Speechrecognition

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Seminar Robocup

Motivation

Why even bother?

- faster and more general way to give robots commands
- a necessity for casual users
- user does not need additional hardware

Content

What is Speechrec? What does it consist of?

Content[®]

- 1. Hardware
- 2. Localisation
- 3. Signal Enhancing
- 4. Voice Activation Detection
- 5. Speaker Recognition
- 6. Speech Recognition
- 7. Natural Language Processing

Hardware

Microphones

Microphone Arrays

Localisation

Sound Source Localisation

Signal Enhancing

Beamforming

Voice Activation Detection

What we use

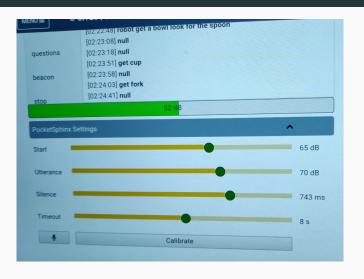


Abb. 1: Double threshold voice activation detection

What we use II

A voice activation detection based on audio loudness with three states:

idle Start in this state

starting switch to this state if the audio > StartDb and stay here as long as audio > UtteranceDb

ending switch to this state if the audio < UtteranceDb and stay as long as specified via Silence, then return to idle

A maximum audio length can be specified via Timeout

Other approaches

ness-based based on decibel calculation, it will only take into account the single most extreme value in an audio frame ergy-based in contrast to loudness-based approaches, energy calculation will take all values in an audio frame into consideration ncy-based will calculate frequencies and search for those typically used by human speech

Speaker Recognition

Speech Recognition

Approaches

Hidden Markov Models vs Deep Learing vs Online

Grammar vs Grammarless

Corrected Spelling vs Phoneme based recognition

Sphinx

Deepspeech

Google/Bing/... Online Speechrec

Natural Language Processing

Idea

 $\bullet\,$ Just recognizing what was said does not solve all our problems

Thanks for the Attention!

Discussion

Sources