### Problem 1:

Consider  $a, b \in \mathbb{R}$ , and consider the set of functions  $u \in C^1([0,1])$  such that u(0) = a, u(1) = b. Without loss of generality, we can take both a and b nonnegative. Call the set of such functions  $\mathcal{U}$ .

Let u and v both minimize the integral  $\int_{0}^{1} |f'(x)|^{2} dx$  among functions in  $\mathcal{U}$ . Then  $\min(u, v)$  minimizes the same integral. Moreover,  $\min(u, v) < u$  or  $\min(u, v) < v$  at some point if  $u \neq v$ . But if that were true at any point, then u or v would fail to minimize that integral; thus, u = v at every point.

Next: the linear function minimizes the integral: let l be the linear function with l(0) = a, l(1) = b, and let  $u \in \mathcal{U}$  with  $u \neq l$  minimize the integral. Also, define  $M_1 = \int_0^1 |u'(x)|^2 dx$  and  $M_2 = \int_0^1 |l'(x)|^2 dx$ . Then  $\int_0^1 |u'(x) - l'(x)|^2 dx \neq 0$ ; that is, u-l fails to minimize the integral  $\int_0^1 |v'(x)|^2 dx$  subject to v(0) = v(1) = 0.

Thus, the linear function is the unique function in  $C^1([0,1])$  that minimizes the integral  $\int_0^1 |f'(x)|^2 dx$ .

### Problem 2:

Consider the set  $A = \{z \in \mathbb{C} : \text{Re}(z) > 0\} \setminus [0, a]$  with  $a \in \mathbb{R}^+$ .

Define the sets  $B = \mathbb{C} \setminus \{z \in \mathbb{R} : z \leq a^2\}$ , and  $C = \mathbb{C} \setminus \{z \in \mathbb{R} : z \leq 0\}$ .

First, the map  $\phi: A \to B$  given by  $z \mapsto z^2$  is a biholomorphism from A to B, and this is clear; the argument that  $z \mapsto z^2$  gives a biholomorphism from the half-plane to the slit plane was made in class, and note that the image of [0, a] under this map is  $[0, a^2]$ : so because the map is a biholomorphism, the half plane excluding [0, a] has the image of the slit plane excluding  $[0, a^2]$ .

Second, the map  $\psi: B \to C$  given by  $z \mapsto z - a^2$  is a biholomorphism from B to C, and this is clear (this is a straight translation).

Third, the map  $\xi: C \to \{\text{Re}(z) > 0\}$  given by  $z \mapsto \sqrt{z}$  (using the branch of  $\sqrt{z}$  that is the natural inverse of  $z^2$ , of course) is a biholomorphism from C to  $\{\text{Re}(z) > 0\}$ , and this was discussed in class.

So their composition is a biholomorphism from A to  $\{\text{Re}(z) > 0\}$ ; that is, the map  $f(z) = \sqrt{z^2 - a^2}$  is a biholomorphism from the above set to  $\{\text{Re}(z) > 0\}$ .

### Problem 3:

Let  $\Omega$  be open and symmetric about the  $\mathbb{R}$ -axis.

Let  $f \in C(\Omega)$ , and f be holomorphic except perhaps on the  $\mathbb{R}$ -axis. Note that f = 0 on the  $\mathbb{R}$ -axis.

Our goal is to show that  $f \in \mathcal{O}(\Omega)$ ; we only need to check that f is holomorphic on the  $\mathbb{R}$ -axis. So, let  $z \in \mathbb{R} \cap \Omega$ . Then there is an open ball centered at z, call it  $D_r(z)$ , contained in  $\Omega$ . This open ball is simply connected. Now, the real part of f, say u = Re(f), is harmonic on  $D_r(z) \setminus \mathbb{R}$ . By the reflection principle discussed in class, u is harmonic on all of  $D_r(z)$ .

Now, u is the real part of some holomorphic function, g, and this holomorphic function is unique up to addition of a constant. So, we can take g(z) = 0.

