



# OpenIPSL

A Modelica Library for Power Systems Simulation

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**Preparatory work – aka *home work!***

Please follow these slides before taking part in the Workshop/Tutorial/Seminar.

# Requirements



## Requirements for the workshop are:

We have only tested our tutorial for the following configurations.

### Windows:

- PC with installed Windows 7 or later
- Installation of OpenModelica

### Mac:

- OSX El Capitan
- Installation of OpenModelica (binaries!)
- Xcode (Version 8.0)



# Getting Started with OpenModelica and OpenIPSL

This presentation is a 2-part guide containing the preparatory work needed to carry out the *hands-on examples* of the Modelica and OpenIPSL workshop/tutorial/seminar.

- Part 1: Setting up **OpenModelica**



- Part 2: Setting up OpenIPSL





# Installation of OpenModelica

## Instructions:

- Download the installation package
  - Windows:
    - <https://www.openmodelica.org/download/download-windows>
    - 1.9.6: <https://build.openmodelica.org/omc/builds/windows/releases/1.9.6/OpenModelica-v1.9.6.exe>
    - 1.9.11:
      - <https://build.openmodelica.org/omc/builds/windows/releases/1.11.0/>
  - Mac:
    - 1.9.6: <https://build.openmodelica.org/omc/builds/mac/binaries/latest-release-1.9.6.mpkg>
- Launch the Installation package and follow the instructions with default options

## Note!

Compatibility with OpenIPSL is checked for OpenModelica versions 1.9.6 (Mac and Windows) and 1.9.11 (on Windows)

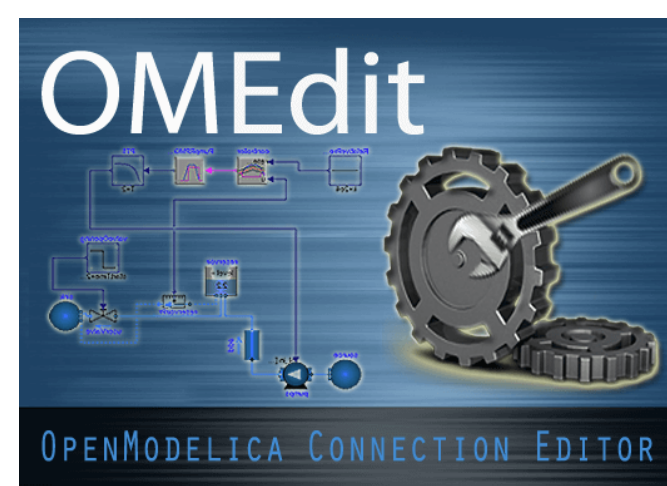
# No MAC OSX or Windows OS – No Problem!

- OpenModelica is available for GNU/Linux distributions here:
  - <https://www.openmodelica.org/download/download-linux>
  - **Note:** the compatibility of OpenIPSL has not been tested under these OS distributions
- Virtual Machine:
  - OpenModelica can be installed through pre-built Virtual Machines containing all the libraries and clients that come with OpenModelica.
  - See instructions here:
    - <https://www.openmodelica.org/download/virtual-machine>
    - **Note:** the compatibility of OpenIPSL has not been tested under these VM configurations.





