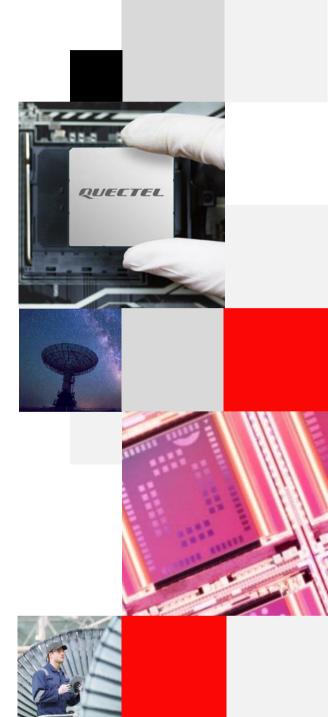




## **Duty of Confidentiality**

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## **GNSS Introduction**

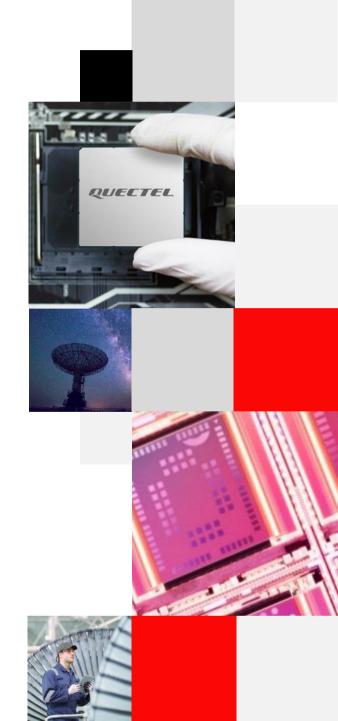
**GNSS Module Portfolio** 

**Specifications & Timelines** 

**Enhanced Technologies** 

**Typical Applications** 

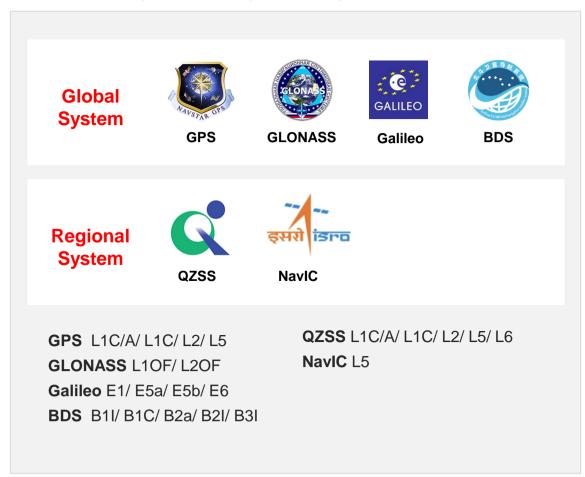
**Quectel GNSS Advantages** 

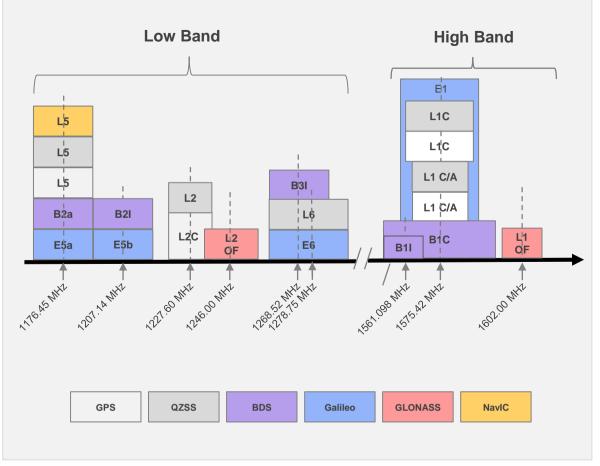


## GNSS (Global Navigation Satellite System)



- Space-based radio-navigation system providing all-weather, 3-dimensional coordinate, velocity and time information anywhere on or near the Earth.
- Consist of global and regional navigation systems.

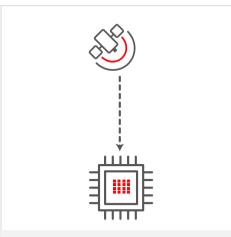




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### **Technologies**





### **Standard Precision (SPG)**

- Meter level positioning accuracy
- Cost-optimized
- Small footprint available
- Low power consumption

### **Application Fields**

- Asset tracking
- Navigation
- Sharing economy



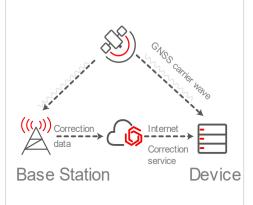


### **Dead Reckoning (DR)**

- · Full-coverage positioning
- Decimeter to centimeter level positioning accuracy with RTK

### **Application Fields**

- Road-vehicle navigation
- Shared e-scooter



### **High Precision (HPG)**

 Decimeter to centimeter level positioning accuracy

### **Application Fields**

- · Autonomous vehicle
- · Robotic lawn mower
- · Precision agriculture
- Unmanned aerial vehicle (UAV)

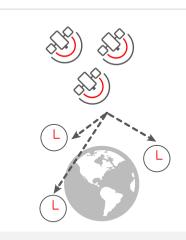


### **ASIL**

- Functional safety
- ASIL-B compliant

### **Application Fields**

- Advanced driverassistance system (ADAS)
- Driver monitor system (DMS)



### Timing

- Nanosecond level accuracy clock
- 1PPS/ 10 MHz time-pulse frequency

### **Application Fields**

- Wireless base station
- Power distribution
- Financial application
- Industrial field



**GNSS** Introduction

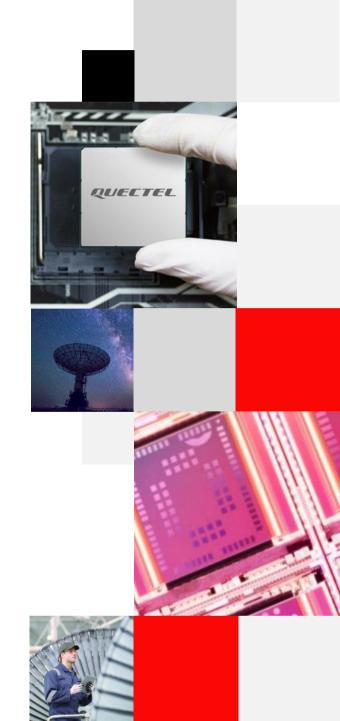
## **GNSS Module Portfolio**

Specifications & Timelines

**Enhanced Technologies** 

**Typical Applications** 

**Quectel GNSS Advantages** 



### **GNSS Module Portfolio**



LC29H Series

· GPS/ GLO/ GAL/ BDS/

### DR/ HPG



#### **LG69T Series**

- TESEO V
- Automotive • GPS/ GLO/ GAL/ BDS/ OZSS/ SBAS
- | 1 + | 2 or | 1 + | 5
- DR/ RTK/ Raw Data



