REPORT

SUBMITTED BY - Mayank Gupta EMAIL - guptamayankwork@gmail.com **PROJECT NAME: SMART AGRICULTURE SYSTEM**

BASED ON IOT

DATE:15-06-2020

PROJECT OVERVIEW

SMART AGRICULTURE SYSTEM IS COMMERCIALLY SCALABLE METHOD WHICH IS BEING BUILT TO REDUCE THE EFFORTS OF FARMERES. THIS PROJECT WILL SOLVE THE MOST IMPORTANT PROBLEM THE FARMERS ARE FACING THAT IS WATERING THE CROPS AT RIGHT TIME AND ACCORDING TO THE REAL TIME FIELD CONDITIONS.

THERE ARE MANY THINGS TO TAKE CARE OF, WHILE WATERING OF CROPS.IF WE WATER THE CROPS TO MUCH, THE CROPS CAN GET DAMAGED DUE TOP WATER LOGGING.IF WE WATER THE CROPS ON A RAINY DAY, THE EXTRA RAINWATER MAY TAMPER THE GROWTH OF CROPS.IF IN ANY CASE THE FARMER FORGET TO WETER THE CROPS FOR ONE DAY OR TWO BECAUSE OF ANY REASON, IT CAN AGAIN MAKE THE SOIL TWO DRY FOR THE PLANTS TO GET THEIR DAILY NUTRITION LEVEL.

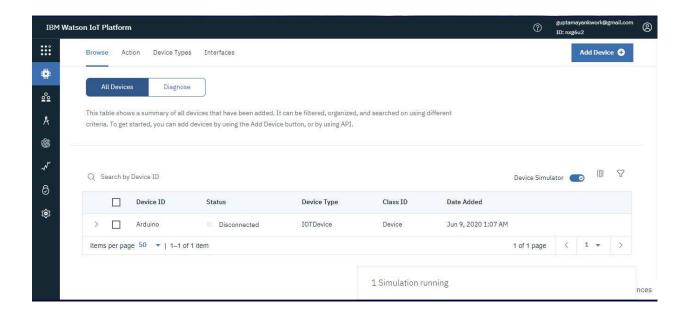
CONSIDERING MANY FACTS ,THE PROJECT IS MAINLY FOCUSED ON AUTOMATING THE PROCESS OF WATER PUMP AND PROVIDING THE FARMERS WITH AN APPLICATION WHERE THEY CAN SEE THE STATUS OF THE PUMP, MOISTURE OF THE SOIL, HUMIDITY ,TEMPERATURE AS WELL AS WEATHER FORECASTING SO THE FARMER CAN MANY ARRANGEMENTS ACCORDINGLY.

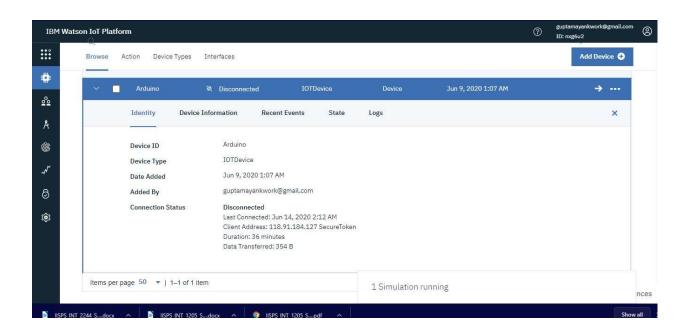
THE ULTIMATE GOAL OF THE PROJECT IS TO INCREASE THE QUALITY OF YIELD BY TAKING CARE OF IRRIGATION PROCESS AND STARING THE REVOLUTIONARY ERA OF FARMERS BY BRINGING TECHNOLGY INTO THE DOMAIN.

