第三章 指数族分布的统计推断

#### Parameter Estimation

- In the GLM model we are interesting in estimating  $\beta$ , the parameters in the linear predictor term.
- Consider maximum likelihood.
- The likelihood function is

$$L(\beta) = \prod_{i=1}^{n} f(y_i | \theta_i, \phi)$$

$$= \prod_{i=1}^{n} \exp(\frac{y_i \theta_i - b(\theta_i)}{a(\phi)} + c(y_i, \phi))$$

$$= \exp(\frac{\sum_{i=1}^{n} (y_i \theta_i - b(\theta_i))}{a(\phi)} + \sum_{i=1}^{n} c(y_i, \phi)).$$
(1)

#### Parameter Estimation

Hence the log-likelihood is

$$I(\beta) = \frac{1}{a(\phi)} \sum_{i=1}^{n} (y_i \theta_i - b(\theta_i)) + \sum_{i=1}^{n} c(y_i, \phi)$$
$$= \sum_{i=1}^{n} I_i(\beta), \tag{2}$$

say.

#### The score functions

• Taking derivatives of the log likelihood with respect to  $\beta_j$ , j = 1, ..., p we obtain the score functions

$$U_j(\boldsymbol{\beta}) = \frac{\partial I(\boldsymbol{\beta})}{\partial \beta_j}, \quad j = 1, ..., p.$$

Remember that

$$\mu_i = \boldsymbol{b}'(\theta_i). \qquad \eta_i = \boldsymbol{g}(\mu_i) = \boldsymbol{x_i}^T \boldsymbol{\beta}.$$

Using the chain rule we have

$$U_{j}(\beta) = \frac{\partial I(\beta)}{\partial \beta_{j}}$$

$$= \sum_{i=1}^{n} \frac{\partial I_{i}(\beta)}{\partial \beta_{j}}$$

$$= \sum_{i=1}^{n} \frac{\partial I_{i}(\beta)}{\partial \theta_{i}} \frac{\partial \theta_{i}}{\partial \mu_{i}} \frac{\partial \mu_{i}}{\partial \eta_{j}} \frac{\partial \eta_{i}}{\partial \beta_{j}}.$$
(3)

#### The derivatives

The derivatives are:

$$\frac{\partial l_i(\boldsymbol{\beta})}{\partial \theta_i} = \frac{1}{a(\phi)}(y_i - b^{'}(\theta_i)) = \frac{y_i - \mu_i}{a(\phi)};$$

$$\frac{\partial \theta_{i}}{\partial \mu_{i}} = \left(\frac{\partial \mu_{i}}{\partial \theta_{i}}\right)^{-1} = \left(\frac{\partial b'(\theta_{i})}{\partial \theta_{i}}\right)^{-1} \\
= \left(b''(\theta_{i})\right)^{-1} \\
= \left(V(\mu_{i})\right)^{-1};$$
(4)

$$\frac{\partial \mu_{i}}{\partial \eta_{i}} = \left(\frac{\partial \eta_{i}}{\partial \mu_{i}}\right)^{-1} = \left(\frac{\partial g(\mu_{i})}{\partial \mu_{i}}\right)^{-1} 
\equiv \left(g'(\mu_{i})\right)^{-1};$$
(5)

$$\frac{\partial \eta_i}{\partial \beta_j} = \frac{\partial \mathbf{x_i}^T \boldsymbol{\beta}}{\partial \beta_j} = \mathbf{x}_{ij},$$

where  $x_{ij}$  is the *j*th element of  $\mathbf{x_i}$ , or equivalently the (i, j) element of matrix  $\mathbf{X}$ .



### The score equations

• To solve for  $\beta$  we need to solve the score equations, that is,

$$U_j(\beta) = 0, \quad j = 1, ..., p.$$

In our case we solve

$$U_{j}(\beta) = \sum_{i=1}^{n} \frac{y_{i} - \mu_{i}}{a(\phi)} (V(\mu_{i}))^{-1} (g'(\mu_{i}))^{-1} x_{ij}$$

$$= \sum_{i=1}^{n} \frac{1}{V(\mu_{i})a(\phi)(g'(\mu_{i}))^{2}} x_{ij} (y_{i} - \mu_{i}) g'(\mu_{i})$$

$$= 0,$$
(6)

for j = 1, ..., p.



