

ASSIGNMENT 03

Q.1) What is Mutual Exclusion? Explain its significance.

- Ans:
- 1) Mutual exclusion is one of the conditions for a deadlock to occur.
 - 2) It must be holding tree for non-shareable resources.
 - 3) Non-shareable resources include printer, memory space, etc.
- Significance of mutual exclusion:
 - 1) Prevents race around conditions.
 - 2) Prevents multiple threads to enter ~~the~~ critical section at the same time.

Q.2) Explain race condition with example?

- Ans:
- 1) A race condition takes place when more than one process write data items so that the final result depends on the order of execution of instructions in the multiple processes.
 - 2) Consider two processes, P_1 and P_2 , which share the global variable "X". At the time of execution process P_1 updates "X" to the value 1 and at the time of execution of another process, P_2 updates "X" to the value 2.
 - 3) Thus, the two tasks are in a race to write variable "X". In this example the process that modifies X value lastly decides the final value of "X".

Q.3>

Explain Critical Section problem. What are the requirements to solve critical-section problem?

Ans:

- 1) The portion of the program where the shared memory is accessed is referred as the Critical section.
- 2) In order to avoid race conditions and faulty results, one must be able to recognize codes in Critical Sections in each thread.
- 3) The typical properties of the code that comprises critical section are as follows
 - These codes reference one or more variables in a "read-update"-write way.
 - At the same time, any of those variables may be changed by another thread.
 - These codes modify one or more variables that can be referenced in "read-update-write" fashion by another thread.
 - Any part of data structure used by the code can be modified by another thread.
 - Codes modify any part of a data structure that is currently in use by another thread.
- 4) When one process is currently executing shared modifiable data in its critical section, other process is to be permitted to execute in its critical section.
- 5) Hence, the execution of critical sections by the processes is mutually exclusive in time.
- 6) In a code called as critical section, only one process executes at a time.
- 7) In a critical section problem, an algorithm ne

to be designed which permits at most one process into the critical section at a time, with no deadlock.

- 8) The critical section's problem solution must obey mutual exclusion, progress and bounded waiting. Any process directly cannot enter in critical section.
- 9) First process has to obtain permission for its entry in its critical section. The segment of code which implements this appeal of process is the entry section. When process comes out of the critical section after completing its execution, then it has to execute exit section.
- 10) The rest of the code is the remainder-section.
- 11) Any solution to the critical-section problem must satisfy the following three necessary conditions:

i) Mutual exclusion:

At a time, single process should be executing in critical section (CS). If currently process P₁ is executing in its CS then other processes should not execute in their critical sections.

ii) Progress:

If process P₁'s CS is free, means it is not executing in its CS. In this situation suppose some processes desire to go into their critical sections for executions.

iii) Bounded waiting:

A limit should be set on the number of times that other processes are permitted to go into their critical sections. After a process has made a request to go to its critical section and before.

that request is approved.

- 12) Semaphore and monitor are the solutions to achieve mutual exclusion.
- 13) A synchronization variable taking positive integers values is called semaphore. Binary semaphore only has two values 0 or 1.
- 14) A synchronization variable taking positive integers values is called counting semaphore.

Q. 6) Differen what is semaphore? Elaborate with the significance of semaphore?

Ans:

- 1) A semaphore S is integer variable whose value can be accessed and changed only by two operations wait and signal. Wait and signal are atomic operations.
- 2) Binary semaphores does not assume all the integer values.
- 3) It assumes only two values 0 and 1. On the contrary, counting semaphores can assume only non-negative values.
- 4) The wait operations on semaphore S , written as wait(S) or P(S), operates as follows:

wait(S): If $S > 0$

Then $S := S - 1$

Else (wait on S)

The signal operation on semaphore S, written as signal(S) or v(S), operates as follows:

signal(S): If one or more process are waiting on S
Then let one of these processes proceed
Else $S := S + 1$

Q: Differentiate counting and binary semaphores?

Ans:

Counting Semaphore	Binary semaphore
1° Can take any initial value	1° Can take only take 0 or 1
2° V operations never blocks.	2° Both P and V operation may block.
3° Completed P and V operations do not have to alternate.	3° Completed P and V operations must alternate.
4° If the initial value is 0, the first completed operation	4° If the initial value is 0, the first completed operation must be V; if the initial value is 1, the first completed operation must be P.

Q: Explain an algorithm for producer - consumer problem?

Ans:

- 1) In operating system Producer is a process which is able to produce data/item.
- 2) Consumer is a process that is able to consume the data/item produced by the producer.

3) Both Producer and Consumer share a common memory buffer. This buffer is a space of fixed size in the memory of the system which is used for storage. The producer produces the data into the buffer and the consumer consumes the data from the buffer.

So, what are the Producer - Consumer rules?

1. Producer Process should not produce any data when the shared buffer is full.
2. Consumer Process should not consume any data when the shared buffer is empty.
3. The access to the shared buffer should be mutually exclusive i.e. at a time only one process should be able to access the shared buffer and make changes to it.

For consistent data synchronization between Producer and Consumer, the producer process should be exclusive.

Q.7.7 Explain how readers-writers problem can be solved with semaphores?

Ans:

- 1) The readers-writers problem relates to an object such as a file that is shared between multiple processes. Some of these processes are reader i.e. they only want to read the data from the object and some of the processes are writer i.e. they want to write onto the object.
- 2) The readers-writers problem is used to maintain synchronization so that there are no problems with the object data.

3) For Example: If two readers access the object at the same time there is no problem. However, if two writers or a reader and writer access the object at the same time, there may be problems.

4) To solve this situation, a writer should get exclusive access to an object. However, multiple readers can access the object at the same time.

5) This can be implemented using semaphore. The codes for the reader and writer process in the reader-writer problem are given as follows-

Reader Process

```
wait (rmutex);  
rc++;  
If (rc == 1)  
wait (wrt);  
signal (rmutex);
```

Writer Process

```
wait (wrt);  
signal (wrt);
```

wait (rmutex)

```
rc--;  
If (rc == 0)  
signal (wrt);  
Signal (rmutex);
```

Q.8.) Explain dining philosopher problem and solve it?

Ans:

- 1) The dining philosopher problem states that there are 5 philosophers sharing a circular table. They eat and think alternatively.
- 2) There is a bowl of rice for each of the philosophers and 5 chopsticks. A philosopher needs both their right and left chopstick to eat.
- 3) A hungry philosopher may only eat if the chopsticks available.
- 4) Otherwise, a philosopher puts down their chopsticks and begins thinking again.
- 5) This problem is a classic synchronization problem as it demonstrates a large class of concurrency control problems.

- Solution of Dining Philosopher problem:

- 1) A solution to the Dining Philosophers Problem is to use a semaphore to represent a chopstick. A chopstick can be picked up by executing a 'wait' operation on the semaphore and released by executing a 'signal' operation.
- 2) The structure of chopstick is shown below:
semaphore chopstick [5];
- 3) Initially, the elements of the chopstick are initialized to 1 as the chopsticks are on the table and not picked up by a philosopher.
- 4) The structure of a random philosopher is given as follows:-

do {

 wait (chopstick[i]);

 wait (chopstick[(i+1) % 5]);

 signal (chopstick[i]);

 signal (chopstick[(i+1) % 5]);

} while(1);

5) In the above structure, first wait operation is performed on chopstick[i] and chopstick[(i+1)%5]. This means that the philosopher I have picked up the chopsticks on his sides. Then the eating function is performed.

6) After that, signal operation is performed on chopstick[i] and chopstick[(i+1)%5]. This means that the philosopher I have eaten and put down the chopsticks on his sides. Then the philosopher goes back to thinking.

Q.9.) Explain sleeping Barber problem? Solution to it?

Ans: i) The sleeping Barber problem, states the analogy is based upon a hypothetical barber shop with one barber.

2) There is a barber shop which has one barber, one barber chair, and n chairs for waiting for customers. If there are any to sit on the chair.

3) If there is no customer, then the barber sleeps in his own chair.

4) When a customer arrives, he has to wake up.

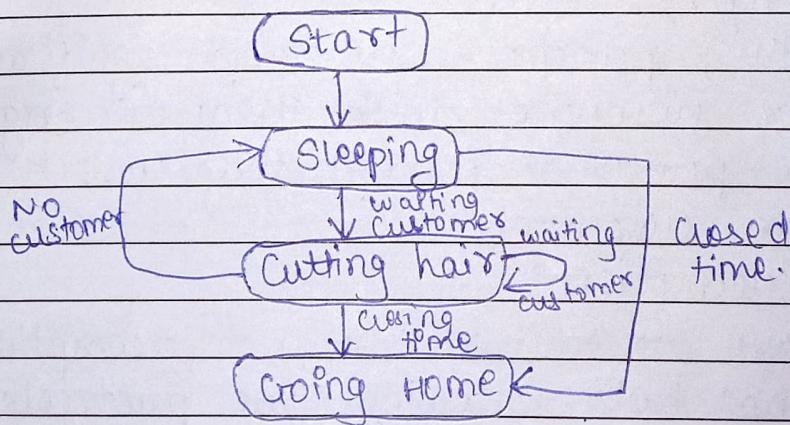
the barber.

- 5) If there are many customers and the barber is cutting a customer's hair, then the remaining customers either wait if there are empty chairs in the waiting room or they leave if no chairs are empty.

Solution:

- 1) The solution to this problem includes three semaphores.
- 2) First is for the customer which counts the number of customers present in the waiting room.
- 3) Second, the barber 0 or 1 is used to tell whether the barber is idle or is working. And the third mutex is used to provide the mutual exclusion which is required for the process to execute.
- 4) In the solution, the customer has the second of the number of customers waiting in the waiting room if the number of customers is equal to the number of chairs in the waiting room then the upcoming customers leaves the barbershop.
- 5) When the barber shows up in the morning, he creates the procedure barber, causing him to block on the semaphore customers because it is initially 0. Then the barber goes to sleep until the first customer comes up.