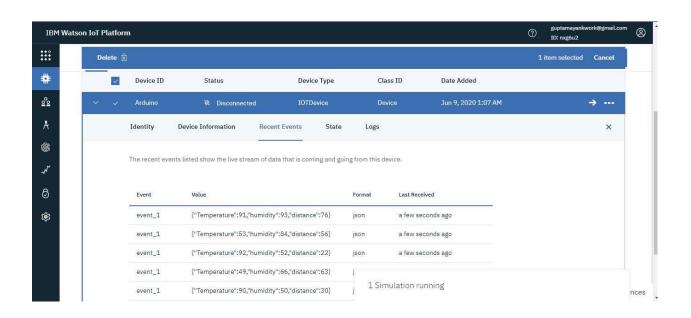
PROJECT SCOPE

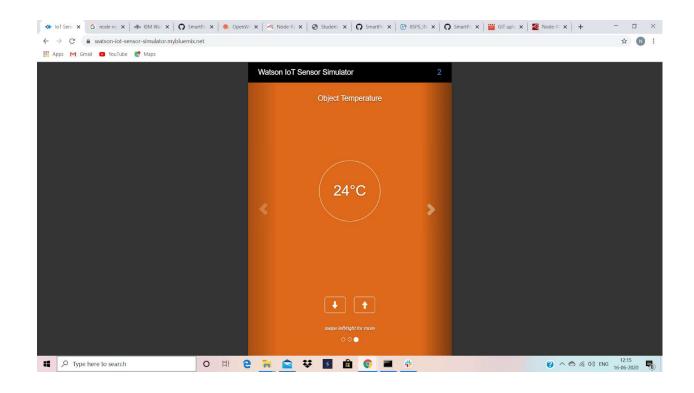
- -WE ARE DEVELOPING AN UI FOR THE FARMERS TO HELP THEM CONTROL THE REAL FIELD PARAMETERS SUCH AS TEMPERATURE, HUMIDITY AND SOIL MOISTURE IN ORDER TO IRRIGATE THE FIELD ACCORDINGLY.
- -THE UI IS BUILD USING NODE RED.
- -THE IBM CLOUD IS USED TO STORE DATA FROM IBM WATSON IOT SIMULATOR WHICH IS KIND OF VIRTUAL SENSOR.
- -THIS UI WILL HELP THE FARMERS CONTROL THE IRRIGATION ACCORDING TO THE FIELD PARAMETERS AND THEY CAN DO SO FROM ANYWHERE.

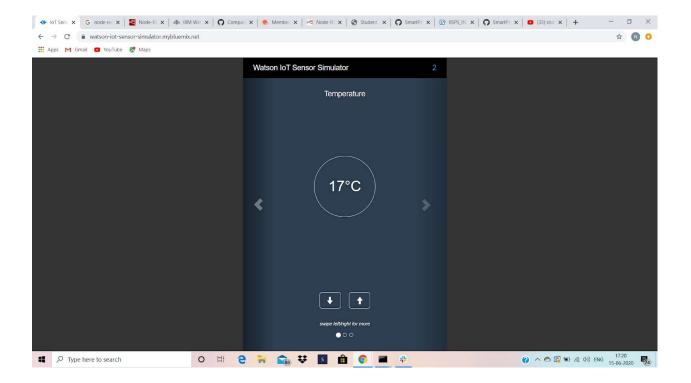
USE OF IBM WATSON

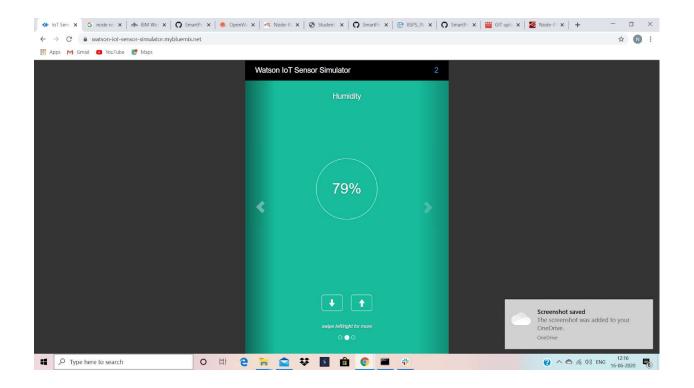










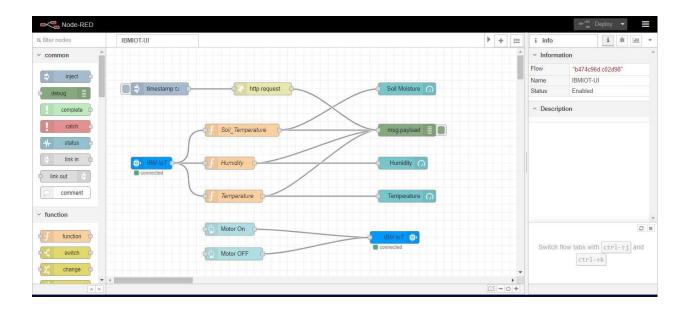




HERE WE HAVE ALL WORKING COMPONENTS SUCH AS THE IOT SENSOR. THE DEVICE WHICH CONNECTS TO THE SENSOR AND UPLOADS DATA INTO THE IBM CLOUD. THE MOTOR WHICH TAKES INPUT FROM THE WEB APP AND THEN UPLOADS INPUT VIA PYTHON CODE ON CLOUD.