# Check of OpenModelica



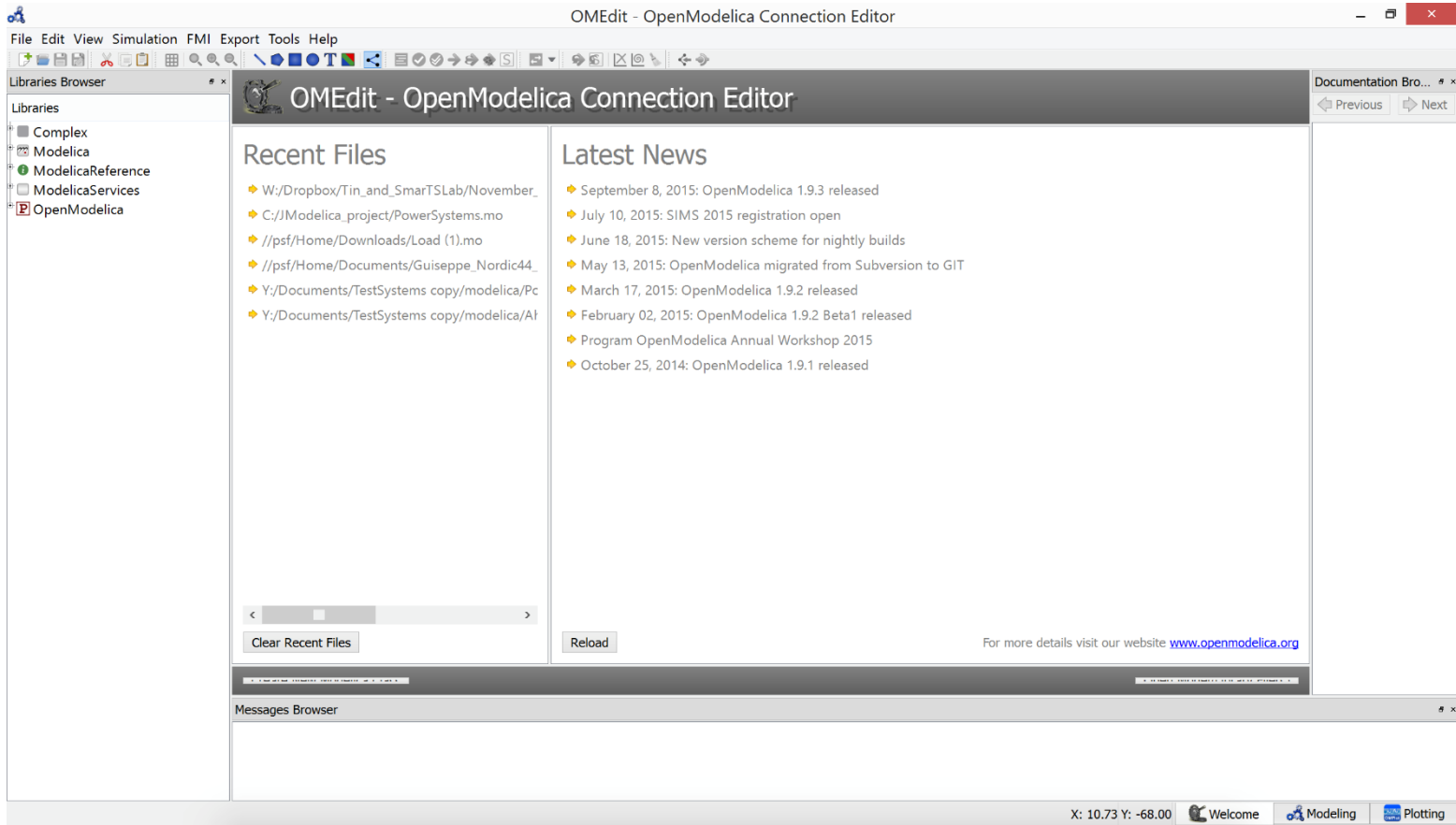
Tasks to check OpenModelica is correctly installed on your computer:

- Start OpenModelica Connection Editor (OMEdit)
- In the Libraries Browser navigate to Modelica.Blocks.Examples.PIDController
- Select Runge Kutta as a solver and simulate the model
- In the “Plotting” view, plot variable speedSensor.w



