

Geometry

2021年7月30日

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§ 1 Introduction

1. represent geometry

Implicit

- points that satisfy specific relationship $F(x,y,z) = 0$
- Constructive Solid Geometry (Boolean operations) $A \cup B$; $A \cap B$; $A \setminus B$
- Distance Functions
- Level Set Methods
- Fractals $\approx \frac{1}{3}$

Inside/Outside is easy

Sampling is easy

Explicit

- given directly
- parameter mapping

$$- : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad (uv) \rightarrow (x,y,z)$$

§ 2 Curves and Surfaces

1. Point Cloud (Explicit)

List of points

Useful for LARGE datasets
often converted into meshes

2. Polygon Mesh

Easy to process / sample/ simulate.
More complicated data structures

3. How to represent an object.

The Wavefront Object File (.obj) Format

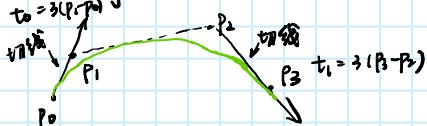
a text file that specifies vertices, normals, texture coordinates
and connectivities.

How vertices are connected
with each other.

4. Curves

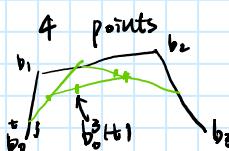
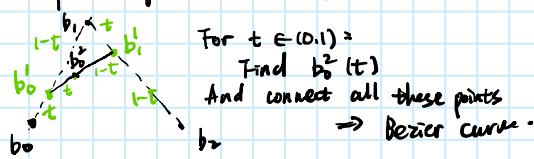
Bézier Curve

Defining Cubic Bézier Curve with tangents



de Casteljau Algorithm.

3 points (quadratic Bézier)



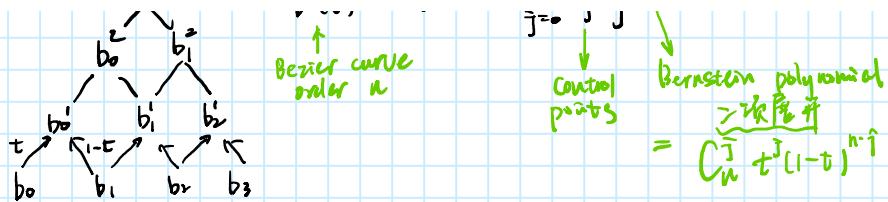
Algebraic Formula

$$b^n(t) = b_0^n(t) = \sum_{j=0}^n b_j B_j^n(t)$$

Bezier curve order n

control

Bernstein polynomial



Properties of Bezier curve.

$$\text{cubic} = b(0) = b_0, b(1) = b_3$$

$$b'(0) = 3(b_1 - b_0), b'(1) = 3(b_3 - b_2)$$

transform curve by transforming control points

(Affine transformation property Note! projection isn't Affine trans.)

Curve is within convex hull of control points
(convex property)

C^0 continuity :

C^1 continuity : $f'(x) \rightarrow$ continuous



5. Other types of splines

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- B-splines

- basic splines

- satisfy all important properties that Bezier curves have -

refer to 魏书生's course on CG.

b. Surfaces

extend Bezier curve to surfaces

4x4 array of control points

每行4个点插值得到一个点，共4个点

对这些点做 Bezier 曲线

对不同 t. 该曲线扫过面积为曲面



Evaluating Bezier surfaces

7. Mesh operations = Geometry Processing

① Mesh subdivision upsampling

② Mesh simplification down sampling

③ Mesh regularization. = modify sample distribution

§ 3

1. Subdivision

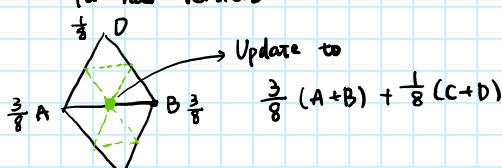
- Loop subdivision

① Split triangles

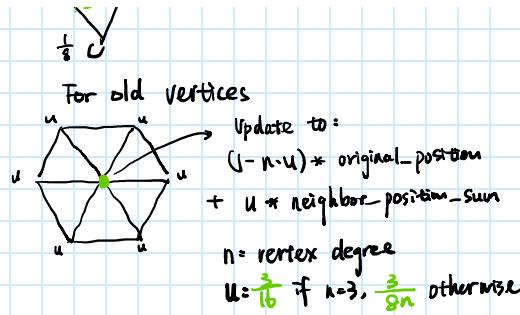


② Assign new vertex positions according to weights

For new vertices



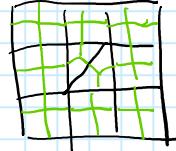
For old vertices



- Catmull - Clark Subdivision General Mesh.

- Subdivision Step:

- add vertex in each face
- add midpoint on each edge
- Connect all new vertices



- FYI: Vertex Update Rules (Quad Mesh)

Face point

$$f = \frac{v_1 + v_2 + v_3 + v_4}{4}$$

Edge point

$$e = \frac{v_1 + v_2 + f_1 + f_2}{4}$$

Vertex point

$$v = \frac{f_1 + f_{12} + f_2 + f_3 + 2(m_1 + m_2 + m_3 + m_4) + q_p}{16}$$

2. Mesh Simplification

① edge collapse

Quadratic Error metric

new vertex should minimize L2 distance to previously related triangle planes

Idea: compute edge midpoint, measure quadratic error



Iteratively collapse edges

Assign score with quadratic error metric.

- approximate distance to surface as sum of distances to planes containing triangles
- iteratively collapse edge with smallest score
- greedy algorithm.