THE BOTTOM CORNER OF THE IMAGE SHOWS SOME CARDS WHICH DISPLAYS THE DATA IN A VISUALLY APPEALING WAY THAN JUST NUMBERS SUCH AS LINE GRAPHS OR GAUGE WHICH MAKES IT EASY TO UNDERSTAND.

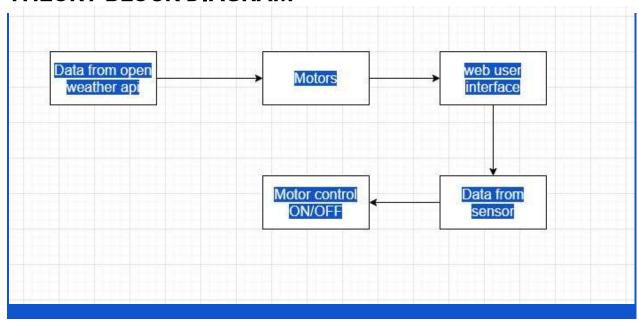
FUNCTIONING OF THE APP



IN THIS FLOW WE HAVE IBM NODES TO GET THE IOT SENSOR DATA FROM IBM CLOUD AND PUSH THE MOTOR ON/OFF COMMANDS FROM THE WEB DASHBOARD FROM THE WEB DASHBOARD BACK TO THE IBM CLOUD.

HERE WE ARE USING HTTP REQUEST WHICH I AM USING TO GET CURRENT WEATHER DATA AND DISPLAY ON THE DASHBOARD.

THEORY BLOCK DIAGRAM



THIS BLOCK DIAGRAM IS SHOWING THEORITICAL COMPUTATION OF WHAT ARE WE BASICALLY DOING IN THIS PROJECT.

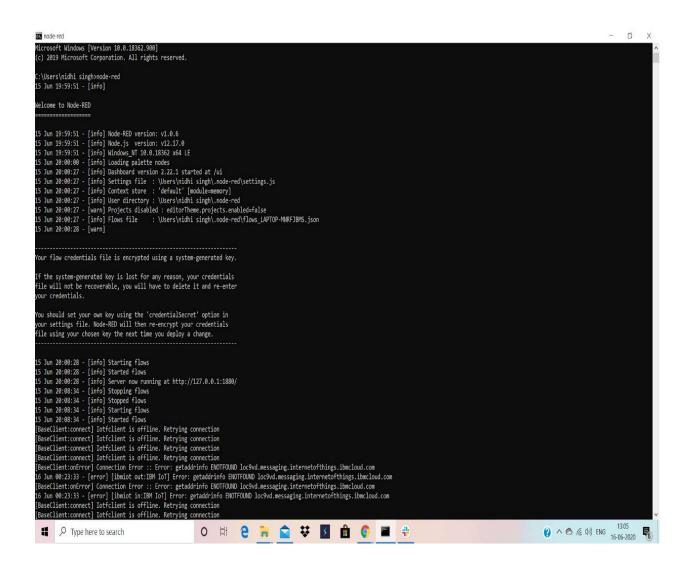
SO, HERE WE ARE BASICALLY MONITORING THE WEATHER CONDITIONS AND COLLECTING DATA FROM OPEN WEATHER API.

THE REAL TIME FIELD CONDITIONS ARE MONITORED VIA SENSOR AND THE DATA IS COLLECTED VIA SENSOR.

AND ACCORDINGLY THE MOTOR IS CONTROLLED BY ON/OFF BUTTONS.

ALL THESE DATAS ARE SEND TO THE WEB USER INTERFACE AND THE MOTOR IS CONTROLLED ACCORDINGLY.

NODE-RED ON COMMAND PROMPT



PROJECT SCHEDULE

WEEK 1	WEEK 2	WEEK 3	WEEK 4
planned my project	created device in	started working	started to prepare
	IBM cloud	with node-red	reports on zoho
			writer
set up the	installed node red	configured IBM iot	pushed my files to
development	locally	sensor and	github repository
environment		node-red UI	
created accounts in	installed the	downloaded python	recorded the
IBM cloud	required nodes	idle and ran the	feedback video
		code	