# Check of OpenModelica – Step 1

Upon launch, the Connection Editor will present the following window

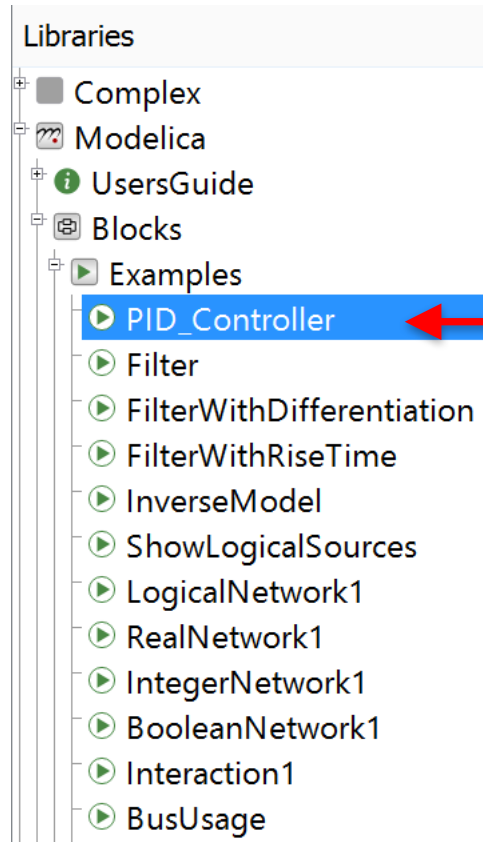






# Check of OpenModelica – Step 2

Browse the Modelica library to find the PID\_Controller and open it



Double-click to  
open

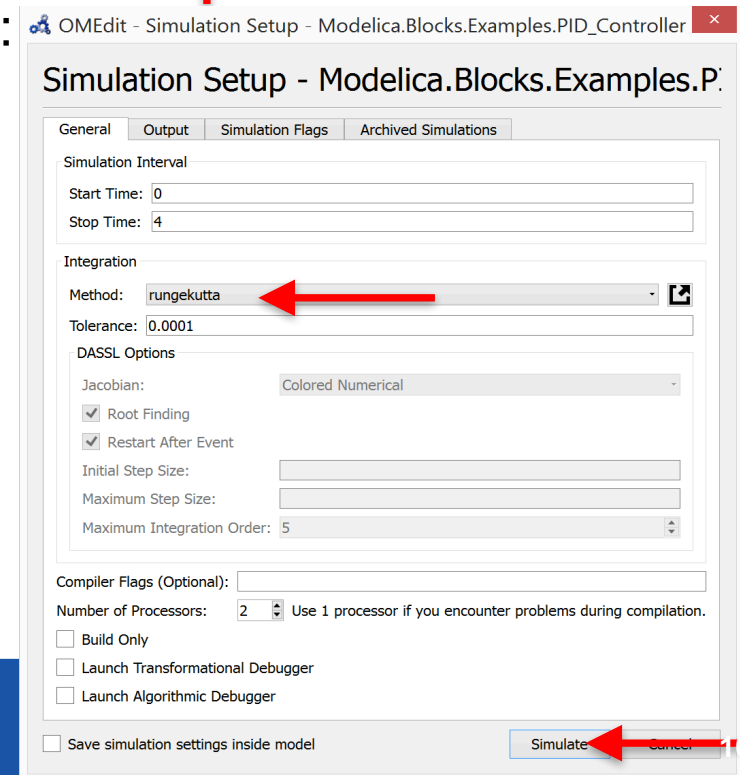
# Check of OpenModelica – Step 3

Simulation settings are accessed on the toolbar:



Adjust the settings to match the followings :

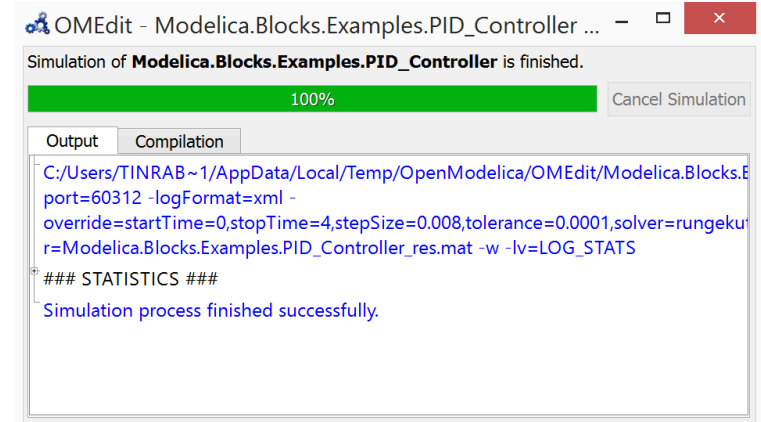
Click on **Simulate** to launch the simulation



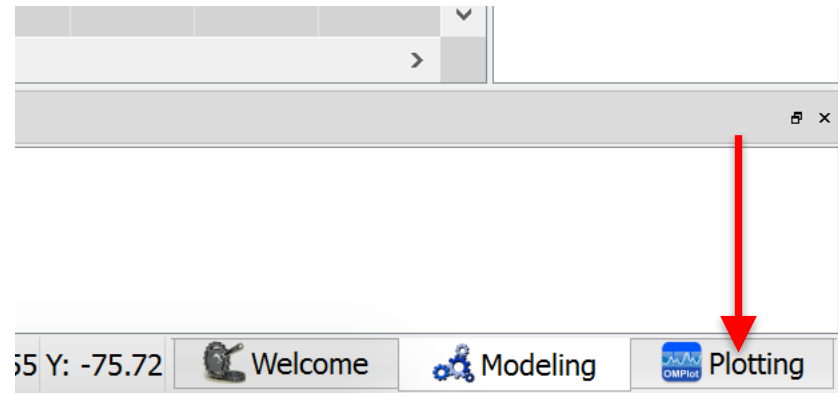


# Check of OpenModelica – Step 4a

Once the simulation is completed (100 %):