- 6) When a customer arrives, he executes customer procedure. The customer acquires the mutex for entering the critical region, if another customers enters thereafter, the second one will not be able to anything until the first one has released the mutex.
- 7) The customer then checks the chairs in the waiting room if waiting customers are less than the number of chairs then he sits otherwise he leaves and releases the mutex.
- 8) If the chair is available the customer sit in the waiting room and increments the variable waiting value and also increases the customer's semaphore this wakes up the barber if he is sleeping.
- 9) At this point, customer and barber are both awake and the barber is ready to give that person a haircut. When the haircut is over, the customer exits the procedure and if there are no customers in waiting room barber sleeps.



Q.10) What are four conditions that create a deadlock?

Ans:

1. The four conditions that create a deadlock.

a) Mutual exclusion:

- Non-sharable resources cannot be shared by processes simultaneously.
- If resources are non-sharable then mutual exclusion condition must hold for them.
- For example, it is not possible to use printer by many processes at the same time. Printer is non-sharable but read-only file is sharable resource and do not require mutually exclusive access.
- Therefore sharable resources such as read file cannot be involved in a deadlock.

b) Hold and wait:

- Here we have to see that hold and wait will never occur. There should be an axiom that, a process should request a resource only if it does not hold any other resource.

c) In this, processes will keep significant and popular resources with them forcing other processes to indefinitely wait for these resources.

c) NO Preemption:

- We have to ensure that no preemption condition does not hold. Following two protocols can be used.

- If a process at present keep some resources with it and requests another resource that cannot be immediately allocated to it, then all resources at present being held should be preempted.
- The list of the resources for which process is waiting is maintained. The preempted resources from the process are included in this list.
- The process now restart the execution provided that it can get back its old preempted resources in addition to the new ones that it is requesting.

d) Circular wait:

- To prevent the occurring of circular-wait condition inflict a total ordering of all resource types. In this case each process should request the resources in an increasing order of assigned numbers to the resources.
- Consider the condition to collection of resources types $R = \{R_1, R_2, \dots, R_n\}$. To this each resource type, a unique integer number is assigned.
- As resources are now recognized by their numbers it is easy to compare them.
- It is also easy to know if one resource precedes the other in our ordering.

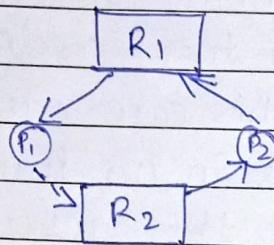
- Q.11) Write short note : a) Resource allocation Graph
 b) Deadlock Avoidance
 c) Dead lock detection
 d) Banker's algorithm.

Ans:

a) Recourse allocation graph:

- If system has resource allocation system with a one instance of each resource type, then only this algorithm is applicable.
- Claim edge in resource allocation graph is like a future request edge.
- When process request a resource, the claim edge is converted to a request edge.
- When a process releases, the assignment edge is converted to a claim edge.

Cycle detection: $O(n^2)$



b) Deadlock Avoidance:

- Deadlock avoidance requires that the system has some information available up front. Initially every process declares the maximum number of resources need which it may require.
- An alternative method for avoiding deadlock is to require additional information about how resources are to be requested.
- If the sequence in which processes will request the resource and will release it is known additionally, then we can decide for each request whether or not the process should wait.

c) Dead lock detection:

- If the system does not make use of deadlock prevention or deadlock detection algorithm, then system will observe the deadlock situation. In this situation, it is necessary that, system should have:
- 1) Algorithm which examines the state of the system to decide whether a deadlock has occurred or not.
 - 2) Algorithm to recover from deadlock if it occurred
 - 3) Both the algorithm requires the overhead including run time cost of maintaining necessary information and executing the detection algorithm and potential losses which are natural in recovering from deadlock.

d) Banker's algorithm:

- It is applicable to the resources allocation system with multiple instances of each resource type.
- It is less efficient than resource - allocation graph algorithm.
- Newly entered process should declare maximum number of instances of each resource type which it may require.
- The request should not be more than total number of resources in the system.

Q.12. >

what is difference between deadlock avoidance and prevention.

Ans:

Deadlock avoidance

1. It blocks at least one of the conditions necessary for deadlock to occur.
2. All the resources are requested together.
3. Sometimes, preemption occurs more frequently.
4. Deadlock prevention has low device utilization.

5. E.g: Spooling and non-blocking synchronization algorithms are used.

Deadlock Prevention

1. It ensures that system does not get in unsafe state.
2. Resource requests are done according to the availability safe path.
3. In deadlock avoidance, there is no preemption.
4. Deadlock avoidance, can block processes for too long.
5. E.g Bunker's and safety algorithm is used.