

敏捷建模：算力-算法-灰度

关键词：Computing Force、混沌、信息流、SVI

2021.10.20

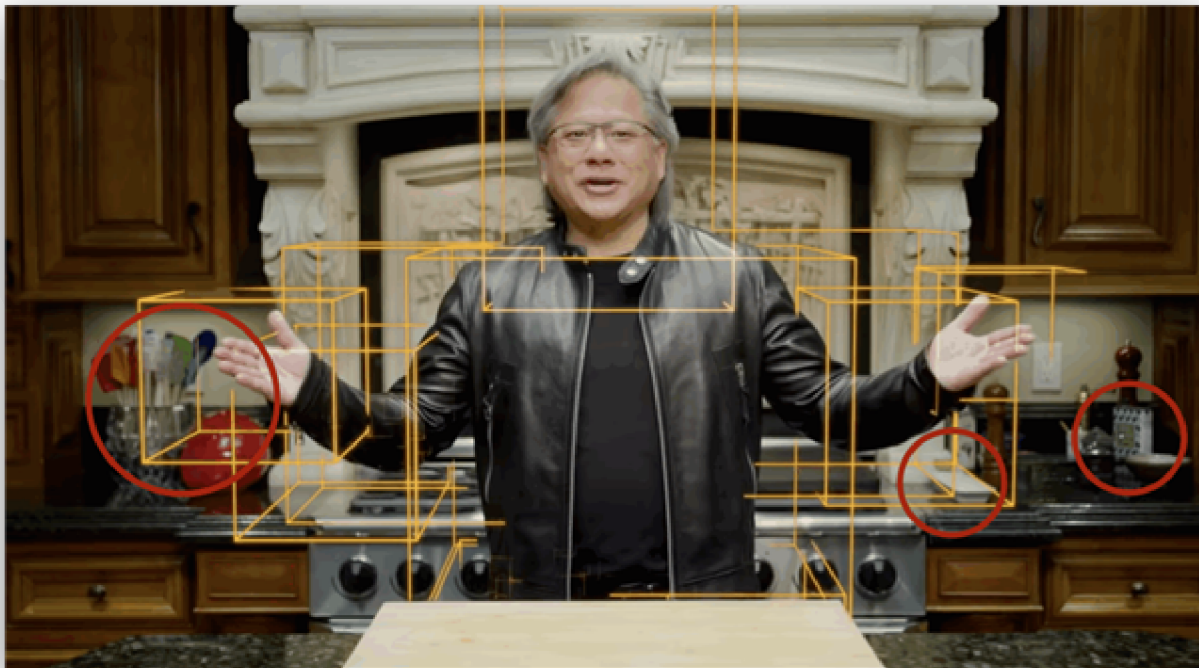
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Available at <https://github.com/SmartDataLab/CF-Share>

