type name: CIVIC 1st LH DOM SLL3



#### type management

#### <u>general</u>

Input typename CIVIC 1st LH DOM SLL3
set of boundery parts 49

retractor

retractor article code P34361270A

retractor type top-connect

retractor laser job number 1

**MGG** 

MGG article code 34311248

MGG color 5 - light grey YAZAKI top-connect

 MGG cam angle tolerance
 10.000 [deg.]

 FW max. - angle pos.
 190.000 [deg.]

 FW - set angle pos.
 180.000 [deg.]

FW min. - angle pos. 170.000 [deg.]

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type name: CIVIC 1st LH DOM SLL3



# positions, speed, geometry & clamping force

### Z1 - axis: feed spindle

basic position / start loading position MGG	270.000	[mm]
planarity measuring position	232.800	[mm]
MGG transfer position / end loading position MGG	225.500	[mm]
MGG nok unload position	225.000	[mm]
basic position feed	1500.0	[mm]
full speed feed	30000.0	[mm]

#### X1 - axis: stator clamping

basic position	61.000	[mm]
pre position clamping	12.800	[mm]
clamping pos.	12.600	[mm]
full speed feed	5000.0	[mm/min]

#### geometry data

1. chuck length spindle	97.000	[mm]
2. unsupported length spindle	0.000	[mm]
3. part length spindle	3.000	[mm]
4. free length spindle (cup-length)	32.000	[mm]
5. chuck length stator clamping	23.000	[mm]
6. unsupported length stator clamping	5.000	[mm]
safety distance	1.000	[mm]

<u>stat</u>	or c	<u>lam</u>	ping	ı				selection	n	nin force	max force

selection clamping force - control active	no			
setpoint clamping force		22.0	24.0	[kN]
monitoring clamping force	yes	20.0	25.0	[kN]

<u>planarity sensor</u>	selection	min	max	
monitoring planarity MGG	yes	0.000	0.070	[mm]
monitoring distance MGG	no	0.000	0.000	[mm]

#### contact pos.

monitoring - contact pos.	yes	123.800	126.000	[mm]
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	overv	iew - setp	oints			
setpoint clamping force				24.0	[kN]	
contacting safety distance before Start			way [mm]	force [kN]	feed [mm/min]	
pat down before clamping		no	5.000	3.0		
pat down after clamping		yes		15.0		
contact mode				force ct	r. (rot.)	
contacting parameter			4.000	6.000	200.000	
lifting			0.600	,	2000 000	
recontact			0.400		8000.000	
process friction welding						
phase friction welding	1.friction 1	2.friction 2	3.braking	4.upsetting 1	5.upsetting 2	
force	9.000	5.000		9.000	9.000	[kN]
force gradient time	0.000	0.080		0.050	0.020	[s]
rotation	14000.0	14000.0		2000.0		[rpm]
switch - mode	time	time		time		
process time	0.030	0.100	+0.020	0.040	0.250	[s]
reduction	0.020	0.040	+0.000	0.100	0.100	[mm]
angle pos.	180.000	[degree]				
set angle pos.	yes					
process control	0. contacting	1. friction 1	2. friction 2	4. upsetting 1	5. upsetting 2	
Kp: P - contribution	4.000	3.000	2.000	2.000	1.000	[s]
Tn: I - contribution	0.000	0.000	0.000	0.000	0.000	[s]
Tv: D - contribution	0.000	0.250	0.270	0.270	0.300	
V_max	300.000	150.000	250.000	600.000	300.000	[mm/min]
V_offset		0.000	0.000	0.000	0.000	[% V_max]

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### overview - monitoring values

process time	1. friction 1	2. friction 2	3. braking	4. upsetting 1	5. upsetting 2	rotation speed = 0	
selection	yes	yes	yes	yes	yes	yes	
maximum - time	0.035	0.105	0.230	0.045	0.255	0.320	[s]
minimal - time	0.025	0.095	0.190	0.035	0.245	0.245	[s]
force gradient time	1. friction 1	2. friction 2		4. upsetting 1	5. upsetting 2		
selection	no	no		no	no		
maximum - time	0.000	0.000		0.025	0.000	[s]	
minimal - time	0.000	0.000		0.008	0.000	[s]	
reduction	1. friction 1	2. friction 2	3. braking /		5. upsetting 2	overall	
selection		no	4.upsetting 1				
	no		yes		no	yes	
maximum - reduction	0.280	0.100	1.200		0.140	1.900	[mm]
minimal - reduction	0.100	0.025	0.700		0.020	1.000	[mm]
<u>rotation</u>	1. friction 1	2. friction 2		4. upsetting 1			
selection	yes	no		no			
maximum - rotation	14100.0	13010.0		27.0	[rpm]		
minimal - rotation	12000.0	12990.0		-120.0	[rpm]		

<u>part length</u>	part length
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 selection
 no

 maximum - length
 0.00
 [mm]

 minimal - length
 0.00
 [mm]

### <u>part angle</u> angle pos.

maximum - angle 190.000
minimal - angle 170.000

[deg.]

[deg.]

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# overview - force envelope settings

overall- activation	yes				
friction 1	min force	max force		phase - time	
point 1	+5.000	+8.500	[kN]	0	[ms]
point 2	+6.500	+10.500	[kN]	13	[ms]
point 3	+6.500	+11.200	[kN]	22	[ms]
point 4	+6.500	+11.700	[kN]	30	[ms]
point 5	+6.500	+12.000	[kN]	38	[ms]
activation	yes				
friction 2	min force	max force		phase - time	
point 1	+6.500	+12.000	[kN]	0	[ms]
point 2	+6.500	+12.500	[kN]	16	[ms]
point 3	+5.300	+9.500	[kN]	70	[ms]
point 4	+4.400	+6.500	[kN]	120	[ms]
point 5	+4.200	+6.400	[kN]	290	[ms]
activation	yes				
activation	yes				
upsetting 1	min force	max force		phase - time	
upsetting 1 point 1	min force +4.200	+6.400	[kN]	0	[ms]
upsetting 1 point 1 point 2	min force +4.200 +3.000	+6.400	[kN]	0 12	[ms]
upsetting 1 point 1 point 2 point 3	min force +4.200 +3.000 +2.500	+6.400 +5.900 +5.600	[kN]	0 12 18	
upsetting 1 point 1 point 2 point 3 point 4	min force +4.200 +3.000 +2.500 +2.000	+6.400 +5.900 +5.600 +4.500	[kN]	12 18 30	[ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5	min force +4.200 +3.000 +2.500	+6.400 +5.900 +5.600	[kN]	0 12 18	[ms]
upsetting 1 point 1 point 2 point 3 point 4	min force +4.200 +3.000 +2.500 +2.000	+6.400 +5.900 +5.600 +4.500	[kN] [kN] [kN]	12 18 30	[ms] [ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5	min force +4.200 +3.000 +2.500 +2.000 +2.000	+6.400 +5.900 +5.600 +4.500	[kN] [kN] [kN]	12 18 30	[ms] [ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5 activation	min force +4.200 +3.000 +2.500 +2.000 +2.000 yes	+6.400 +5.900 +5.600 +4.500 +5.500	[kN] [kN] [kN]	0 12 18 30 38	[ms] [ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5 activation upsetting 2	min force +4.200 +3.000 +2.500 +2.000 +2.000 yes min force	+6.400 +5.900 +5.600 +4.500 +5.500	[kN] [kN] [kN]	0 12 18 30 38 phase - time	[ms] [ms] [ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1	min force +4.200 +3.000 +2.500 +2.000 +2.000 yes min force +2.000	+6.400 +5.900 +5.600 +4.500 +5.500 max force +5.500	[kN] [kN] [kN]	0 12 18 30 38 phase - time	[ms] [ms] [ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1 point 2	min force +4.200 +3.000 +2.500 +2.000 +2.000 yes min force +2.000 +4.000	+6.400 +5.900 +5.600 +4.500 +5.500 max force +5.500 +9.000	[kN] [kN] [kN] [kN]	0 12 18 30 38 phase - time 0 12	[ms] [ms] [ms] [ms]
upsetting 1 point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1 point 2 point 3	min force +4.200 +3.000 +2.500 +2.000 +2.000 yes min force +2.000 +4.000 +7.000	+6.400 +5.900 +5.600 +4.500 +5.500 max force +5.500 +9.000 +10.500	[kN] [kN] [kN] [kN] [kN]	0 12 18 30 38 phase - time 0 12 28	[ms] [ms] [ms] [ms] [ms]