PYTHON CODE

```
诸 subscribeibm.py - C:\Users\mayan\Desktop\ibmsubscribe-master\subscribeibm.py (3.7.4)
File Edit Format Run Options Window Help
import time
 import sys
import ibmiotf.application # to install pip install ibmiotf
 import ibmiotf.device
authMethod = "token"
authToken = "123456789" #Replace the authtoken
def mvCommandCallback(cmd): # function for Callback
           print("Command received: %s" % cmd.data)
if cmd.data('command']=='motoron':
    print("Motor ON IS RECEIVED")
           elif cmd.data['command'] == 'motoroff':
                       print ("Motor OFF IS RECEIVED")
           if cmd.command == "setInterval":
                      if 'interval' not in cmd.data:
                                 print("Error - command is missing required information: 'interval'")
                                  interval = cmd.data['interval']
           elif cmd.command == "print":

if 'message' not in cmd.data:
                                 print("Error - command is missing required information: 'message'")
                       else:
                                   output=cmd.data['message']
                                  print (output)
try:
           deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method": authMethod, "auth-token": authToken}
            deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
           print("Caught exception connecting device: %s" % str(e))
            sys.exit()
subscribeibm.py - C\Users\nidhi singh\Desktop\ibmsubscribe-master\subscribeibm.py (3.8.3)
                                                                                                                                                                                         – a ×
File Edit Format Run Options Window Help
import time
import sys
import sys
import import sys
import import imiotf.application # to install pip install ibmiotf
import ibmiotf.device
#Provide your IBM Watson Device Credentials organization = "loofwd" freplace the ORG ID deviceType "motor"#replace the Device type wi devicetd = "2"#replace Device ID authMethod = "token" authMethod = "12345678" #Replace the authtoken
def myCommandCallback(cmd): # function for Callback
    print("Command received: %2" % cmd.data)
    if cmd.data['command']=='lighton':
        print("MOTOR ON IS RECEIVED")
        elif cmd.data['command']=='lightoff':
    print("MOTOR OFF IS RECEIVED")
        if cmd.command == "setInterval":
                if 'interval' not in cmd.data:
    print("Error - command is missing required information: 'interval'*)
        else:
interval = cmd.data['interval']
elif cmd.command == "print";
if 'message' not in cmd.data:
    print("Error - command is missing required information: 'message'")
else:
                       output=cmd.data['message']
print(output)
        except Exception as e:
    print("Caught exception connecting device: %s" % str(e))
    sys.exit()
# Connect and send a datapoint "hello" with value "world" into the cloud as an event of type "greeting" 10 times deviceCli.connect()
while True:
                                                                                                                                                                    Ln:23 Col:32

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(3) ENG 16:06-2020
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```

```
*Python 3.7.4 Shell*
                                                                       X
File Edit Shell Debug Options Window Help
Motor OFF IS RECEIVED
                                                                               4
Command received: {'command': 'motoroff'}
Motor OFF IS RECEIVED
Command received: {'command': 'motoroff'}
Motor OFF IS RECEIVED
Command received: {'command': 'motoroff'}
Motor OFF IS RECEIVED
2020-06-17 17:42:40,212
                       ibmiotf.device.Client
                                                   ERROR Unexpected disconne
ct from the IBM Watson IoT Platform: 1
2020-06-17 17:42:42,144 ibmiotf.device.Client
                                                   INFO Connected successfu
11y: d:nxg6u2:IOTDevice:Arduino
Command received: {'command': 'motoron'}
Motor ON IS RECEIVED
Command received: {'command': 'motoron'}
Motor ON IS RECEIVED
Command received: {'command': 'motoron'}
Motor ON IS RECEIVED
2020-06-17 17:42:43,759 ibmiotf.device.Client
                                                   ERROR Unexpected disconne
ct from the IBM Watson IoT Platform: 1
2020-06-17 17:42:45,737 ibmiotf.device.Client
                                                 INFO Connected successfu
11y: d:nxg6u2:IOTDevice:Arduino
                                                  ERROR Unexpected disconne
2020-06-17 17:42:47,377 ibmiotf.device.Client
ct from the IBM Watson IoT Platform: 1
2020-06-17 17:42:49,234 ibmiotf.device.Client INFO Connected successfu
```

WHEN THE MOTOR COMMANDS ARE GIVEN ON THE NODE-RED DASHBOARD, WE GET SIGNAL IN THE PYTHON PROGRAM.

BIBLIOGRAPHY

- 1.https://cloud.ibm.com/
- 2.https://watson-iot-sensor-simulator.mybluemix.net/
- 3.https://loc9vd.internetofthings.ibmcloud.com/dashboard/devices/browse
- 4.http://localhost:1880/ui/#!/0?socketid=cxfzbgCJL5U8bODKAAAc

<u>5.http://localhost:1880/#flow/23ee611b.2e0ebe</u> <u>6.https://github.com/SmartPracticeschool/IISPS-INT-2244-Smart-Agriculture-system-based-on-loT</u>