Written by Marp and Mermaid in Markdown

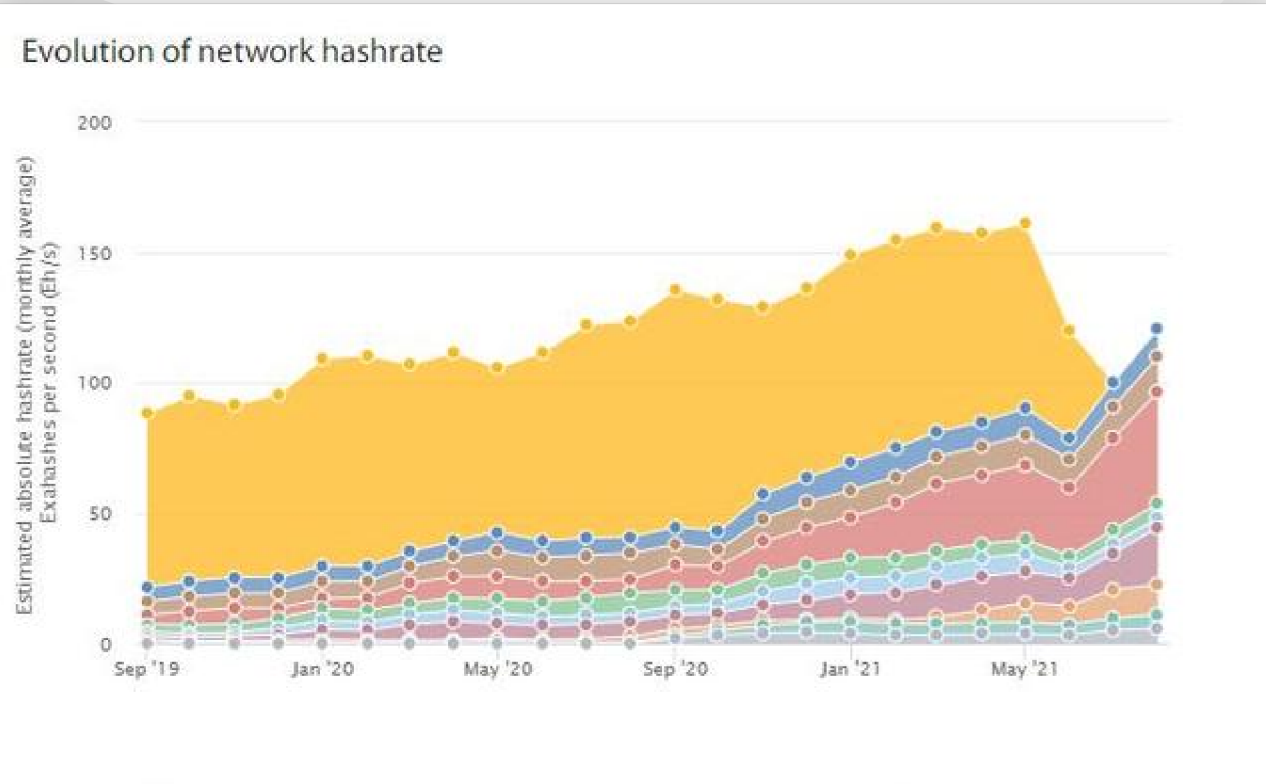
厨房、皮衣与矿池

- 游戏党与年度最佳投资



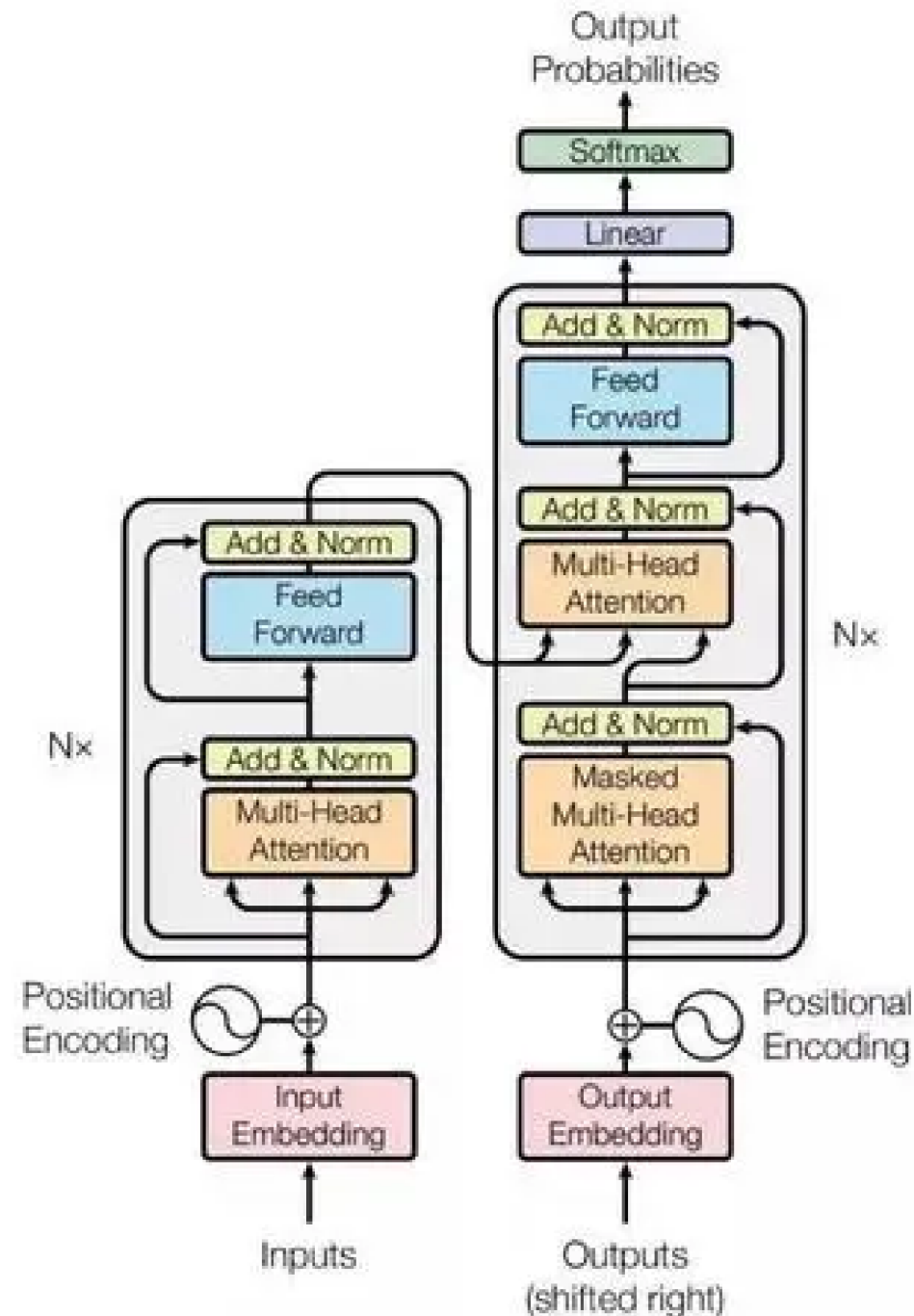
算力

- Computing Performance
- GeForce(Geometry Force) Nvidia GPU



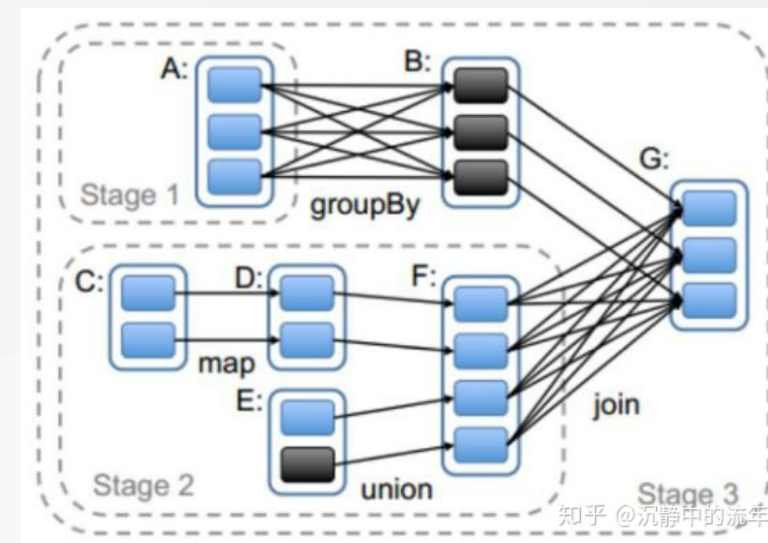
复杂问题建模

- Algebra - Geometry
- Analytic - Graphic
- Linear - Nonlinear
- Breadth - Depth



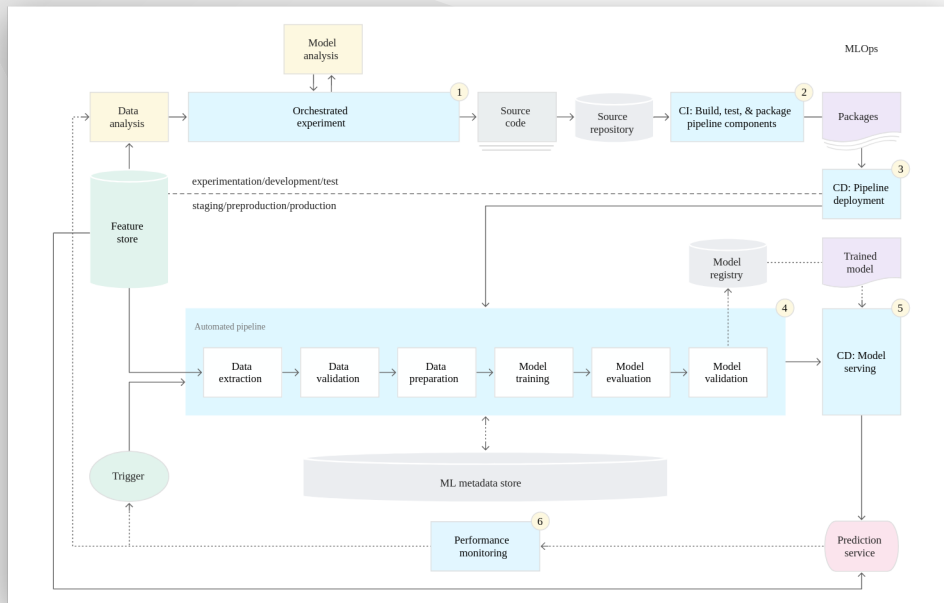
信息流与混沌

- 数据库发展
RDBMS --> NoSQL
- 计算引擎的发展
Map-Reduce & Resilient Distributed Dataset
- 建模与假设
Attention is all you need
- 模型求解
BackProp Hinton & Lecun
Pretrain Finetune
