# Wirebridge Example Code for PowerBasic

There are currently 3 models of Wirebridge available.

Model 1A with 8 I/O pins, 3 channels of PWM output, SPI and I2C connectivity. This is 3.3Volt or 5V switched.

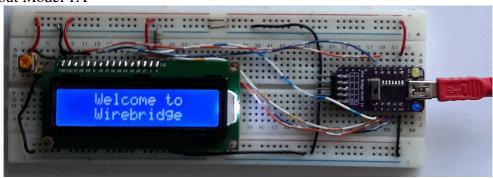
Model 1B with 8 I/O pins, 3 channels of PWM output, SPI and I2C connectivity. This is 5V only.

Model 2 with 6 Output pins, 2 input Pins and 2 PWM channels. This has open drain mosfet outputs which can tolerate up to 24v. The inputs can also handle voltages up to 24V if needed.

### Model 1A

Sample code for driving a 2 line by 16 character LCD using a Hitachi HD44780 controller or compatible chipset. This will work with the model 1B. With modification it could be made to work with a Model 2 but would require resistors/ transistors and a powersupply, just not sensible.

Breadboard layout Model 1A



**Note** with 8 pins the Nibble (2 off 4bit data chunks) method is used to display info on the LCD using a total of 6 pins.

This is wired as follows:

LCD Pins 1(VSS) and 5(R/W) to ground (0V)

LCD Pin 2(VDD) to 5V

LCD Pin 3(V0) to a 10k pot for contrast. \*

LCD Pin4 (RS) to Wirebridge pin 3

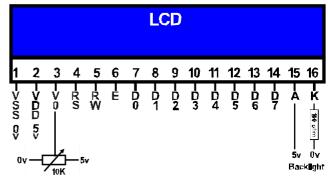
LCD Pin 6 (E) to Wirebridge pin 4

LCD pin 11 (D4) to Wirebridge pin 5

LCD pin 12 (D5) to Wirebridge pin 6

LCD pin 13 (D6) to Wirebridge pin 7

LCD pin 14 (D7) to Wirebridge pin 8



The Wirebridge 5V and Ground pins provide the power, a WB can provide upto 100ma but the LCD only needs 10-20ma depending on the backlight so this is fine.

To drive the LCD a sample PowerBasic Program is provided as source code and compiled.

<sup>\*</sup>Anything between 1 and 10k is OK.

The program demonstrates the following functions but is not intended as a PowerBasic Tutorial. In the Wirebridge.inc file the function calls are detailed along with the types of variable used. For example the WB\_SetMultiplePinsDigital Function is as follows.

The return is a byte – called wb\_outcome to follow the convention in the API documentation for other languages. The WB\_SMPD\_ENTRY is a double word pointer (address) of an array of type WB\_SMDP which is defined in the Wirebridge.inc as two bytes

```
TYPE WB_SMPD_ENTRY

WB_PIN_NUMBER AS BYTE 'pin_number internal of the WB there is an ENUM for this

WB_SMPD_STATE AS BYTE 'state, this is defined by an ENUM.

END TYPE
```

```
ENUM WB_Model1A 'Byte)
                                  ENUM WB_SMPD_STATE 'Byte
 Pin1 = 5
                                       OutputLow = \&b00 '(0)
                                       OutputHigh = \&b01 '(1)
 Pin2 = 4
 Pin3 = 13
                                       OutputFloat = &b10 '(2)
 Pin4 = 12
                                       InputSet = \&b11 '(3)
 Pin5 = 11
                                  END ENUM
 Pin6 = 10
 Pin7 = 9
 Pin8 = 8
                                DIM Array (7) AS WB SMPD ENTRY
 PWM_Channel1 = 5
                                'to set Array(0) to WB Model 1A Pin 1 and Output
 PWM Channel2 = 13
                                'high the following is needed.
                                Array(0).WB PIN NUMBER = WB Model1A.Pin1
 PWM Channel3 = 11
                                Array(0).WB SMPD STATE = WB SMPD STATE.Outputhigh
 SPI MOSI = 10
  SPI MISO = 9
  SPI SCK = 8
  I2C SDA = 9
                   'i2c
  I2C SCL = 8
                   'i2c
  LED Pin = 8
END ENUM
```