#### LG69T (AB)

- TESEO APP
- Automotive
- · GPS/ GLO/ GAL/ BDS/ QZSS
- L1 + L2 or L1 + L5
- · Raw Data/ ASIL-B

### **Timing**



### LC98S

- TESEO III · GPS/ GLO/ GAL/
- BDS/ QZSS/ SBAS
- L1
- 1PPS



#### LC99T

- TESEO V
- · GPS/ GLO/ GAL/ BDS/ QZSS/ NavIC/ SBAS

NEW

- · 11+15
- 1PPS/ 10 MHz time-pulse frequency



### LC26G-T

- AG3352 Industrial
- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS

NEW

- L1
- 1PPS

#### OUECTE L26-DR L2BXX-XXX QX-XXXXX gx-xxxxx

DUECTEL

OUECTEL

OUECTEL

LC29H

LC28H-XXX

L26-P

L26P-XXX DX-XXXXX

L26-T

L28T-XXX 31-AXXXX

#### L26-DR

- TESEO III
- Automotive
- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS
- 11
- DR

#### L26-P

- · TESEO III
- Industrial · GPS/ GLO/ GAL/ BDS/ OZSS/ SBAS
- 11
- Raw Data



#### L26-T

· GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS

LC29H (AA)

· GPS/ GLO/ GAL/

BDS/ QZSS/ SBAS

- L1
- 1PPS

AG3335

• I1+I5



OUECTEL

DX-30000X

LC29H

OUECTEL

LC02H

#### I C02H Series AG3335

AG3335

Industrial

• 11+15

· DR/ RTK

QZSS/ SBAS

- Industrial
- · GPS/ GOL/ GAL/ BDS/
- QZSS/ SBAS • L1
- RTK
- LC29T NEW

NEW

NEW



#### • TESEO V

- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS
- 11
- 1PPS/ 10 MHz time-pulse frequency

### **SPG** (Dual-band)



#### LC79H

- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS
- L1 + L5

### L76-L **SPG** (Single-band)

#### AG3335



QUECTEL

LC76F

L76-L

LC76F

• GK9501

 MT3333 · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS

· GPS/ GLO/ GAL/

QZSS/ SBAS



#### LC76G

- AG3352
- · GPS/GLO/GAL/ BDS/ QZSS/ SBAS



NEW



#### LG77L

- MT3333
- · GPS/ GAL/ BDS/ GLO/ QZSS/ SBAS



#### L26

- MT3333
- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS



#### LC26G

- · AG3352 · GPS/ GLO/ GAL/



### Integrated **Antenna**



### L86

- MT3333 · GPS/ GLO/ GAL/
- BDS/ QZSS/ SBAS



### LC86L

- MT3333
- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS



### LC86G

- AG3352 · GPS/ GLO/ GAL/
- BDS/ QZSS/ SBAS



### L96

- MT3333
- · GPS/ GLO/ GAL/ BDS/ QZSS/ SBAS
- L1



### L89 R2.0

- AG3335MN
- · GPS/ GLO/ GAL/ BDS/ QZSS/ NavIC/ SBAS
- · AIS140 Compliant • L1 + L5

NEW



**GNSS** Introduction

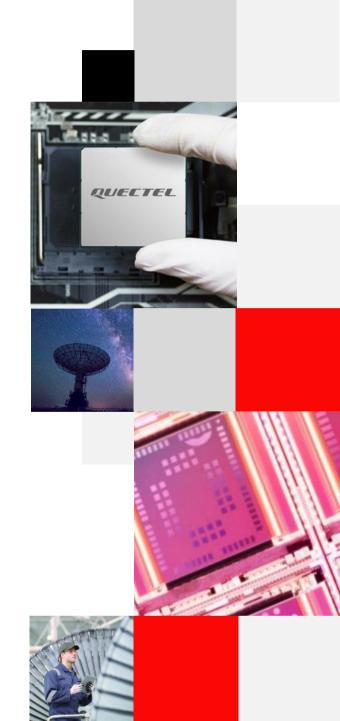
**GNSS Module Portfolio** 

# **Specifications & Timelines**

**Enhanced Technologies** 

**Typical Applications** 

**Quectel GNSS Advantages** 



### **SPG Modules**





- Multi-constellation
- Multi-band<sup>①</sup>
- AGNSS









High reliability



- Cost-optimized
- Low power consumption



- Multiple industry standard footprints
- Pin-to-pin compatible product iterations

## SPG Module Specifications – Single-band



Variant			L76-L	LC76F	LC76G (AB)	LC76G (PA)	L26	LC26G (AB)	LG77L (IC)
Typical	Characteris	stics	Cost-optimized	Support I2C	All Constellations	Low Power Consumption	Multi-constellation	All Constellations	Small Footprint
	Band			l	_1		l	_1	L1
0	Size (mm)			10.1	× 9.7	16 ×	: 12.2	7 × 7	
General	Chipset		MT3333	GK9501 AG3352		AG3352	MT3333	AG3352	MT3333
	Precision (C	EP 50)	2.5 m	2.5 m	1.5 m	1.5 m	2.5 m	1.5 m	2.5 m
	Default		GPS + GLNOASS + QZSS	GPS + GLONASS + QZSS	GPS + GLNOASS + Galileo + BDS + QZSS	GPS + GLNOASS + Galileo + BDS + QZSS	GPS + GLNOASS + QZSS	GPS + GLNOASS + Galileo + BDS + QZSS	GPS + GLNOASS + QZSS
		GPS/ QZSS	•	•	•	•	•	•	•
GNSS		GLONASS	•	•	•	•	•	•	•
GNSS	0	Galileo	•	•	•	•	•	•	•
	Supported	BDS	•	-	•	•	•	•	•
		NavIC	-	-	-	-	-	-	-
		SBAS	•	•	•	•	•	•	•
Interfac	e		UART/ I2C	UART/ I2C	UART/ I2C/ SPI*	UART/ I2C	UART	UART/ I2C	UART/ I2C
Firmwai	re Upgrade		•	•	•	•	•	•	•
Power Supply (Typ.)		3.3 V	3.3 V	3.3 V	3.3 V	3.3 V	3.3 V	3.3 V	
Power C	Consumptiong)	on <sup>①</sup>	31 mA	30 mA	36 mA	10 mA	21 mA 36 mA		23 mA
Project	Stage		MP	MP	CS	CS	MP CS		MP