# Using adjusted dependent variables

Let

$$\omega_i = \frac{1}{V(\mu_i)a(\phi)(g'(\mu_i))^2}.$$

Then the score equations become

$$U_{j}(\beta) = \sum_{i=1}^{n} \omega_{i} \mathbf{x}_{ij} (\mathbf{y}_{i} - \mu_{i}) \mathbf{g}'(\mu_{i}) = 0,$$

for j = 1, ..., p.

Also define

$$\mathbf{z}_i = \eta_i + (\mathbf{y}_i - \mu_i)\mathbf{g}'(\mu_i).$$

Thus

$$U_j(\beta) = \sum_{i=1}^n \omega_i \mathbf{x}_{ij} (\mathbf{z}_i - \eta_i) = 0,$$

for 
$$j = 1, ..., p$$
.



### Matrix notation

• Let  $\mathbf{W} = diag(\omega_1, ..., \omega_n)$ ,  $\mathbf{X}$  denote the design matrix,  $\mathbf{z} = (z_1, ..., z_n)^T$  and  $\boldsymbol{\eta} = (z_1, ..., z_n)^T$ . Also let  $\mathbf{U}(\boldsymbol{\beta}) = (U_1(\boldsymbol{\beta}), ..., U_n(\boldsymbol{\beta}))^T$ . Then  $\mathbf{U}(\boldsymbol{\beta}) = \mathbf{X}^T \mathbf{W} (\mathbf{z} - \boldsymbol{\eta}) = 0.$ 

Since  $\eta = X\beta$ , we have that

$$\mathbf{X}^T \mathbf{W} \mathbf{z} = \mathbf{X}^T \mathbf{W} \mathbf{X} \boldsymbol{\beta}.$$

This is the weighted least squares (WLS) problem. When  ${\bf X}$  and  ${\bf W}$  are known, the estimate of  ${\boldsymbol \beta}$  which solves the normal equations are

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W} \mathbf{z}.$$

Problem: **W** and **z** depend on  $\beta$ !



# Iteratively weighted least squares(IWLS)

- Solution: we iterate!
- Start with a guess for η:

$$\eta^{(0)}=g(\mathbf{y}).$$

(we may need to adjust this slightly in practice).

- Iteratively calculate the following for j = 1, 2, ...
  - 1.  $\mu = h(\eta^{(j-1)})$  (where we let  $h(\cdot)$  denote the inverse link function).
  - 2. **W** =  $diag([V(\mu)a(\phi)(g'(\mu))^2]^{-1}).$
  - 3.  $\mathbf{z} = \eta + (\mathbf{y} \mu)g^{'}(\mu)$ .
  - 4.  $\beta = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W} \mathbf{z}$ .
  - 5.  $\eta^{(j)} = X\beta$ .
- We stop iterating when  $\beta^{(j)} \beta^{(j-1)}$  is "small" (equivalently we can look at changes in  $\eta$ ).



### Remarks on parameter estimation

- ullet We could also estimate eta using a Fisher scoring or Newton-Raphson scheme.
  - -Fisher scoring is

$$\boldsymbol{\beta}^{(j)} = \boldsymbol{\beta}^{(j-1)} + [\mathbf{I}(\boldsymbol{\beta}^{(j-1)})^{-1}]\mathbf{U}(\boldsymbol{\beta}^{(j-1)}),$$

where Fisher's information matrix is

$$I(\beta) = -E(\frac{\partial^2 I(\beta)}{\partial \beta \partial \beta^T}).$$

This can be shown to be equivalent to IWLS.

-The Newton-Raphson algorithm is

$$\boldsymbol{\beta}^{(j)} = \boldsymbol{\beta}^{(j-1)} + [\mathbf{i}(\boldsymbol{\beta}^{(j-1)})^{-1}]\mathbf{U}(\boldsymbol{\beta}^{(j-1)}),$$

where the observed information matrix is

$$\mathbf{i}(\boldsymbol{\beta}) = -(\frac{\partial^2 l(\boldsymbol{\beta})}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T}).$$

This is equivalent to IWLS, Fisher scoring for canonical links only.



