

Micaiah “Cai” Scheidler

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Education

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| UC Berkeley – Bachelor of Science in Electrical Engineering and Computer Science | Expected May 2029 |
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Work Experience

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| STEM (Python + Calculus) Tutor , Freelance – Monrovia, CA | Sep 2024 – PRESENT |
| • Provide weekly 1-on-1 Python instruction focused on foundational programming concepts | |
| • Guided 2 high school students through all 8 units of AP Calculus AB with weekly in-person and online tutoring | |
| Code Coach , theCoderSchool – Pasadena, CA | Jul 2024 – Jul 2025 |
| • Taught students in Unity/C#, Python, and Scratch through personalized, project-based, 1 hour tutoring sessions | |
| • Provided informative summaries of each session to parents/guardians of students | |
| Code Coach Intern , theCoderSchool – Pasadena, CA | Jul 2024 |
| • Helped teach students the basics of Python and robotics in 2 separate weeklong summer programs | |
| Content Creator , Singleton Foundation – Pasadena, CA | Jul 2023 – Feb 2024 |
| • Marketed Venture Valley, a game meant to teach financial literacy, through scripting, recording, and editing short and long form promotional content | |
| • Created videos explaining how to play Venture Valley for Polish teachers and students as a part of a partnership between Venture Valley and the Polish government | |
| Quality Assurance Intern , Singleton Foundation – Pasadena, CA | Jun 2023 – Jul 2023 |
| • Tested the mobile version of Venture Valley for any bugs, accumulating 60+ total hours of time spent debugging | |
| • Documented each bug with a video or image, steps for reproducing the bug, and an exact explanation of the bug | |

Projects

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| Physical Digital Darts | devpost.com/software/digital-physical-darts-wii-darts |
| • Won Best Beginner Hack out of 700 projects at CalHacks 12.0 by working on a team of 4 to develop an electronic dart-shaped controller and accompanying Python dartboard simulation | |
| • Developed an accurate simulation for dart launches in Python and integrated this simulation with serially-communicated, real-time dart controller orientation data | |
| • Minimized the form factor of a dart controller designed for assembly using Fusion 360 | |
| DoodleDogs | github.com/LarryHellen/DoodleDogs |
| • Won the Congressional App Challenge for CA31 by working on a team of 6 to develop a 2D, story-driven, iOS mobile game using Unity which follows the player's journey to become the greatest dogsitter in Paris | |
| • Achieved 200+ downloads by creating enjoyable UI/UX functionality using C# and by promoting collaborative development efforts by leading scrums for the team | |
| FIRST Tech Challenge Team 4625, Kings and Queens | github.com/Slipperee-CODE/4625-FTC-IntoTheDeep |
| • Won 1st Inspire out of 35 teams in the 2024-25 season by leading a team of 10 to produce a competitive robot | |
| • Led robot design (in Fusion 360), robot programming (in Java), and in-house robot manufacturing and assembly | |
| A Human Hand Tracking Robot Arm | github.com/Slipperee-CODE/ArmControlledTurret |
| • Mapped hand movements into the movements of a custom designed, servo-controlled robot arm with 3 degrees of freedom by communicating webcam data from a Python program running on a laptop to an Arduino Uno | |

Technical Skills

LANGUAGES: C#, Java, Python

SOFTWARE: DaVinci Resolve, Fusion 360, Unity

OTHER: Agile development