①: Tested under default constellations

Supported

-: Unsupported

\*: Under development

CEP: Circular Error Probable MP: Mass Production

CS: Commercial Sample

ES: Engineering Sample

## SPG Module Specifications – Dual-band



Variant			LC79H (AL)	LC29H (AA)		
Typical Cl	haracteristic	es	Small Footprint, PVT	Industry Standard Footprint		
	Band		L1 + L5	L1 + L5		
General	Size (mm)		10.1 × 9.7	16 × 12.2		
General	Chipset		AG3335M	AG3335M		
	Precision (C	EP 50)	1.0 m	1.0 m		
	Default		GPS + GLONASS + Galileo + BDS + QZSS + SBAS	GPS + GLONASS + Galileo + BDS + QZSS + SBAS		
		GPS/ QZSS				
		GLONASS	•	•		
GNSS	Supported	Galileo		•		
	Supported	BDS		•		
		NavIC	-	-		
		SBAS	•	•		
Interface			UART/ I2C*	UART/ I2C/ SPI*		
Firmware	Upgrade		•	•		
Power Su	pply (Typ.)		1.8 V	3.3 V		
Power Co	Power Consumption <sup>①</sup> (Tracking)		33 mA	24 mA		
Project St	age		MP	CS		

①: Tested under default constellations PVT: Position, Velocity and Time

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### **SPG Module Timelines**



2022											2023						
Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sep.	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Jun.

### **LC76G (PA)**



### LC26G (AB)



### LC29H (AA)



ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request. MP: Hardware and software ready for mass production.

## Integrated Antenna GNSS Modules





- Multi-constellation
- AGNSS









High reliability



- Integrated antenna
- Integrated LNA

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## Integrated Antenna GNSS Module Specifications



Variant			L96	L89 R2.0	L86	LC86G (LA)	LC86G (AA)	LC86G (AB)	LC86L (IC)
Typical C	haracteristi	cs	Compact Antenna	Support NavIC	All Constellations, Low Power Consumption	Large Size Antenna, All Constellations	Compact Antenna, Multi-constellation (including BDS)	Compact Antenna, Multi-constellation (including GLONASS)	Compact Footprint, All Constellations
	Band		L1	L1 + L5	L1		L1		L1
0	Size (mm)		14 × 9.6	26.4 × 18.4	18.4 × 18.4	18.4 × 18.4 16 × 16		16 × 16	16 × 16
General	Chipset		MT3333	AG3335MN	MT3333	AG3352 AG3352		AG3352	MT3333
	Precision (	CEP 50)	2.5 m	1.8 m	2.5 m	1.5 m	1.5 m	1.5 m	2.5 m
	Default		GPS + GLONASS + QZSS + SBAS	GPS + Galileo + QZSS + NavIC + SBAS	GPS + GLNOASS + QZSS	GPS + GLNOASS + Galileo + BDS + QZSS			GPS + GLNOASS + QZSS + SBAS
		GPS/ QZSS	•	•	•	•	•	•	•
		GLONASS	•	•	•	•	-	•	•
GNSS	Occurs out out	Galileo	•	•	•	•	•	•	•
	Supported	BDS	•	•	•	•	•	-	•
		NavIC	-	•	-	-	-	-	-
		SBAS	•	•	•	•	•	•	•
Interface			UART/ I2C	UART/ I2C	UART	UART	UART	UART	UART
Power Su	upply (Typ.)		3.3 V	3.3 V	3.3 V	3.3 V	3.3 V	3.3 V	3.3 V
	Power Consumption <sup>①</sup> (Tracking)		20 mA	32 mA	26 mA	33 mA	29 mA	29 mA	30 mA
Project S	tage		MP	MP	MP	cs	CS	ES	MP

1: Tested under default constellations

Supported

-: Unsupported

CEP: Circular Error Probable

MP: Mass Production

CS: Commercial Sample

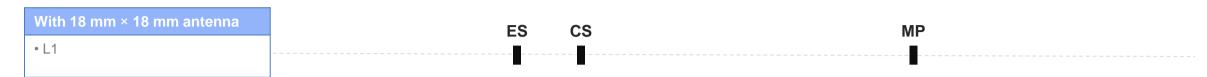
ES: Engineering Sample

### LC86G Series Timelines



	2022												2023				
Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sep.	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Jun.

### LC86G (LA)



### LC86G (AA)



### LC86G (AB)



ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request.

MP: Hardware and software ready for mass production.

### DR/ HPG Modules





- DR/RTK
- Up to centimeter level positioning accuracy











- High reliability
- Up to 105 °C operating temperature<sup>①</sup>





Abundant successful customer applications

- Automotive or industrial grade
- IATF 16949 compliant<sup>①</sup>
- ASIL-B compliant<sup>①</sup>

## L26 Series Specifications



Variant			L26-DR (UDR)	L26-DR (ADR)	L26-P
Typical Chara	cteristics		UDR	ADR	IMU & Raw Data
	Grade		Industrial	Automotive	Industrial
	Band			L1	L1
General	Size (mm)		12.2	2 × 16	12.2 × 16
	Chipset		TES	EO III	TESEO III
	Precision (C	EP 50)	1.	5 m	Depending on external RTK
Technology	DR		UDR	ADR	-
recillology	Raw Data		-		IMU & Raw Data
	Default		GPS + GLONASS + Galileo + SBAS	GPS + GLONASS + Galileo + SBAS	GPS + BDS + SBAS
		GPS/ QZSS	•	•	•
		GLONASS	•	•	•
GNSS	Supported	Galileo	•	•	•
	Supported	BDS	•	•	•
		NavIC	-	-	-
		SBAS	•	•	•
Interface			UART/ SPI*	UART/ SPI*	UART/ SPI*
Power Supply	/ (Typ.)		3.3 V	3.3 V	3.3 V
Power Consu	mption <sup>①</sup> (Tı	acking)	81 mA	74 mA	62 mA
Project Stage			MP	MP	MP

1: Tested under default constellations ADR: Automotive Dead Reckoning

Supported

-: Unsupported \*: Under development IMU: Inertial Measurement Unit MP: Mass Production

CEP: Circular Error Probable

RTK: Real-Time Kinematic UDR: Untethered Dead Reckoning

## LC29H Series Specifications



Variant			LC29H (BA)	LC29H (CA)	LC29H (DA)	LC29H (EA)	LC29H (BS)				
Typical Chara	cteristics		DR + RTK	DR Only	RTK (1 Hz)	RTK (10 Hz)	Base Station				
	Grade			In	dustrial		Industrial				
	Band			L	1 + L5		L1 + L5				
General	Size (mm)			12.2 × 16							
	Chipset			AG3335A/T	AG3335A	AG3335M					
	Precision (C	EP 50)	10 cm	1 m	1 cm	1 cm	-				
	IMU		•	•	-	-	-				
Taskaslamı	RTK		•	-	•	•	-				
Technology	DR <sup>®</sup>		•	•	-	-	-				
	Raw Data		-	-	-	-	•				
	Default		GPS + GLONASS + Galileo + BDS + QZSS	GPS + GLONASS + Galileo + BDS + QZSS	GPS + GLONASS + Galileo + BDS + QZSS	GPS + GLONASS + Galileo + BDS + QZSS	GPS + GLONASS + Galileo + BDS + QZSS + SBAS				
		GPS/ QZSS	•	•	•	•	•				
		GLONASS	•	•	•	•	•				
GNSS	Supported	Galileo	•	•	•	•	•				
	Supported	BDS	•	•	•	•	•				
		NavIC	-	-	-	-	-				
		SBAS	•	•	•	•	•				
Interface			UART/ I2C/ SPI*	UART/ I2C/ SPI*	UART/ I2C/ SPI*	UART/ I2C/ SPI*	UART/ I2C/SPI*				
Power Supply	/ (Typ.)		3.3 V	3.3 V	3.3 V	3.3 V	3.3 V				
Power Consum	nption <sup>①</sup> (Tra	cking)	30 mA	28 mA	25 mA	25 mA	25 mA				
Project Stage			CS (4 wheel DR + RTK) ES (2 wheel DR + RTK)			Developing	ES				

①: 2 wheel ADR and 4 wheel ADR & UDR are supported by different software versions ②: Tested under default constellations DR: Dead Reckoning CS: Commercial Sample ES: Engineering Sample

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## LG69T Series Specifications



Variant			LG69T (AA)	LG69T (AQ)	LG69T (AM)
Typical Chara	cteristics		IMU & GNSS Raw Data	Industrial, RTK + DR	Automotive, RTK
	Grade		Automotive	Industrial	Automotive
	Operating Te	mperature	-40 °C to 85 °C		-40 °C to 85 °C
General	Band		L1 + L5		L1 + L5
General	Size (mm)		22 × 17		22 × 17
	Chipset		TESEO V		TESEO V
	Precision (C	EP 50)	$cm^{\textcircled{1}}$ / 1 $m^{\textcircled{2}}$		1 cm
	RTK		-	•	•
Tachnalasu	DR		-	•	-
Technology	IMU		•	•	-
	Raw Data		•	-	-
	Default		GPS + Galileo + BDS + QZSS	GPS + Galileo + BDS	GPS + Galileo + BDS
		GPS	•	•	•
		QZSS	•	-	-
GNSS	Supported	GLONASS	-	-	-
		Galileo	•	•	•
		BDS	•	•	•
		SBAS	•	-	-
Interface			UART	UART	UART
Power Supply	Power Supply (Typ.)		3.3 V	3.3 V	3.3 V
Power Consur	Power Consumption <sup>®</sup> (Tracking)		237 mA	TBD	340 mA
<b>Project Stage</b>			CS	ES	CS

①: Depending on external Precision Positioning Engine

<sup>2:</sup> Without external Precision Positioning Engine

③: Tested under default constellations IMU: Inertial Measurement Unit

## LG69T Series Specifications



Variant			LG69T (AS)	LG69T (AB)
Typical Char	acteristics		Automotive, Base Station	ASIL-B
	Grade		Automotive	Automotive & ASIL-B
	Operating Te	emperature	-40 °C to 85 °C	-40 °C to 105 °C
	Band		L1 + L5	L1 + L5/ L1 + L2
General	Size (mm)		22 × 17	22 × 17
	Chipset		TESEO V	TESEO APP
	Precision (C	EP 50)	-	cm <sup>①</sup>
	RTK		-	-
Tachnalagy	nnology IMU		-	-
rechnology	IMU		-	-
	Raw Data		Base Station	•
	Default		GPS + Galileo + BDS + QZSS	GPS + GLONASS + Galileo + BDS + QZSS
		GPS/ QZSS	•	
GNSS		GLONASS	-	
ONOO	Supported	Galileo	•	•
		BDS	•	•
		SBAS	-	-
Interface			UART	UART
Power Suppl	у (Тур.)		3.3 V	3.3 V @ VCC; 1.2 V @ VCC_CORE
Power Consu	umption <sup>②</sup> (T	racking)	360 mA	65 mA @ VCC; 236 mA @ VCC_CORE
Project Stage	e		CS	CS

①: Depending on external Precision Positioning Engine

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<sup>2:</sup> Tested under default constellations

## LG69T Series Specifications



Variant			LG69T (AJ)	LG69T (AI)		
Typical Charac	cteristics		IMU & GNSS Raw Data	GNSS Raw Data		
	Grade		Auto	motive		
	Operating To	emperature	-40 °C	o 105 °C		
General	Band		L1 + L5	L1 + L5/ L1 + L2		
General	Size (mm)		22 × 17	22 × 17		
	Chipset		TES	SEO V		
	Precision (C	EP 50)	cm <sup>①</sup>	cm <sup>①</sup>		
Technology	IMU			-		
recillology	Chipset Precision (C		IMU & GNSS Raw Data	GNSS Raw Data		
	Default		GPS + Galileo + BDS + QZSS	GPS + GLONASS + Galileo + BDS + QZSS		
		GPS/ QZSS				
GNSS		GLONASS	-			
01400	Supported	Galileo	•	•		
		BDS				
		SBAS	-	-		
Interface			UART	UART		
Power Supply	(Тур.)		3.3 V	3.3 V		
Power Consur	nption <sup>②</sup> (Tr	acking)	245 mA	295 mA		
Project Stage			MP	MP		

①: Depending on external Precision Positioning Engine

<sup>2:</sup> Tested under default constellations

## LC02H Series Specifications



Variant			LC02H (AA)	LC02H (BA)							
Typical Char	acteristics			Orientation Measurement							
	Grade			Industrial							
	Band			L1							
	Size (mm)		24 × 22								
General	Chipset		AG3335								
	Orientation		Heading Angle Accuracy: 0.2 °/m Tilt Angle Accuracy: 0.3 °/m	Heading Angle Accuracy: 0.2 °/m Tilt Angle Accuracy: 0.3 °/m Roll Angle Accuracy <sup>①</sup> : 1.2 °/m							
	Precision (C	CEP 50)	1.5 m	1.5 m							
	IMU		-	•							
Technology	RTK		•								
	DR		-	-							
	Default		GPS + GLONASS + Galileo + BDS + QZSS + SBAS	GPS + GLONASS + Galileo + BDS + QZSS + SBAS							
		GPS/ QZSS	•								
		GLONASS	•								
GNSS	Cummented	Galileo	•								
	Supported	BDS	•								
		NavIC	-	-							
		SBAS	•	•							
Interface			UART/ SPI*/ I2C <sup>2</sup>	UART/ SPI*/ I2C <sup>©</sup>							
Power Supp	ly (Typ.)		3.3 V	3.3 V							
Power Cons	umption <sup>®</sup>	(Tracking)	103 mA	108 mA							
Project Stag	е		Developing	Developing							

①: The roll angle depends on the IMU output ②: Multiplexed with SPI interface ③:Tested under default constellations

### LC29H Series Timelines





ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request. MP: Hardware and software ready for mass production.

### LC29H Series Timelines



	2022												2023				
Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sep.	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Jun.

### LC29H (EA)



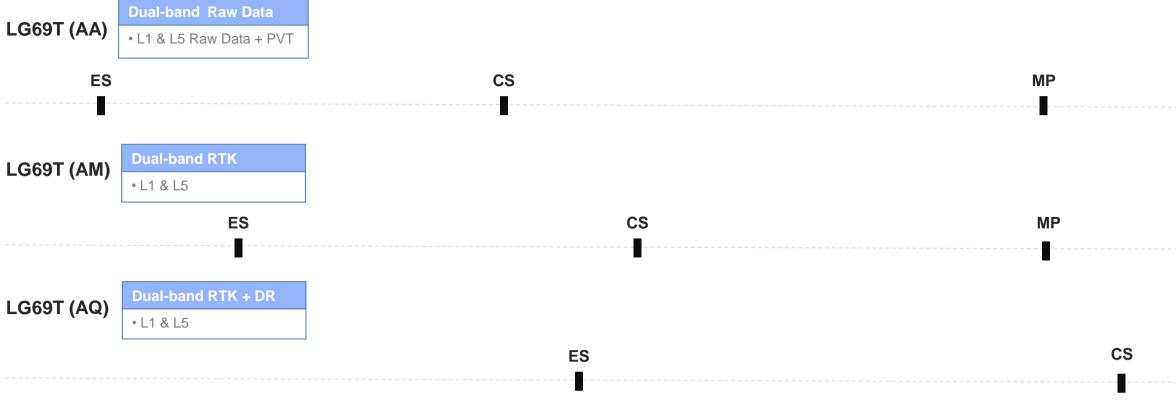
ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request. MP: Hardware and software ready for mass production.

### LG69T Series Timelines



2021				2022										2023			
Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sept.	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.
		Duel benef	Daw Dat														
LG69T	(AA)	Dual-band	aw Data +														



ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

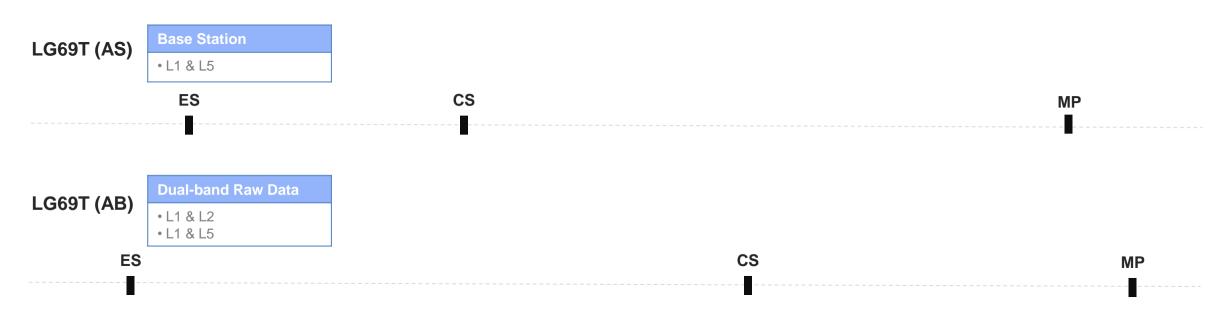
MP: Hardware and software ready for mass production.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request.

### LG69T Series Timelines



2021				2022									2023				
Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sept.	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.



ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request. MP: Hardware and software ready for mass production.

### LC02H Series Timelines



					20	23					
Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sept.	Oct.	Nov.	Dec.

### LC02H (AA)



### LC02H (BA)





ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request. MP: Hardware and software ready for mass production.

## Timing GNSS Modules





- Nanosecond level accuracy
- 1PPS/ 10 MHz time-pulse frequency









High reliability



- Multi-constellation
- Multi-band
- Single-satellite timing



- Widely used on 4G/5G base stations
- Suitable for Open Radio Access Network (O-RAN)

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## Timing GNSS Module Specifications



Variant	t		LC98S	LC99T	L26-T	LC29T	LC26G-T (AA)				
Typical	Characterist	ics	Single-band	Dual-band, All Constellations	Single-band	Single-band, All Constellations	Single-band, All Constellations				
	Band		L1	L1 + L5	L1						
	Size (mm)		22	.4 × 17		12.2 × 16					
Gener al	Chipset		TESEO III	TESEO V	TESEO III	TESEO V	AG3352				
	Precision 1PPS (@ 1σ)		< 6.8 ns	< 6 ns	< 6.8 ns	< 6 ns	< 8 ns				
	10 MHz Output		-	•	-	•	-				
	Default		GPS + BDS + QZSS	GPS + GLONASS + Galileo + BDS + NavIC	GPS + GLONASS + Galileo	GPS + GLONASS + Galileo + BDS	GPS + GLONASS + Galileo + BDS + QZSS				
	Comparted	GPS/ QZSS	•	•	•	•	•				
		GLONASS	•	•	•	•	•				
GNSS		Galileo	•	•	•	•	•				
	Supported	BDS	•	•	•	•	•				
		NavIC	-	•	-	-	-				
		SBAS	•	•	•	•	•				
Interfac	ce		UART	UART	UART	UART	UART/ I2C				
Power	Supply (Typ.	.)	3.3 V	3.3 V	3.3 V	3.3 V	1.8 V				
	Power Consumption <sup>①</sup> (Tracking)		74 mA	285 mA	75 mA	232 mA	36 mA				
Project	Stage		MP	ES	MP	ES	Developing				

①: Tested under default constellations

Supported

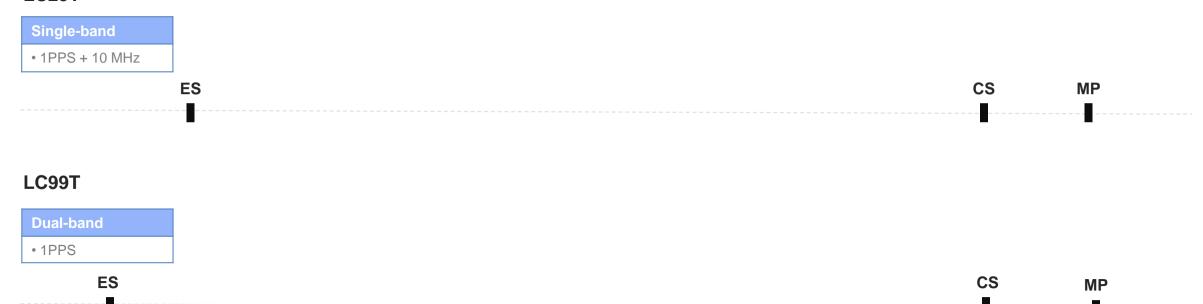
-: Unsupported \*: Under development CEP: Circular Error Probable ES: Engineering Sample MP: Mass Production

### LC29T & LC99T Timelines



2022							2023							
Jul.	Aug.	Sept.	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.	May	Jun.			

### LC29T



ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

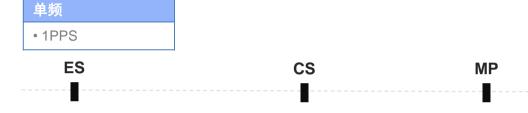
CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request.

### LC26G-T Timelines



					20	23					
Jan.	Feb.	Mar.	Apr.	May	Jun.	Jul.	Aug.	Sept.	Oct.	Nov.	Dec.

### LC26G-T (AA)



ES: Engineering samples ready. Basic functions are available for customers' simple demo purpose.

CS: Commercial samples ready. Stable hardware design and quite stable software design. New software features can be added upon request. MP: Hardware and software ready for mass production.



**GNSS** Introduction

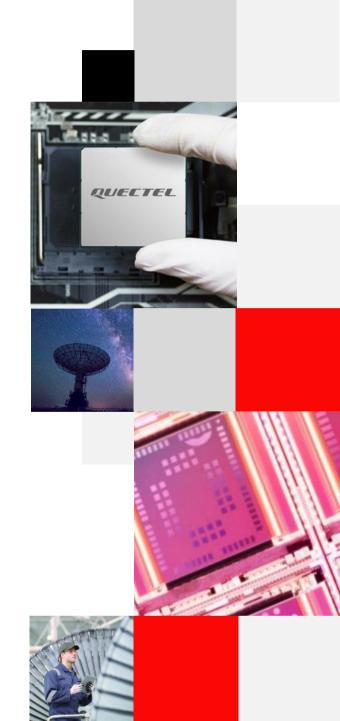
**GNSS Module Portfolio** 

**Specifications & Timelines** 

# **Enhanced Technologies**

**Typical Applications** 

**Quectel GNSS Advantages** 

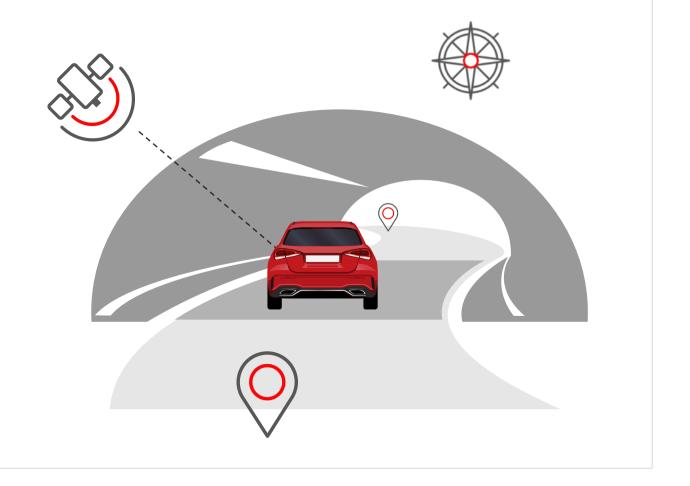


## DR Technology



### **Dead Reckoning (DR)**

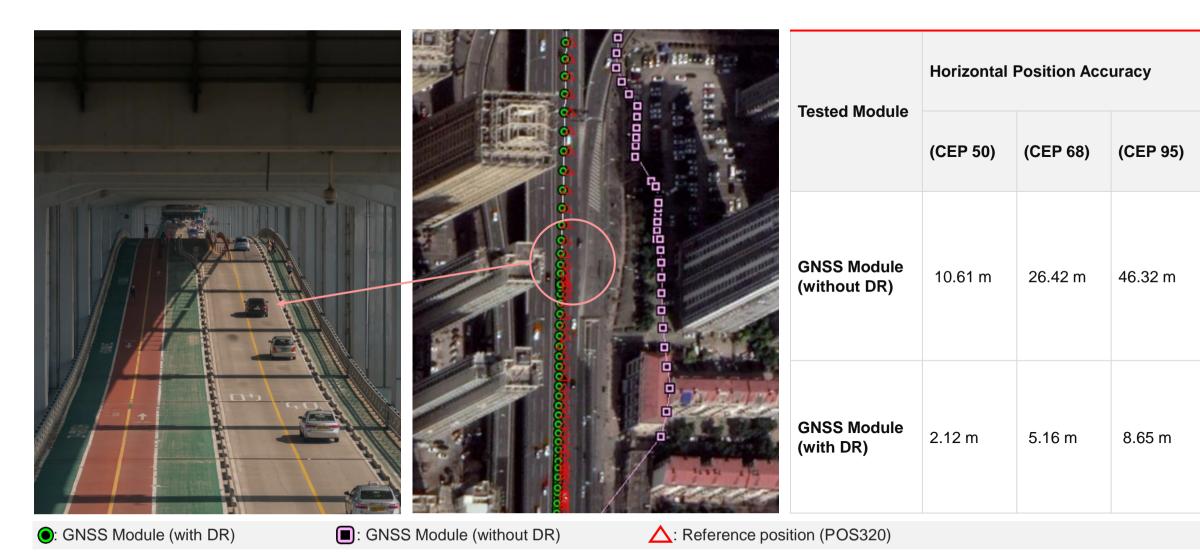
- DR uses GNSS and INS (Internal Navigation System) in a fused solution to provide continuous high accuracy positioning. If the GNSS visibility drops due to obstructions, the INS will provide the information until the satellite visibility improves.
- Based on this technology, the device can get full coverage positioning or navigation even in parking garages, tunnels and urban canyons.



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### **DR** Performance



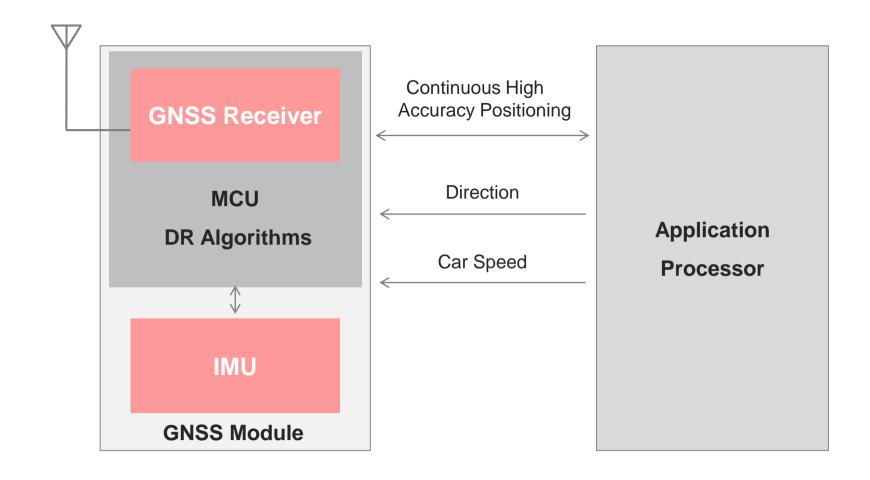


Testing Environment: Driving under the elevated road with high buildings on both sides. Result: The accuracy can be improved to meter level after using DR technology.

Page 34 / 46 CEP: Circular Error Probable Version: 4.4 | Status: Released

## **DR** Application Architecture





• GNSS module receives direction, car speed and runs DR algorithms to achieve continuous high accuracy positioning.

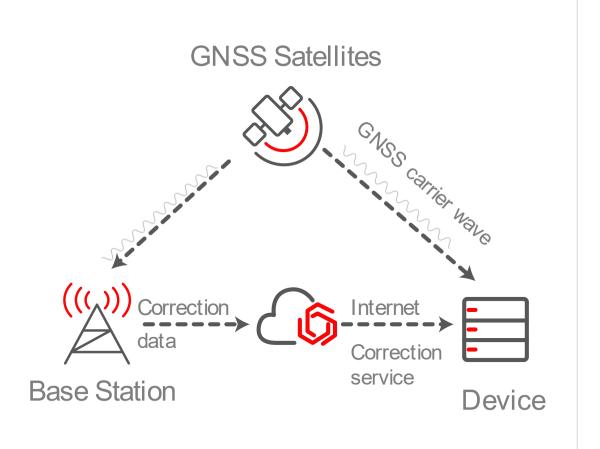
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## RTK Technology



# Real-Time Kinematic (RTK) Positioning Process:

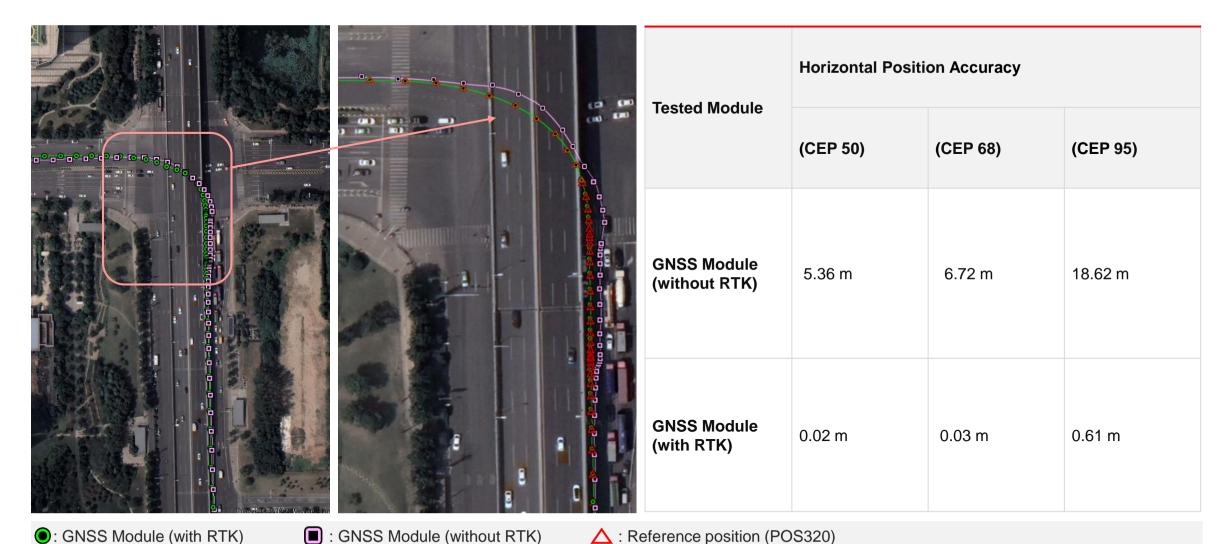
- Satellites broadcast the signal.
- The base station calculates the common errors based on carrier phase, and then transfer them to the cloud server.
- The device or receiver calculates a precise position with the carrier phase it received and the correction data from correction server.
- Based on this technology, the device can achieve up to centimeter level positioning accuracy.