Stochastic Variational Inference



生产实际问题

- Continuous Machine Learning(concept from CI&CD)
- Data Transfer Problem(Model Degeneration)
- AB-test & Gray-test (hypothesis test & PSM-DID)



趋势：云原生与微服务

- 容器化技术（ Docker K8S ）
- 美团的GPU集群出售
- Yale NLP相关的暑研(AWS)



贝叶斯方法在深度学习

- 随机项 ϵ 在传统统计模型的重要意义($\epsilon \perp X$) :
 - confidence interval
 - p value
- Interpretable methods in ML(Variance-Bias: Data Quality)
 - data perturbation(data augmentation)
 - model parameter randomness(random seed)
 - hyperparameter perturbation(NAS)
- Hybrid: Stochastic Model + Neural Network

Stochastic Variational Inference

- Notation: observation x , model parameter θ latent variables z

$$p_{\theta}(\mathbf{x}, \mathbf{z}) = p_{\theta}(\mathbf{x} \mid \mathbf{z})p_{\theta}(\mathbf{z})$$

- Parameter Learning Target: log evidence & Latent Posterior

$$\log p_{\theta}(\mathbf{x}) = \log \int d\mathbf{z} p_{\theta}(\mathbf{x}, \mathbf{z})$$

$$p_{\theta_{\max}}(\mathbf{z} \mid \mathbf{x}) = \frac{p_{\theta_{\max}}(\mathbf{x}, \mathbf{z})}{\int d\mathbf{z} p_{\theta_{\max}}(\mathbf{x}, \mathbf{z})}$$

SVI in Pyro cont.