- Access the plotting facility by clicking on the **Plotting** tab in the lower right corner of the screen





# Check of OpenModelica – Step 4b

In the plotting facility, browse the variable to find the rotational speed  $w$

Variables Browser

Find Variables

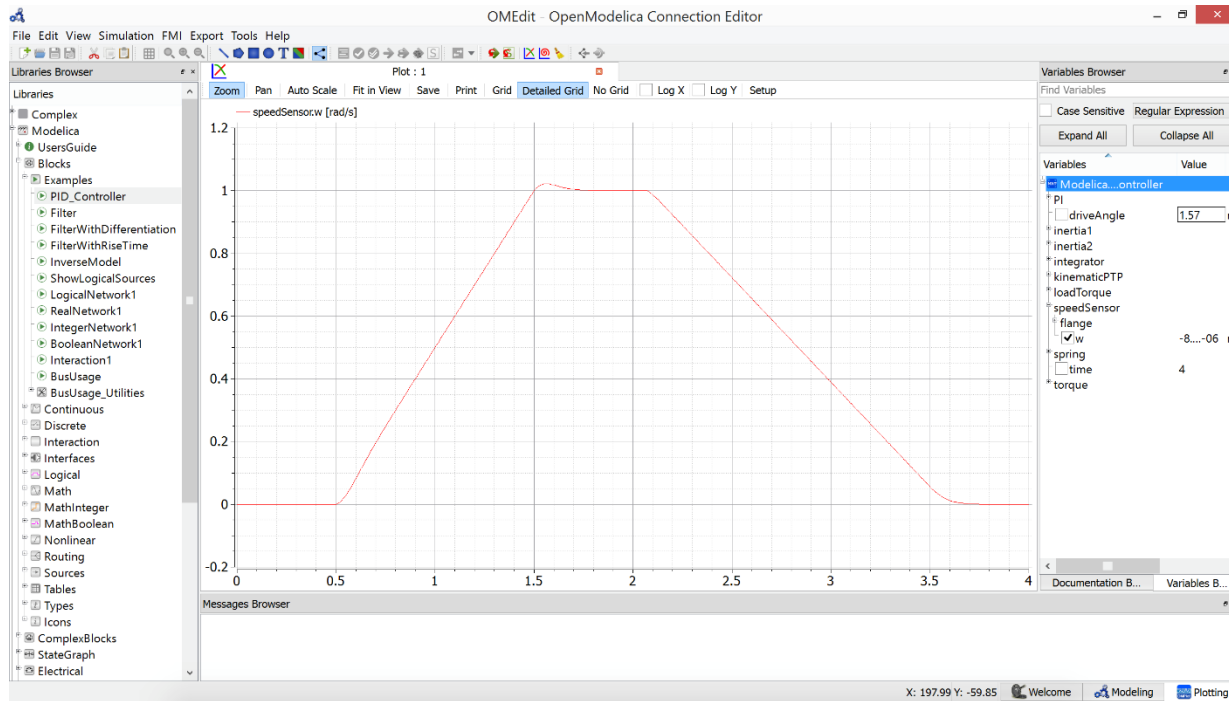
Case Sensitive Regular Expression

Expand All Collapse All

Variables	Value	Unit
Modelica...ontroller		
PI		
<input type="checkbox"/> driveAngle	1.57	rad
inertia1		
inertia2		
integrator		
kinematicPTP		
loadTorque		
speedSensor		
flange		
<input checked="" type="checkbox"/> w	-8.00000	rad/s
spring		
<input type="checkbox"/> time	4	
torque		



# Check of OpenModelica – Final Result



If your screen looks like this, you're ready to go!



# Part 2

## Setting up OpenIPSL



# Download the OpenIPSL Source!



Go to our Github repo:

[https://github.com/SmarTS-Lab/OpenIPSL/releases/tag/Tutorial\\_ModelicaConf2017](https://github.com/SmarTS-Lab/OpenIPSL/releases/tag/Tutorial_ModelicaConf2017)

**Note:** The files will also be available on a USB stick(s) that we can circulate on the day of the tutorial.

Please ask me for it if you need it.

Pre-release

Tutorial\_Mo...  
d7e59d5

## Tutorial for the 12th Modelica Conference @ Prague

Ivanfretti released this 9 days ago



This release of OpenIPSL's "Tutorial" was prepared for a tutorial at the 12th Modelica Conference in Prague on May 15th, 2017.

The preparatory work that needs to be done prior to the tutorial can be found in this .pdf:

[OpenIPSL\\_Tutorial\\_Prep.pdf](#)

The slides with the hands-on examples, explained step by step, can be found here:

[OpenIPSL\\_HandsOn\\_Examples.pdf](#)

The presentation for the first part of the tutorial will be made available after the event to the participants only.

### Downloads

[Source code \(zip\)](#)

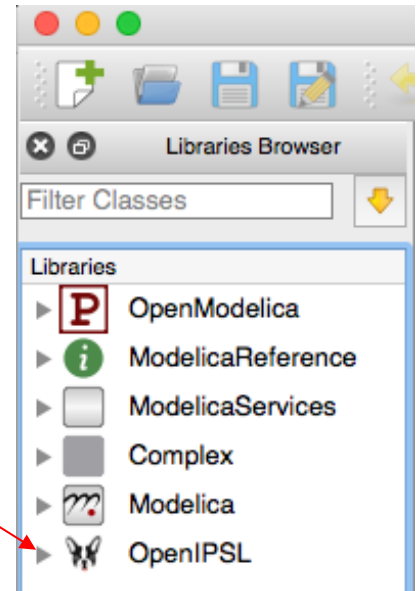
[Source code \(tar.gz\)](#)

[Click Here!](#)

# Load the OpenIPSL to OMEdit

External libraries, e.g. OpenIPSL, must be loaded in OMEdit to be used:

- Unzip the package downloaded at the previous step
- Open OpenModelica Connection Editor (OMEdit)
- Go to **File/Load Library**
- Browse to the location of the unzipped folder
- Choose the **/OpenIPSL** folder
- The icon with the OpenIPSL puppy should appear
- *Alternatively:*
- Drag & drop the **package.mo** file to the **Library Browser** in OMEdit.

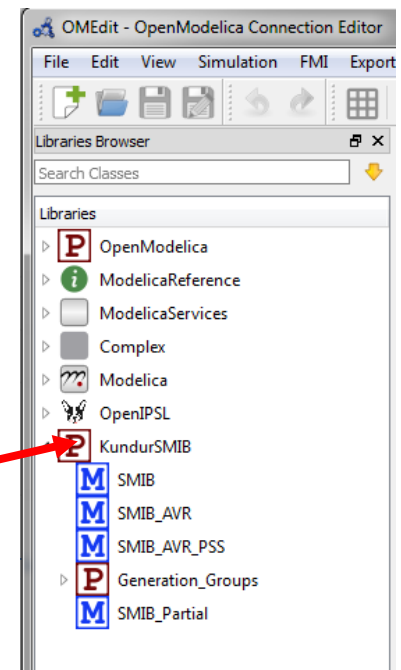
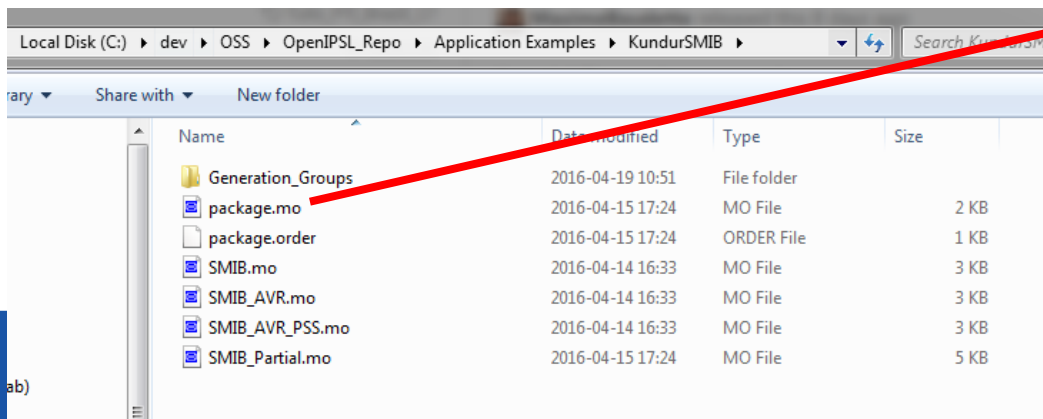




# Load an Application Example to OMEdit

Once the OpenIPSL is loaded (see previous slide) in OMEdit, you can load an “Application Example”:

- Go to **Open Model/Library File(s)**
- Browse to the location of the unzipped folder
- Go to the **/Application Examples/KundurSMIB** folder, and select **package.mo**
- *Alternatively:*
- Drag & drop the **package.mo** file to the **Library Browser** in OMEdit.





# Check that it simulates

Click on “SMIB”, “Simulation Setup” and “Simulate”

OMEdit - OpenModelica Connection Editor

Libraries Browser

- OpenModelica
- ModelicaReference
- ModelicaServices
- Complex
- Modelica
- OpenIPSL
- KundurSMIB
  - SMIB
  - SMIB\_AVR
  - SMIB\_AVR\_PSS
  - Genera...Groups
  - SMIB\_Partial

Click Here!

Example 1: Single-machine infinite bus model  
(Constant EIM)

Messages Browser

```
At:Order6$G1$machine, .Real type: Real
G1.machine.e1d:VARIABLE(start = 0.4107654957816427 ) "d-
axis transient voltage".KundurSMIB.SMIB, .KundurSMIB.Generation_Groups.Generator$G1, .OpenIPSL
s.PSAT.Order6$G1$machine, .Real type: Real
G1.machine.e1q:VARIABLE(start = 1.02809219904626 ) "q-
axis transient voltage".KundurSMIB.SMIB, .KundurSMIB.Generation_Groups.Generator$G1, .OpenIPSL
s.PSAT.Order6$G1$machine, .Real type: Real
```

X: -118.67 Y: 38.52

OMEdit - Simulation Setup - KundurSMIB

Simulation Setup - KundurSMIB.SMIB

General Output Simulation Flags

Simulation Interval

Start Time: 0

Stop Time: 10

Number of Intervals: 100000

Interval: 0.0001

Integration

Method: dassl

Tolerance: 1e-06

DASSL Options

Jacobian: Colored Numerical

Root Finding

Restart After Event

Initial Step Size:

Maximum Step Size:

Maximum Integration Order: 5

Compiler Flags (Optional):

Number of Processors: 4 Use 1 processor if you encounter

Click Here!