#### The second derivative

We have already shown that

$$\frac{\partial l_i(\boldsymbol{\beta})}{\partial \beta_j} = \omega_i \boldsymbol{g}'(\mu_i) \boldsymbol{x}_{ij} (\boldsymbol{y}_i - \mu_i).$$

Now

$$\frac{\partial l_i^2(\beta)}{\partial \beta_j \partial \beta_k} = \frac{\partial}{\partial \beta_k} [\omega_i \mathbf{g}'(\mu_i) \mathbf{x}_{ij} (\mathbf{y}_i - \mu_i)] 
= [\frac{\partial}{\partial \beta_k} \omega_i \mathbf{g}'(\mu_i)] \mathbf{x}_{ij} (\mathbf{y}_i - \mu_i) + \omega_i \mathbf{g}'(\mu_i) \mathbf{x}_{ij} [\frac{\partial}{\partial \beta_k} (\mathbf{y}_i - \mu_i)].$$
(7)

- Start by ignoring the first term!
- In the second term, we know that

$$\frac{\partial \mu_{i}}{\partial \beta_{k}} = \frac{\partial \mu_{i}}{\partial \eta_{i}} \frac{\partial \eta_{i}}{\partial \beta_{k}} = (g'(\mu_{i}))^{-1} X_{ik},$$

and so

$$\frac{\partial_{i}^{2}(\beta)}{\partial \beta_{i}\partial \beta_{k}} = \left[\frac{\partial}{\partial \beta_{k}}\omega_{i}g^{'}(\mu_{i})\right]x_{ij}(y_{i} - \mu_{i}) - \omega_{i}g^{'}(\mu_{i})x_{ij}(g^{'}(\mu_{i}))^{-1}x_{ik}.$$

#### The Fisher information matrix

Simplifying we have

$$\frac{\partial l_{i}^{2}(\boldsymbol{\beta})}{\partial eta_{i}\partial eta_{k}} = [\frac{\partial}{\partial eta_{k}}\omega_{i}g^{'}(\mu_{i})]\mathbf{x}_{ij}(\mathbf{y}_{i} - \mu_{i}) - \omega_{i}\mathbf{x}_{ij}\mathbf{x}_{ik}.$$

• Since  $E(Y_i) = \mu_i$ , the Fisher information for observation *i* is

$$-E(\frac{\partial l_i^2(\boldsymbol{\beta})}{\partial \beta_j \partial \beta_k}) = 0 + \omega_i \mathbf{x}_{ij} \mathbf{x}_{ik}.$$

The Fisher information for the whole sample is

$$-E(\frac{\partial l^2(\boldsymbol{\beta})}{\partial \beta_j \partial \beta_k}) = \sum_{i=1}^n \omega_i \mathbf{x}_{ij} \mathbf{x}_{ik}.$$

In the matrix notation already defined,

$$I(\beta) = X^T W X.$$



### Estimating the Fisher information matrix

X is known in practice, but, W is a diagonal matrix with entries

$$\omega_i = \frac{1}{V(\mu_i)\mathsf{a}(\phi)(g'(\mu_i))^2}.$$

• We can estimate  $\mu_i$  using

$$\mu_i = h(\eta_i) = h(\mathbf{x}_i^T \hat{\boldsymbol{\beta}}),$$

- where we let  $h(\cdot)$  denote the inverse of the link function,  $g(\cdot)$ , and  $\hat{\beta}$  denote the resulting estimator of  $\beta$  obtained from the IWLS.
- In certain cases we do not need to estimate  $\phi$ .

-Why?



#### 按照上述迭代模拟过程 (二项分布)

```
# 牛 成 x 1, x 2
m = 2000
x1=rnorm(m)
x2=rnorm(m)
eta=rep(1,m)+x1+x2
mu=exp(eta)/(1+exp(eta))
#生成y
y=NULL
for(i in 1:m){
  y[i]=rbinom(1,1,mu[i])
# summary(y)
# table(y)
X=model.matrix(~x1+x2)#设计矩阵
```

4□ > 4□ > 4 = > 4 = > = 900

```
############
beta=c(0,0,0)
eta=X%*%beta
n=0
beta0=c()
repeat {
  beta old=beta
  mu=exp(eta)/(1+exp(eta))
  w=diag(as.vector(mu*(1-mu)))
  z=eta+(v-mu)/(mu*(1-mu))
  beta=solve((t(X)%*%w%*%X))%*%t(X)%*%w%*%z
  #print(beta)#输出每一次迭代得到的beta
  eta=X%*%beta
  D=max(abs(beta-beta old))
  n=n+1
  if(D<1e-8)
   hreak
n#迭代次数
beta
data=as.data.frame(cbind(y,x1,x2))
y.glm=glm(y~x1+x2,family=binomial(link="logit"),data=data)
summary(y.glm)
```