Now, h = f - g is holomorphic except perhaps on the real axis, where it is 0. Moreover, the real part of h is 0; by the Cauchy-Riemann equations, the imaginary part of h must be constant (except perhaps on the real axis). Thus, because the imaginary part of h is 0 on the real axis (and h is continuous), the imaginary part of h is 0. So, h = 0; that is, f = g.

So, f is holomorphic on  $D_r(z)$ ; in particular, f is holomorphic at z.

Because holomorphy is a local property, this yields the desired result; fis holomorphic on  $\Omega$ .

## Problem 4:

Let  $\phi \in \operatorname{Aut}(\overline{\mathbb{C}})$  be such that  $\phi(\{z \in \mathbb{C} : \operatorname{Im}(z) > 0\}) = D_1(0)$ .

A biholomorphism that takes the disk  $D_1(0)$  to  $\{z \in \mathbb{C} : \text{Im}(z) > 0\}$  is  $\phi_C:\mathbb{C}\to\mathbb{C}$  given by  $z\mapsto i\frac{1+z}{1-z}$ ; this is the Cayley transform. Its inverse is  $\psi_C: \mathbb{C} \to \mathbb{C}$  given by  $z \mapsto \frac{z-i}{z+i}$ . (I pulled these maps from Complex Made Simple; any other transform would've worked).

So,  $\psi = \phi_C \circ \phi$  is a biholomorphism of the plane that fixes  $\{z \in \mathbb{C} :$  $\operatorname{Im}(z) > 0$ ; by an earlier homework problem, this means that  $\phi_C \circ \phi$  is of the form  $z \mapsto \frac{az+b}{cz+d}$  with  $a,b,c,d \in \mathbb{R}$ , as proven in an earlier homework problem. Fix  $z \in \mathbb{C}$ . Let  $w = \overline{z}$ . Then

$$\psi(w) = \frac{aw + b}{cw + d}$$

$$= \frac{a\overline{z} + b}{c\overline{z} + d}$$

$$= \frac{az + b}{cz + d}$$

$$= \overline{\psi(z)}$$

Now,  $\psi_C \circ \psi = \phi$ . So,

$$\phi(w) = \psi_C(\psi(w))$$

$$= \psi_C(\overline{\psi(z)})$$

$$= \frac{\overline{\psi(z)} - i}{\overline{\psi(z)} + i}$$

$$= \frac{i\frac{1+\phi(z)}{1-\phi(z)} - i}{i\frac{1+\phi(z)}{1-\phi(z)} + i}$$

$$= \frac{-i\frac{1+\phi(z)}{1-\phi(z)} - i}{-i\frac{1+\phi(z)}{1-\phi(z)} + i}$$

$$= \frac{\overline{1+\phi(z)}}{\frac{1+\phi(z)}{1-\phi(z)} + 1}$$

$$= \frac{\overline{1+\phi(z)}}{\frac{1+\phi(z)}{1-\phi(z)} - 1}$$

### Problem 5:

Let  $f \in \mathcal{O}(\Omega)$ , where  $\Omega$  is a symmetric domain (with respect to  $\mathbb{R}$ ), and  $\mathbb{R} \cap \Omega \neq \emptyset$ . Moreover, let  $f(\mathbb{R} \cap \Omega) \subset \mathbb{R}$ . Then the function g(z) = f(Re(z)) is a holomorphic function.

Now, consider h = f - g; this is holomorphic. Note that h restricted to  $A = \Omega^+ \cup (\Omega \cap \mathbb{R})$  satisfies the requirements for the reflection principle; h

restricted to A extends to  $\Omega$ ; call this extension j. (Note that  $j(\overline{z}) = \overline{j(z)}$ .) Now, j - h is identically 0 on A. Because j - h is 0 on an open subset of  $\Omega$ , it is 0 on all of  $\Omega$  (This follows by uniqueness principle, as  $\Omega$  is a domain...it is connected.)

So 
$$j = h$$
. So  $h(\overline{z}) = \overline{h(z)}$ . So

$$\begin{split} f(\overline{z}) &= h(\overline{z}) - g(\overline{z}) \\ &= \overline{h(z)} - g(z) \\ &= \overline{h(z)} - \overline{g(z)} \\ &= \overline{f(z)} \end{split}$$

as desired.

# Problem 6: