_i(t)\cos 2\pi f_{LO}t = m(t)\cos 2\pi f_{image}t\cos 2\pi f_{LO}t$$
$$= \frac{1}{2}m(t)[\cos 2\pi f_{IF}t + \cos 2\pi (2f_c + 3f_{IF})t)$$

So the bandwidth of the RF amplifier to the range





- 3.4.2 FM Radio Broadcasting (studying by yourself)
- **3.4.3** Television Broadcasting (studying by yourself)

Summarizing

Angle modulation

Including: basic idea and implementation

问题: 角度调制信号的带宽是多少?

$$B_c = 2(\beta + 1)W$$



Chapter 3

Thank you for your attention!

Any question?