# Statistical inference on $\beta$ .

- We obtain the estimate of  $\beta$ ,  $\hat{\beta}$ , from IWLS.
- Asymptotically, for large sample sizes we will have

$$\hat{\boldsymbol{\beta}} \stackrel{d}{\rightarrow} N_p(\boldsymbol{\beta}, \mathbf{I}(\boldsymbol{\beta})^{-1}).$$

- We also estimate  $I(\beta)$  from the data (see previous slide).
- As with the linear model we can now write down a table of the estimated coefficients.

### **Goodness of fit for GLMs**

- In linear models we often assess the goodness of fit by looking at sums of squares,e.g.,RSS
- How do we assess the fit for GLMs?
- We measure the goodness of fit of a GLM using the **deviance** and **Pearson**  $\chi^2$  **statistic**
- Both statistics look at how the data, y, estimated from the GLM.
- The deviance compares log likelihoods, whereas the Pearson statistic is a sum of squares (with an appropriate scaling for the mean-variance relationship).

#### The deviance

- The deviance compares the fit of the full model (when we n parameters, on for each observation) to the fit of the reduced model (when we fit p parameters). It compares log likelihoods.
- Remember the log likelihood is

$$I(\beta) = \frac{\sum_{i=1}^{n} (y_i \theta_i - b(\theta_i))}{a(\phi)} + \sum_{i=1}^{n} c(y_i, \phi)$$

• We will evaluate this log likelihood (in terms of  $\theta_i$  or  $\mu_i = b_{\theta_i}^{'}$ ) for the full and reduced model.



# The deviance(cont.)

- Let  $\widetilde{\theta}_i$  denote the estimate of the canonical parameter,  $\theta_i$ , when we fit the full model, that is, when we estimate  $\mu_i$  using  $\widetilde{\mu} = y_i$ .
- Let  $\hat{\theta}$  be the estimate of  $\theta_i$  in the reduced model, and  $\mu_i$  denote the associated estimate of  $\mu_i$
- Then the deviance is defined to be

$$D(y, \hat{\mu}) = 2a(\phi)[I(\tilde{\theta}) - I(\hat{\theta})]$$

$$= 2a(\phi)\left\{\frac{\sum_{i=1}^{n} [y_i(\tilde{\theta}_i - \hat{\theta}_i) - (b(\tilde{\theta}_i) - b(\hat{\theta}_i))]}{a(\phi)}\right\}$$

$$+ a(\phi)\sum_{i=1}^{n} [c(y_i, \phi) - c(y_i, \phi)]$$

$$= 2\sum_{i=1}^{n} [y_i(\tilde{\theta}_i - \hat{\theta}_i) - (b(\tilde{\theta}_i) - b(\hat{\theta}_i))]$$
(8)

### **Example:Normal**

For normally distributed data we have

$$a(\phi) = \sigma^2$$
  $b(\theta_i) = \frac{\theta_i^2}{2}$ 

$$\theta_i = \mu_i$$

- In the full model we have  $\widetilde{\theta}_i = \widetilde{\mu}_i = y_i$ , and in the reduced model  $\widehat{\theta}_i = \widehat{\mu}_i$ .
- The deviance is

$$D(y, \hat{\mu}) = 2 \sum_{i=1}^{n} [y_i(y_i - \hat{\mu}_i) - \frac{y_i^2}{2} + \frac{\hat{\mu}_i^2}{2}]$$

$$= \sum_{i=1}^{n} (y_i - \hat{\mu}_i)^2.$$
(9)



### **Example:Binomial**

For data following a binomial distribution we have.