- Intuition: Guide $q_{\phi}(\mathbf{z}) \sim p_{\theta_{\max}}(\mathbf{z} \mid \mathbf{x})$

```
def model():  
    pyro.sample("z_1", ...)  
def guide():  
    pyro.sample("z_1", ...)
```

- Optimization Target: Evidence Lower Bound (ELBO): MM method

$$\text{ELBO} \equiv \mathbb{E}_{q_{\phi}(\mathbf{z})} [\log p_{\theta}(\mathbf{x}, \mathbf{z}) - \log q_{\phi}(\mathbf{z})]$$

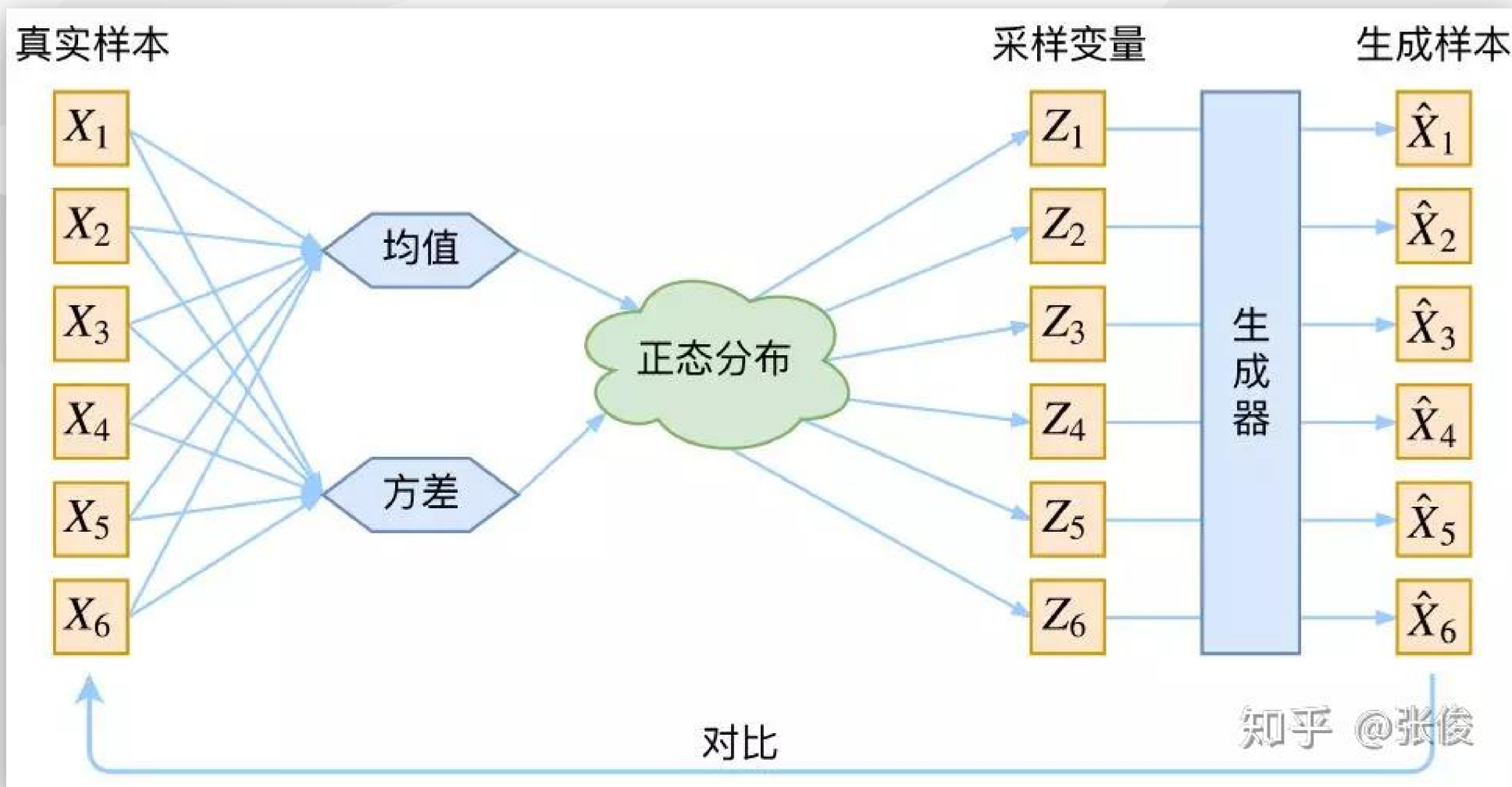
$$\log p_{\theta}(\mathbf{x}) - \text{ELBO} = \text{KL}(q_{\phi}(\mathbf{z}) \parallel p_{\theta}(\mathbf{z} \mid \mathbf{x}))$$