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# overview - distance envelope settings

overall- activation	yes				
friction 1	min dist.	max dist.		phase - time	
point 1	-0.030	+0.030	[mm]	0	[ms]
point 2	+0.000	+0.060	[mm]	10	[ms]
point 3	+0.015	+0.070	[mm]	15	[ms]
point 4	+0.030	+0.080	[mm]	20	[ms]
point 5	+0.040	+0.100	[mm]	28	[ms]
activation	yes				
friction 2	min dist.	max dist.		phase - time	
point 1	+0.040	+0.100	[mm]	0	[ms]
point 2	+0.060	+0.200	[mm]	30	[ms]
point 3	+0.100	+0.460	[mm]	100	[ms]
point 4	+0.330	+0.870	[mm]	210	[ms]
point 5	+0.550	+1.250	[mm]	302	[ms]
activation	yes				
upsetting 1	min dist.	max dist.		phase - time	
upsetting 1 point 1	min dist. +0.550	max dist. +1.250	[mm]	phase - time	[ms]
			[mm]	_	[ms]
point 1	+0.550	+1.250		0	
point 1 point 2	+0.550	+1.250	[mm]	0 12	[ms]
point 1 point 2 point 3	+0.550 +0.600 +0.670	+1.250 +1.300 +1.400	[mm]	0 12 22	[ms]
point 1 point 2 point 3 point 4	+0.550 +0.600 +0.670 +0.830	+1.250 +1.300 +1.400 +1.570	[mm] [mm]	0 12 22 38	[ms] [ms]
point 1 point 2 point 3 point 4 point 5	+0.550 +0.600 +0.670 +0.830 +0.870	+1.250 +1.300 +1.400 +1.570	[mm] [mm]	0 12 22 38	[ms] [ms]
point 1 point 2 point 3 point 4 point 5 activation	+0.550 +0.600 +0.670 +0.830 +0.870 yes	+1.250 +1.300 +1.400 +1.570 +1.600	[mm] [mm]	0 12 22 38 42	[ms] [ms]
point 1 point 2 point 3 point 4 point 5 activation upsetting 2	+0.550 +0.600 +0.670 +0.830 +0.870 yes min dist.	+1.250 +1.300 +1.400 +1.570 +1.600	[mm] [mm] [mm]	0 12 22 38 42 phase - time	[ms] [ms] [ms]
point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1	+0.550 +0.600 +0.670 +0.830 +0.870 yes min dist. +0.870	+1.250 +1.300 +1.400 +1.570 +1.600 max dist. +1.600	[mm] [mm] [mm]	0 12 22 38 42 phase - time	[ms] [ms] [ms]
point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1 point 2	+0.550 +0.600 +0.670 +0.830 +0.870 yes min dist. +0.870 +1.000	+1.250 +1.300 +1.400 +1.570 +1.600 max dist. +1.600 +1.900	[mm] [mm] [mm] [mm]	0 12 22 38 42 phase - time 0 28	[ms] [ms] [ms] [ms]
point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1 point 2 point 3	+0.550 +0.600 +0.670 +0.830 +0.870 yes min dist. +0.870 +1.000	+1.250 +1.300 +1.400 +1.570 +1.600 max dist. +1.600 +1.900 +1.900	[mm] [mm] [mm] [mm] [mm]	0 12 22 38 42 phase - time 0 28	[ms] [ms] [ms] [ms]
point 1 point 2 point 3 point 4 point 5 activation  upsetting 2 point 1 point 2 point 3 point 4	+0.550 +0.600 +0.670 +0.830 +0.870 yes  min dist. +0.870 +1.000 +1.000	+1.250 +1.300 +1.400 +1.570 +1.600 max dist. +1.600 +1.900 +1.900	[mm] [mm] [mm] [mm] [mm] [mm]	0 12 22 38 42 phase - time 0 28 120 200	[ms] [ms] [ms] [ms] [ms] [ms]

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