### **Example:Possion**

For Possion distributed data we have

$$a(\phi) = 1$$
  $b(\theta_i) = e^{\theta_i}$   $\theta_i = log\mu_i$ 

- In the full model we have  $\hat{\theta}_i = log \tilde{\mu}_i = log y_i$ , and in the reduced model  $\hat{\theta}_i = log \hat{\mu}_i$ .
- The deviance is

$$D(y, \hat{\mu}) = 2 \sum_{i=1}^{n} [y_i (log y_i - log \hat{\mu}_i) - (y_i - \hat{\mu}_i)]$$

$$= 2 \sum_{i=1}^{n} [y_i log (y_i / \hat{\mu}_i) - (y_i - \hat{\mu}_i)].$$
(10)

# **Using deviance**

- Note that the deviance dose **not depend** on  $\phi$ .
- Suppose we fit two GLMs, with one model being a subset of the other. We
  can compare the fit of these two models by calculating the difference
  of the deviances. This is equivalent to a likelihood ratio test (see next
  page).
- Similar to the analysis of variance table we produce for linear models we can create an analysis of deviance table for GLMs
  - Except for the normal cases, the distribution of differences in the deviance are asymptotic.
  - Thus, we need to interpret the analysis of deviance table carefully.

# Likelihood ratios tests(LRTs)

Consider a partition of the p dim coefficient vector, β

$$\beta = \left(\begin{array}{c} \beta_1 \\ \beta_2 \end{array}\right)$$

where  $\beta_1$  is a q dim vector, and  $\beta_2$  is a p-q dim vector.

- Suppose we want to test  $H_0: \beta_2 = \beta_2^0$ .
- Then the likelihood ratio statistic,

$$\lambda(\hat{\beta}_2) = 2[I(\hat{\beta}_1, \hat{\beta}_2) - I(\hat{\beta}_1, \beta_2^0)]$$

is asymptotically  $\chi^2_{p-q}$ .



# Pearson $\chi^2$ statistic

- As before, suppose that we have estimated  $\hat{\mu}_i$  from the data.
- Then the **Pearson**  $\chi^2$  **statistic** is defined by

$$\chi^{2} = \sum_{i=1}^{n} \frac{(y_{i} - \hat{\mu}_{i})^{2}}{V(\hat{\mu}_{i})}$$

- Some examples:
  - **1** Normal:  $\chi^2 = \sum_{i=1}^n (y_i \hat{\mu}_i)^2$ , the RSS.
  - ② Binomial:  $\chi^2$
  - Poisson:

$$\chi^{2} = \sum_{i=1}^{n} \frac{(y_{i} - \hat{\mu}_{i})^{2}}{\hat{\mu}_{i}}$$

# **Residual plots for GLMs**

Similar to linear models we want to:

- Plot residuals versus fitted:
  - Check for appropriateness of the fit.
  - Do we need to transform the response?
  - Check for constancy of the variance of errors.
  - Look for outliers.
- Residual versus time or collection order.
  - Check for systematic problems in the residuals(e.g.,serial correlation).
- Q Q plot of residuals.
  - Check distributional assumptions of the errors.



### Residual plots for GLMs(cont.)

- Plot residuals versus each predictor/covariate in the model.
  - Check adequacy of the fit for each predictor.
  - Curvature may indicate the need to transform predictors.
- Plot residual versus potential predictors NOT in the model.
  - Have any variables been omitted from the model?

#### But, what do we use for residuals in a GLM?

- Residuals for GLMs are harder to interpret.
- Checking the adequacy of variance and link functions are important for GLMs.

### The deviance and Pearson residuals

We showed that the deviances are given by

$$D(y, \hat{\mu}) = 2 \sum_{i=1}^{n} [y_i(\tilde{\theta}_i - \hat{\theta}_i) - (b(\tilde{\theta}_i) - b(\hat{\theta}_i))]$$

$$= \sum_{i=1}^{n} D_i.$$
(11)

The deviance residuals are defined by

$$(r_D)_i = sign(y_i - \hat{\mu}_i)\sqrt{D_i}$$

The Pearson residuals are defined by

$$(r_P)_i = \frac{y_i - \hat{\mu}_i}{\sqrt{V(\hat{\mu}_i)}}$$



# The working and Anscomebe residuals

We obtain the working residuals from the IWLS algorithm:

$$(r_W)_i = z_i - \hat{\eta}_i$$
  
=  $[\hat{\eta}_i + (y_i - \hat{\mu}_i)g'(\hat{\mu}_i)] - \hat{\eta}_i$   
=  $y_i - \hat{\mu}_i)g'(\hat{\mu}_i)$  (12)

- For the Anscombe residuals, see McCullagh and Nelder, page 38.
  - The general idea:transform the Pearson residual to be less skewed.