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### RTK Performance





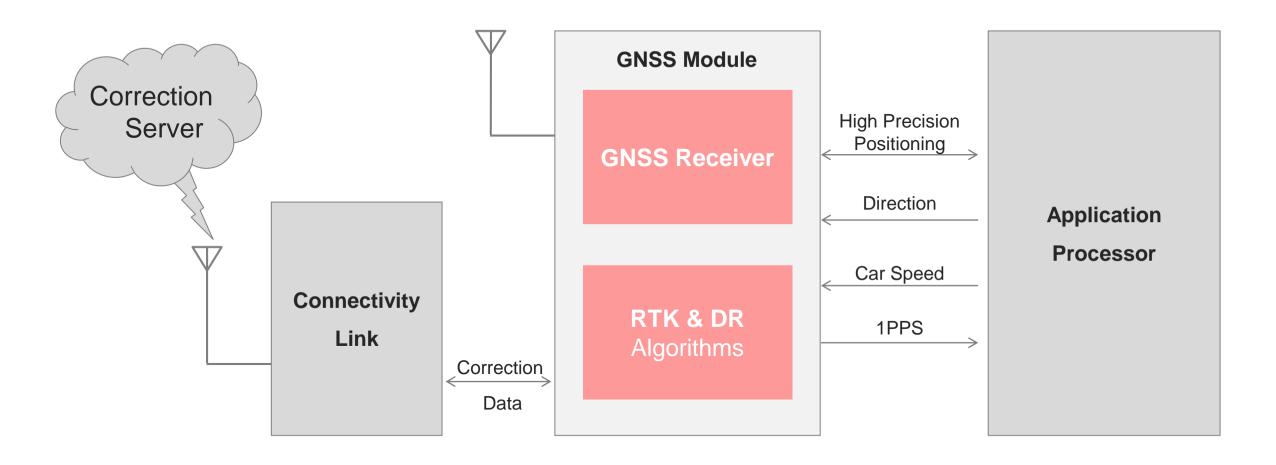
Testing Environment: Driving in an open sky environment.

Result: The accuracy can be improved to centimeter level after using RTK technology.

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## **RTK Application Architecture**





• GNSS module receives correction data, direction, car speed and runs RTK & DR algorithms to achieve centimeter level accuracy positioning.

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**GNSS** Introduction

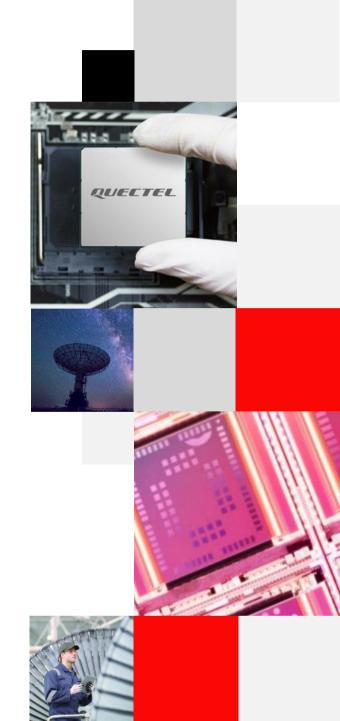
**GNSS Module Portfolio** 

**Specifications & Timelines** 

**Enhanced Technologies** 

# **Typical Applications**

**Quectel GNSS Advantages** 



## Typical Applications – Positioning







### UAV

- Formation flight performance
- UAVs for precision agriculture
- Firefighting UAVs

## Precision Agriculture

- Automatic tillage and harvesting
- Accurate operation
- Reduced labor costs

## **Robotic Lawn Mower**

- Borderless automatic mowing
- Accurate operation
- Reduced labor costs

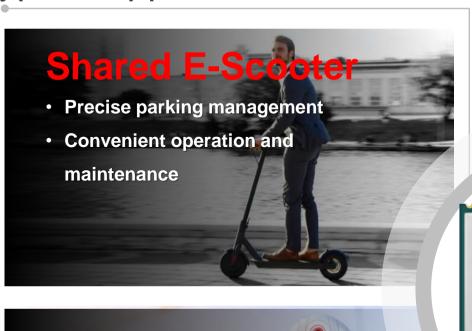
ADAS: Advanced Driver-assistance System

UAV: Unmanned Aerial Vehicle

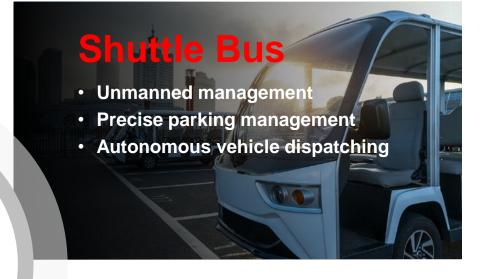
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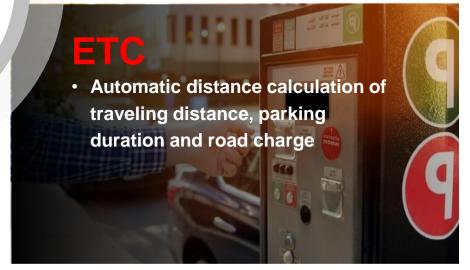
## Typical Applications – Positioning











ETC: Electronic Toll Collection

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QUECTEL

LC29H

LC29HXXXX

## Typical Applications – Timing













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## Typical Application Scenarios





**Personal & Pet Trackers** 



**OBD (On-board Diagnostics)** 



**Vehicle Tracking** 



**Asset Tracking** 



**Shared Bike** 



**Construction or Mining** 



**GNSS** Introduction

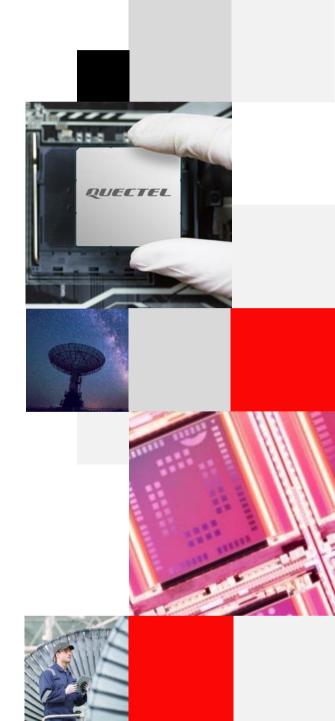
**GNSS Module Portfolio** 

**Specifications & Timelines** 

**Enhanced Technologies** 

**Typical Applications** 

# **Quectel GNSS Advantages**



## Quectel GNSS Module Advantages



### **What Quectel Has**











### What You Will Get



GNSS Testing and Antenna Tuning Services



Shortened Development Cycle



Multiple Compatible Modules for Supply Shortage

### **Perfect Results**

Products can be released in shorter time. Additionally, R&D investment is minimized and stable supply can be guaranteed.

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We are a global IoT solutions provider, backed by outstanding support and services, to deliver a smarter world.

- Unbeatable choice from the broadest module portfolio in the world
- High quality range of off-the-shelf and customized antennas
- Providing Connectivity-as-a-Service
- Superb support with the largest R&D team in the industry
- Continuous innovation in 5G, LPWA, CV2X, Smart Modules
- A passionate, dedicated team of "Quectelers" ensure our customers always come first



**Build a Smarter World** 

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