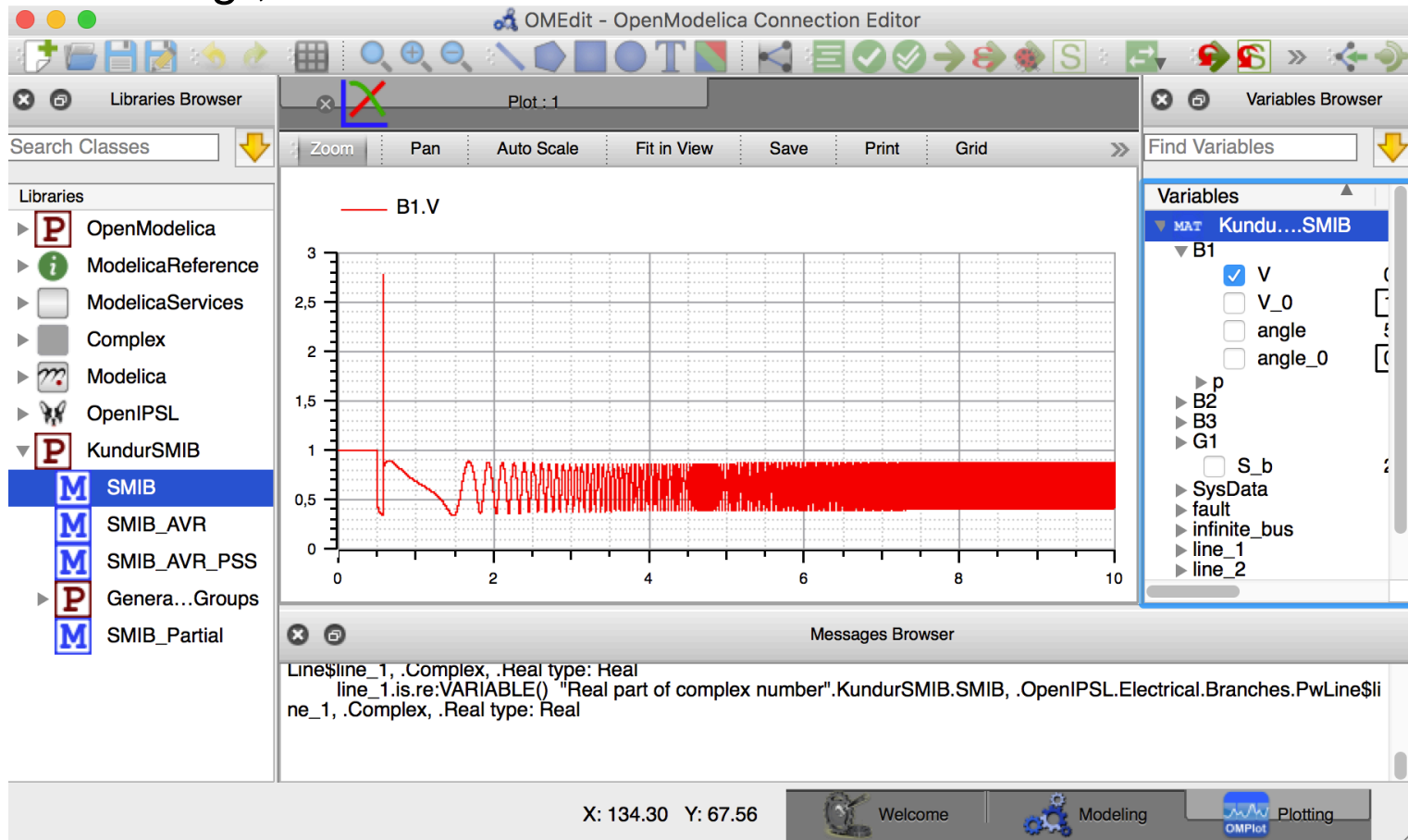
Launch Algorithmic Debugger

Simulation settings inside model

Simulate Cancel

# Plot the results

Click on “Plotting”, scroll to “B1” and select “V”



The screenshot shows the OMEdit - OpenModelica Connection Editor interface. The main window displays a plot titled "Plot : 1" showing a red line representing the variable "B1.V". The plot has a y-axis ranging from 0 to 3 and an x-axis ranging from 0 to 10. The signal starts at 1, drops to approximately 0.5, and then exhibits damped oscillations around 0.5. The Variables Browser on the right shows the hierarchy: MAT Kundu...SMIB > B1 > V (checked). The Libraries Browser on the left shows the "KundurSMIB" library selected, with "SMIB" highlighted. The Messages Browser at the bottom shows error messages related to the plot.

OMEdit - OpenModelica Connection Editor

Libraries Browser

Search Classes

Zoom Pan Auto Scale Fit in View Save Print Grid

Variables Browser

Find Variables

Variables

- MAT Kundu...SMIB
  - B1
    - V
    - V\_0
    - angle
    - angle\_0
  - p
  - B2
  - B3
  - G1
    - S\_b
  - SysData
  - fault
  - infinite\_bus
  - line\_1
  - line\_2

Messages Browser

```
Line$line_1, .Complex, .Real type: Real  
line_1.is.re:VARIABLE() "Real part of complex number".KundurSMIB.SMIB, .OpenIPSL.Electrical.Branches.PwLine$li  
ne_1, .Complex, .Real type: Real
```

X: 134.30 Y: 67.56

Welcome Modeling Plotting OMPLOT



# Finally, take a look at our repository and documentation!

Repository: <https://github.com/SmarTS-Lab/OpenIPSL>

Go to: <http://openipsl.readthedocs.io/en/latest/index.html>

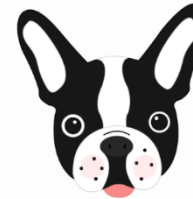
[Docs](#) » OpenIPSL's documentation!

[Edit on GitHub](#)

## OpenIPSL's documentation!

Welcome to **OpenIPSL** - The Open-Instance Power System Library.

This documentation is the main source of information for **users** and **developers** working with (or contributing to) the **OpenIPSL** project.



## OpenIPSL in short

The OpenIPSL or Open-Instance Power System Library is a [Modelica](#) library, fork of of the [iTesla Power System Library](#) developed and maintained by the [SmarTS Lab](#) research group, collaborators and friends (contributions are welcome!).

The library contains a set of power system component models and test power system networks adopting the "phasor" modeling approach. [Time domain simulations](#) can be carried out using a

# You are ready!

See you for the workshop/tutorial/seminar!

