# Parameterize the Generation of Realistic Faces

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# **Background**

- generation of realistic faces ongoing problem
- need for better self-presentation
- 3 approaches for modeling
  - parameter model
  - physiological muscle model
  - visual modeling based on images



#### **Previous work**

- FaceMaker: tool for generating parameterized face models
- Generative Adversarial Networks (GANs)
  - "Generative" part (Generator): using a label to predict a feature
  - "Adversarial" part (Discriminator): using a feature to predict a label
  - both parts are learning and improving through feedback loops



# **Research question**

- generate paired samples: artificial faces and corresponding real face
- use data for tuning and improving GANs' results
- validate model by comparing generated (by participants) and realistic faces

# Deep Labeling of Motion Capturing Markers

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# **Background**

- Body motions get captured with markers/sensors and cameras
- Markers transmit signals either actively or passively
- Labeling of those markers is either time-consuming work or must be automated with software



#### **Previous work**

- Initialization of the persons skeleton before tracking is important [1,2]
- For the calculation of the skeleton and the labeling of the markers, better results could be achieved by using more than just information from the last frame [3]

[1] Meyer, J., Kuderer, M., Müller, J., & Burgard, W. (2014). Online marker labeling for fully automatic skeleton tracking in optical motion capture.

[3] Yu, Q., Li, Q., & Deng, Z. (2007). Online Motion Capture Marker Labeling for Multiple Interacting Articulated Targets.

<sup>[2]</sup> Han, S., Liu, B., Wang, R., Ye, Y., Twigg, C. D., & Kin, K. (2018). Online Optical Marker-based Hand Tracking with Deep Labels.



# **Research question**

Can an approach based on convolutional neural networks in the automatic labeling of whole bodies yield results comparable to old fashioned methods?

# Optimizing mouse transfer function using reinforcement learning

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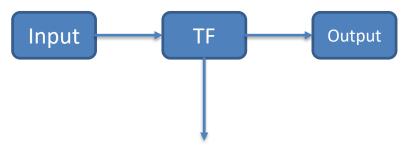
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## **Background**



 Mapping movement in real world space to computer space representation



#### **Previous work**

- Has shown that the use of the default TF in common os is superior to constant CD-Gain [1]
- DRL is promising in solving certain task, without prior knowledge about the data [2],[3]

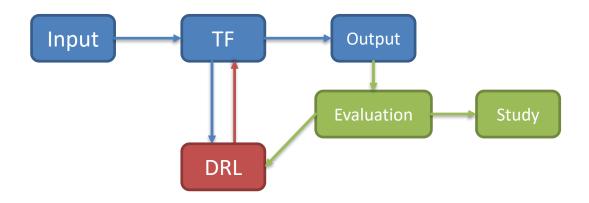
<sup>[1]</sup> Casiez, G., Vogel, D., Balakrishnan, R., & Cockburn, A. (2008). The impact of control-display gain on user performance in pointing tasks. Human–computer interaction, 23(3), 215-250.

<sup>[2]</sup> Mnih, V., Kavukcuoglu, K., Silver, D., Graves, A., Antonoglou, I., Wierstra, D., & Riedmiller, M. (2013). Playing atari with deep reinforcement learning. arXiv preprint arXiv:1312.5602.

<sup>[3]</sup> Silver, D., Huang, A., Maddison, C. J., Guez, A., Sifre, L., Van Den Driessche, G., ... & Dieleman, S. (2016). Mastering the game of Go with deep neural networks and tree search. nature, 529(7587), 484.



### **Research question**



 Is it possible to design a TF via DRL to increase UX and user perforance in certain tasks?