Other Functions used in this example are.

```
Result = WB_EnumerateDevicesBegin(WBERR)
wb_outcome = WB_EnumerateDevicesNext( DevHandle, DEVINFO,WBERR)
Result = WB_EnumerateDevicesEnd( DevHandle)
WB_DevHandle = WB_OpenDevice( VARPTR(wb_path) , WBERR )
Result = WB_BuildTimestamp(dtp)
wb_outcome = WB_SetPinDirection ( WB_Devhandle, WB_PIN_NUMBER, WB_PIN_DIR,WBERR))
wb_outcome = WB_WritePinDigital(WB_Devhandle, WB_PIN_NUMBER,WB_DIGITAL_PIN_VALUE, WBERR)
wb_outcome = WB_SetMultiplePinsDigital(WB_Devhandle,WB_SMPD_ENTRY,PCOUNT,WBERR)
```

The WBERR, which is a pointer to an error structure can be replaced with BYVAL %NULL if not required.

The first subroutine enumerates the Wirebridges to discover what is attached. This is generic and can be used as a template for other Wirebridge programs to list suitable available boards.

Example program subroutines used to communicate with the Wirebridge and on to the LCD.

### EnumWB (hdlg, WB\_DEVICEHANDLE, reply, Myerror)

This Sub returns the WB device handle, as well as information on what is found and any error message. On exit it sets the WB DEVICEHANDLE as a Global variable for ease of use.

```
SUB EnumWB(hdlg AS LONG, WB_DEVHANDLE AS DWORD, reply AS STRING, MyError AS STRING)
LOCAL WbErr AS WB_ERROR PTR
LOCAL WB_ERR AS WB_ERROR
LOCAL DT AS WB_Datetime
                                  'Pointer to the error structure
                                  'Variable of type WB_ERROR
                                  'Variable of Type WB_DateTime
LOCAL DTP AS WB_DATETIME PTR
                                  'Pointer to the WB_DateTime Structure
LOCAL result, I, J AS LONG
LOCAL devinfo AS WB ENUMDEVINFO PTR 'Pointer to WB ENUMDEVINFO structure
LOCAL wb Outcome AS BYTE
LOCAL WB Path AS WSTRINGZ * %MAX PATH 'Path to the USB info
LOCAL model AS STRING
WBERR=VARPTR (WB ERR)
                                 'set the wberr pointer up
wb_path = STRING$$(%MAX_PATH, 32) 'sets up the path variable filled with spaces
wb_dev.USB_path = VARPTR (wb_path) 'Set the pointer to the string for the path
devinfo = VARPTR(wb_dev)
                                 'Set the devinfo pointer up
                                 'Set the datetime pointer up
dtp=VARPTR(DT)
WB_DEVENUMERATION = WB_EnumerateDevicesBegin ( wberr) 'Call and retrieve the handle
IF WB_DEVENUMERATION=%False THEN
                                           'Test if a handle is returned
 myerror=WB ERRORTYPE(@wberr.WB ERRORTYPE) 'extract the readable error
                                           'Bail out and return the error (MyError)
 EXIT SUB
END IF
'Handle returned so find the Wirebridge(s) - this is set to exit on first it could be
'modified to give a list of found devices. This is left to the user.
DO
 wb_outcome = WB_EnumerateDevicesNext ( WB_DEVENUMERATION, devinfo, Wberr)
 model = wb_dev.devinfo.productname ' extract the model name from the pointer
    IF INSTR (model, "1B") THEN
      reply="Wirebridge 1B found"
                                   'comment out if not wanted
                                    'comment out if not wanted
      EXIT LOOP
    ELSEIF INSTR (model, "1A") THEN
      reply="Wirebridge 1A found"
                                   'comment out if not wanted
      EXIT LOOP
                                    'comment out if not wanted
    ELSEIF INSTR (model, "2") THEN
     ' reply="Wirebridge 2 found"
                                   'comment out if not wanted
     ' EXIT LOOP
                                     'comment out if not wanted
    END IF
                                          'none attached
    myerror="Device not detected"
                                          ' return a message
                                          ' Bail out
   EXIT SUB
  END IF
'Arrived with a model 1A or IB these are usable, first job is end the enumeration.
Result = WB_EnumerateDevicesEnd(WB_DEVENUMERATION) 'close Enumeration
   Now Open the Wirebridge device and make the handle global for ease of use
WB_DevHandle = WB_OpenDevice( VARPTR(wb_path) , WBERR ) 'retrieve the handle
IF result=%False THEN
                                           'bad handle is an oops!
 myerror=WB_ERRORTYPE(@wberr.WB_ERRORTYPE)
                                          'return error
 EXIT SUB
                                           'and bail out
END IF
'getinformation from the DLL on its build to make sure its usable!
result = WB_BuildTimestamp(dtp)
```

```
'reply currently contains the model now check and add the DLL date and the
Wirebridge.in date, test it!
I= VAL(PARSE$($Dlldate,"/",1))*1000+VAL(PARSE$($Dlldate,"/",2))*40 + _
  +VAL(PARSE$($Dlldate, "/", 3))
J= dt.year*1000+ DT.MONTH*40+ DT.Day
IF J=>I THEN
                                                       ' great its later or the same
   Reply = Reply+$CRLF+"Wirebridge DLL suitable"+$CRLF
ELSEIF I>J THEN
                                                        'problem
   Reply =Reply+$CRLF+"DLL is too old, Newer needed"+$CRLF
   Reply=Reply+"Use after "+$DLLDATE
   CONTROL SET USER hdlg, %IDC_BUT_ENUM, 0, 1 'disable buttons
   MyError="Wirebridge DLL out of date"
   EXIT SUB
                                              'Bail Out
END IF
'Update the reply text
 reply = reply +$CRLF+"Requires DLL Date "+$DLLDATE +$CRLF +_
          "Using"+STR$(dt.year)+"/"+TRIM$(STR$(DT.MONTH))+"/"+
          TRIM$ (STR$ (DT.Day)) + STR$ (DT.Hour) + ": "+RIGHT$ ("0"+TRIM$ (STR$ (dt.minute)), 2)
 GWB_DEVHANDLE = WB_DevHandle 'Finally setup the global gWb_devHandle
 END SUB
```

#### Find and Initilise Wirebridge

Wirebridge 1A found Wirebridge DLL suitable Requires DLL Date 2024/04/05 Using 2024/4/8 15:13

## Find and Initilise Wirebridge

Wirebridge 1A found DLL is too old, Newer needed Use after 2024/05/05

Once the Wirebridge is found and is suitable and the DLL is OK then setup the LCD

There are 2 basic subroutines

SendCommand 'sends a command SendData 'send data

These simply emulate how the LCD is used by setting pins and toggling the RS and E lines.

Everything else including setting up the LCD is done by calling these routines with data/commands

```
SUB sendcommand (cmd AS BYTE)
  LOCAL wb_outcome, LN , HN, BT AS BYTE
  LOCAL WbErr AS WB_ERROR PTR
  LOCAL WB_ERR AS WB_ERROR
  LOCAL RS, E AS BYTE
  LOCAL P1, P2, P3, P4, P5, P6, p7, P8 AS BYTE
  LOCAL I AS LONG
  DIM pinmask(7) AS WB_SMPD_ENTRY
  LOCAL Pmask, pcount AS LONG' Used as pointer
   WbErr = VARPTR (WB_ERR)
   'setup the LCD pins
   rs=%WB_Model1A.pin3
   E =%WB_Model1A.pin4
   pinmask(0).wb_pin_number=%WB_Model1A.pin5 'setup Pinmask() to actual pin
   pinmask(1).wb_pin_number=%WB_Model1A.pin6 'two blocks of 4 in this case
   pinmask(2).wb_pin_number=%WB_Model1A.pin7 \ for the two nibbles
   pinmask(3).wb_pin_number=%WB_Model1A.pin8
```

```
pinmask(4).wb_pin_number=%WB_Model1A.pin5
   pinmask(5).wb_pin_number=%WB_Model1A.pin6
   pinmask(6).wb_pin_number=%WB_Model1A.pin7
   pinmask(7).wb_pin_number=%WB_Model1A.pin8
   'makesure E is high and RS low as this is the command option.
   wb_outcome = WB_WritePinDigital(qWB_Devhandle ,E, %DP_Value.high, WBERR)
                                                                               'Enable
   wb_outcome = WB_WritePinDigital(gWB_Devhandle ,RS, %DP_Value.low, WBERR)
                                                                               'Command
  pinmask(0).wb smpd state = BIT(cmd, 0) 'this sets the mask to the
  pinmask(1).wb_smpd_state = BIT(cmd,1) 'bit value in the BYTE
  pinmask(2).wb_smpd_state = BIT(cmd,2)
  pinmask(3).wb_smpd_state = BIT(cmd,3)
  pinmask(4).wb_smpd_state = BIT(cmd,4)
  pinmask(5).wb_smpd_state = BIT(cmd,5)
  pinmask(6).wb_smpd_state = BIT(cmd,6)
  pinmask(7).wb_smpd_state = BIT(cmd,7)
      'send HIGH nibble first that is Pinmask 4/5/6/7 Set the pointer to pinmask(4) and
      tell the WB to use the next 4 as WB_SMPD_ENTRY
                               ' point to the High nibble it starts at pinmask(4)
    PMask = VARPTR(pinmask(4))
                                '4 pins at once
    pcount=4
   wb_outcome = WB_SetMultiplePinsDigital(gWB_Devhandle,pMask,PCOUNT,BYVAL %NULL)
   wb_outcome = WB_WritePinDigital(gWB_Devhandle ,E, %DP_Value.low, WBERR)
   wb_outcome = WB_WritePinDigital(gWB_Devhandle ,E,%DP_Value.high, WBERR)
   'now send LOW Nibble IE PinMask 0,1,2,3. 4 entries from PinMask(0)
                                 ' point to the Low nibble now
   PMask = VARPTR(pinmask(0))
                                 ' still 4 pins
   pcount=4
   wb_outcome = WB_SetMultiplePinsDigital(gWB_Devhandle,pMask,PCOUNT,BYVAL %NULL)
   wb_outcome = WB_WritePinDigital(gWB_Devhandle ,E, %DP_Value.low, WBERR)
   wb_outcome = WB_WritePinDigital(gWB_Devhandle ,E,%DP_Value.high, WBERR)
END SUB
```

The Sendtext subroutine is the same apart from setting RS to Data not Command, the two could be merged if wanted with a flag variable to switch between data and Command.

```
SUB sendtext(cmd AS BYTE)

'this is the change
  wb_outcome = WB_WritePinDigital(gWB_Devhandle ,RS,%DP_Value.high, WBERR) ' data

END SUB
```

All that remains is to initialise the LCD screen. The Subroutine WB\_SETUP does that,

```
SUB WB_Setup(hdlg AS LONG) 'To be here a WB has been found!
  LOCAL wb_outcome AS BYTE
  LOCAL WbErr AS WB_ERROR PTR
  LOCAL WB ERR AS WB ERROR
  LOCAL RS, E, D4, D5, D6, D7 AS BYTE
  LOCAL temp AS STRING
  LOCAL I AS LONG
   WbErr = VARPTR (WB_ERR)
   rs=%WB_Model1A.pin3
                               'setup the LCD pins
   E= %WB_Model1A.pin4
   D4=%WB_Model1A.pin5
   D5=%WB_Model1A.pin6
   D6=%WB_Model1A.pin7
   D7=%WB Model1A.pin8
' Set the pin direction, in this case all output as we're not reading the LCD
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin1 , %PinDir.Dir_out,BYVAL %NULL)
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin2 , %PinDir.Dir_out,BYVAL %NULL)
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin3 , %PinDir.Dir_out,BYVAL %NULL)
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin4 , %PinDir.Dir_out,BYVAL %NULL)
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin5 , %PinDir.Dir_out,BYVAL %NULL)
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin6 , %PinDir.Dir_out,BYVAL %NULL)
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin7 , %PinDir.Dir_out,BYVAL %NULL)
```

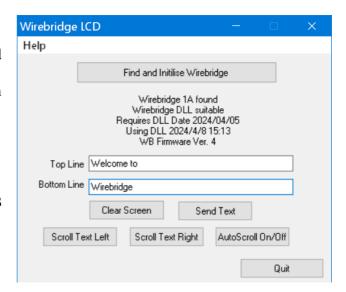
```
wb_outcome = WB_SetPinDirection ( gWB_Devhandle, %WB_Model1A.pin8 , %PinDir.Dir_out,BYVAL %NULL)
```

END SUB

All the rest of the program is to do with the GUI, entering text, demonstrating sending the scroll command etc.

You are welcome to use any and all parts of the program in your own work.

This is a simple demonstration of writing to a LCD using the normal pin method. The pins on the 1A and 1B can be used for other purposes limited only by imagination.



Other Programs demonstrate the I2C and SPI interfaces as well as the PWN functions are planned, The Model2 is interesting here as it has an open output and can be used to drive loads needing higher voltages and power than are available with the 1A and 1B