base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 base link inertia base Broadcaster: /ur hardware interface Broadcaster: /robot state publisher Average rate: $500.1\overline{1}1$ Average rate: $47.5\overline{2}6$ Buffer length: 5.007 Buffer length: 4.945 Most recent transform: 1653293218.723 Most recent transform: 1653293218.676 Oldest transform: 1653293213.716 Oldest transform: 1653293213.732 tool0 controller shoulder link Broadcaster: /robot state publisher Average rate: 47.526 Buffer length: 4.945 Most recent transform: 1653293218.676 Oldest transform: 1653293213.732 upper arm link Broadcaster: /robot state publisher Average rate: 47.526 Buffer length: 4.945 Most recent transform: 1653293218.676 Oldest transform: 1653293213.732 forearm link Broadcaster: /robot state publisher Average rate: $47.5\overline{2}6$ Buffer length: 4.945 Most recent transform: 1653293218.676 Oldest transform: 1653293213.732 $wrist_1_{link}$ Broadcaster: /robot state publisher Average rate: $47.5\overline{2}6$ Buffer length: 4.945 Most recent transform: 1653293218.676 Oldest transform: 1653293213.732 wrist_2_link Broadcaster: /robot state publisher Average rate: $47.5\overline{2}6$ Buffer length: 4.945 Most recent transform: 1653293218.676 Oldest transform: 1653293213.732 wrist_3_link Broadcaster: /robot state publisher Broadcaster: /static transform publisher 1653293155561584533 Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 flange camera link Broadcaster: /robot_state_publisher Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 tool0 $camera_depth_frame$ Broadcaster: /camera/realsense2 camera manager Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0

camera depth optical frame

view frames Result

Recorded at time: 1653293218.7575574