view\_frames Result Recorded at time: 1638200641.055 world Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.206 Hz Most recent transform: 1638200641.016 ( 0.039 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.899 sec table link\_1 base camera\_bottom\_screw\_frame setup\_camera Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10.206 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 1638200641.016 ( 0.039 sec old) Buffer length: 0.000 sec Buffer length: 4.899 sec link\_2 camera\_link Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.206 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) | Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 1638200641.016 ( 0.039 sec old) Buffer length: 0.000 sec Buffer length: 4.899 sec camera\_gyro\_frame link\_3 camera\_depth\_frame camera\_color\_frame camera\_infra1\_frame camera\_infra2\_frame camera\_accel\_frame Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /camera/realsense2\_camera\_manager Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10.206 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 1638200641.016 ( 0.039 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec Buffer length: 4.899 sec Buffer length: 0.000 sec camera\_color\_optical\_frame camera\_infra2\_optical\_frame camera\_accel\_optical\_frame camera\_infra1\_optical\_frame camera\_gyro\_optical\_frame link\_4 camera\_depth\_optical\_frame Broadcaster: /robot\_state\_publisher Broadcaster: /opencv\_example Average rate: 10000.000 Hz Average rate: 10.206 Hz Most recent transform: 1638200640.106 ( 0.949 sec old) Most recent transform: 1638200641.016 ( 0.039 sec old) Buffer length: 4.899 sec Buffer length: 0.000 sec link\_5 object\_pose Broadcaster: /robot\_state\_publisher Average rate: 10.206 Hz Most recent transform: 1638200641.016 ( 0.039 sec old) Buffer length: 4.899 sec link\_6 Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec flange Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec tool0 Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec spray\_tool Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1638200641.055 sec old) Buffer length: 0.000 sec