A Simple Example : toss the coin

```
def model(data):  
    # 先验知识, 正面向上的概率为 1/2  
    alpha0 = torch.tensor(10.0)  
    beta0 = torch.tensor(10.0)  
    f = pyro.sample("latent_fairness", dist.Beta(alpha0, beta0))  
    for i in range(len(data)):  
        pyro.sample("obs_{}".format(i), dist.Bernoulli(f), obs=data[i])
```

```
def guide(data):  
    alpha_q = pyro.param("alpha_q", torch.tensor(15.0),  
                          constraint=constraints.positive)  
    beta_q = pyro.param("beta_q", torch.tensor(15.0),  
                        constraint=constraints.positive)  
    pyro.sample("latent_fairness", dist.Beta(alpha_q, beta_q))
```

Example: Variational Auto-Encoder



```

class VAE(nn.Module):
    def __init__(self, z_dim=50, hidden_dim=400, use_cuda=False):
        super(VAE, self).__init__()
        self.encoder = Encoder(z_dim, hidden_dim)
        self.decoder = Decoder(z_dim, hidden_dim)
        if use_cuda:
            self.cuda()
        self.use_cuda = use_cuda
        self.z_dim = z_dim
    # define the model p(x|z)p(z)
    def model(self, x):
        pyro.module("decoder", self.decoder)
        with pyro.plate("data", x.shape[0]):
            z_loc = x.new_zeros(torch.Size((x.shape[0], self.z_dim)))
            z_scale = x.new_ones(torch.Size((x.shape[0], self.z_dim)))
            z = pyro.sample("latent", dist.Normal(z_loc, z_scale).to_event(1))
            loc_img = self.decoder.forward(z)
            pyro.sample("obs", dist.Bernoulli(loc_img).to_event(1), obs=x.reshape(-1, 784))
    def guide(self, x):
        pyro.module("encoder", self.encoder)
        with pyro.plate("data", x.shape[0]):
            z_loc, z_scale = self.encoder.forward(x)
            pyro.sample("latent", dist.Normal(z_loc, z_scale).to_event(1))
    def reconstruct_img(self, x):
        z_loc, z_scale = self.encoder(x)
        z = dist.Normal(z_loc, z_scale).sample()
        loc_img = self.decoder(z)
        return loc_img

```

More Popular Stochastic Model

- Deep Generative Models
- Discrete Latent Variables
- Reinforcement Learning : Policy Gradient
- Previous Major Application
 - Time Series
 - Gaussian Processes: Kalman Filter
 - Epidemiology
 - Space Trace

Technical Trend or Hot topic

- Batch、 Batch and Batch
 - More Efficient Stochastic Gradient(Dropout and Oneshot)
 - Federated Learning (Distributed)
 - Multi-Stage Transfer Learning
- Hyper、 Hyper and Hyper
 - Neural Architecture Search
- Multi、 Multi and Multi
 - Pretrained Model(self supervised task) and Transfer Learning
 - Multi-Source, Multi-Modal: Auto Feature Engineering

Online Reference

<https://zhuanlan.zhihu.com/p/63276887>

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http://sofasofa.io/forum_main_post.php?postid=1005437

<http://yann.lecun.com/exdb/publis/pdf/lecun-98b.pdf>

<https://www.zhihu.com/question/264189719>



Thanks